

## Android&Linux

# Compilation and Integration Guide

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#### **Contact Information**

- Website: www.amlogic.com
- Pre-sales consultation: contact@amlogic.com

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Technical support: <a href="mailto:support@amlogic.com">support@amlogic.com</a>

## **Revision History**

#### Issue 0.2 (2019-12-18)

This is the 0.2 release.

- 1. buildroot\_sdk add 32bit compilation environment under linux environment, compiles 32bit/64bit executable files through parameter control.
- 2. Added a description of the openvx\_case directory in the case code.

#### Issue 0.1 (2019-07-22)

This is the Initial release.



## **Contents**

Rev	/ision	History		ii	
1. Introduction					
2.	Cas	Case Code			
	2.1 Introduction			2	
	2.2	Proce	ess	2	
		2.2.1	Case Code Generation Process	2	
		2.2.2	Major interfaces and Parameter Acquisition	2	
3.	Android-based Compilation and Integration				
	3.1	Introd	uction	5	
	3.2	1.TFli	te-based Development	5	
		3.2.1	Instructions	5	
		3.2.2	Running Environment Confirmation	6	
		3.2.3	FAQ		
	3.3	JNI-b	ased Development	7	
		3.3.1	Introduction	7	
		3.3.2	Compilation Environment	7	
		3.3.3	Ndk Compilation		
4.	Linux-based Compilation and Integration				
	4.1	Introd	uction	9	
	4.2	Comp	oiling buildroot Executable Files	9	
		4.2.1	Introduction to the SDK Package	9	
		4.2.2	Compiling Executable Files	9	
		4.2.3	Running Executable Files	9	
5	FAC	)		10	

## 1. Introduction

This document provides the guidance to the case code compilation and integration process in Linux and Android OSs after model transcoding for internal developers and external users.



## 2. Case Code

#### 2.1 Introduction

The following figure shows the model-transcoded case code:

```
577 12月 18 16:55 BUILD

5835 12月 18 16:55 main.c

2000 12月 18 16:55 makefile.linux

12691 12月 18 16:55 mobilenettf.vcxproj

1063 12月 18 16:55 nbg_meta.json

3447390 12月 18 16:55 network_binary.nb

4096 12月 18 16:55 openvx_case

358 12月 18 16:55 vnn_global.h

7505 12月 18 16:55 vnn_mobilenettf.c

977 12月 18 16:55 vnn_mobilenettf.h

3629 12月 18 16:55 vnn_post_process.c

462 12月 18 16:55 vnn_post_process.h

24058 12月 18 16:55 vnn_pre_process.c

1545 12月 18 16:55 vnn_pre_process.h
```

- 1. **mobilenet\_tf.nb** generates an nbg file with its default name of **network\_binary.nb**, but you can rename the file as **needed**.
- vnn\_mobilenettf.c/vnn\_mobilenettf.h is the header file and results corresponding
  to model creation and release. (The vnn\_modelname.c file is generated upon case
  code generation.)
- vnn\_pre\_process.c/vnn\_post\_process.h is the model pre-processing file, where
  case code quantization is performed upon the result of the number of read images
  minus the average value and then divided by scale.
- 4. vnn\_post\_process.c/vnn\_pre\_process.h is the model post-processing file, where the quantized output results are obtained, converted to float32 data, and processed with top operations. (Top5 processing is performed for all case code due to a single template.)
- openvx\_case: directly call the openvx interface to run the case code of the nbg model. currently It is not used.

## 2.2 Process

#### 2.2.1 Case Code Generation Process

**TODO** 

## 2.2.2 Major interfaces and Parameter Acquisition

The unique global handle is vsi\_nn\_graph\_t \* graph.

Step 1 Create a handle graph = vnn\_CreateNeuralNetwork( path\_to\_xxx.nb).

Alternatively, use graph = vnn\_CreateXXXX(path\_to\_xxx.nb, NULL) in vnn\_xxxmodel.c.

Step 2 vnn VerifyGraph(vsi nn graph t\*graph)

#### Step 3 Prepare the following parameters:

Number of input sources: graph->input.num

Obtain the corresponding vsi\_nn\_tensor\_t \* tensor:

tensor = vsi\_nn\_GetTensor( graph, graph->input.tensors[i]);

obtain the size of the related tensor:

sz = vsi\_nn\_GetElementNum(tensor)

obtain the dimension information:

dim\_num = tensor->attr.dim\_num

width = tensor->attr.size[0];

height = tensor->attr.size[1];

channel = tensor->attr.size[2];

batch = tensor->attr.size[3];

obtain quantization parameters:

2.75.W Int8/int16: indicates the number of decimal places, ff:

fl = tensor->attr.dtype.fl

U8: indicates scale and zero point:

scale = tensor->attr.dtype.scale

zero\_point= tensor->attr.dtype.zero\_point

Copy the data to the related tensor:

vsi\_nn\_CopyDataToTensor(graph, tensor, data)

Perform quantization:

Quantize input values after the operations of average value deduction and scale division:

Int8/16:

float fl = pow(2.,tensor->attr.dtype.fl)

value\_int8 = (int)(value\_float \* fl)

U8:

value\_uint8 = value\_float/scale + zero\_point

Step 4 Deduce and calculate:

vnn\_ProcessGraph(graph)

Step 5 Obtain output results:

Number of output results: graph->output.num

Obtain the corresponding tensor:

tensor = vsi\_nn\_GetTensor(graph, graph->output.tensors[i])

Obtain the results and convert them to float32 data:

```
stride = vsi_nn_TypeGetBytes(tensor->attr.dtype.vx_type); (It is 2 for int16 and
         1 for int8/u8.)
         uint8_t * tensor_data = (uint8_t *)vsi_nn_ConvertTensorToData(graph, tensor);
         sz = vsi_nn_GetElementNum(tensor);
         buffer = (float *)malloc(sizeof(float) * sz);
         Obtain quantization parameters:
         Int8/int16: indicates the number of decimal places, fl:
         fl = tensor->attr.dtype.fl
         U8: indicates scale and zero_point:
         float scale = tensor->attr.dtype.scale
         int zero_point= tensor->attr.dtype.zero_point
         Convert the quantized results to float32 data:
         float fl_value = pow(2., -tensor->attr.dtype.fl);
         for (i = 0; i < sz; i++) {
         buffer[i] = tensor_data[stride * i] *fl_value;
         or buffer[i] = (tensor_data[stride * i] -zero_point)*scale
         }
         Perform debugging:
Step 6
         Save tensor to the following files:
         vsi_nn_SaveTensorToBinary(graph, tensor, "data.txt");
         vsi_nn_SaveTensorToText( graph, tensor, "input.txt", NULL);
         vsi_nn_SaveTensorToTextByFp32( graph, tensor, filename, NULL);
```

## 3. Android-based Compilation and Integration

## 3.1 Introduction

Currently, the NN function is integrated into the Android platform. The following describes two Android-based development methods:

1. TFlite-based development:

**Advantage**: If an apk has been developed based on TFlite, you only need to add a code line and quantize the model to int8 data.

#### Disadvantages:

- Only quantized TFlite models are supported.
- There is a limit on operators and might be compatible problems once an operator is not supported by the TFlite structure.
- 2. JNI-based development:

**Advantage**: A variety of model types are supported, including caffe, tensorflow, onnx, darknet, and tflite. Many algorithms are also supported.

**Disadvantage**: Currently, interfaces are not packaged. Therefore, it is mandatory for JNI-based development to extract the corresponding interfaces based on the transcoded case code, package the interfaces, and then compile them to so.

## 3.2 1.TFlite-based Development

#### 3.2.1 Instructions

Amlogic implements compatibility with the bottom layer of the TFlite structure in the Android platform. The supported layers are listed in the **OperationCode** enumeration variable. (It is defined in the **NeuralNetworks.h** file in the **frameworks/ml/nn/runtime/include** directory for Android code.)

Only operators that are used on site and listed in the **AddOpsAndParams** interface in the **nnapi\_delegate.cc** file are supported. You can ask onsite configurations for reference.

Compatibility details about APK running on NN:

- Step 1 Ensure that the tflite is a 8bit quantization model. If not, use the official TFLiteConverter tool provided by Tensorflow to quantize the mode.
  - a) Compile the executable tf file: bazel build tensorflow/contrib/lite/toco:toco
  - b) Perform quantization:

bazel-bin/tensorflow/contrib/lite/toco/toco \

- --input\_file=\$(pwd)/mobilenet\_v1\_1.0\_224/frozen\_graph.pb \
- --input\_format=TENSORFLOW\_GRAPHDEF \
- --output format=TFLITE \
- --output\_file=/tmp/mobilenet\_v1\_1.0\_224.tflite \

```
--inference_type=FLOAT \
--input_type=FLOAT \
--input_arrays=input \
--output_arrays=MobilenetV1/Predictions/Reshape_1 \
--input_shapes=1,224,224,3
```

Step 2 Enable the bottom layer to run on NN by adding tfliteOptions.setUseNNAPI(true) to code.

#### 3.2.2 Running Environment Confirmation

After you perform the operations in the previous section, compatibility between TFLite-based apk and NN is achieved. Before apk running, you need to check whether the Android version used in the board support the NN environment. Do as follows upon Adb shell connection:

- Run the following command to check if the nn server is started:
  - : ps -A |grep neuralnetwork
- 2. Run the following command to check if the npu module is loaded:
  - : Ismod |grep galcore
- 3. Run the following command to check if the npu node is normal: (Permissions are 664)
  - : Is /dev/galcore -I

If the results for all the preceding checks are yes, the current Android version support the NN environment, and the apk can be revoked to the NPU through the nn server.

#### 3.2.3 FAQ

How do I deal with the following error when I enable NNAPI after the TFLite model is loaded?

```
E/tflite: Op code 98 is currently not delegated to NNAPI
E/tflite: Returning error since TFLite returned failure nnapi_delegate.cc:738.
E/tflite: Failed to build graph for NNAPI
```

**Root cause**: As mentioned above, the TFLite structure facilitates compatibility between the NN bottom layer and some layers defined in **NeuralNetworks.h**. This error is reported because a custom layer that is not defined in the header file exists in the TFLite model. If you set NNAPI to true, the TFLite framework will check every layer of the TFLite model. Once there is any layer that is not defined in the **NeuralNetworks.h**, this error will be reported.

**Solution**: You can split the TFLite model, remove the undefined layer from **NeuralNetworks.h** through CPU operations, and generate a new TFLite model. Alternatively, you can use the JNI-based development method.

## 3.3 JNI-based Development

Compared with the TFLite-based development method, JNI-based development supports more layers and is more flexible. Currently, this method applies to all the models running on the Buildroot platform.

#### 3.3.1 Introduction

Amlogic provides a sdk package upon ndk compilation, including so and header files that are required for case code compilation. Developers can use this package to compile executable files of the case code and even the so file that corresponds to the interface required by apk development.

### 3.3.2 Compilation Environment

#### Ndk installation

Step 1 Download the ndk package.

https://dl.google.com/android/repository/android-ndk-r17-linux-x86\_64.zip

Step 2 Decompress the zip file and configure environment variables.

Open ~/.bashrc and add the following information to the end of the file (or /etc/profile).

export NDKROOT=/usr/ndk/android-ndk-r17b

export PATH=\$NDKROOT:\$PATH

Save and exit. Then, update the **source** ~/.bashrc environment variable.

Step 3 Verify the ndk installation.

Open shell and enter **ndk-build** to check whether the ndk environment is successfully installed. If any information except for **ndk-build not found** is displayed, the environment is ready.

#### Sdk package introduction



**ReadMe.txt** introduces how to install the ndk environment and compile so and executable files.

Android\_sdk:Header files and so needed to compile case code.

**conversion\_scripts\_nbg\_unify:** demo code, run cmd: ndk-build in this directory.

### 3.3.3 Ndk Compilation

Step 1 Compile Android executable files.

Refer to the current demo **conversion\_scripts\_nbg\_unify**. Run **ndk-build** to compile case code.

Do as follows to compile your own case code:

- a) Create a directory named **code\_dir** in the same directory as **conversion\_scripts\_nbg\_unify**.
- b) In the **code\_dir** directory, create a **jni** directory and store case code to this directory.
- c) Copy Android.mk and Applicatoin.mk in the ovx\_src\_facenet\_88\jni directory to the jni directory.
- d) Modify common\_src\_files (listing all .c files) in Android.mk
- e) In the **code\_dir** directory, run ndk-build.

#### Note

If any information indicating no **libjpeg-t.so** is displayed, you can rename **libjpeg.so** in the **sdk/lib** directory to **libjpeg-t.so**, and then copy it to the board.

- Step 2 Compile the Android so file.
  - Repeat the procedure for compiling executable files.
  - b) Modify the end of Android.mk as follows:

```
44
45 #LOCAL_CFLAGS += -pie -fPIE
46 #LOCAL_LDFLAGS += -pie -fPIE
47 #include $(BUILD_EXECUTABLE)
48
49 include $(BUILD_SHARED_LIBRARY)
50
```

Step 3 Run the compilation command ndk-build.



Currently, only the 32-bit so file can be compiled.

## 4. Linux-based Compilation and Integration

## 4.1 Introduction

For buildroot-based development, there is an independent major version, supporting compilation of the case code sdk package. This chapter describes how you can compile the transcoded case code to buildroot-based executable files. (Only guidance to compilation to executable files is provided because there is uncertainty about buildroot in other development environments.)

## 4.2 Compiling buildroot Executable Files

#### 4.2.1 Introduction to the SDK Package

buildroot_sdk	2019/12/13 10:08 文件夹	
nbg_unify_mobilenet_tf	2019/12/13 10:22 文件夹	

**buildroot\_sdk** is the sdk packaged upon buildroot compilation, including header and so files and other resources required for compilation.

nbg\_unify\_mobilenet\_tf is the demo program.

#### 4.2.2 Compiling Executable Files

- Step 1 Modify line15: export AQROOT=/path\_to/buildroot\_sdk of build\_vx.sh in nbg\_unify\_mobilenet\_tf.
- Step 2 In this directory, run ./build\_vx.sh arm/arm64.
- Step 3 Copy case code to a directory that is in the same level as nbg\_unify\_mobilenet\_tf in case you want to compile your own case code.
- Step 4 Copy build\_vx.sh in nbg\_unify\_mobilenet\_tf to the case code directory.
- Step 5 Compile and run ./build\_vx.sh arm/arm64 to generate executable files in the bin\_r directory.

## 4.2.3 Running Executable Files

- Step 1 Copy the compiled executable files, **xxx.nb**, and images to the board.
- Step 2 Run ./xxxx xxxx.nb xxxx.jpg.

#### Note

- Case code supports only jpeg images.
- By default, only images in the same size as the model can be processed.
- After running export VSI\_USE\_IMAGE\_PROCESS=1, you can upload images in different sizes.

## 5. FAQ

None

