

Summary of pre-recorded videos

- Memory hierarchy
- Cache design principles
- General organization of cache
- Cache placement policy
- Direct-mapped cache
- Fully associative cache
- Set associative cache

Review: Principle of Locality

Temporal Locality

 a resource that is referenced at one point in time will be referenced again sometime in the near future

Spatial Locality

- the likelihood of referencing a resource is higher if a resource near it was just referenced
- 90/10 Locality Rule of Thumb
 - a program spends 90% of its execution time in only 10% of its code
 - a consequence of how we program and store data in the memory
 - hence, it is possible to predict with reasonable accuracy what instructions and data a program will use in the near future based on its accesses in the recent past

Cache Concepts

- The term "Cache"
 - the first level of the memory hierarchy (from the CPU)
 - often used to refer to any buffering technique exploiting the principle of locality

 Directly exploits temporal locality providing faster access to a smaller subset of the main memory which contains copy of data <u>recently</u> used

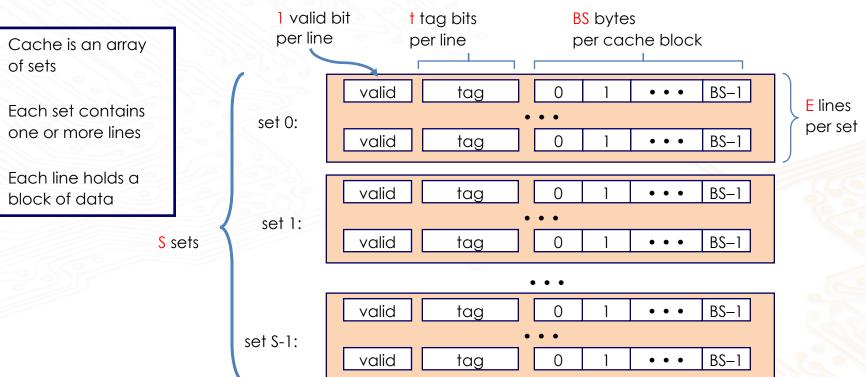
 When a cache miss occurs, a fixed-size block of <u>contiguous</u> memory cells is retrieved from the main memory based on the principle of spatial locality

Example

```
for ( i= 0 ; i< 20 ; i++)
for( j=0; j<10; j++)
a[i]=a[i]*j;
```

- Temporal locality: for the inner loop, it accesses memory a[i] repeatedly in each iteration.
- Spatial locality: for the outer loop, it accesses memory a[0], a[1], ...,a[20] sequentially.

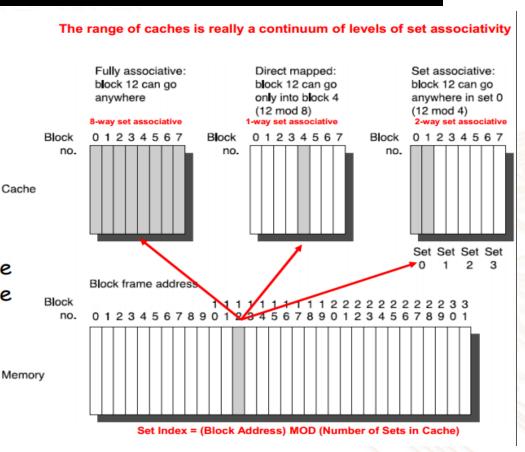
General Organization of a Cache (Part 1/3)



Cache size: $C = (1 \text{ bit} + 1 \text{ bits} + BS \text{ bytes}) \times E \times S$

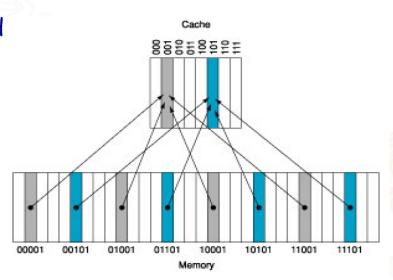
Cache Organization Schemes: Placing a Memory Block into Cache

- Block
 - unit of memory transferred across hierarchy levels
- Set
 - a group of blocks
- Modern processors
 - direct map
 - 2-way set associative
 - 4-way set associative
- Modern memories
 - millions of blocks
- Modern caches
 - thousands of block frames



Example: Direct Mapped Cache with 8 Blocks

- Each memory block is mapped to one cache entry
 - cache index = (block address)mod (# of cache blocks)
 - e.g., with 8 blocks, 3 low-order address bits are sufficient
 - Log2(8) = 3
- Is a block present in cache?
 - must check cache block tag
 - upper bit of block address
- Block offset
 - addresses bytes in a block
 - block==word ⇒ offset =2 bits
- How do we know if data in a block is valid?
 - add valid bit to each entry





The tag index boundary moves to the right as we increase associativity (no index field in fully associative caches)

Example: Measuring Cache Size

- How many total bits are required for a direct-mapped cache with 16KB of data and 4-word block frames assuming a 32-bit address?
- 16KB of data = 4K words = 2¹² words
- Block Size of 4 (= 2^2) words $\Rightarrow 2^{10}$ blocks

TAG	INDEX	OFFSET
18	10	2 2

- # Bits in a Tag = 32 (10 + 2 + 2) = 18
- # Bits in a block = # Tag Bits + # Data Bits + Valid bit
- # Bits in a block = $18 + (4 * 32)_{10} + 1 = 147$
- Cache Size= # Blocks x #Bits in a block= 2 x 147=147Kbits
- Cache Overhead = 147Kbits / 16KB = 147 / 128 = 1.15