

As Much Resilience As You Want: A Resilient Legion

Karthik Murthy, Mike Bauer, Wonchan Lee, Elliott Slaughter, Sean Treichler,
and Alex Aiken

Stanford University, USA,

Abstract. Resilient is an important aspect of scaling applications on large clusters. As we approach parallelism profiles of several millions and long running applications, we need to ensure that ineffect “we reach the end”. Defining the policy interaction with the programming model features necessitates that we revisit the memory consistency model. Recoverability, a critical step in resilience, opens the door to optimizations such as speculation. We also evaluate this. ...

Keywords: resilience

1 Introduction

2 Resilience Policy

3 Interaction of Resilience Policy with Legion Features

which are the legion features of importance ?

put a figure of interaction.

what is the memory consistency angle here ?

what does it mean to advance the commit wavefront

Resilience is a tangling of the lifetime of a task and a region snapshot- 1) when can we advance a commit wavefront ? 2) whats the lifetime of a region-instance snapshot ?

on this front, we see it as a two-step process a) define a consistent cut of tasks problem, b) commit any task strictly behind this wavefront c) garbage collect any snapshot that serves as input to any task that is already committed

consistent cut of tasks that can be part of the commit wavefront: a set of tasks whose inputs are need_preserve'ed, or they are strictly post-dominated by tasks whose inputs are need_preserved.

3) what about copy/index/tasks ? copy local to local follows the above semantics copy local to remote get committed immediately after successful execution. index launch tasks, actually feel need not be in the task graph, unless virtual mapping is used. they can be garbage collected immediately after all child tasks are included in the dependence analysis wavefront - I am thinking we will never have a case where are relaunching the index launch, since hte child tasks either are part of the committed wavefront or are not (pending a discussion on phase barriers)

Question on what to do about must_epoch tasks with phase_barrier inside them ?

answer: restartable phase_barrier with generation commit callback

4 Implementation

5 Experiments

5.1 local recover vs global recovery

5.2 compute/comm vs no-failure/single failure/multi-failure

5.3 S3D, Pennant, Stencil, Circuit

5.4 Some Interesting Task Graphs for Recovery

6 Resilience Application: Speculation

6.1 Experiments

7 Adaptive Resilience

7.1 Resilience Policy Implemented via Mapper: Example 1 Generic

7.2 Resilience Policy Implemented via Mapper: Example 2 UT Austin

Interaction of need_preserve with the commit wavefront

Obtaining dependence graph in the mapper before calling need_preserve

8 Related Work

9 Conclusion

References

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