Face Recognition: Methods and Applications

Hasham Asad Department of Computer Science & IT, University of Lahore, Lahore, Pakistan Hasham Asad

Abstract

Faces have been the main focus when it comes to recognition for a human being. The machine on the other hand failed to perceive plains like a human mind does and thus it's harder for a machine to recognize a face then on top of that recognize whose face it is. Image processing has been a hardware demanding job for machines and a lengthy and tiring process for humans, but with the recent improvements in hardware and software image recognition is no longer a thing of the past.

The goal of this research is to present a simple and efficient face recognition model that is easier to develop and improve upon.

The most important part of an image recognition system is obtaining the dataset, for this research in question a custom data set of a class containing almost 22 university students is used, to show the ability of the model to be extended into a face recognition based attendance system. Good high definition camera is the basic requirement. The photos must be different in different lighting conditions, different angles of class and different backgrounds.

The model used face recognition is the pre trained Yolov8m object detection model. Which is well documented and easy to train. Altho the model is based on object detection but ignoring the facial features and considering faces as 2 dimensional objects it can perform just as well. The model is trained on 100 epochs and a dataset of 859 png with 22 different faces. The number is achieved by rotating the images 3 sides 90, 180 1nd 270.

A removing duplication algorithm is used to remove duplication in images and furthermore median filter is applied for the removal of noise and histogram is used for contrast equalization.

Keyword: face detection, yolo, image processing

Introduction

Facial recognition technology has become a cornerstone of modern security systems, social media platforms, and user authentication processes. The ability to accurately and efficiently identify individuals based on their facial features holds significant promise for applications ranging from surveillance and access control to personalized user experiences. Recent advancements in deep learning and computer vision have paved the way for more robust and precise facial recognition models. Among these advancements, the YOLO (You Only Look Once) family of models has emerged as a powerful framework for real-time object detection and recognition.

In this research paper, we explore the development and implementation of a facial recognition model based on the YOLOv8 architecture. YOLOv8, the latest iteration in the YOLO series, introduces several enhancements over its predecessors, including improved accuracy, faster processing speeds, and more efficient handling of small and densely packed objects. These characteristics make YOLOv8 particularly well-suited for the task of facial recognition, where precision and speed are paramount.

Our study aims to harness the capabilities of YOLOv8 to create a facial recognition system that can operate effectively in diverse and dynamic environments. We address key challenges such as varying lighting conditions, occlusions, and differences in facial expressions. Additionally, we evaluate the model's performance against existing facial recognition benchmarks to determine its viability for real-world applications.

Through this research, we contribute to the growing body of knowledge in the field of facial recognition by demonstrating how state-of-the-art object detection models like YOLOv8 can be adapted and optimized for identifying human faces with high accuracy and efficiency. This paper presents a comprehensive overview of our methodology, experimental results, and potential future directions for enhancing the model's capabilities.

Literature Review

The literature found for face detection provides a variety of different ideas for the performance, optimization and more accurate predictions, making the model both fast and accurate. Firstly to improve the dataset, the quality of the images it is suggested to use a median filter in order to reduce noise in an image and use histogram for the contrast balacement of different images.

Viola P and Jones M rectangular suggested a feature detection method which is widely used for its efficiency and effectiveness. According to them there are three kinds of rectangle features;

- Two rectangle features is the difference between the sums of the pixels within two rectangular regions.
- A three rectangle feature computes the sum within two outside rectangles subtracted from the sum in a center rectangle.
- Four rectangles compute the difference between diagonal pairs of rectangles.

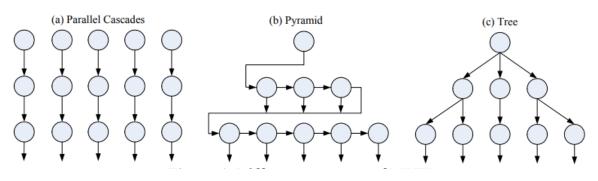
A simple edge detection can be used to differentiate the background d from the face and then the background can be removed forming a smaller image and processing time.

Using a face feature picking algorithm then using that to identify the mood of the person can also be performed.

This research is also based on Viola and Jones framework. They propose to extend the framework by training different cascades individually for each view and then use them as a whole like figure. They propose the following structure for better performance.

WFS Tree-Structure Detector

Pyramid structure adopts coarse-to-fine strategy to handle pose variance



And following algorithm is used

- 0. (Input) Given a sample **x** and the constructed tree detector *T*.
- 1. (Initialization) Set the node list *L* empty; push the root node of *T* into *L*; empty the output list *O*.
- 2. (WFS procedure)
 - While *L* is not empty, do
 - Pop the first node *d* from *L*.
 - Calculate the determinative vector $\mathbf{G}^{(d)}(\mathbf{x})$, where $\mathbf{G}^{(d)}(\mathbf{x}) = \left[g_1^{(d)}(\mathbf{x}), ..., g_n^{(d)}(\mathbf{x}) \right]$
 - For t=1,...,n:
 - If $g_t^{(d)}(\mathbf{x}) = 1$

Get the *t*-th child node s_i of *d*

If s_i is a leaf node

Push l_i , the label of s_i , into the list O.

Else

Push s_i into the list L.

- End if
- End if

End for

End do

3. (Output) Output all labels in the list *O* for sample **x**.

Methodology

The Data:

The pictures were obtained from a wide variety of tours and classes with different lighting conditions, backgrounds and locations. The total number was summed up to be about 214.

Rotating:

These images where rotating to 3 angles for a larger dataset and variety of pictures, using following python code,

```
from PIL import Image
import os
def rotate and save(img, save path prefix):
       rotated img = img.rotate(angle, expand=True)
       save path = f"{save path prefix} rotated {angle} Image.png"
       rotated img.save(save path)
save directory = ''
images directory = ''
def open_images_in_directory(directory):
    files = os.listdir(directory)
    image_files = [file for file in files if
file.lower().endswith(('.jpg', 'jpeg', '.png'))]
    for image file in image files:
        image_path = os.path.join(directory, image file)
        save path = os.path.join(save directory,
os.path.splitext(image file)[0])
        img = Image.open(image path)
        rotate and save(img, save path)
open images in directory(images directory)
```

Removing Duplicates:

```
import os
from PIL import Image
import imagehash
def find duplicates(directory):
   duplicates = []
   for root, dirs, files in os.walk(directory):
       for file in files:
            if file.endswith(".jpg") or file.endswith(".png"):
                file path = os.path.join(root, file)
               with open(file path, 'rb') as f:
                        image = Image.open(f)
                        hash value = str(imagehash.average hash(image))
                            duplicates.append(file path)
                            hashes[hash_value] = file_path
                        print(f"Error processing {file path}: {e}")
   return duplicates
def delete duplicates(duplicates):
   for duplicate in duplicates:
       os.remove(duplicate)
       print(f"{duplicate} Deleted")
if name == ' main ':
   directory = ''
   duplicates = find duplicates(directory)
   if duplicates:
       delete duplicates (duplicates)
       print("No Duplicates")
```

File Conversion:

The pictures shot from an iphone are transferred with the extension of heic while other pictures include jpg and jpeg so to uniform the extension they are al converted into png.

```
from PIL import Image
import os
from pillow heif import register heif opener
def convert heic to png(heic path, png path):
    register_heif_opener()
        with Image.open(heic_path) as heic_img:
            heic img.convert('RGB').save(png path, formate='PNG')
       print(e)
heic directory = ""
png_directory = ""
img_path = ""
for file in os.listdir(img path):
    if file.endswith('.HEIC') or file.endswith(('.heic', 'jpg', 'jpeg')):
        heic_path = os.path.join(heic_directory, file)
       png path = os.path.join(png directory, os.path.splitext(file)[0] +
        convert heic to png(heic path, png path)
```

Numbering

All the images are numbered for the ease of png file aligning with txt files.

```
import os
import glob
def rename_img_files(directory):
    os.chdir(directory)
    png_files = glob.glob('*.png')
    png_files.sort()
    for index, filename in enumerate(png_files):
        new_name = f"{index + 1}.png"
        os.rename(filename, new_name)
        print(f"Renamed {filename} to {new_name}")
img_directory_path = ''
rename_img_files(img_directory_path)
```

Dependencies:

Following dependencies are required when training the yolo model

- Pip
- Python
- Conda (env management)
- ultralytics

Training:

Yolov8 can be directly trained from the command line by passing following parameters

yolo task=detect mode=train model=yolov8m.pt data=data_custom.yaml epoch=100 imgsz=640

Or you can right the following python code

from ultralytics import YOLO

mode = YOLO("yolov8m.pt")

```
results = mode.train(data="/kaggle/input/yaml-file-for-yolo-training/data_custom.yaml", epochs=100, imgsz=640)
```

Yolov8m is the name of pretrained model, where m stands for medium and other types include yolov8n and yolov8s

Yaml file is used, with the following structure:

```
train: <path_of_train_folder>
val: <path_of_val_folder>
nc: <number_of_classes>
names: [
"Array of classes"
]
```

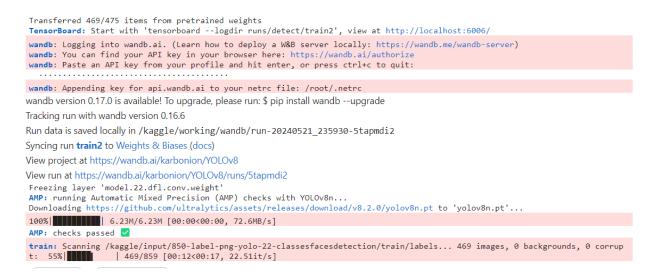
In my case it looked as as shown below

```
train: /kaggle/input/850-label-png-yolo-22-classesfacesdetection/train
val: /kaggle/input/val-data-for-yolo-4-png-with-labels/val
nc: 27
names: [
    "Bilal Munir",
    "Ali Ahmed",
    "Mustafa Raja",
    "Bilal Ch",
    "Mustafa RajaW",
```

Performance:

Start

Loads all the images.



Starts with the cls loss of 3.517 box loss of 1.646 and dfl loss 1.32

train: Scanni t: 100%					sesfacesdeted	tion/trai	n/labels	859 in	nages, 0) backgrounds	, 0 corrup
train: WARNIN	G ☆ Cache o	directory /	kaggle/inpu	t/850-label	-png-yolo-22	-classesfa	cesdetectio	n/traim	n is not	t writeable,	cache not s
<pre>aved. albumentation it=(1, 4.0),</pre>)), MedianB	lur(p=0.01, ł	olur_limit	=(3, 7)), T	oGray(p	o=0.01),	, CLAHE(p=0.0	1, clip_lim
val: Scanning			ta-for-yolo	-4-png-with	-labels/val/]	labels (4 images, 0	backgr	rounds,	0 corrupt: 1	00%
val: WARNING	∆ Cache di	rectory /ka	ggle/input/	val-data-fo	r-yolo-4-png	with-labe	ls/val is n	ot writ	teable,	cache not sa	ved.
<pre>Plotting labe optimizer: 'o tum' automati</pre>	ptimizer=a				nd 'momentum=	0.937' an	d determini	ng best	t 'optim	nizer', 'lr0'	and 'momen
<pre>optimizer: Ad =0.0)</pre>	amW(lr=0.00	00323, mome	ntum=0.9) w	ith paramet	er groups 77	weight(de	cay=0.0), 8	4 weigh	nt(decay	/=0.0005), 83	bias(decay
TensorBoard:			tion added	~							
Image sizes 6 Using 2 datal											
Logging resul	ts to runs ,	/detect/tra									
	ts to runs ,	/detect/tra									
Logging resul	ts to runs ,	/detect/tra		dfl_loss	Instances	Size					
Logging resul Starting trai	ts to runs , ning for 10 GPU_mem 7.32G	/detect/tra 00 epochs box_loss 1.646	<pre>cls_loss 3.517</pre>	1.32	152	640:	100%			01:54<00:00,	
Logging resul Starting trai Epoch 1/100	ts to runs , ning for 10 GPU_mem	/detect/tra 00 epochs box_loss 1.646	cls_loss	_		640:				01:54<00:00,	
Logging resul Starting trai Epoch	ts to runs , ning for 10 GPU_mem 7.32G	/detect/tra 00 epochs box_loss 1.646	<pre>cls_loss 3.517</pre>	1.32	152	640:					
Logging resul Starting trai Epoch 1/100	ts to runs , ning for 10 GPU_mem 7.32G Class	/detect/tra 30 epochs box_loss 1.646 Images	cls_loss 3.517 Instances	1.32 Box(P	152 R	640: mAP50	mAP50-95):				
Logging resul Starting trai Epoch 1/100 2.40s/it]	ts to runs , ning for 10 GPU_mem 7.32G Class all	/detect/tra 00 epochs box_loss 1.646 Images 4	cls_loss 3.517 Instances 62	1.32 Box(P 0.117	152 R 0.391	640: mAP50 0.124	mAP50-95):				
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Logging resul Starting trai Epoch 1/100 2.40s/it] Epoch	ts to runs, ning for 1(GPU_mem 7.32G Class all GPU_mem 7.25G Class	/detect/tra 20 epochs box_loss 1.646 Images 4 box_loss 1.276 Images	cls_loss 3.517 Instances 62 cls_loss 2.212 Instances	1.32 Box(P 0.117 dfl_loss 1.096 Box(P	152 R 0.391 Instances 174 R	640: mAP50 0.124 Size 640: mAP50	mAP50-95): 0.0842 100% mAP50-95):	100%	54/54 [[01:51<00:00,	02<00:00, 2.07s/it]
Logging resul Starting trai Epoch 2.40s/it] Epoch 2/100	ts to runs , ning for 10 GPU_mem 7.32G Class all GPU_mem 7.25G	/detect/tra 30 epochs box_loss 1.646 Images 4 box_loss 1.276	cls_loss 3.517 Instances 62 cls_loss 2.212	1.32 Box(P 0.117 dfl_loss 1.096	152 R 0.391 Instances 174	640: mAP50 0.124 Size 640:	mAP50-95): 0.0842	100%	54/54 [[01:51<00:00,	02<00:00, 2.07s/it]
Logging resul Starting trai Epoch 1/100 2.40s/it] Epoch 2/100 1.31it/s]	ts to runs, ning for 16 GPU_mem 7.32G Class all GPU_mem 7.25G Class all	/detect/tra 20 epochs box_loss 1.646 Images 4 box_loss 1.276 Images 4	cls_loss 3.517 Instances 62 cls_loss 2.212 Instances 62	1.32 Box(P 0.117 dfl_loss 1.096 Box(P 0.453	152 R 0.391 Instances 174 R 0.404	640: mAP50 0.124 Size 640: mAP50 0.497	mAP50-95): 0.0842 100% mAP50-95):	100%	54/54 [[01:51<00:00,	02<00:00, 2.07s/it]
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On 27 epochs trained the loss drops to 0.509 for cls, 0.9817 for box and 1.009 for dfl

2	1/100	7.2G Class all	1.033 Images 4	0.5678 Instances 62	1.032 Box(P 0.942	157 R 0.974		100% 54/54 [01:50<00:00, 2.04s/it] mAP50-95): 100% 1/1 [00:00<00:00, 11.67it/s] 0.765
	Epoch 2/100	GPU_mem 7.21G	box_loss 1.024	cls_loss 0.5489	dfl_loss 1.021	Instances 142	Size 640:	100% 54/54 [01:48<00:00, 2.01s/it]
		Class all	Images 4	Instances 62	Box(P 0.909	R 0.991	mAP50 0.995	mAP50-95): 100%
	Epoch	GPU_mem	box_loss	cls_loss	dfl_loss	Instances	Size	
2	3/100	7.27G Class all	1.001 Images 4	0.5379 Instances 62	1.021 Box(P 0.949	147 R 0.94		100%
	Epoch	GPU_mem	box_loss	cls_loss	dfl_loss	Instances	Size	
2	4/100	7.2G Class		0.5353 Instances	1.021 Box(P	242 R	mAP50	100% 54/54 [01:46<00:00, 1.97s/it] mAP50-95): 100% 54/54 [01:46<00:00, 12.95it/s]
		all	4	62	0.929	0.973	0.995	0.763
	Epoch	GPU_mem	box_loss	cls_loss	dfl_loss	Instances	Size	
2	100	7.18G Class all	0.9912 Images 4	0.5313 Instances 62	1.017 Box(P 0.934	227 R 0.955		100% 54/54 [01:52<00:00, 2.09s/it] mAP50-95): 100% 1/1 [00:00<00:00, 12.84it/s] 0.751
	Epoch	GPU_mem	box_loss	cls_loss	dfl_loss	Instances	Size	
2	6/100	7.24G Class	0	0.5318 Instances	1.021 Box(P	96 R	mAP50	100% 54/54 [01:53<00:00, 2.10s/it] mAP50-95): 100% 1/1 [00:00<00:00, 11.26it/s]
		all	4	62	0.896	0.977	0.984	0.761
	Epoch	GPU_mem	box_loss	cls_loss	dfl_loss	Instances	Size	
2	7/100	7.26G	0.9817	0.509	1.009	337	640:	94% 51/54 [01:44<00:08, 2.73s/it]

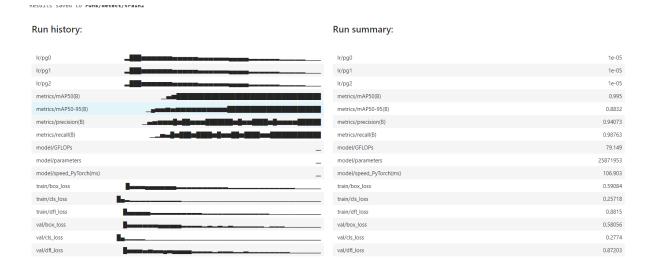
Half way through the cls loss is 0.4144, box loss is 0.8432 and dfl loss 0.9637

44/100	7.22G	0.8773	0.4332	0.9738	188	640:	100%	54/54 [[01:46<00:00, 1.98s/it]	
	Class	Images	Instances	Box(P	R				1/1 [00:00<00:00, 12.	.86it/s]
	all	4	62	0.96	0.925	0.995	0.833			
	CDU			161 1	. .	<i>c</i> ·				
Epoch	GPU_mem	box_loss	_	_	Instances	Size				
45/100	7.21G	0.8651	0.4285	0.9629	167				01:56<00:00, 2.15s/it]	
	Class		Instances	Box(P	R			100%	1/1 [00:00<00:00, 12.	.86it/s]
	all	4	62	0.96	0.901	0.993	0.832			
Epoch	GPU_mem	box_loss	cls_loss	dfl_loss	Instances	Size				
6/100	7.2G	0.8741	0.4264	0.9663	202	640:	100%	54/54	01:54<00:00, 2.12s/it]	
	Class	Images	Instances	Box(P	R	mAP50	mAP50-95):	100%	1/1 [00:00<00:00, 12.	.84it/s]
	all	4	62	0.927	0.991	0.993	0.835			
Epoch	GPU mem	box loss	cls loss	dfl loss	Instances	Size				
	_	_	_	_						
47/100	7.21G Class	0.8522	0.4187 Instances	0.9562	181 R				[01:51<00:00, 2.06s/it] 1/1 [00:00<00:00, 13.	243+(-1
	all	1mages 4	1nstances 62	Box(P 0.93	0,959	0.988	0.826	100%	1/1 [00:00000:00, 15.	2111/5]
	911	+	02	0.95	0.555	0.565	0.820			
Epoch	GPU_mem	box_loss	cls_loss	dfl_loss	Instances	Size				
48/100	7.25G	0.8643	0.4246	0.9628	172				01:50<00:00, 2.05s/it]	
	Class		Instances	Box(P	R			100%	1/1 [00:00<00:00, 7.	.98it/s]
	all	4	62	0.921	0.969	0.993	0.846			
Epoch	GPU_mem	box_loss	cls_loss	dfl_loss	Instances	Size				
49/100	7.18G	0.8519	0,4158	0.954	165	640:	100%	54/54	01:51<00:00, 2.06s/it]	
, 200	Class		Instances	Box(P	R				1/1 [00:00<00:00, 13.	30it/s]
	all	4	62	0.904	0.97	0.993	0.833	•	, , , , , , , , , , , , , , , , , , , ,	/-1
Epoch	GPU mem	box loss	cls loss	dfl loss	Instances	Size				
	_	_	_	_			4 20/1	1 7/54 54		
50/100	7.18G	0.8438	0.4144	0.9637	270	640:	13%	7/54 [6	00:09<00:59, 1.26s/it]	

Epoch	GPU_mem	box_loss	cls_loss	dfl_loss	Instances	Size	
95/100	7.17G	0.6102	0.2665	0.8879	91		100% 54/54 01:52<00:00, 2.09s/it]
	Class		Instances	Box(P	R		mAP50-95): 100%
	all	4	62	0.957	0.959	0.993	0.874
Epoch	GPU_mem	box_loss	cls_loss	dfl_loss	Instances	Size	
96/100	7.18G	0.6058	0.2636	0.8902	95	640:	100% 54/54 [01:56<00:00, 2.15s/it]
	Class	Images	Instances	Box(P	R		mAP50-95): 100%
	all	4	62	0.958	0.959	0.993	0.873
Epoch	GPU_mem	box_loss	cls_loss	dfl_loss	Instances	Size	
97/100	7,17G	0,6057	0.2664	0.8859	108	640:	100% 54/54 [01:51<00:00, 2.07s/it]
	Class		Instances	Box(P	R		mAP50-95): 100%
	all	4	62	0.943	0.969	0.993	0.872
-	6811			161-1			
Epoch	GPU_mem	box_loss	_	_	Instances	Size	
98/100	7.2G	0.5936	0.2603	0.8798	86		100%
	Class	1mages 4	Instances 62	Box(P 0.955	R 0.965	0.993	mAP50-95): 100%
	911	+	02	0.933	0.905	0.995	0.074
Epoch	GPU_mem	box_loss	cls_loss	dfl_loss	Instances	Size	
99/100	7.17G	0.5976	0.2632	0.8802	134	640:	100% 54/54 [01:55<00:00, 2.14s/it]
	Class	Images	Instances	Box(P	R	mAP50	mAP50-95): 100%
	all	4	62	0.953	0.965	0.993	0.872
Epoch	GPU_mem	box_loss	cls_loss	dfl_loss	Instances	Size	
cpoen				0.8815	91	640:	100% 54/54 [01:51<00:00, 2.06s/it]
	7.18G	0.5908	0.25/2				
100/100	7.18G Class		0.2572 Instances	0.8815 Box(P	R		mAP50-95): 100%
	Class	Images	Instances	Box(P	R	mAP50	mAP50-95): 100%

At the last run the losses are as fallows box 0.5968 , cls 0.2572 an dfl 0.8815

The model was fully trained with up to 94% accuracy.



otimizer stripped from r	runs/detect	t/train2/weig	ghts/best.p	t, 52.1MB							
lidating runs/detect/tr	ain2/weigh	nts/best.pt									
tralytics YOLOv8.2.19	🖉 Python-	3.10.13 torc	h-2.1.2 CU	A:0 (Tesla	T4, 15102M	iB)					
del summary (fused): 21	l8 layers,	25855393 par	rameters, 0	gradients,	78.8 GFLOF	s					
Class	Images	Instances	Box(P	R	mAP50	mAP50-95);	100%	1/1 [00:00<00:00,	8.73it/s1		
all	4	62	0.941	0.988	0.995	0.883		, , , ,			
Muhammad Abdullah	4	4	0.954	1	0.995	0.894					
Raheeb Gill	4	4	0.954	1	0.995	0.908					
Hasham Asad	4	3	0.958	1	0.995	0.846					
Muaz Asim	4	4	0.975	1	0.995	0.911					
Hamza Khalid	4	2	0.952	1	0.995	0.808					
Bilal Munir	4	4	0.904	1	0.995	0.87					
Ali Ahmed	4	4	1	0.916	0.995	0.874					
Mustafa Raja	4	4	0.954	1	0.995	0.925					
Bilal Ch	4	1	0.903	1	0.995	0.995					
Hasham Mukhtar	4	1	0.868	1	0.995	0.796					
Abdullah Arshad	4	1	0.965	1	0.995	0.995					
Ghulam Mujtaba	4	4	1	0.852	0.995	0.846					
Zaid Atif	4	4	1	0.985	0.995	0.834					
Sahar Arif	4	4	0.903	1	0.995	0.869					
Anmol Nisar	4	3	0.935	1	0.995	0.844					
Sahil Kumar	4	4	0.943	1	0.995	0.85					
Jannat Sameer	4	3	0.915	1	0.995	0.895					
Faizan Rasul	4	4	0.917	1	0.995	0.865					
Rumaiha	4	1	0.866	1	0.995	0.895					
Rizwan Ghuri	4	3	0.949	1	0.995	0.942					

After the training the folder contains following files

data_custom.yaml runs train val yolov8m.pt

Weights contains the best.pt model which act as a custom trained model and can use to predict faces on the given img.

Prediction:

yolo task=detect mode=predict model=path_to_best.pt show=True conf=0.5 source=filepath.png

Or write a python script passing the same parameters.

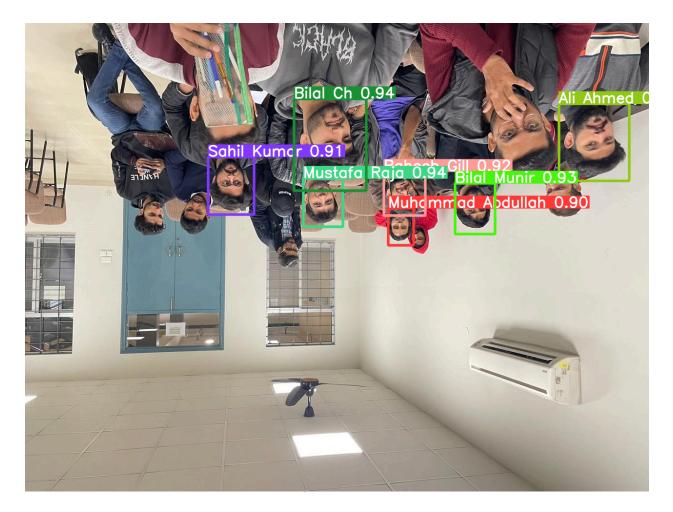
The predicted image will be stored inside run/detect/predict Some of the examples are



One with a little less people



And 1 in a class setting and inverted



References:

- <u>https://www.researchgate.net/profile/Anila-Satish/publication/225292501_Simple_and_F</u> ast_Face_Detection_System_Based_on_Edges/links/09e414fd75a23d2c1b000000/Sim ple-and-Fast-Face-Detection-System-Based-on-Edges.pdf
- <u>Awais-Jumani/publication/Face Detection and Recognition System for Enhancing Se</u> <u>curity Measures_Using Artificial_Intelligence_System</u>
- ieeexplore.ieee.org/stamp/stamp.jsp
- <u>Ibrahim-Ali-Mohammed/An-Exploratory-Study-Into-The-Face-Detection-And-Recognition</u> -System-To-Strengthen-Security-Precautions-Using-An-Artificial-Intelligence-System
- <u>https://rogerioferis.com/ClassMarch10/HomeworkVectorBoosting</u>