Lecture 5 Representation-based Search

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This week

Topics:

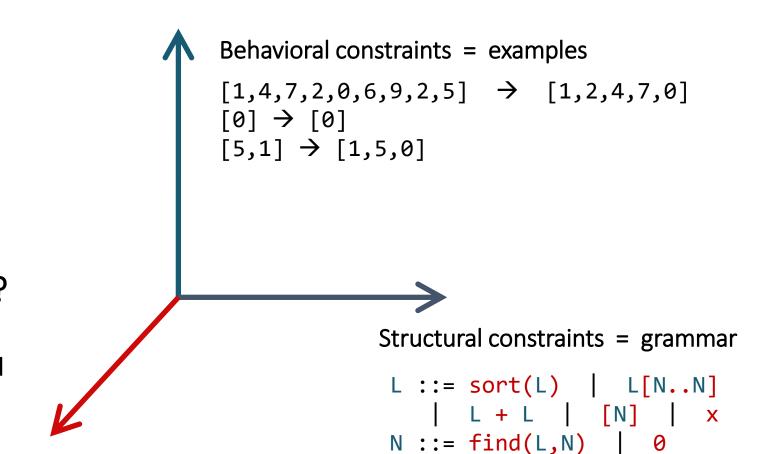
- Representation-based search
- Stochastic search

Paper: Rishabh Singh: <u>BlinkFill: Semisupervised Programming By Example for Syntactic String Transformations</u>. VLDB'16

Projects:

- Proposals due Friday
- Should demonstrate that you started working on the project or at least researched the area
- Once you have decided on the topic, put it on the Google sheet next to any of the team members
- If you haven't decided, talk to me after class or in OH

The problem statement



Search strategy?

Enumerative

Representation-based

Stochastic

Constraint-based

Representation-based search

Idea:

- 1. build a graph that represents the search space
- 2. search in that graph (or not)

Tradeoff: easy to build vs easy to search

Representations

Version Space Algebra (VSA)

Finite Tree Automaton (FTA)

Type Transition Net (TTN)

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Version Space Algebra

Idea: build a data structure that succinctly represents the set of programs consistent with a spec

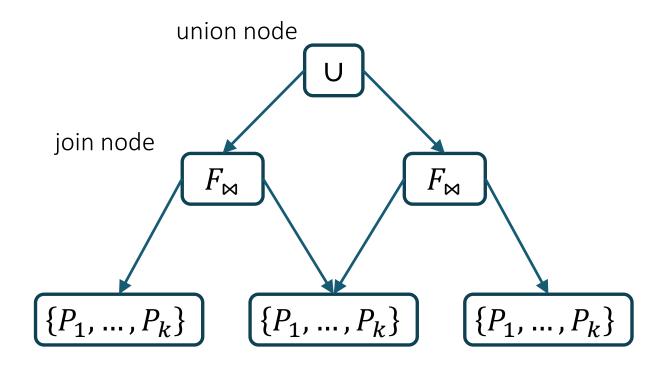
called a version space

Operations on version spaces:

- learn <i, o> → VS
- $VS_1 \cap VS_2 \rightarrow VS$
- pick VS → program

Version Space Algebra

direct set



Volume of a VSA V(VSA) (the number of nodes)

Size of a VSA (the number of programs) |VSA|

 $V(VSA) = O(\log|VSA|)$

Version Space Algebra: history

Mitchell: Generalization as search. Al 1982

Lau, Domingos, Weld. Version space algebra and its application to programming by example. ICML 2000

Gulwani: Automating string processing in spreadsheets using input-output examples. POPL 2011.

- BlinkFill, FlashExtract, FlashRelate, ...
- generalized in the PROSE framework

FlashFill

Simplified grammar:

```
E::= F | concat(F, E) "Trace" expression

F::= cstr(S) | sub(P, P) Atomic expression

P::= cpos(K) | pos(R, R) Position expression

R::= tokens(T_1, ..., T_n) Regular expression

T::= C | C+
```

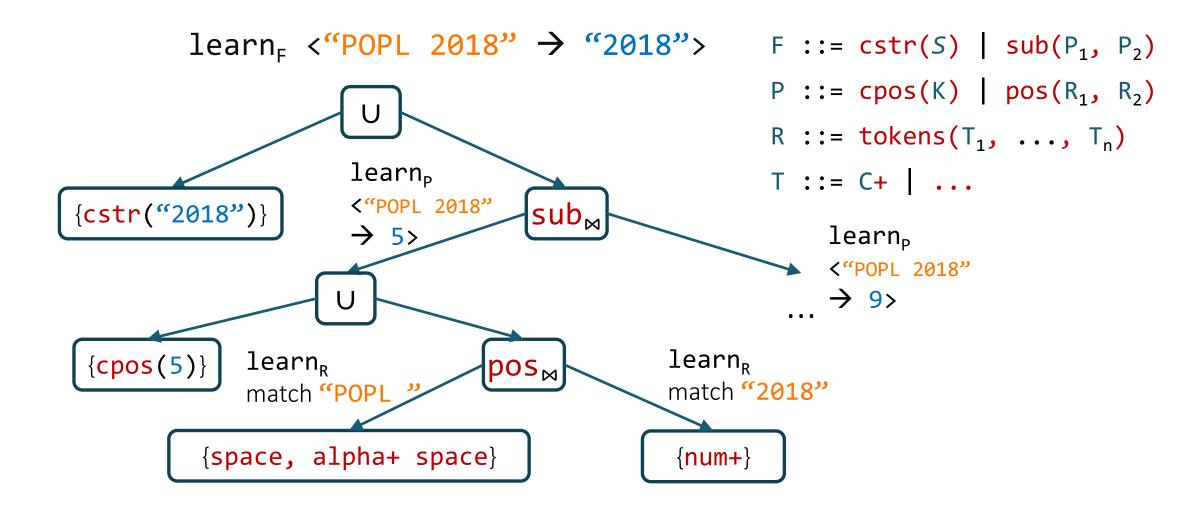
FlashFill: example

```
"Hello POPL 2020" → "POPL'2020"
"Goodbye PLDI 2019" → "PLDI'2019"

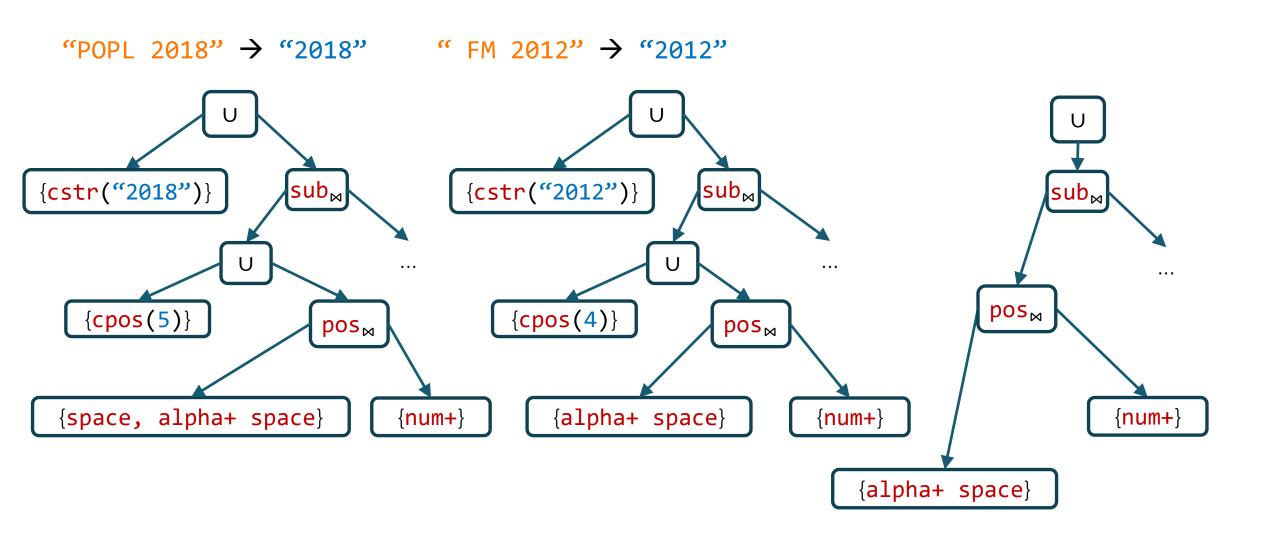
concat(
    sub(pos(ws, C), pos(C, ws)),
    concat(
        cstr("'"),
        sub(pos(ws, d), pos(d, $))))
```

```
E ::= F | concat(F, E)
F ::= cstr(S) | sub(P, P)
P ::= cpos(K) | pos(R, R)
R ::= tokens(T<sub>1</sub>, ..., T<sub>n</sub>)
T ::= C | C+
```

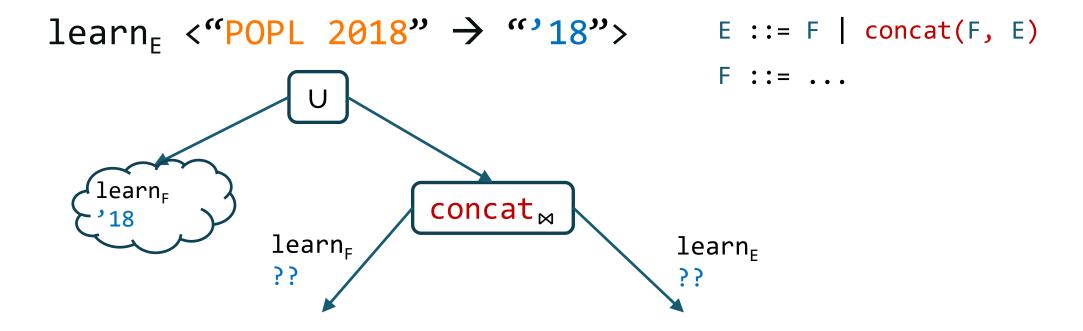
Learning atomic expressions



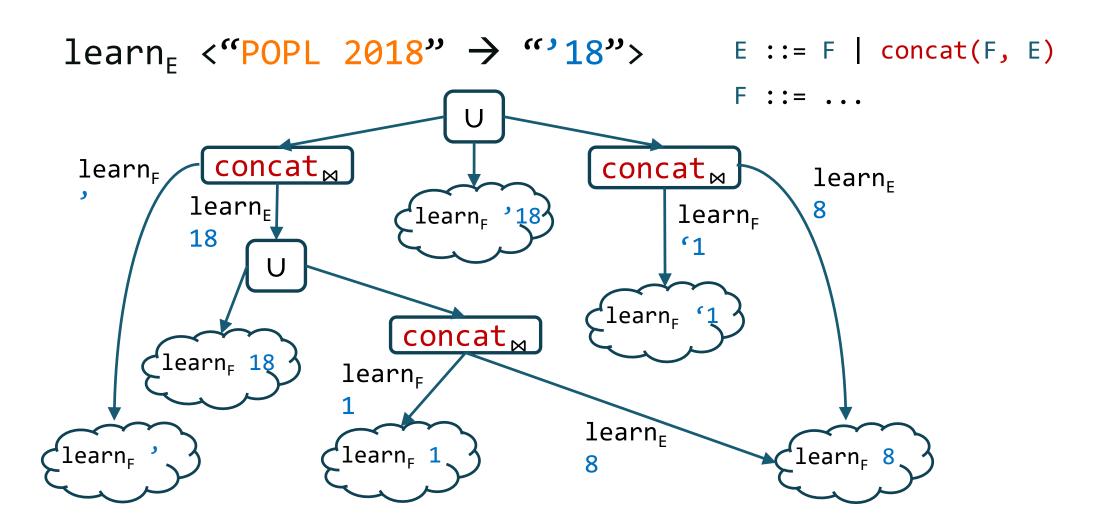
Intersection



Learning trace expressions



Learning trace expressions



Discussion

Why could we build a finite representation of all expressions?

• Could we do it for this language?

```
E::= F + F

K \in \mathbb{Z} + is integer addition
```

• What about this language?

```
E::= F | F + E
F::= K | \times K \in [0,9] + is addition mod 10
```

Discussion

Why could we build a *compact* representation of all expressions?

• Could we do this for this language?

```
E::= F & F

F::= K \mid x

K is a 32-bit word, & is bit-and
```

VSA: DSL restrictions

Every operator has a small, easily computable inverse

• Example when an inverse is small but hard to compute?

Every recursive rule generates a strictly smaller subproblem

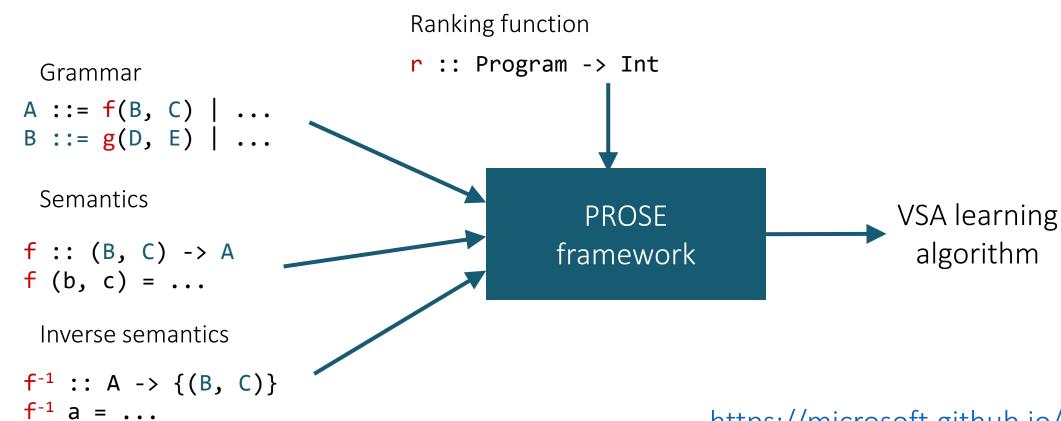
```
E ::= F | concat(F, E)

learn<sub>E</sub> '18

learn<sub>E</sub> 18
```

Otherwise, limit depth and "unroll" the grammar

PROSE



https://microsoft.github.io/prose/

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Example

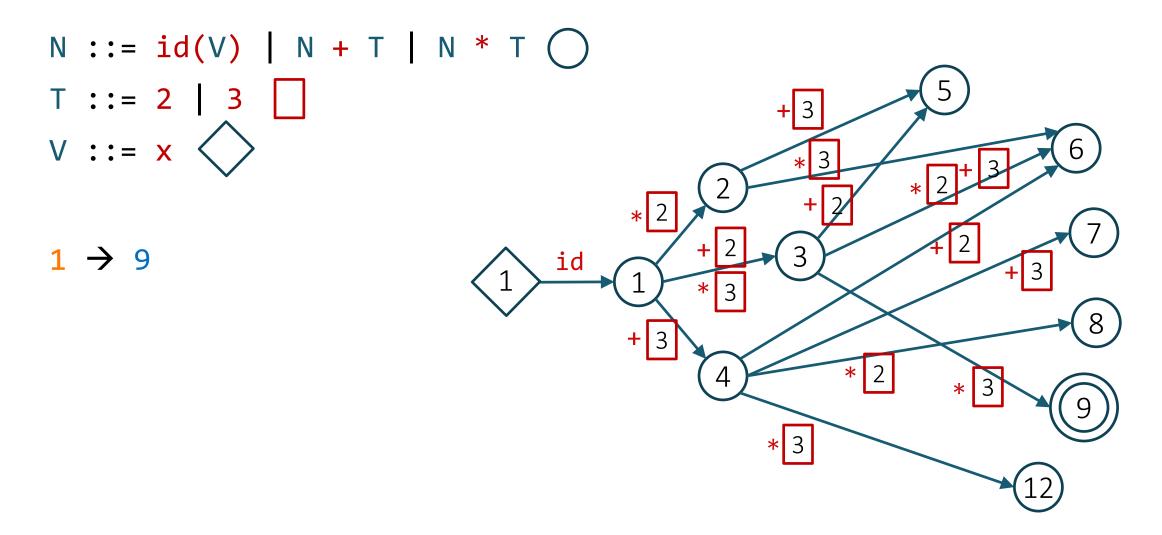
```
Grammar Spec  N ::= id(V) \mid N + T \mid N * T   1 \rightarrow 9   T ::= 2 \mid 3   V ::= x
```

Finite Tree Automata

```
\langle A, \mathbb{Z} \rangle
                                                                                   \{\langle N, 9 \rangle\}
A \in \{N, T, X\}
                                                                final states
                                   states
                                 \mathcal{A} = \langle Q, F, \overline{Q_f}, \Delta \rangle
                                   alphabet
                                                                  transitions
                                                                 f(q_1, \dots, q_n) \to q
                    id, +, *
                                                                               +(\langle N, 1 \rangle, \langle T, 2 \rangle) \rightarrow \langle N, 3 \rangle
```

Finite Tree Automata

[Wang, Dillig, Singh OOPSLA'17]



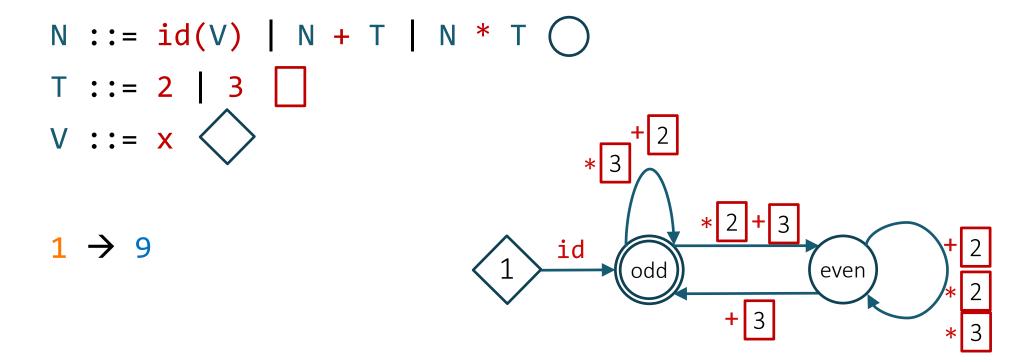
Abstract FTA

Challenge: FTA still has too many states

Idea:

- instead of one state = one value
- we can do one state = set of values (= abstract value)

[Wang, Dillig, Singh POPL'18]



In the paper:

- different abstractions
- refining the abstractions to eliminate spurious paths

Representations

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Type Transition Net (TTN)

Type-Transitions Nets

Context: Component-based synthesis

- given a library of components
- and a query: type + examples?
- synthesize composition of components

Idea: Build a compact graph of the search space using

- types as nodes
- components as transitions

TTN: History

Mandelin, Xu, Bodik, Kimelman: *Jungloid mining: helping to navigate the API jungle.* PLDI'05

Gvero, Kuncak, Kuraj, Piskac: Complete completion using types and weights. PLDI'13

Feng, Martins, Wang, Dillig, Reps: Component-based synthesis for complex APIs. POPL'17

Guo, James, Justo, Zhou, Wang, Jhala, Polikarpova: Synthesis by type-Guided Abstraction Refinement. POPL'20

TTN: History

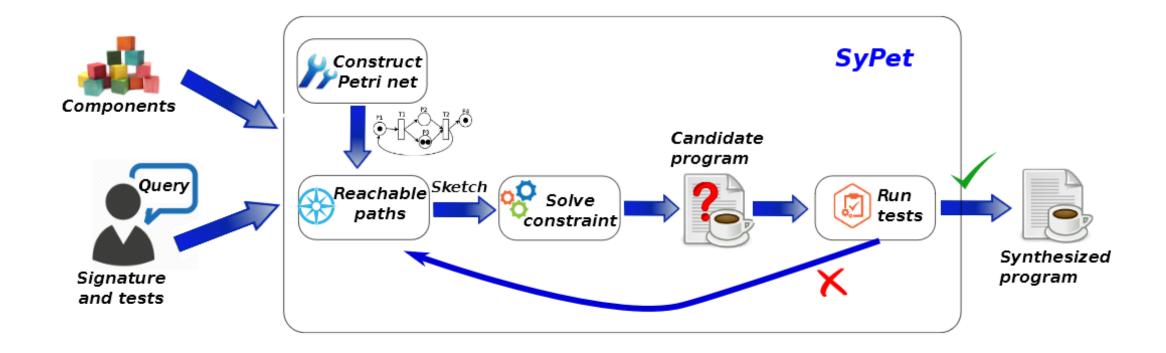
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SyPet: workflow



SyPet: example

Signature

```
Area rotate(Area obj, Point2D pt, double angle)
{ ?? }

Test

public void test1() {
   Area a1 = new Area(new Rectangle(0, 0, 10, 2));
   Area a2 = new Area(new Rectangle(-2, 0, 2, 10));
   Point2D p = new Point2D.Double(0, 0);
   assertTrue(a2.equals(rotate(a1, p, Math.PI/2)));
}
```

Components

```
java.awt.geom
```

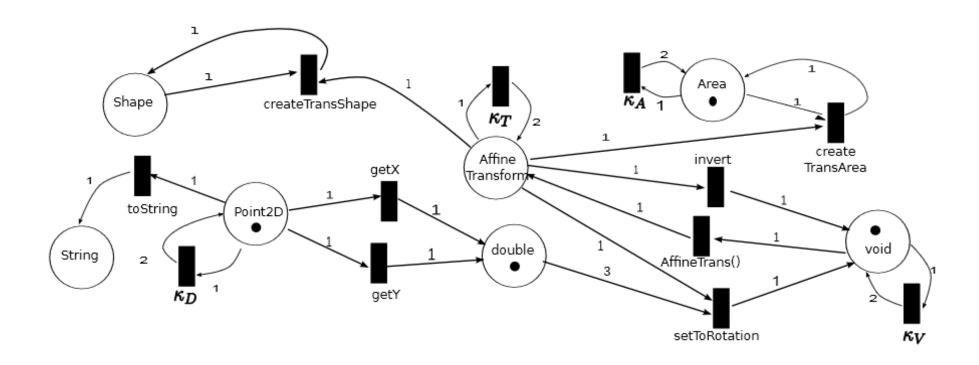
Output

```
Area rotate(Area obj, Point2D pt, double angle) {
   AffineTransform at = new AffineTransform();
   double x = pt.getX();
   double y = pt.getY();
   at.setToRotation(angle, x, y);
   Area obj2 = obj.createTransformedArea(at);
   return obj2;
}
```

Petri Nets



Library as a Petri Net



Discussion

Representation-based vs enumerative

- Enumerative unfolds the search space in time, while representationbased stores it in memory
- Benefits / limitations?

FTA ~ bottom-up

• with observational equivalence

VSA ~ top-down

with top-down propagation

Discussion

Trade-off between work during and after building the representation:

- VSA/FTA: hard to build but easy to find a program
- TTN: easy to build but harder to find a program