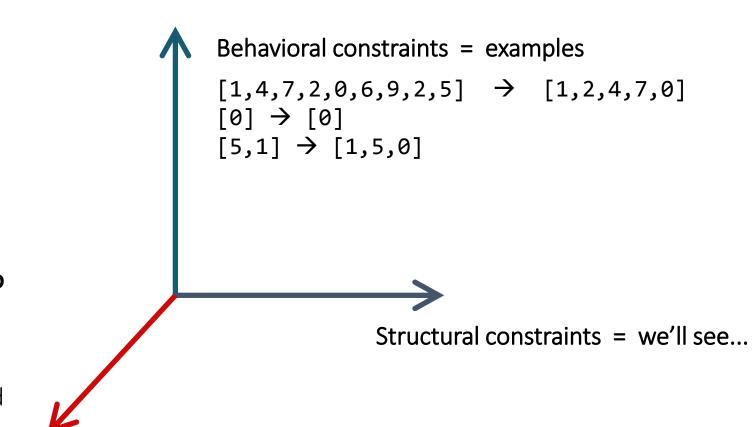
# Lecture 7 Constraint-based search

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# The problem statement



## Search strategy?

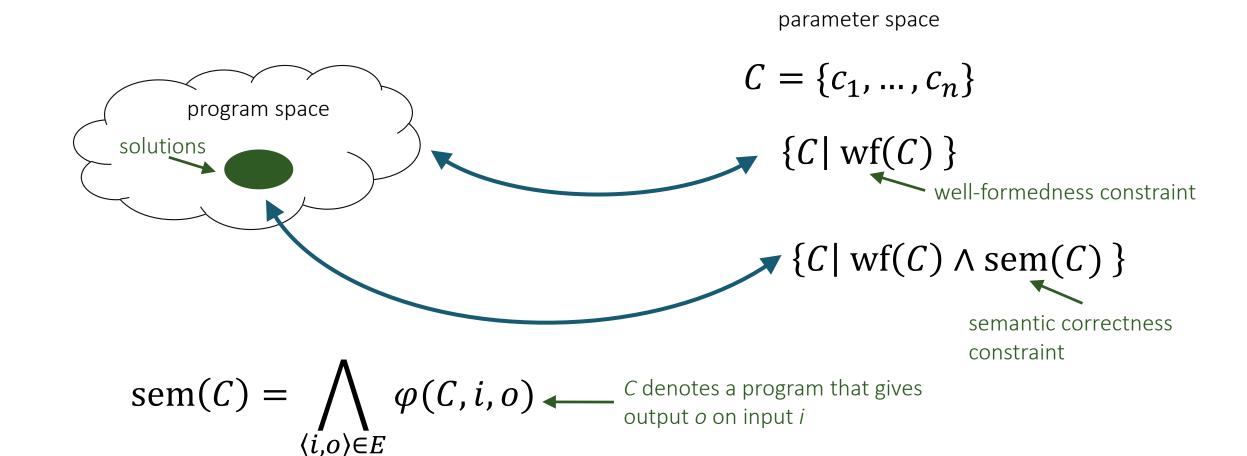
Enumerative Stochastic Representation-based

Constraint-based

## Constraint-based search

Idea: encode the synthesis problem as a SAT/SMT problem and let a solver deal with it

# What is an encoding?



# How to define an encoding

```
Define the parameter space C = \{c_1, \dots, c_n\}
```

- encode : Prog → C
- decode : C → Prog (might not be defined for all C)

## Define a formula $wf(c_1, ..., c_n)$

• that holds iff decode[C] is a "well-formed" program

## Define a formula $\varphi(c_1, ..., c_n, i, o)$

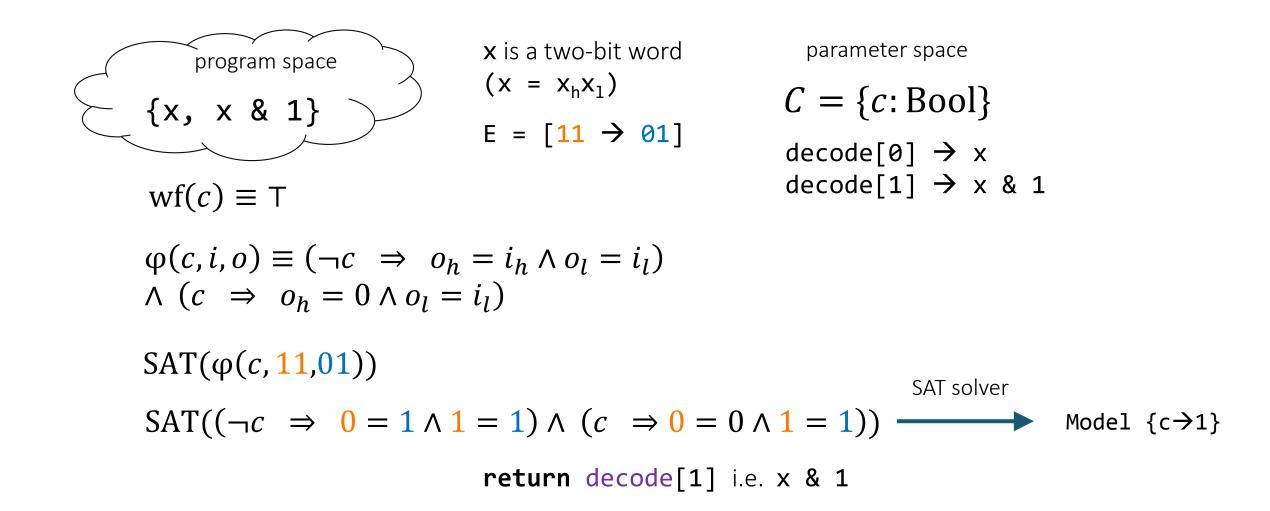
that holds iff (decode[C])(i) = o

## Constraint-based search

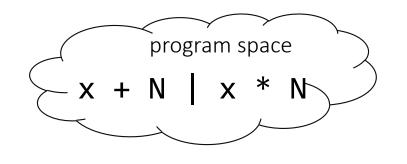
```
constraint-based (wf, \varphi, E = [i \rightarrow o]) {
    match SAT(wf(\mathcal{C}) \land \land_{(i,o) \in E} \varphi(\mathcal{C},i,o)) with \longleftarrow for c_1, \ldots, c_n
    Unsat -> return "No solution" (i and o are fixed)

Model C* -> return decode[C*]
```

# SAT encoding: example



# **SMT** encoding: example



 $wf(c) \equiv T$ 

**N** is an in integer literal **x** is an integer

$$E = [2 \rightarrow 9]$$

parameter space

$$C = \{c_{op} : \text{Bool}, c_N : \text{Int}\}$$

$$\text{decode[0,N]} \rightarrow \text{x + N}$$

$$\text{decode[1,N]} \rightarrow \text{x * N}$$

$$\phi(c_{op}, c_N, i, o) \equiv (\neg c_{op} \Rightarrow o = i + c_N)$$

$$\wedge (c_{op} \Rightarrow o = i * c_N)$$

$$SAT(\varphi(c, 2, 9))$$

$$SAT((\neg c_{op} \Rightarrow 9 = 2 + c_N) \land (c_{op} \Rightarrow 9 = 2 * c_N))$$

return decode [0,7] i.e. x + 7

SMT solver

Model  $\{c_{op} \rightarrow 0,$ 

# What is a good encoding?

#### Sound

• if  $wf(C) \land sem(C)$  then decode[C] is a solution

## Complete

• if decode[C] is a solution then  $wf(C) \wedge sem(C)$ 

## Small parameter space

avoid symmetries

## Solver-friendly

• decidable logic, compact constraint

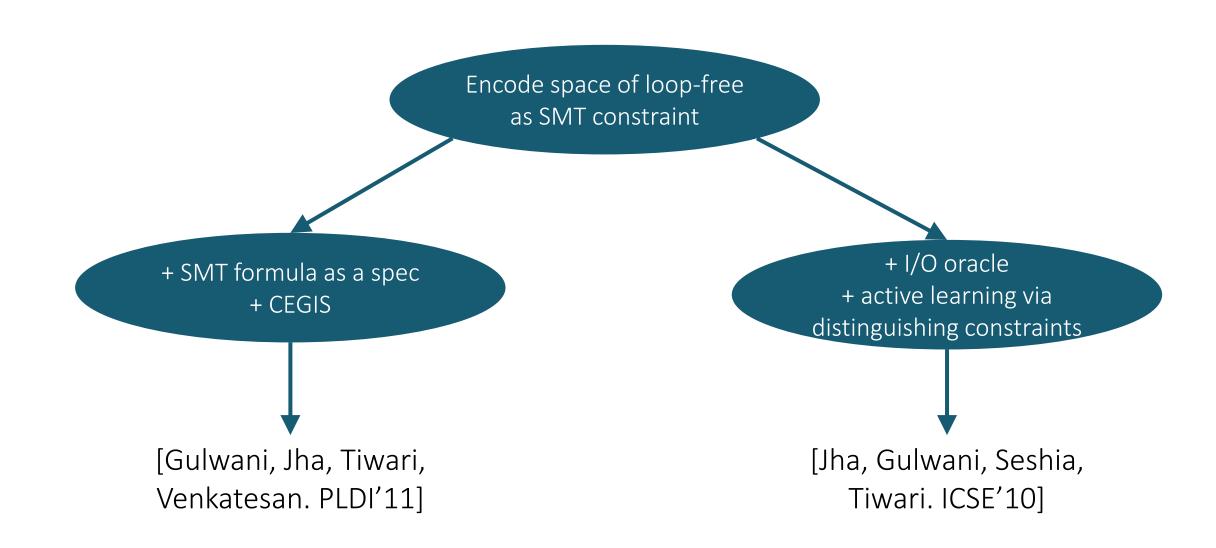
## **DSL** limitations

Program space can be parameterized with a finite set of parameters

Program semantics  $\varphi(\mathcal{C},i,o)$  is expressible as a (decidable) SAT/SMT formula

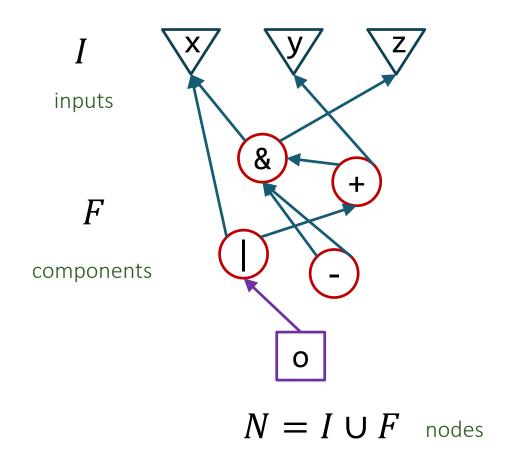
Counterexample

## Brahma

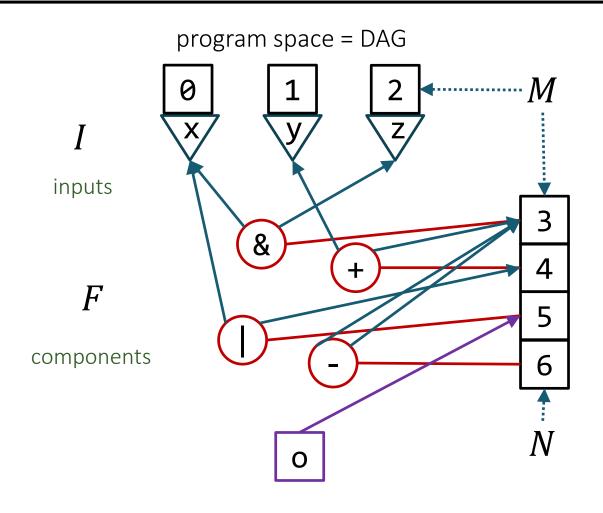


# Brahma encoding

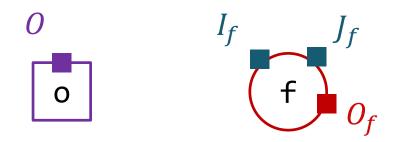
program space = DAG



# Brahma encoding: take 2



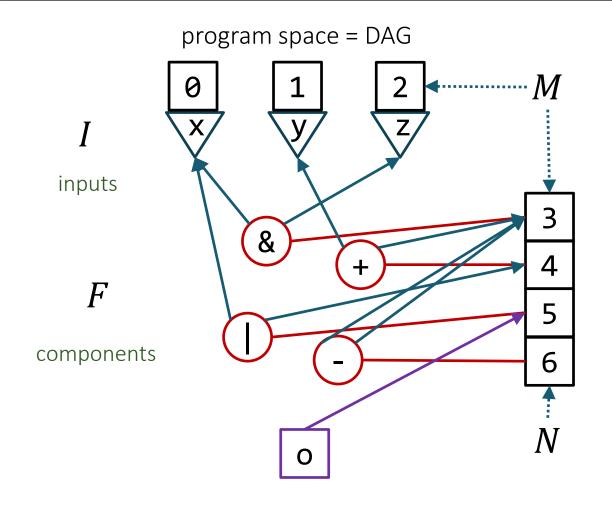
$$C = \{c_o: \operatorname{Int}\} \cup \bigcup_{f \in F} \{c_{O_f}, c_{I_f}, c_{J_f}: \operatorname{Int}\}$$



$$\operatorname{wf}(C) \equiv c_O \in M \wedge \bigwedge_{f \in F} c_{O_f} \in N \wedge c_{I/J_f} \in M$$

$$\wedge \bigwedge_{f,g \in F,f \not\equiv g} c_{O_f} \neq c_{O_g} \wedge \bigwedge_{f \in F} c_{I/J_f} < c_{O_f}$$

# Brahma encoding: take 2



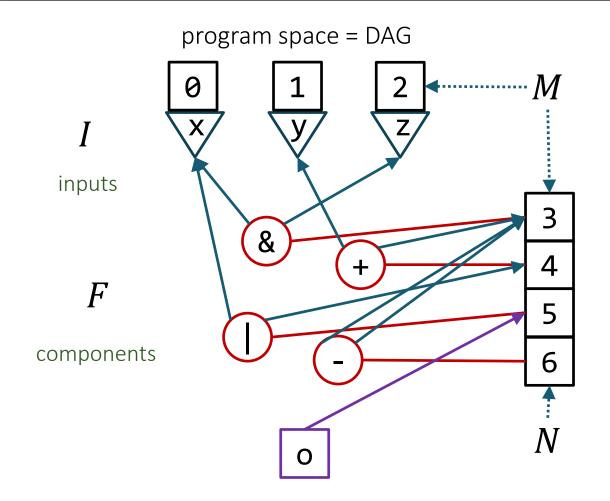
$$C = \{c_o: \text{Int}\} \cup \bigcup_{f \in F} \{c_{O_f}, c_{I_f}, c_{J_f}: \text{Int}\}$$

$$P = \bigcup_{f \in F} \{I_f, J_f\} \qquad R = \bigcup_{f \in F} \{O_f\}$$

$$\varphi(C, I, o) \equiv \exists P, R. \bigwedge_{f \in F} O_f = F(I_f, J_f)$$

$$\wedge \bigwedge_{x \in P \cup R \cup I \cup \{O\}} c_x = c_y \Rightarrow x = y$$

# Limit #components to K?



$$C = \{c_o: \operatorname{Int}\} \cup \bigcup_{f \in F} \{c_{O_f}, c_{I_f}, c_{J_f}: \operatorname{Int}\}$$

$$\operatorname{wf}(C) \equiv c_O \in M \land \bigwedge_{f \in F} c_{O_f} \in N \land c_{I/J_f} \in M$$
 $\land \cdots$ 

$$wf'(C) \equiv wf(C) \wedge c_O < |I| + K$$

# Comparison of search strategies

