Driven systems

In[1]:=

```
SetDirectory@NotebookDirectory[];
<< ".../MMA library.m"</pre>
```

Problem 1: Solve DiffEQ

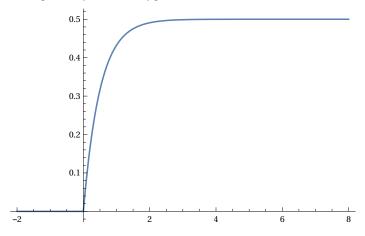
```
With[{context = "p1`"}, If[Context[] ≠ context, Begin[context]]];
Dynamic[Refresh[Context[], UpdateInterval → 1]]
p2`
eqn = y'[t] + 2y[t] == x[t]
drive = x[t] == UnitStep[t]
initial = y[0] == 0
2y[t] + y'[t] == x[t]
x[t] == UnitStep[t]
y[0] == 0
```

Approach 1: Full Mathematica

 $sol = Simplify@DSolveValue\big[\big\{eqn,\ drive,\ initial\big\},\ y\big[t\big],\ t\big]$

$$\frac{1}{2}\,\,\mathrm{e}^{-2\,t}\,\left(-\,1\,+\,\,\mathrm{e}^{2\,t}\right)\,\,\text{UnitStep}\,[\,t\,]$$

Plot[sol, {t, -2, 8.}]



Approach 2: Mathematica Laplace

```
lap = LaplaceTransform[eqn, t, s]
lap2 = Solve[lap, LaplaceTransform[y[t], t, s]][[1, 1, 2]]
lap3 = lap2 /. \{y[0] \rightarrow 0, x[t_] :> UnitStep[t]\}
sol2 = InverseLaplaceTransform[lap3, s, t]
2 LaplaceTransform[y[t], t, s] + s LaplaceTransform[y[t], t, s] - y[0] = 
 LaplaceTransform[x[t], t, s]
LaplaceTransform[x[t], t, s] + y[0]
                2 + s
s(2+s)
Plot[sol2, {t, -2., 8.}]
```

```
Simplify[sol = sol2]
e^{-2t} = 1 \mid \mid t \geq 0
With[{context = "p1`"}, If[Context[] == context, End[]]];
Dynamic[Refresh[Context[], UpdateInterval → 1]]
p2`
```

Car Suspension

```
ln[3]:= With [{context = "p2`"}, If [Context[] \neq context, Begin[context]]];
     Dynamic[Refresh[Context[], UpdateInterval → 1]]
\text{Out}[3]=\ p2`
```

Setup

$$\begin{array}{ll} & \text{In}[91] \coloneqq & \text{eqn} = \text{m} \, \text{y} \, \text{''} \left[\, \text{t} \, \right] \, + \, c \, \, \text{y'} \left[\, \text{t} \, \right] \, + \, k \, \, \text{y} \left[\, \text{t} \, \right] \, = \, c \, \, x \, \, \text{'} \left[\, \text{t} \, \right] \, + \, k \, \, x \left[\, \text{t} \, \right] \\ & \text{drive} = \left\{ x \left[\, \text{t} \, \right] \, \Rightarrow \, \text{UnitStep} \left[\, \text{t} \, \right] \right\}; \\ & \text{Out}[91] = \left. k \, \, \text{y} \left[\, \text{t} \, \right] \, + \, c \, \, \, \text{y'} \left[\, \text{t} \, \right] \, + \, m \, \, \, \text{y''} \left[\, \text{t} \, \right] \, = \, k \, \, x \left[\, \text{t} \, \right] \, + \, c \, \, x' \left[\, \text{t} \, \right] \end{array}$$

$$\text{In[112]:= initial = } \left\{ y \left[\theta \right] \rightarrow \theta \text{, } x \left[\theta \right] \rightarrow \theta \text{, } y \text{'} \left[\theta \right] \rightarrow \theta \right\};$$

a) Laplace

$$\left\{ \left\{ \mathcal{L}_t[y(t)]\left(s\right) \to \frac{c\,s+k}{s\left(c\,s+k+m\,s^2\right)} \right\} \right\}$$

Out[115]=
$$\frac{\mathbf{k} + \mathbf{C} \mathbf{S}}{\mathbf{S} \left(\mathbf{k} + \mathbf{C} \mathbf{S} + \mathbf{m} \mathbf{S}^{2}\right)}$$

c) Solve it

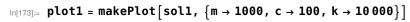
Setup desired roots

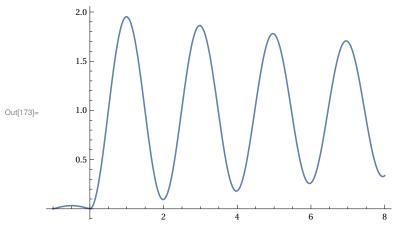
$$\begin{aligned} &\text{In}[37] = \text{ Roots} \left[\text{ m s }^2 + \text{ c s } + \text{ k } = \text{ 0, s} \right] \\ &\text{Out}[37] = \text{ s } = \frac{-\text{ c} - \sqrt{\text{ c}^2 - 4 \text{ k m}}}{2 \text{ m}} \mid \mid \text{ s } = \frac{-\text{ c } + \sqrt{\text{ c}^2 - 4 \text{ k m}}}{2 \text{ m}} \\ &\text{In}[38] = \text{ roots } = \left\{ \text{r1} = \frac{-\text{ c} - \sqrt{\text{ c}^2 - 4 \text{ k m}}}{2 \text{ m}}, \text{ r2} = \frac{-\text{ c } + \sqrt{\text{ c}^2 - 4 \text{ k m}}}{2 \text{ m}} \right\} \\ &\text{Out}[38] = \left\{ \text{r1} = \frac{-\text{ c} - \sqrt{\text{ c}^2 - 4 \text{ k m}}}{2 \text{ m}}, \text{ r2} = \frac{-\text{ c} + \sqrt{\text{ c}^2 - 4 \text{ k m}}}{2 \text{ m}} \right\} \end{aligned}$$

Approach 1: Pure Mathematica

$$In[62]:=$$
 initial2 = $\{y[0] == 0, y'[0] == 0\};$

$$\begin{aligned} & \text{Out} [76] = & \frac{1}{2 \, \sqrt{c^4 - 4 \, c^2 \, k \, m}} \, e^{-\frac{\left(c^2 + \sqrt{c^4 - 4 \, c^2 \, k \, m} \,\right) \, t}{2 \, c \, m}} \, \left(- 2 \, c^2 \, \left(- \, 1 \, + \, e^{\frac{\sqrt{c^4 - 4 \, c^2 \, k \, m} \, t}} \, e^{-\frac{\left(c^2 + \sqrt{c^4 - 4 \, c^2 \, k \, m} \, t}{c \, m} \, \right)}{c \, m}} \right) \, - \\ & \left(- \, c^2 \, \left(- \, 1 \, + \, e^{\frac{\sqrt{c^4 - 4 \, c^2 \, k \, m} \, t}}{c \, m}} \right) \, + \, \left(1 \, + \, e^{\frac{\sqrt{c^4 - 4 \, c^2 \, k \, m} \, t}}{c \, m} \, - \, 2 \, e^{\frac{\left(c^2 + \sqrt{c^4 - 4 \, c^2 \, k \, m} \, t} \, t\right)}{2 \, c \, m}} \right) \, \sqrt{c^4 - 4 \, c^2 \, k \, m}} \, \right) \, UnitStep [t] \, \end{aligned}$$





Approach 2: From Laplace

$$ln[64]:=$$
 lap4 = $\frac{k + c s}{s (s - a_1) (s - a_2)};$

sol2 = InverseLaplaceTransform[lap4, s, t]

$$\text{Out[65]=} \ \ \frac{\text{e}^{\text{t} \, a_1} \, \left(\, k \, + \, c \, \, a_1 \right)}{a_1 \, \left(\, a_1 \, - \, a_2 \, \right)} \, + \, \frac{k}{a_1 \, a_2} \, + \, \frac{\text{e}^{\text{t} \, a_2} \, \left(\, - \, k \, - \, c \, \, a_2 \right)}{\left(\, a_1 \, - \, a_2 \, \right) \, a_2}$$

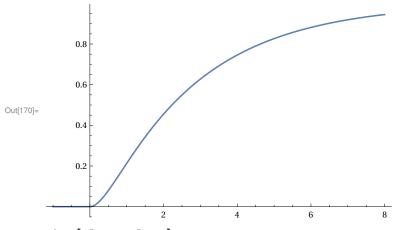
Plot it

$$\label{eq:loss} \begin{array}{ll} \mbox{ln[168]:=} & \mbox{makePlot[sol_, params_]} := \mbox{With} \Big[\Big\{ \mbox{roots} = \Big\{ a_1 \rightarrow \frac{-c - \sqrt{c^2 - 4 \, k \, m}}{2 \, m} \,, \, a_2 \rightarrow \frac{-c + \sqrt{c^2 - 4 \, k \, m}}{2 \, m} \Big\} \Big\} \,, \\ & \mbox{Plot[sol/. roots/. params, $\{t, -1, 8\}]} \Big] \end{array}$$

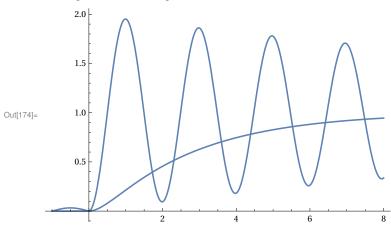
 $\label{eq:loss_loss} \mathsf{In[169]:=} \ \mathsf{makePlot}\big[\mathsf{sol2}, \ \big\{\mathsf{m} \to \mathsf{1000}, \ \mathsf{c} \to \mathsf{100}, \ \mathsf{k} \to \mathsf{10000}\big\}\big]$

Play with it

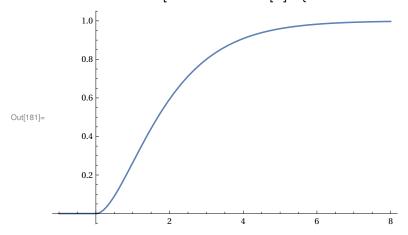
 $\text{In[170]:= plot2 = makePlot[sol1*UnitStep[t], } \left\{\text{m} \rightarrow \text{1000, c} \rightarrow \text{3000, k} \rightarrow \text{1000}\right\}\right]$

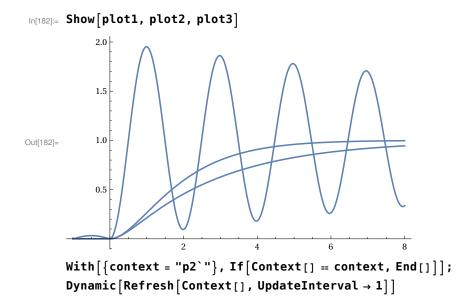


In[174]:= Show[plot1, plot2]



 $\text{ln[181]:} \quad \textbf{plot3} = \texttt{makePlot}\big[\textbf{sol1} \star \textbf{UnitStep}\big[\textbf{t} \big] \,, \, \big\{ \textbf{m} \rightarrow \textbf{1000} \,, \, \, \textbf{c} \rightarrow \textbf{2001} \,, \, \, \textbf{k} \rightarrow \textbf{1000} \big\} \, \big]$





Scratch Work

In[183]:= exportNotebookPDF[]