
Definitions

Eigenvalues and Eigenvectors of a Diagonal Matrix

Eigenvalues of a Triangular Matrix

$$\text{Solve}\left[\left(\begin{pmatrix} 1 & 1 \\ 0 & 1 \end{pmatrix} \cdot \{x, y\} == \{x, y\}, \{x, y\}\right]\right]$$

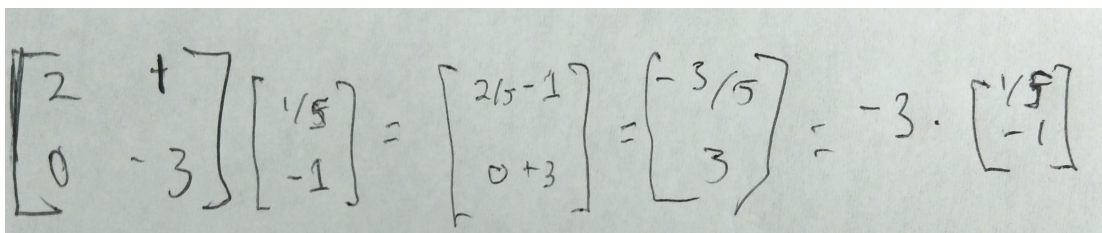
Solve::svars: Equations may not give solutions for all "solve" variables. >>

$\{\{y \rightarrow 0\}\}$

$$\text{Roots}\left[\text{Det}\left[\begin{pmatrix} a & b \\ 0 & c \end{pmatrix} - \lambda \text{IdentityMatrix}[2]\right] == 0, \lambda\right]$$

$\lambda == c \mid \mid \lambda == a$

3.


$$\begin{bmatrix} 2 & 1 \\ 0 & -3 \end{bmatrix} \begin{bmatrix} 1/5 \\ -1 \end{bmatrix} = \begin{bmatrix} 2/5 - 1 \\ 0 + 3 \end{bmatrix} = \begin{bmatrix} -3/5 \\ 3 \end{bmatrix} = -3 \cdot \begin{bmatrix} 1/5 \\ -1 \end{bmatrix}$$

4.

I decided to automate here, and gained a ton of insight from doing so. In particular, thinking about solving the equation $A.x = \lambda.x$ for known λ as looking for the null space of a matrix is really cool.

```
In[7]:= triangleEigens[A_] := Module[{},  
  values = Diagonal[A];  
  vectors = Table[MatrixForm@  
    Transpose@NullSpace[A - val IdentityMatrix[Length@A]], {val, values}];  
  Grid[Transpose[{values,  
    vectors}], Frame -> All]  
]
```

```
triangleEigens[ $\begin{pmatrix} 1 & 0 \\ 1 & 2 \end{pmatrix}$ ]
```

1	$\begin{pmatrix} -1 \\ 1 \end{pmatrix}$
2	$\begin{pmatrix} 0 \\ 1 \end{pmatrix}$

```
triangleEigens[ $\begin{pmatrix} 1 & 0 & 0 \\ -1 & 2 & 0 \\ 2 & 1 & 3 \end{pmatrix}$ ]
```

1	$\begin{pmatrix} -2 \\ -2 \\ 3 \end{pmatrix}$
2	$\begin{pmatrix} 0 \\ -1 \\ 1 \end{pmatrix}$
3	$\begin{pmatrix} 0 \\ 0 \\ 1 \end{pmatrix}$

```
triangleEigens[ $\begin{pmatrix} 2 & 0 & 0 \\ 0 & 2 & 0 \\ 0 & 1 & 4 \end{pmatrix}$ ]
```

2	$\begin{pmatrix} 0 & 1 \\ -2 & 0 \\ 1 & 0 \end{pmatrix}$
2	$\begin{pmatrix} 0 & 1 \\ -2 & 0 \\ 1 & 0 \end{pmatrix}$
4	$\begin{pmatrix} 0 \\ 0 \\ 1 \end{pmatrix}$

This last problem is particularly interesting because the value 2 appears multiple times on the diagonal, and is thus a repeated eigenvalue. There *are* still three distinct eigenvectors, but pairing them up nicely is difficult.

The Characteristic Equation

Nice explanation! When I first learned this, it seemed unmotivated, but seeing the derivation this plainly makes it obvious.

```
In[8]:= myCharacteristicEqn[A_] := Module[{},
  Factor@Det[A - λ IdentityMatrix[Length@A]] == 0
]
```

Diagonal matrices

```
myCharacteristicEqn[DiagonalMatrix[{-3, -1, 4}]]
- (-4 + λ) (1 + λ) (3 + λ) == 0
```

I don't know why exactly the leading - snuck in, but it isn't particularly important.

```
myCharacteristicEqn[DiagonalMatrix[{1, 1, 2}]]
- (-2 + λ) (-1 + λ)2 == 0
```

As expected, there is a squared term representing the duplicate eigenvalue.

```
myCharacteristicEqn[DiagonalMatrix[{2, 4, 0}]]
- (-4 + λ) (-2 + λ) λ == 0
```

And bare eigenvalues of 0 work too!

Triangular Matrices

```
myCharacteristicEqn[ $\begin{pmatrix} 1 & 0 \\ 1 & 2 \end{pmatrix}$ ]
```

```
(-2 + λ) (-1 + λ) == 0
```

```
myCharacteristicEqn[ $\begin{pmatrix} 1 & 0 & 0 \\ -1 & 2 & 0 \\ 2 & 1 & 3 \end{pmatrix}$ ]
```

```
- (-3 + λ) (-2 + λ) (-1 + λ) == 0
```

```
myCharacteristicEqn[ $\begin{pmatrix} 2 & 0 & 0 \\ 0 & 2 & 0 \\ 0 & 1 & 4 \end{pmatrix}$ ]
```

```
- (-4 + λ) (-2 + λ)2 == 0
```

8.

Because A is triangular, $A - \lambda I$ must also be diagonal. We showed earlier that this implies that $\det(A - \lambda I)$ is the product of the diagonal elements of that matrix, which are first-degree polynomials of the form $(a - \lambda)$ where $a \in \text{Diagonal}(A)$. Thus, their product is a degree- n polynomial with roots consisting of the diagonal elements of A .

7.

Diagonal matrices are triangular. See problem 8.

Eigenvalues and Eigenvectors of 2x2

9.

```
In[22]:= A =  $\begin{pmatrix} 18 & -2 \\ 12 & 7 \end{pmatrix}$ ;
```

```
15 → MatrixForm@NullSpace[A - 15 IdentityMatrix[2]] [[1]]
```

```
10 → MatrixForm@NullSpace[A - 10 IdentityMatrix[2]] [[1]]
```

```
Out[23]= 15 →  $\begin{pmatrix} 2 \\ 3 \end{pmatrix}$ 
```

```
Out[24]= 10 →  $\begin{pmatrix} 1 \\ 4 \end{pmatrix}$ 
```

10.

```
In[34]:= A =  $\begin{pmatrix} 3 & -2 \\ 4 & -1 \end{pmatrix}$ ;
HoldForm@Det[A] == A[[1, 1]] * A[[2, 2]] - A[[1, 2]] * A[[2, 1]]
HoldForm@Tr[A] == Total@Diagonal@A
TraditionalForm[ $\lambda^2 - \text{Tr}[A] \lambda + \text{Det}[A] == 0$ ]
```

```
Out[35]= Det[A] == 5
```

```
Out[36]= Tr[A] == 2
```

```
Out[37]//TraditionalForm=
 $\lambda^2 - 2\lambda + 5 = 0$ 
```

Relatively standard

```
In[38]:= A =  $\begin{pmatrix} 0 & -1 \\ 1 & 0 \end{pmatrix}$ ;
HoldForm@Det[A] == A[[1, 1]] * A[[2, 2]] - A[[1, 2]] * A[[2, 1]]
HoldForm@Tr[A] == Total@Diagonal@A
TraditionalForm[ $\lambda^2 - \text{Tr}[A] \lambda + \text{Det}[A] == 0$ ]
```

```
Out[39]= Det[A] == 1
```

```
Out[40]= Tr[A] == 0
```

```
Out[41]//TraditionalForm=
 $\lambda^2 + 1 = 0$ 
```

This equation has no real roots.

```
In[46]:= A =  $\begin{pmatrix} \cos[\theta] & -\sin[\theta] \\ \sin[\theta] & \cos[\theta] \end{pmatrix}$ ;
HoldForm@Det[A] == A[[1, 1]] * A[[2, 2]] - A[[1, 2]] * A[[2, 1]]
HoldForm@Tr[A] == Total@Diagonal@A
TraditionalForm[Simplify[ $\lambda^2 - \text{Tr}[A] \lambda + \text{Det}[A] == 0$ ]]
```

```
Out[47]= Det[A] == Cos[ $\theta$ ]2 + Sin[ $\theta$ ]2
```

```
Out[48]= Tr[A] == 2 Cos[ $\theta$ ]
```

```
Out[49]//TraditionalForm=
 $-2\lambda \cos(\theta) + \lambda^2 + 1 = 0$ 
```

After throwing on a simplify, lots of the trig goes away, which is nice.

11.

```
In[140]:= myEigenValues[A_] := (
  Clear@ $\lambda$ ;
  List@@Roots[myCharacteristicEqn[A],  $\lambda$ ][[All, 2]]
)
```

```

In[163]:= myEigenValues@ $\begin{pmatrix} 3 & -2 \\ 4 & -1 \end{pmatrix}$ 
Out[163]= {1 - 2 i, 1 + 2 i}

In[164]:= myEigenValues@ $\begin{pmatrix} 0 & -1 \\ 1 & 0 \end{pmatrix}$ 
Out[164]= {i, -i}

In[170]:= myEigenValues@ $\begin{pmatrix} \text{Cos}[\theta] & -\text{Sin}[\theta] \\ \text{Sin}[\theta] & \text{Cos}[\theta] \end{pmatrix}$ 
% == myEigenValues@RotationMatrix@ $\theta$ 
Out[170]= {Cos[ $\theta$ ] - i Sin[ $\theta$ ], Cos[ $\theta$ ] + i Sin[ $\theta$ ]}
Out[171]= True

```

12.

There is an awesome theorem showing that the sum of the roots of any polynomial in standard form is always $-\frac{b}{a}$ where b is the coefficient on the x^{n-1} term and a is the coefficient on the x^n term. In this case, $b = -\det(A) \wedge a = 1$, so the sum of the roots (the sum of the eigenvalues) must be $\det(A)$.

13.

A second related theorem shows that the product of the roots of any polynomial is $(-1)^n * \frac{z}{a}$ where n is the degree of the polynomial, and z is the constant term. In this case, $n = 2 \wedge z = \det(A)$, so the product of the roots is $\det(A)$.

14.

Consider $A = \begin{pmatrix} a & b \\ b & d \end{pmatrix}$. $\det(A) = ad - b^2$. $\text{tr}(A) = a + d$. In order for the eigenvalues to be complex, it is necessarily true that $\text{tr}(A)^2 - 4 \det(A) < 0$. Expanding, $(a + d)^2 - 4(-b^2 + ad) < 0$, or $a^2 + 4b^2 - 2ad + d^2 < 0$. In the worst case, $b = 0$, so $a^2 - 2ad + d^2 = (a - d)^2 < 0$. Because $a - d$ is real, its square must be non-negative, so the discriminant of the equation must be nonnegative, and the eigenvalue(s) must be real.

```

In[57]:= A = {{a, b}, {b, d}};
In[83]:= Tr[A]^2 - 4 Det[A] < 0
Expand[%
% /. b -> 0
Factor[%
Out[83]= (a + d)^2 - 4 (-b^2 + a d) < 0
Out[84]= a^2 + 4 b^2 - 2 a d + d^2 < 0
Out[85]= a^2 - 2 a d + d^2 < 0
Out[86]= (a - d)^2 < 0

```

Or, the lame way,

```
In[88]:= Reduce[Tr[A]^2 - 4 Det[A] < 0]
Out[88]= False
```

15.

As discovered Nathan and Sam, the problem here should read $v_2 = \begin{pmatrix} 1 \\ i \end{pmatrix}$.

```
In[123]:= A =  $\begin{pmatrix} 1 & -1 \\ 1 & 1 \end{pmatrix}$ ;
          λ2 = 1 - i;
          v2 =  $\begin{pmatrix} 1 \\ i \end{pmatrix}$ ;
          A.v2 // MatrixForm
          λ2 v2 // MatrixForm
```

```
Out[126]/MatrixForm=
 $\begin{pmatrix} 1 - i \\ 1 + i \end{pmatrix}$ 
```

```
Out[127]/MatrixForm=
 $\begin{pmatrix} 1 - i \\ 1 + i \end{pmatrix}$ 
```

16.

This uses definitions from problem 11.

```
In[151]:= myEigenvectors[A_] := (
          DeleteDuplicates@
          Flatten[Map[NullSpace[A - # IdentityMatrix[Length@A]] &, myEigenValues[A]], 1]
        )
```

```
In[155]:= MatrixForm /@ myEigenvectors@ $\begin{pmatrix} 3 & -2 \\ 4 & -1 \end{pmatrix}$ 
```

```
Out[155]=  $\left\{ \begin{pmatrix} 1 - i \\ 2 \end{pmatrix}, \begin{pmatrix} 1 + i \\ 2 \end{pmatrix} \right\}$ 
```

```
In[156]:= MatrixForm /@ myEigenvectors@ $\begin{pmatrix} 0 & -1 \\ 1 & 0 \end{pmatrix}$ 
```

```
Out[156]=  $\left\{ \begin{pmatrix} i \\ 1 \end{pmatrix}, \begin{pmatrix} -i \\ 1 \end{pmatrix} \right\}$ 
```

```
In[160]:= MatrixForm /@ myEigenvectors@ $\begin{pmatrix} \cos[\theta] & -\sin[\theta] \\ \sin[\theta] & \cos[\theta] \end{pmatrix}$ 
          MatrixForm /@ myEigenvectors@RotationMatrix[θ]
          myEigenValues@RotationMatrix[θ]
```

```
Out[160]=  $\left\{ \begin{pmatrix} -i \\ 1 \end{pmatrix}, \begin{pmatrix} i \\ 1 \end{pmatrix} \right\}$ 
```

```
Out[161]=  $\left\{ \begin{pmatrix} -i \\ 1 \end{pmatrix}, \begin{pmatrix} i \\ 1 \end{pmatrix} \right\}$ 
```

```
Out[162]=  $\{\cos[\theta] - i \sin[\theta], \cos[\theta] + i \sin[\theta]\}$ 
```

Misc