ASSIGNMENT 4

Ultrasonic sensor simulation in Wokwi

PROJECT NAME: Real-Time River Water Quality Monitoring and Control

System

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Question: Write a code and connections in wokwi for the ultrasonic sensor. Whenever the distanceis less than 100cms send an "Alert" to IBM cloud and display in the device recent events.

Wokwi simulation link: https://wokwi.com/projects/347124503089775188

WOKWI OUTPUT SCREENSHOT:

```
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                                                                                                                                                                                                                    Docs
                                                                                                                         Simulation
  sketch.ino diagram.json Library Manager ▼
                                                                                                                                                                                                                Ō00:30.796 (₹)99%
             void setup() {
   Serial.begin(115200);
   pinMode(LED_BUILTIM, OUTPUT);
   pinMode(TRIG_PIN, OUTPUT);
   pinMode(ECHO_PIN, INPUT);
                                                                                                                       Editing Ultrasonic Distance Senso
                                                                                                                                                                                               Ш
             float readDistanceCM() {
               digitalWrite(TRIG_PIN, LOW);
delayMicroseconds(2);
digitalWrite(TRIG_PIN, HIGH);
               digitalWrite(IRIG_PIN, Fiber);
delayMicroseconds(10);
digitalWrite(IRIG_PIN, LOW);
int duration = pulseIn(ECHO_PIN, HIGH);
return duration * 0.034 / 2;
                                                                                                                      Measured distance: 218.94
                                                                                                                       Measured distance: 239.84
                                                                                                                       Measured distance: 239.84
             void loop() {
  float distance = readDistanceCM();
                                                                                                                       Measured distance: 113.56
                                                                                                                       person detected
                                                                                                                       person detected
                                                                                                                       person detected
             else{
| Serial.print("Measured distance: ");
                                                                                                                                                                                                                        <u>⊬</u> II ©
```

CODE:

```
#define ECHO_PIN 2
#define TRIG_PIN 3
#define organization = "md8rdq"
#define deviceType = "123"
#define deviceId = "123456"
#define authMethod = "token"
#define authToken = "Titik@2002"

void setup() {
    Serial.begin(115200);
    pinMode(LED_BUILTIN, OUTPUT);
    pinMode(TRIG_PIN, OUTPUT);
    pinMode(ECHO_PIN, INPUT);
}
```

```
float readDistanceCM() {
  digitalWrite(TRIG_PIN, LOW);
  delayMicroseconds(2);
  digitalWrite(TRIG_PIN, HIGH);
  delayMicroseconds(10);
  digitalWrite(TRIG_PIN, LOW);
  int duration = pulseIn(ECHO_PIN, HIGH);
  return duration * 0.034 / 2;
void loop() {
  float distance = readDistanceCM();
if(distance<=100)</pre>
  Serial.println(" person detected");
else{
  Serial.print("Measured distance: ");
  Serial.println(readDistanceCM());
  delay(1000);
```





