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State Finished

Completed on Thursday, 8 June 2023, 12:25 PM

**Time taken** 28 mins 17 secs

Marks 6.00/8.00

**Grade 5.25** out of 7.00 (**75**%)

Question 1

Partially correct

Mark 0.50 out of 1.00

If  $A = \begin{pmatrix} p & 0.3 \\ 1-p & 0.7 \end{pmatrix}$  is transition matrix, then the steady state vecto

p is the last digit of your roll number  $\times$  0. 1.

- Eigenvector corresponding to Second largest eigenvalue.
- $^{\square}$  b. Only the negative elements of first column of  $A^k$  , where  $k o \infty$
- $^{\circ}$  Only the negative elements of the first row of  $A^k$ , where  $k \to \infty$
- Eigenvector corresponding to largest eigenvalue.

Your answer is partially correct.

You have selected too many options.

The correct answer is:

Eigenvector corresponding to largest eigenvalue.

Mark 2.00 out of 2.00

$$A = \begin{bmatrix} 0 & 1 & 0 \\ 0 & 0 & 1 \\ 1 & 0 & 0 \end{bmatrix} \quad \text{and} \quad B = \begin{bmatrix} \cos \theta & \sin \theta \\ \sin \theta & \cos \theta \end{bmatrix}$$

Then the following statement(s) are true:

- $^{\square}$  If  $\lambda$  is the eigenvalue of A then  $|\lambda|=1$  and for B ,  $\lambda=e^{\pm i heta}$
- b. None of these.
- ||Ax|| = ||x||, and ||Bx|| < ||x||
- $^{-1}$  d is the last digit of your roll number. Det(A)=1; and det(B) = $\theta$
- $^{-}$  If  $\theta$  is the any digit of your roll number, then  $|\lambda|=\infty$

Your answer is correct.

The correct answer is: None of these.

Mark 2.00 out of 2.00

$$A = \begin{bmatrix} 1 & 2 & 2 \\ -1 & 1 & 2 \\ -1 & 0 & 1 \\ 1 & 1 & 2 \end{bmatrix}$$

Let A=QR, where Q is orthogonal, and R is upper triangular.

Which statement(s) is /are correct?

- a. None of these.
- b. The matrix is not invertible. Thus QR decomposition cannot be performed.

d.
$$Q = [\mathbf{q}_1 \quad \mathbf{q}_2 \quad \mathbf{q}_3] = \begin{bmatrix} 1/2 & 3\sqrt{5}/10 & -\sqrt{6}/6 \\ -1/2 & 3\sqrt{5}/10 & 0 \\ -1/2 & \sqrt{5}/10 & \sqrt{6}/6 \\ 1/2 & \sqrt{5}/10 & \sqrt{6}/3 \end{bmatrix}$$

$$R = \begin{bmatrix} 2 & 1 & 1/2 \\ 0 & \sqrt{5} & 3\sqrt{5}/2 \\ 0 & 0 & \sqrt{6}/2 \end{bmatrix}$$

Your answer is correct.

The correct answer is:

$$Q = \begin{bmatrix} \mathbf{q}_1 & \mathbf{q}_2 & \mathbf{q}_3 \end{bmatrix} = \begin{bmatrix} 1/2 & 3\sqrt{5}/10 & -\sqrt{6}/6 \\ -1/2 & 3\sqrt{5}/10 & 0 \\ -1/2 & \sqrt{5}/10 & \sqrt{6}/6 \\ 1/2 & \sqrt{5}/10 & \sqrt{6}/3 \end{bmatrix}$$

$$\begin{bmatrix}
2 & 1 & 1/2 \\
0 & \sqrt{5} & 3\sqrt{5}/2 \\
0 & 0 & \sqrt{6}/2
\end{bmatrix}$$

Mark 0.00 out of 1.00

If 
$$A = \begin{bmatrix} 1-p & p \\ p & 1-p \end{bmatrix}$$
 is transition matrix, then the steady state vec

p is (your roll number%3+1) 
$$\times$$
 0. 1.

- a. One of the elements of the steady state vector is closely 0.5.
- b. One of the elements of the steady state vector is closely 1-p.
- c. One of the elements of the steady state vector is closely p.
- d. None of these.

Your answer is incorrect.

The correct answer is:

One of the elements of the steady state vector is closely 0.5.

Question **5** 

Mark 1.00 out of 1.00

If 
$$A = \begin{pmatrix} a & b \\ c & -d \end{pmatrix}$$
, then the eigenvalues are

$$\lambda_{1,2} = \frac{1}{2}(a - d \pm \sqrt{(a+d)^2 + 4bc})$$
, determinant(A)= $\lambda_1 \lambda_2$ 

$$\lambda_{1,2} = \frac{1}{2}(a + d \pm \sqrt{(a+d)^2 + 4bc})$$
, determinant(A)+trace(A

$$\lambda_{1,2} = \frac{1}{2}(a - d \pm \sqrt{(a+d)^2 + 4bc})$$
, determinant(A)= $\lambda_1 + \lambda_2$ 

$$\lambda_{1,2} = \frac{1}{2}(a + d \pm \sqrt{(a - d)^2 + 4bc}), \text{ trace(A)} = \lambda_1 \lambda_2$$

Your answer is correct.

The correct answer is:

$$\lambda_{1,2} = \frac{1}{2}(a - d \pm \sqrt{(a+d)^2 + 4bc})$$
, determinant(A)= $\lambda_1 \lambda_2$ 

## Find the orthonormal basis for the column space of the matrix

## Check (during calculation) which statements is/are true:

Gram-Schmidt (GS) procedure is required, as two of the column they are:

$$\mathbf{u}_{1} = \frac{\mathbf{w}_{1}}{\|\mathbf{w}_{1}\|} = \frac{1}{2\sqrt{5}} \begin{pmatrix} 3\\1\\-1\\3 \end{pmatrix}, \qquad \mathbf{u}_{2} = \frac{\mathbf{w}_{2}}{\|\mathbf{w}_{2}\|} = \frac{1}{2\sqrt{5}} \begin{pmatrix} 1\\3\\3\\\cdot 1 \end{pmatrix}, \qquad \mathbf{u}_{3} = \frac{\mathbf{v}_{3}}{\|\mathbf{v}_{3}\|} = \frac{1}{2\sqrt{5}} \begin{pmatrix} 1\\3\\3\\\cdot 1 \end{pmatrix}, \qquad \mathbf{u}_{3} = \frac{\mathbf{v}_{3}}{\|\mathbf{v}_{3}\|} = \frac{1}{2\sqrt{5}} \begin{pmatrix} 1\\3\\3\\\cdot 1 \end{pmatrix}, \qquad \mathbf{u}_{3} = \frac{\mathbf{v}_{3}}{\|\mathbf{v}_{3}\|} = \frac{1}{2\sqrt{5}} \begin{pmatrix} 1\\3\\3\\\cdot 1 \end{pmatrix}, \qquad \mathbf{u}_{3} = \frac{\mathbf{v}_{3}}{\|\mathbf{v}_{3}\|} = \frac{1}{2\sqrt{5}} \begin{pmatrix} 1\\3\\3\\\cdot 1 \end{pmatrix}, \qquad \mathbf{u}_{3} = \frac{\mathbf{v}_{3}}{\|\mathbf{v}_{3}\|} = \frac{1}{2\sqrt{5}} \begin{pmatrix} 1\\3\\3\\\cdot 1 \end{pmatrix}, \qquad \mathbf{u}_{3} = \frac{\mathbf{v}_{3}}{\|\mathbf{v}_{3}\|} = \frac{1}{2\sqrt{5}} \begin{pmatrix} 1\\3\\3\\\cdot 1 \end{pmatrix}, \qquad \mathbf{u}_{3} = \frac{\mathbf{v}_{3}}{\|\mathbf{v}_{3}\|} = \frac{1}{2\sqrt{5}} \begin{pmatrix} 1\\3\\3\\\cdot 1 \end{pmatrix}, \qquad \mathbf{u}_{3} = \frac{\mathbf{v}_{3}}{\|\mathbf{v}_{3}\|} = \frac{1}{2\sqrt{5}} \begin{pmatrix} 1\\3\\3\\\cdot 1 \end{pmatrix}, \qquad \mathbf{u}_{3} = \frac{\mathbf{v}_{3}}{\|\mathbf{v}_{3}\|} = \frac{1}{2\sqrt{5}} \begin{pmatrix} 1\\3\\3\\\cdot 1 \end{pmatrix}, \qquad \mathbf{u}_{3} = \frac{\mathbf{v}_{3}}{\|\mathbf{v}_{3}\|} = \frac{1}{2\sqrt{5}} \begin{pmatrix} 1\\3\\3\\\cdot 1 \end{pmatrix}, \qquad \mathbf{u}_{3} = \frac{\mathbf{v}_{3}}{\|\mathbf{v}_{3}\|} = \frac{1}{2\sqrt{5}} \begin{pmatrix} 1\\3\\3\\\cdot 1 \end{pmatrix}, \qquad \mathbf{u}_{3} = \frac{\mathbf{v}_{3}}{\|\mathbf{v}_{3}\|} = \frac{1}{2\sqrt{5}} \begin{pmatrix} 1\\3\\3\\\cdot 1 \end{pmatrix}, \qquad \mathbf{u}_{3} = \frac{\mathbf{v}_{3}}{\|\mathbf{v}_{3}\|} = \frac{1}{2\sqrt{5}} \begin{pmatrix} 1\\3\\3\\1\\1 \end{pmatrix}, \qquad \mathbf{u}_{3} = \frac{\mathbf{v}_{3}}{\|\mathbf{v}_{3}\|} = \frac{1}{2\sqrt{5}} \begin{pmatrix} 1\\3\\3\\1\\1 \end{pmatrix}, \qquad \mathbf{u}_{3} = \frac{\mathbf{v}_{3}}{\|\mathbf{v}_{3}\|} = \frac{1}{2\sqrt{5}} \begin{pmatrix} 1\\3\\3\\1\\1 \end{pmatrix}, \qquad \mathbf{u}_{3} = \frac{\mathbf{v}_{3}}{\|\mathbf{v}_{3}\|} = \frac{1}{2\sqrt{5}} \begin{pmatrix} 1\\3\\3\\1\\1 \end{pmatrix}, \qquad \mathbf{u}_{3} = \frac{\mathbf{v}_{3}}{\|\mathbf{v}_{3}\|} = \frac{1}{2\sqrt{5}} \begin{pmatrix} 1\\3\\3\\1\\1 \end{pmatrix}, \qquad \mathbf{u}_{3} = \frac{\mathbf{v}_{3}}{\|\mathbf{v}_{3}\|} = \frac{1}{2\sqrt{5}} \begin{pmatrix} 1\\3\\3\\1\\1 \end{pmatrix}, \qquad \mathbf{u}_{3} = \frac{\mathbf{v}_{3}}{\|\mathbf{v}_{3}\|} = \frac{1}{2\sqrt{5}} \begin{pmatrix} 1\\3\\3\\1\\1 \end{pmatrix}, \qquad \mathbf{u}_{3} = \frac{\mathbf{v}_{3}}{\|\mathbf{v}_{3}\|} = \frac{1}{2\sqrt{5}} \begin{pmatrix} 1\\3\\3\\1\\1 \end{pmatrix}, \qquad \mathbf{u}_{3} = \frac{\mathbf{v}_{3}}{\|\mathbf{v}_{3}\|} = \frac{1}{2\sqrt{5}} \begin{pmatrix} 1\\3\\3\\1\\1 \end{pmatrix}, \qquad \mathbf{u}_{3} = \frac{\mathbf{v}_{3}}{\|\mathbf{v}_{3}\|} = \frac{1}{2\sqrt{5}} \begin{pmatrix} 1\\3\\3\\1\\1 \end{pmatrix}, \qquad \mathbf{u}_{3} = \frac{\mathbf{v}_{3}}{\|\mathbf{v}_{3}\|} = \frac{1}{2\sqrt{5}} \begin{pmatrix} 1\\3\\3\\1\\1 \end{pmatrix}, \qquad \mathbf{u}_{3} = \frac{\mathbf{v}_{3}}{\|\mathbf{v}_{3}\|} = \frac{1}{2\sqrt{5}} \begin{pmatrix} 1\\3\\3\\1\\1 \end{pmatrix}, \qquad \mathbf{u}_{3} = \frac{1}{2\sqrt{5}} \begin{pmatrix} 1\\3\\3\\1\\1\\1 \end{pmatrix}, \qquad \mathbf{u}_{3} = \frac{1}{2\sqrt{5}} \begin{pmatrix} 1\\3\\3\\1\\1\\1\\1 \end{pmatrix}, \qquad \mathbf{u}_{3} = \frac{1}{2\sqrt{5}} \begin{pmatrix} 1\\3\\3\\1\\1\\1\\1 \end{pmatrix}, \qquad \mathbf{u}_{3} = \frac{1}{2\sqrt{5}} \begin{pmatrix} 1\\3\\3\\$$

- b. The columns are already orthogonal to one another. As a result, anyone may readily find the orthonormal basis. The person who posed the inquiry is absolutely inept.
- c. Don't waste our time. None of these are correct.
- d. Columns are linearly independent. Thus, GS is not required.

Your answer is partially correct.

You have selected too many options.

The correct answer is:

Don't waste our time. None of these are correct.

→ Group A Quiz

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