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The discrete Fourier transform

3.1 Introduction

Let $f(t)$ be a function describing a physical process in the *time domain*. An *equivalent* representation of the process, $F(\nu)$, is possible in the *frequency domain*, and the two representations are connected by means of the direct and inverse Fourier transforms:

$$F(\nu) = \int_{-\infty}^{\infty} f(t) e^{2\pi i \nu t} dt \quad (3.1)$$

$$f(t) = \int_{-\infty}^{\infty} F(\nu) e^{-2\pi i \nu t} d\nu. \quad (3.2)$$

In the most common situations, the function $f(t)$ is sampled at a finite number of time arguments. Suppose that we have N consecutive sampled values:

$$f_j \equiv f(t_j),$$

with

$$t_j \equiv (j-1)\Delta, \quad j = 1, 2, \dots, N, \quad (3.3)$$

where Δ denotes the *sampling interval*.

We consider the N discrete frequencies

$$\nu_k = \frac{k-1}{N-1} \frac{1}{\Delta}, \quad k = 1, 2, \dots, N,$$

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and approximate the integral (3.1) by a discrete sum:

$$F(\nu_k) \simeq \sum_{j=1}^N f_j e^{2\pi i \nu_k t_j} \Delta = \Delta \sum_{j=1}^N f_j \exp \left[2\pi i \frac{(j-1)(k-1)}{N-1} \right].$$

The last sum is called the *discrete Fourier transform* of the N values f_j :

$$F_k = \sum_{j=1}^N f_j \exp \left[2\pi i \frac{(j-1)(k-1)}{N-1} \right], \quad k = 1, 2, \dots, N. \quad (3.4)$$

The discrete Fourier transform maps N complex numbers, f_j , into N complex numbers, F_k .

Having the N values F_k of the discrete Fourier transform, the N original values f_j can be recovered by the *discrete inverse Fourier transform*:

$$f_j = \frac{1}{N} \sum_{k=1}^N F_k \exp \left[-2\pi i \frac{(j-1)(k-1)}{N-1} \right]. \quad (3.5)$$

It is obvious that a routine designed to calculate the discrete Fourier transform can calculate the inverse transform, too.

There are two important particular cases of the Fourier transform. If the transformed function $f(t)$ vanishes at the origin ($f(0) \equiv f_0 = 0$), then the basis functions should behave similarly and the natural transform in this case is the *sine transform*:

$$F_k = \sum_{j=1}^N f_j \sin \left[\frac{(j-1)(k-1)}{N-1} \pi \right], \quad k = 1, 2, \dots, N. \quad (3.6)$$

If the *derivative* of the transformed function $f(t)$ vanishes at the origin, then the basis functions should show the same behavior, too, and the natural transform in this case is the *cosine transform*:

$$F_k = \sum_{j=2}^{N-1} f_j \cos \left[\frac{(j-1)(k-1)}{N-1} \pi \right] + \frac{1}{2} [f_1 + (-1)^{k-1} f_N], \quad k = 1, 2, \dots, N. \quad (3.7)$$

The cosine transform is its own inverse,

$$f_j = \sum_{k=2}^{N-1} F_k \cos \left[\frac{(j-1)(k-1)}{N-1} \pi \right] + \frac{1}{2} [F_1 + (-1)^{j-1} F_N], \quad j = 1, 2, \dots, N, \quad (3.8)$$

and the transformed values F_k appear in the Fourier expansion of f_j as weights of the cosine functions with the frequencies

$$\nu_k = \frac{k-1}{N-1} \frac{1}{2\Delta}, \quad k = 1, 2, \dots, N. \quad (3.9)$$

We remind that $t_j = (j-1)\Delta$.

The straightforward implementation of the discrete cosine transform (3.7)-(3.9) is:

```

=====
subroutine FTcos0(f,ft,n)
!-----
!   Straightforward implementation of the discrete cosine transform
!
!   f  - input data
!   ft - transformed data
!   n  - no. of data values
!
!   Frequencies corresponding to the transformed data:
!       freq(k) = (k-1) / (2.d0 * dt * (n-1)), k=1,n
!-----
  implicit real(8) (a-h,o-z)

  real(8), parameter :: pi = 3.1415926535897932385d0

  real(8) f(n), ft(n)

  isgn = 1
  fact = pi / (n-1)
  do k = 1,n
    theta = (k-1) * fact

    sum = 0.d0
    do j = 2,n-1
      sum = sum + f(j) * cos((j-1)*theta)
    end do

    ft(k) = sum + 0.5d0 * (f(1) + isgn*f(n))
    isgn = -isgn
  end do
end

```

Due to the repeated evaluations of the cosine function, the above implementation is highly inefficient and the execution time becomes critical when the number of observations N exceeds 10^5 .

3.2 Efficient discrete Fourier transform

We consider only the sum in expression (3.7) of the cosine transform F_k ,

$$G_k = \sum_{j=2}^{N-1} f_j \cos [(j-1)\theta_k^0], \quad (3.10)$$

with

$$\theta_k^0 = \frac{k-1}{N-1}\pi, \quad (3.11)$$

and split it in even- j and odd- j terms:

$$G_k = \sum_{j=2,4} f_j \cos [(j-1)\theta_k^0] + \sum_{j=3,5} f_j \cos [(j-1)\theta_k^0].$$

The addition formula $\cos [(j-1)\theta] = \cos \theta \cos(j\theta) + \sin \theta \sin(j\theta)$ is used to expand the first sum, and the index j is changed to $j+1$ in the second one:

$$G_k = \sum_{j=2,4} f_j [C_k \cos(j\theta_k^0) + S_k \sin(j\theta_k^0)] + \sum_{j=2,4} f_{j+1} \cos(j\theta_k^0),$$

where

$$C_k = \cos \theta_k^0, \quad S_k = \sin \theta_k^0.$$

Now, we replace the index j by $2j$ in both sums and group together the sine and cosine functions with the same argument:

$$G_k = \sum_{j=1}^M [U_j \cos(j\theta_k) + V_j \sin(j\theta_k)]. \quad (3.12)$$

Here we use the notations:

$$U_j = C_k f_{2j} + f_{2j+1}, \quad V_j = S_k f_{2j}, \quad (3.13)$$

$$\theta_k = 2\theta_k^0, \quad (3.14)$$

and

$$M = \left\lfloor \frac{N-1}{2} \right\rfloor \quad (3.15)$$

is the integer part of $(N-1)/2$.

Next, the arguments of the trigonometric functions will be modified in the even- j moiety. To this end, G_k is split first into odd- j and even- j terms, and in the odd- j terms the argument $j\theta_k$ is replaced by $(j+1)\theta_k - \theta_k$:

$$\begin{aligned} G_k &= \sum_{j=1,3}^{M \text{ or } M-1} \{U_j \cos[(j+1)\theta_k - \theta_k] + V_j \sin[(j+1)\theta_k - \theta_k]\} \\ &+ \sum_{j=2,4}^{M \text{ or } M-1} [U_j \cos(j\theta_k) + V_j \sin(j\theta_k)]. \end{aligned}$$

In the first sum, addition formulas for the modified cosine and sine functions are applied:

$$\begin{aligned} G_k &= \sum_{j=1,3}^{M \text{ or } M-1} U_j \{\cos[(j+1)\theta_k] \cos \theta_k + \sin[(j+1)\theta_k] \sin \theta_k\} \\ &+ \sum_{j=1,3}^{M \text{ or } M-1} V_j \{\sin[(j+1)\theta_k] \cos \theta_k - \cos[(j+1)\theta_k] \sin \theta_k\} \\ &+ \sum_{j=2,4}^{M \text{ or } M-1} [U_j \cos(j\theta_k) + V_j \sin(j\theta_k)]. \end{aligned}$$

Now, all arguments imply even multiples of θ_k . In order to be able to group the trigonometric functions, $j+1$ is replace by $2j$ in the first two sums, and j by $2j$ in the last one:

$$\begin{aligned} G_k &= \sum_{j=1} U_{2j-1} \{\cos(2j\theta_k) \cos \theta_k + \sin(2j\theta_k) \sin \theta_k\} \\ &+ \sum_{j=1} V_{2j-1} \{\sin(2j\theta_k) \cos \theta_k - \cos(2j\theta_k) \sin \theta_k\} \\ &+ \sum_{j=1} [U_{2j} \cos(2j\theta_k) + V_{2j} \sin(2j\theta_k)]. \end{aligned}$$

Collecting the terms and making the notations:

$$\begin{aligned} U_j^{(1)} &= U_{2j-1} \cos \theta_k - V_{2j-1} \sin \theta_k + U_{2j} \\ V_j^{(1)} &= U_{2j-1} \sin \theta_k + V_{2j-1} \cos \theta_k + V_{2j}, \end{aligned} \tag{3.16}$$

leads to the following form of G_k :

$$G_k = \sum_{j=1}^{[(M+1)/2]} \left[U_j^{(1)} \cos(2j\theta_k) + V_j^{(1)} \sin(2j\theta_k) \right], \quad (3.17)$$

where $[(M+1)/2]$ is the integer part of $(M+1)/2$. For odd M , the new coefficients, $U_j^{(1)}$ and $V_j^{(1)}$, imply for $j = [(M+1)/2]$ the old coefficients, U_{M+1} and V_{M+1} , which do not actually exist. These terms should be interpreted as zero.

By comparing expression (3.17) of G_k with its original form (3.12), it can be seen that at the expense of having to evaluate a new set of coefficients ($U_j^{(1)}$ and $V_j^{(1)}$ for $j = 1, [(M+1)/2]$), the number of summed terms was condensed by a factor of almost 2 (according to the parity of M). The corresponding sine and cosine functions may be easily evaluated from the duplication formulas:

$$\begin{aligned} \sin(2j\theta_k) &= 2 \sin(j\theta_k) \cos(j\theta_k), \\ \cos(2j\theta_k) &= 2 \cos^2(j\theta_k) - 1. \end{aligned} \quad (3.18)$$

A careful analysis shows that if such a *condensation* procedure is repeated N_{cond} times, where

$$N_{\text{cond}} = \lceil \log_2(2M - 1) \rceil, \quad (3.19)$$

then just two terms remain and one gets the final expression:

$$G_k = U_1^{(N_{\text{cond}})} \cos(2^{N_{\text{cond}}} \theta_k) + V_1^{(N_{\text{cond}})} \sin(2^{N_{\text{cond}}} \theta_k), \quad (3.20)$$

from which G_k can be easily evaluated.

By this condensation procedure, the number of sines and cosines evaluations is reduced from M to N_{cond} , or, for instance, from 1000 to 10. Actually, one just has to evaluate before starting the condensation procedure $\cos \theta_k$ and $\sin \theta_k$ for $j = 1, M$, the rest of the sine and cosine functions forming a sequence which can be readily generated by the duplication formulas (3.18).

The routine listed below represents the exact implementation of the presented algorithm.

```
!=====
subroutine FTcos(f,ft,n)
!-----
!  Calculates the cosine transform of an array f of n real values.
!  The transformed data is returned in array ft.
!-----
implicit real(8) (a-h,o-z)
```

```

parameter (pi = 3.1415926535897932385d0)

real(8) f(n), ft(n)
real(8), allocatable :: u(:), v(:)

n2 = (n-1)/2
allocate(u(n2+1), v(n2+1))

ncond = int(log(2.d0*n2-1.d0)/log(2.d0))

isgn = 1
fact = pi / (n-1)
fn = f(n); f(n) = 0.d0
do k = 1,n
  theta = (k-1) * fact
  c = cos(theta); s = sin(theta)

  do j = 1,n2
    j2 = 2 * j
    u(j) = c * f(j2) + f(j2+1)
    v(j) = s * f(j2)
  end do

  s = 2.d0 * s * c
  c = 2.d0 * c * c - 1.d0
  nterm = n2
  do icond = 1,ncond
    u(nterm+1) = 0.d0; v(nterm+1) = 0.d0
    nterm = int((nterm+1)/2)
    do j = 1,nterm
      j2 = 2*j - 1
      utmp = c * u(j2) - s * v(j2) + u(j2+1)
      v(j) = s * u(j2) + c * v(j2) + v(j2+1)
      u(j) = utmp
    end do
    s = 2.d0 * s * c
    c = 2.d0 * c * c - 1.d0
  end do
  ft(k) = c * u(1) + s * v(1) + 0.5d0 * (f(1) + isgn*fn)
  isgn = -isgn
end do

deallocate(u,v)
end

```

Bibliografie

- [1] Aubanel, E.E. and Oldham, K.B., "Fourier smoothing without the fast Fourier transform", *Byte*, February 1985, p. 207.

- [2] W.H. Press, S.A. Teukolsky, W.T. Vetterling, B.P. Flannery, *Numerical Recipes in C, Second Edition* (Cambridge University Press, Cambridge, 1992).