This is for OpenPose 1.70 with Python.

System Configuration

Stuff you will need before downloading openpose,

OpenPose works best when running on GPU, so have all GPU installations. Don't use CPU mode as it is slow and comes with less functionality.

Downloads for GPU:

CUDA version: 11.1.1

i. CUDA Toolkit 11.1 Update 1 Downloads | NVIDIA Developer

o cuDNN version: 8.0.5.39

i. <u>cuDNN Archive | NVIDIA Developer</u>

cuDNN will need a developer account to download:

Email: HATlabuvic@outlook.com

Password: standard HATlab password

It is good to know the GPU model incase errors occur.

GPU model: Nvidia GeForce RTX 3060 Laptop 6GB(if using the HATlaptop01 or HATlaptop02, if not check to find your GPU model)

Download CMake to configure OpenPose build.(version 3.19.0 was recommended but newer versions also worked)

Download | CMake

Download Python version 3.8.6

Python Release Python 3.8.6 | Python.org

Once python is installed check to make sure it is the default python version running on command prompt. Open command prompt and type "python --version"

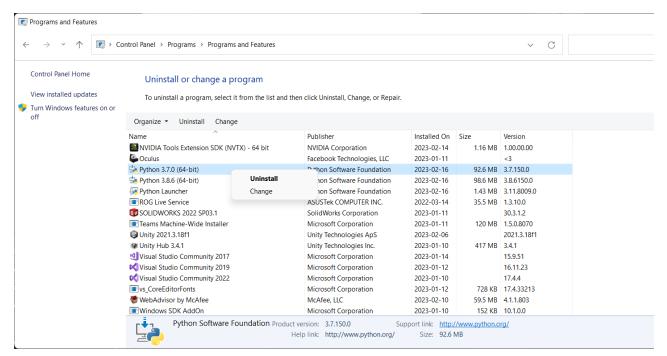
Command Prompt

```
Microsoft Windows [Version 10.0.22000.1574]
(c) Microsoft Corporation. All rights reserved.

C:\Users\hatla>python --version

Python 3.8.6
```

If it returns Python 3.8.6, you are good to go! If not, go to the control panel and install all python versions.



Go to Uninstall a program(at the bottom-left of the control panel menu). From the list of programs click the python versions to get the option to uninstall them.

After they are all uninstalled, reinstall 3.8.6 and try again.

After you are on the correct version you will have to install some python packages.

1. Install numpy(numpy==1.19.3)

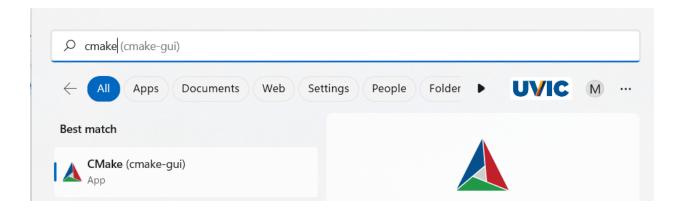
```
C:\Users\hatla>pip install numpy==1.19.3
```

2. Install cv2(called opency-python when installing, but in files called cv2) (version: 4.4.0.40)

```
C:\Users\hatla>pip install opencv-python==4.4.0.40
```

Go to github and clone Openpose to your computer.

After python is fully configured, open cmake-gui.



Select the OpenPose root folder in the Where is the source code:

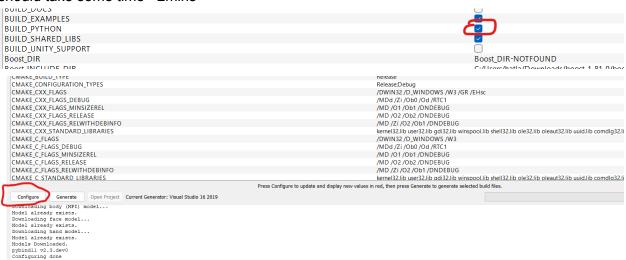
C://users/hatia/OneDrive/Documents/ Githlub/openpose

∨ Browse Build...

Create a build folder in the OpenPose root folder and select it in the where to build binaries:

If Prompted, select Visual Studio Code 2019 and x64 architecture

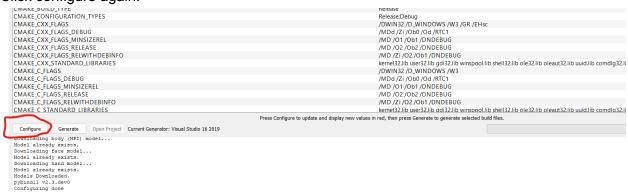
I list of options should appear, select BUILD_PYTHON and click configure, the configuration should take some time ~2mins



Some new options should appear, click PYTHO_EXECUTABLE and select the file path that matches the image below. Also make sure PYBIND11_INSTALL is checked.



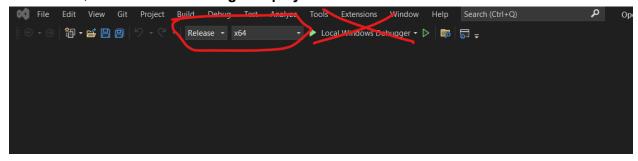
Click configure again:



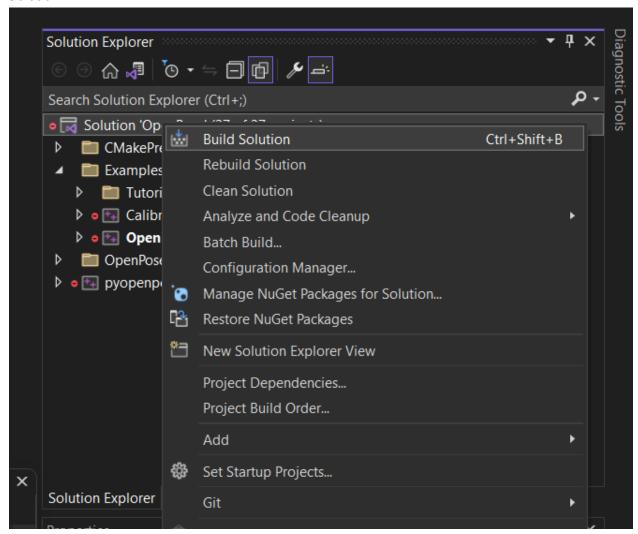
If options highlighted red appear, click configure until they stop appearing.

Next click **Generate**, the button beside Configure. After the project is generated, click **Open Project**.

When visual studios has opened: select **Release** as the Solution Configuration and **x64** as the architecture, but **do not click the green play button!!**



Go to the solution explorer at the side of the page and right click on the solution tab, click "Build Solution"



After the Solution should build without any errors.

If you have an error message saying "ssize_t is not identified" or something similar, go to file explorer and open up the OpenPose root directory.

Go to "openpose\3rdparty\pybind11\include\pybind11" and open up numpy.h

```
C numpy.h 2 X

C: > Users > hatla > OneDrive > Documents > GitHub > openpose > 3rdparty > pybind11 > include > pybind11 > C numpy.h > ...

#include <cstring>
19 #include <sstream>
20 #include <string>
21 #include <functional>
22 #include <utility>
23 #include <vector>
24 #include <typeindex>

25

# pragma warning(push)
28 # pragma warning(disable: 4127) // warning C4127: Conditional expression is constant
29 #endif

30

31 /* This will be true on all flat address space platforms and allows us to reduce the
32 whole npy_intp / ssize_t / Py_intptr_t business down to just ssize_t for all size
33 and dimension types (e.g. shape, strides, indexing), instead of inflicting this
34 upon the library daser.
35 static_assert(size(f(size_t)) == sizeof(Py_intptr_t), "size_t! = Py_intptr_t");
```

change **ssize_t** to **size_t** on all instances of ssize_t in the document.

Now rebuild the solution, and make sure most of the processes succeed.

```
▼ 🗖 ×
Output
  Show output from: Build
                                                                                                                                                     5>Done building project "pyopenpose.vcxproj".
  25> Creating library C:/Users/hatla/OneDrive/Documents/GitHub/openpose/build/examples/openpose/Release/OpenPoseDemo.lib and object C:/Users/hatla/OneDri
  25>OpenPoseDemo.vcxproj -> C:\Users\hatla\OneDrive\Documents\GitHub\openpose\build\x64\Release\OpenPoseDemo.exe
  25>Done building project "OpenPoseDemo.vcxproj".
  23> Creating library C:/Users/hatla/OneDrive/Documents/GitHub/openpose/build/examples/tutorial_api_cpp/Release/02_whole_body_from_image_default.lib and
  23>82_whole_body_from_image_default.vcxproj -> C:\Users\hatla\OneDrive\Documents\GitHub\openpose\build\x64\Release\02_whole_body_from_image_default.exe
   7> Creating library C:/Users/hatla/OneDrive/Documents/GitHub/openpose/build/examples/tutorial_api_cpp/Release/18_synchronous_custom_all_and_datum.lib ar
  7>18\_synchronous\_custom\_all\_and\_datum.vcxproj -> C: \Users \hatla \One Drive \Documents \GitHub \open pose \build \x64 \Release \18\_synchronous\_custom\_all\_and\_datum.e
              Creating\ library\ C:/Users/hatla/OneDrive/Documents/GitHub/openpose/build/examples/tutorial\_api\_cpp/Release/13\_asynchronous\_custom\_input\_output\_and\_custom_input\_output\_and\_custom_input\_output\_and\_custom_input\_output\_and\_custom_input\_output\_and\_custom_input\_output\_and\_custom_input\_output\_and\_custom_input\_output\_and\_custom_input\_output\_and\_custom_input\_output\_and\_custom_input\_output\_and\_custom_input\_output\_and\_custom_input\_output\_and\_custom_input\_output\_and\_custom_input\_output\_and\_custom_input\_output\_and\_custom_input\_output\_and\_custom_input\_output\_and\_custom_input\_output\_and\_custom_input\_output\_and\_custom_input\_output\_and\_custom_input\_output\_and\_custom_input\_output\_and\_custom_input\_output\_and\_custom_input\_output\_and\_custom_input\_output\_and\_custom_input\_output\_and\_custom_input\_output\_and\_custom_input\_output\_and\_custom_input\_output\_and\_custom_input\_output\_and\_custom_input\_output\_and\_custom_input\_output\_and\_custom_input\_output\_and\_custom_input\_output\_and\_custom_input\_output\_and\_custom_input\_output\_and\_custom_input\_output\_and\_custom_input\_output\_and\_custom_input\_output\_and\_custom_input\_output\_and\_custom_input\_output\_and\_custom_input\_output\_and\_custom_input\_output\_and\_custom_input\_output\_and\_custom_input\_output\_and\_custom_input\_output\_and\_custom_input\_output\_and\_custom_input\_output\_and\_custom_input\_output\_and\_custom_input\_output\_and\_custom_input\_output\_and\_custom_input\_output\_and\_custom_input\_output\_and\_custom_input\_output\_and\_custom_input\_output\_and\_custom_input\_output\_and\_custom_input\_output\_and\_custom_input\_output\_and\_custom_input\_output\_and\_custom_input\_output\_and\_custom_input\_output\_and\_custom_input\_output\_and\_custom_input\_output\_and\_custom_input\_output\_and\_custom_input\_output\_and\_custom_input\_output\_and\_custom_input\_output\_and\_custom_input\_output\_and\_custom_input\_output\_and\_custom_input\_output\_and\_custom_input\_output\_and\_custom_input\_output\_output\_output\_output\_output\_output\_output\_output\_output\_output\_output\_output\_output\_output\_output\_output\_output\_output\_output\_output\_output\_output\_output\_output\_output\_out
  27>----- Skipped Rebuild All: Project: INSTALL, Configuration: Release x64 -----
  27>Project not selected to build for this solution configuration
                  ==== Rebuild All: 26 succeeded, 0 failed, 1 skipped
                     == Elapsed 01:24.062 ==
  Frror List Output
```

Go to the python api example folder and right click on the whitespace. Click open in Terminal. **Do not run these python files in visual studio or visual studio code as it won't work!!**

Documents > GitHub > openpose > build > examples > tutorial_api_python Name Date modified Type Size CMakeFiles 2023-02-16 1:54 PM File folder 01_body_from_image 2023-02-16 4:00 PM Python Source File 3 KB 02_whole_body_from_image 2023-02-16 1:50 PM Python Source File 4 KB 04_keypoints_from_images 2023-02-16 1:50 PM Python Source File 4 KB 05_keypoints_from_images_multi_gpu 2023-02-16 1:50 PM Python Source File 5 KB 06_face_from_image 2023-02-16 3:45 PM Python Source File 4 KB 07_hand_from_image 2023-02-16 1:50 PM Python Source File 4 KB 08_heatmaps_from_image 2023-02-16 1:50 PM 4 KB Python Source File 09_keypoints_frc Python Source File 4 KB 88 View cmake_install CMake Source File 2 KB ↑ Sort by INSTALL.vcxproj VC++ Project 6 KB ☐ Group by > INSTALL.vcxproj. VC++ Project Filte... 1 KB Undo Rename Ctrl+Z openpose_pythc Python Source File 3 KB \oplus New > pose_deploy.prc PROTOTXT File 44 KB **Properties** Alt+Enter pose_iter_58400 CAFFEMODEL File 102,262 KB Open in Terminal Show more options Shift+F10

To test if the API is working correctly, type "python 01_body_from_image.py"

If you get "OpenPose library could not be found" error

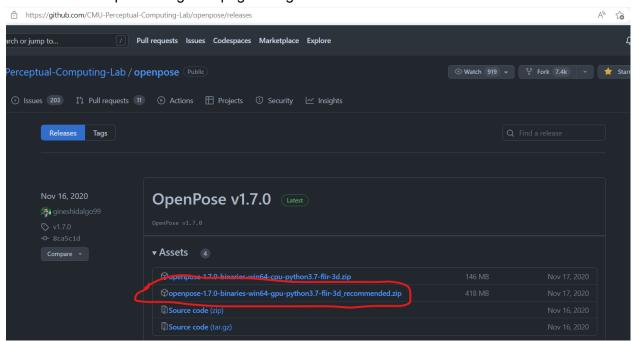
```
Error: OpenPose library could not be found. Did you enable `BUILD_PYTHON` in CMake and have this Python script in the right folder?

DLL load failed while importing pyopenpose: The specified module could not be found.
```

Or if you had the "no module named 'pyopenpose' error

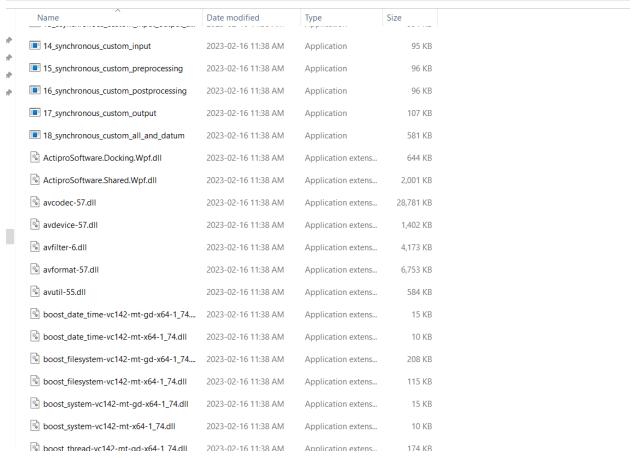
> python 02_whole_body_from_image.py Error: OpenPose library could not be found. Did you enable `BUILD_PYTHON` in CMake and have ve this Python script in the right folder? No module named 'pyopenpose'

Go back to the OpenPose github page and go to the releases.

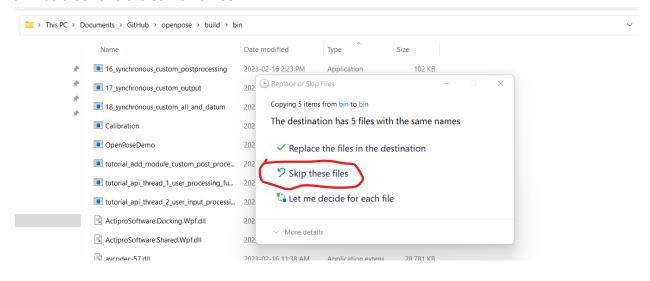


Download "openpose-1.7.0-binaries-win64-gpu-python3.7-flir-3d_recommended.zip". Once downloaded, extract all to a folder in Downloads.

Downloads > openpose-1.7.0-binaries-win64-gpu-python3.7-flir-3d_recommended > openpose > bin



Go to the bin folder and copy all .dll files and move them to your main OpenPose bin folder, Skip all files that have the same names.



For each test file you will have to add "os.add_dll_directory(dir_path + '/../../bin')" before importing pyopenpose.

```
File Edit Selection View Go Run ...  

Dependence

Dep
```

Try running "python 01_body_from_image.py" again

```
Windows PowerShell × + ✓ − □ ×

Windows PowerShell
Copyright (C) Microsoft Corporation. All rights reserved.

Install the latest PowerShell for new features and improvements! https://aka.ms/PSWindows

PS C:\Users\hatla\OneDrive\Documents\GitHub\openpose\build\examples\tutorial_api_python>

python 01_body_from_image.py
```

If the picture below opens congratulation you configured it correctly!

