Implementation of biologically-inspired dynamical systems for movement generation: automatic real-time goal adaptation and obstacle avoidance

Alan Gomez, Samuel Parra, and Brennan Penfold

***Abstract*—**

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Our two papers [1], [2]

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III. Experiments

A. Testing

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C. Results

IV. Use case

A. Single arm

B. Dual arm

C. Self collision

V. Conclusion

Appendices

Acknowledgments

References

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