# Homework 1 MATH CS 120 Convex Optimization

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### Exercise 2.3

A set C is midpoint convex if whenever two points a, b are in C, the average or midpoint (a+b)/2 is in C. Obviously a convex set is midpoint convex. It can be proved that under mild conditions midpoint convexity implies convexity. As a simple case, prove that if C is closed and midpoint convex, then C is convex.

Let  $C \in \mathbb{R}^n$  be a midpoint convex, closed set and let  $a, b \in \mathbb{C}$ . Let  $c = \theta a + (1 - \theta)b$  for some  $\theta \in [0, 1]$ , that is, c is a convex combination of a and b. We aim to prove that  $c \in C$ , thereby proving C is convex. To do so, we construct a sequence of line segments betwen  $a_n$  and  $b_n$  for all  $n \in \mathbb{N}$  in the following way:

$$a_0 = a, \quad b_0 = b,$$

and given  $a_{n-1}, b_n - 1$ , define  $m_n = \frac{1}{2}(a_{n-1} + b_{n-1})$  and if c is on the line segment from  $a_n$  to  $m_n$ , define

$$a_n = a_{n-1}, \quad b_n = m_n.$$

Otherwise, if c is on the line segment from  $m_n$  to  $b_n$ , define

$$a_n = m_n, \quad b_n = b_{n-1}.$$

Since c is on the line segment between  $a_n$  and  $b_n$  for all  $n \in \mathbb{N}$ , we have that

$$|a_n - c| \le |a_n - b_n| = \frac{1}{2^n} |a - b|.$$

So the sequence  $\{a_n\}_{n=1}^{\infty}$  converges to c. And since each  $a_n$  is define by a midpoint of elements of C, each  $a_n \in \mathbb{C}$ . Thus c is a limit point of C, and since C is closed,  $c \in \mathbb{C}$ . Therefore, C is convex.

#### Exercise 2.8

Which of the following sets S are polyhedra? If possible, express S in the form  $S = \{x : Ax \leq b, Fc = g\}$ .

(a)  $S = \{y_1a_1 + y_2a_2 : -1 \le y_1 \le 1, -1 \le y_2 \le 1\}$ , where  $a_1, a_2 \in \mathbb{R}^n$ . Any point  $x \in S$  corresponds to a convex combination

$$x = \theta_1(a_1 + a_2) + \theta_2(a_1 - a_2) + \theta_3(a_2 - a_1) + \theta_4(-a_1 - a_2),$$

where

$$y_1 = \theta_1 + \theta_2 - \theta_3 + \theta_4,$$
  
 $y_2 = \theta_1 + \theta_3 - \theta_2 + \theta_4.$ 

So S can be equivalently defined as the simplex given by the convex hull of the points

$$(a_1 + a_2), (a_1 - a_2), (a_2 - a_1), (-a_1 - a_2).$$

If  $a_1, a_2$  are affinely dependent, then this is simply a line segment. Either way, this is a polyhedron.

(b)  $S = \{x \in \mathbb{R}^n : x \succeq 0, 1^T x = 1, \sum_{i=1}^n x_i a_i = b_1, \sum_{i=1}^n x_i a_i^2 = b_2\}$  where  $a_1, \dots, a_n \in \mathbb{R}$  and  $b_1, b_2 \in \mathbb{R}$ .

To see that S is a polyhedron, the conditions for S can simply be rewritten. If we define

$$A = \begin{bmatrix} 1 & \cdots & 1 \\ a_1 & \cdots & a_n \\ a_1^2 & \cdots & a_n^2 \end{bmatrix}, \qquad b = \begin{bmatrix} 1 \\ b_1 \\ b_2 \end{bmatrix},$$

then we can equivalently write S as

$$S = \{x \in \mathbb{R}^n : (-I_n)x \leq 0, Ax = b\},\$$

thus S is a polyhedron.

(c) 
$$S = \{x \in \mathbb{R}^n : x \succeq 0, x^T y \le 1 \text{ for all } y \text{ with } |y| = 1\}.$$

This set is equivalent to the nonnegative vectors of the closed unit ball centered at the origin in  $\mathbb{R}^n$ . This can be seen since any negative x would not satisfy  $x \succeq 0$  and any vector with a length greater than 1 would not satisfy  $x^Ty \leq 1$  for the unit vector y in the direction of x. However, any nonnegative unit vector satisfies both of these. Because of this, S cannot be expressed as the intersection of finitely many halfspaces and hyperplanes, and thus is not a polyhedron.

(d) 
$$S = \{x \in \mathbb{R}^n : x \succeq 0, x^T y \le 1 \text{ for all } y \text{ with } \sum_{i=1}^n |y_i| = 1\}.$$

This set is equivalent to the set of vectors in  $\mathbb{R}^n$  with each element between 0 and 1. Similar to (c), each x must be nonnegative, but in this case each element of x must be less than or equal to 1. For any such vector, the dot product  $x^Ty$  is less than or equal to the sum of all  $|y_i|$ , which is equal to 1. However, for any x with an element greater than 1, there is some y for which the dot product is greater than 1. Therefore, we can equivalently define

$$S = \{ x \in \mathbb{R}^n : \begin{bmatrix} -I_n \\ I_n \end{bmatrix} x \preceq \begin{bmatrix} 0 \\ 1 \end{bmatrix} \}.$$

#### Exercise 2.10

Let  $C \in \mathbb{R}^n$  be the solution set of a quadratic inequality,

$$C = \{x \in \mathbb{R}^n : x^T A x + b^T x + c \le 0\},\$$

with  $A \in S^n$ ,  $b \in \mathbb{R}^n$ , and  $c \in \mathbb{R}$ . (note:  $S^n$  is the set of  $n \times n$  symmetric matrices.)

(a) Show that C is convex if  $A \succeq 0$ . Let  $x, y \in C$  and  $\theta \in [0, 1]$ . We aim to prove that the convex combination

$$x + \theta(y - x)$$

is in C. To show this, we substitute the point into the inequality for C to find

$$(x + \theta(y - x))^{T} A(x + \theta(y - x)) + b^{T} (x + \theta(y - x)) + c$$
  
=  $(y - x)^{T} A(y - x)\theta^{2} + (2(y - x)^{T} Ax + b^{T} (y - x))\theta + x^{T} Ax + b^{T} x + c.$ 

Notice that this is a quadratic function on  $\theta$ , which is less than or equal to zero for values of  $\theta = 0$  and  $\theta = 1$ , since these values correspond to the inequality for C on x and y, respectively. Therefore, this expression is less than or equal to zero if and only if the  $a_2$  term is positive. Since

$$a_2 = (y - x)^T A (y - x)$$

and A is positive semidefinite, we in fact have  $a_2 \ge 0$ . Thus, the expression is less than or equal to 0, giving us  $x + \theta(y - x) \in C$ . The converse, however, is not true, since we could pick  $A = -I_n, b = 0, c = 0$ , and then the condition for C becomes

$$-x^T x \le 0,$$

which is true for all  $x \in \mathbb{R}^n$ , making  $C = R^n$ , which is convex.

(b) Show that the intersection of C and the hyperplane defined by  $g^T x + h = 0$  (where  $g \neq 0$ ) is convex if  $A + \lambda g g^T \succeq 0$  for some  $\lambda \in \mathbb{R}$ .

Similar to (a), we let  $x, y \in C \cap \{x \in \mathbb{R}^n : g^T + h = 0\}, \theta \in \mathbb{R}$  and we aim to prove

$$x + \theta(y - x) \in C \cap \{x \in \mathbb{R}^n : g^T x + h = 0\}.$$

Since the hyperplane is convex, we already know that

$$x + \theta(y - x) \in \{x \in \mathbb{R}^n : g^T x + h = 0\}.$$

So we just need to show that the point is in C. And similar to (a), this is the case if

$$(y-x)^T A(y-x) \ge 0.$$

To show this is satisfied, we assume  $A + \lambda gg^T \succeq 0$  for some  $\lambda \in \mathbb{R}$ . So

$$0 \le (y - x)^{T} (A + \lambda g g^{T})(y - x)$$
  
=  $(y - x)^{T} A (y - x) + \lambda (g^{T} y - g^{T} x)^{2}$   
=  $(y - x)^{T} A (y - x) + \lambda (-h + h)^{2}$   
=  $(y - x)^{T} A (y - x)$ .

Thus,  $x + \theta(y - x) \in C \cap \{x \in \mathbb{R}^n : g^T x + h = 0\}$ , so the intersection is convex.

### Exercise 2.20

Suppose  $A \in \mathbb{R}^{m \times n}$ ,  $b \in \mathbb{R}^m$ , with  $b \in R(A)$ . Show that there exists an x satisfying

$$x \succ 0$$
,  $Ax = b$ 

if and only if there exists no  $\lambda$  with

$$A^T \lambda \succeq 0$$
,  $A^T \lambda \neq 0$ ,  $b^T \lambda < 0$ .

Hint. First prove the following fact from linear algebra:  $c^T x = d$  for all x satisfying Ax = b if and only if there is a vector  $\lambda$  such that  $c = A^T \lambda$ ,  $d = b^T \lambda$ 

We first prove that  $c^T x = d$  for all x satisfying Ax = b if and only if there is a vector  $\lambda$  such that  $c = A^T \lambda$ ,  $d = b^T \lambda$ . Suppose there is a vector  $\lambda$  such that  $c = A^T \lambda$ ,  $d = b^T \lambda$ . Then for any x such that Ax = b, we find

$$c^T x = A^T \lambda x = \lambda^T A x = \lambda^T b = b^T \lambda = d.$$

Now suppose that  $c^T x = d$  for all x such that Ax = b. Let v be such that Av = b, then for any x such that Ax = b, there is some  $u \in \ker A$  such that x = u + v. Now since  $c^T v = d$  and  $c^T x = d$ , we find

$$d = c^t(u+v) = c^T u + c^T v,$$

which implies that  $c^T u = 0$  for all  $u \in \ker A$ . Now since c is orthogonal to all the vectors in the kernel of A, it must be in the orthogonal complement to  $\ker A$  which is given by the rowspace of A. So c is a linear combination of the rows of A, that is,  $c = A^T \lambda$  for some  $\lambda$ . From this, we find

$$d = c^T x = (A^T \lambda)^T x = \lambda^T A x = \lambda^T b = b^T \lambda.$$

Thus  $c^T x = d$  for all x satisfying Ax = b if and only if there is a vector  $\lambda$  such that  $c = A^T \lambda, d = b^T \lambda$ .

Suppose there exists  $x \succ 0$  such that Ax = b. We now assume for the purpose of contradiction that there is some  $\lambda$  such that

$$A^T \lambda \succeq 0, \quad A^T \lambda \neq 0, \quad b^T \lambda \leq 0.$$

Then we have

$$A^T \lambda x = b^T \lambda.$$

However, since x is strictly positive,  $A^T\lambda$  is nonnegative, and  $b^T\lambda$  is strictly positive. Therefore, no such  $\lambda$  exists.

Lastly suppose that there does not exist an x > 0 such that Ax = b. In other words, the set  $G = \{x \in \mathbb{R}^n : Ax = b\}$  is disjoint with the set  $H = \{x \in \mathbb{R}^n : x > 0\}$ . Since both of these sets are convex, there is a hyperplane defined by  $c \in \mathbb{R}^n, k \in \mathbb{R}$  such that

$$\begin{cases} c^T g \le k, & \forall g \in G; \\ c^T h \ge k, & \forall h \in H. \end{cases}$$

From this, we see that c must be nonnegative, since otherwise we could find  $c^T h < k$  for large enough  $h \in H$ . And since  $c^T h$  can be made arbitrarily close to zero for small h, we must have  $k \leq 0$ . And since G is affine,  $c^T g$  must be the same for all  $g \in G$ , since otherwise we could picking two points with different values find a third along the line with an arbitrarily large value for  $c^T g$ . Call this value d, so  $c^T x = d$  for all  $x \in G$ . Then the desired  $\lambda$  is given by  $c = A^T \lambda$  and  $d = b^T \lambda$ .

#### Exercise 2.21

Suppose that C and D are disjoint subsets of  $\mathbb{R}^n$ . Consider the set of  $(a,b) \in \mathbb{R}^{n+1}$  for which  $a^Tx \leq b$  for all  $x \in C$ , and  $a^Tx \geq b$  for all  $x \in D$ . Show that this set is a convex cone (which is the singleton  $\{0\}$  if there is no hyperplane that separates C and D).

Let  $(a, b), (c, d) \in \mathbb{R}^{n+1}$  define separating hyperplanes for C and D. We consider for some  $\theta_1, \theta_2 \geq 0$  the conic combination

$$(e, f) = (\theta_1 a + \theta_2 c, \, \theta_1 b + \theta_2 d).$$

Then for any  $x \in C$ , we have

$$e^{T}x = (\theta_{1}a + \theta_{2}b)^{T}x = \theta_{1}a^{T}x + \theta_{2}c^{T}x \le \theta_{1}b + \theta_{2}d = f.$$

And for any  $x \in D$ , we have

$$e^{T}x = (\theta_{1}a + \theta_{2}b)^{T}x = \theta_{1}a^{T}x + \theta_{2}c^{T}x \ge \theta_{1}b + \theta_{2}d = f.$$

So in fact, (e, f) defines a separating hyperplane of C and D. Thus the set of separating hyperplanes is a convex cone.

## Exercise 2.25

Let  $C \in \mathbb{R}^n$  be a closed convex set, and suppose that  $x_1, \ldots, x_K$  are on the boundary of C. Suppose that for each i,  $a_i^T(x - x_i) = 0$  defines a supporting hyperplane for C at  $X_i$ , i.e.,  $C \subseteq \{x : a_i^T(x - x_i) \le 0\}$ . Consider the two polyhedra

$$P_{\text{inner}} = \mathbf{conv}\{x_1, \dots, x_K\}, \quad P_{\text{outer}}(x : a_i^T(x - x_i) \le 0, i = 1, \dots, K\}.$$

Show that  $P_{\text{inner}} \subseteq C \subseteq P_{\text{outer}}$ . Draw a picture illustrating this.

Let  $x \in P_{\text{inner}}$ . Since C is closed, the points  $x_1, \ldots, x_K \in C$ . And since x is a convex combination of points in C, which is a convex set, we have  $x \in C$ . Thus,  $P_{\text{inner}} \subseteq C$ .

Now let  $x \in C$ . Then for each of the defined supporting hyperplanes of C, we have  $a_i^T(x-x_i) \leq 0$ , which is precisely the condition for  $P_{\text{outer}}$ , so  $x \in P_{\text{outer}}$ . Thus  $C \subseteq P_{\text{outer}}$ .