

aml_lfd.lqr.lqr_traj
_follow.LQRTrajFollow

- + idx
- + H
- + target_traj
- + model
- + reward
- + num_states
- + num_ctrls
- + num_links
- + robot
- + A
- + B
- + Q
- + Qf
- + R
- + Rf
- + Alist
- + Blist
- + Qlist
- + Rlist
- + Klist
- + target_xlist
- + target_ulist
- + dxlist
- + xlist
- + ulist

- + __init__()
- + configure()
- + compute_dx()
- + err_simulate()
- + compose_dx()
- + simulate_f()
- + linearized_dynamics()
- + lqr()
- + dlqr()
- + find_feedback_gains()