```
object
aml robot.bullet.bullet
     robot.BulletRobot
+ ___init___()
+ configure_default_pos()
+ configure_camera()
+ get_image()
+ get_ee_pose()
+ get_pos_ori()
+ get_contact_points()
+ set_default_pos_ori()
+ set_pos_ori()
+ get_jnt_state()
```

+ set_jnt_state() + apply_external_force() + apply_external_torque()