aml_ctrl.classical_controllers.MinJerkController

+ left_arm
+ right_arm
+ start_pos
+ goal_pos
+ start_qt
+ goal_qt
+ tau
+ dt
+ timesteps
+ osc_pos_threshold

+ __init__()
+ configure()
+ get_arm_handle()
+ set_neutral()
+ tuck_arms()
+ untuck_arms()
+ standard_shape_traj()
+ get_min_jerk_trajectory()
+ osc_position_cmd()
+ osc_torque_cmd()
+ relative_jac()
+ osc_torque_cmd_2()
+ plot_min_jerk_traj()