**camera_calib.Baxter
_Eye_Hand_Calib**

+ left_arm
+ right_arm
+ aruco_pose
+ aruco_pose2
+ aruco_pose3
+ pose_data_filled
+ pose2_data_filled
+ pose_pos
+ pose_ori
+ pose2_pos
+ pose2_ori
+ tf
+ br

+ __init__()
+ broadcast_frame()
+ aruco_pose_callback()
+ aruco_pose2_callback()
+ aruco_pose3_callback()
+ save_calib_data()
+ load_calib_data()
+ self_calibrate()
+ get_box_transform()