# Quadratic equations

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### COMP9021 Principles of Programming

## [1]: from math import sqrt

A quadratic equation is determined by three real numbers a, b and c with  $a \neq 0$ . Depending on whether  $\Delta = \frac{-b}{2a}$  is strictly negative, equal to 0 or strictly positive, the equation has no real root, a single real root or two distinct real roots, respectively. We want to be able to:

- create a quadratic equation with specific values for a, b and c;
- modify a given quadratic equation by changing the value of any of a, b and c, possibly two of them, possibly all of them;
- nicely display a given quadratic equation;
- automatically compute the root or roots of a given quadratic equation, if a unique root or two
  distinct roots exist, respectively, when the equation is created, and whenever the equation is
  modified.

We will go through 5 successive designs via gradual modifications, the first design being satisfactory from a functional point of view, the last one satisfactory from an object oriented point of view. Going through this exercise will provide us with a deep understanding of object oriented design and syntax.

To create a quadratic equation, it is sensible to define a function that provides the default values of 1 for a and 0 for b and c (so making  $x^2 = 1$  the default quadratic equation). Some or all of those default values can then be changed using keyword arguments, in any order:

```
[2]: def f(a=1, b=0, c=0):
    print(a, b, c)

f()
    f(a=2)
    f(c=4)
    f(a=2, c=4)
    f(c=4, b=3)
    f(b=3, a=2, c=4)
```

- 1 0 0
- 2 0 0
- 1 0 4
- 2 0 4
- 1 3 4
- 2 3 4

The user can also provide positional arguments, to overwrite the default value of the first argument, or to overwrite the default values of the first and second arguments, or to overwrite the values of the first, second and third arguments:

```
[3]: f(2)
f(2, 3)
f(2, 3, 4)
```

2 3 0

2 3 4

In particular, when the user provides three positional arguments, we expect him to know that they are provided in the order a, b and c. Even if the function is well documented, it is reasonable not to have such an expectation, and force the user to explictly name each value. The \* symbol can be used on its own for that purpose. With the version of f() that follows, only the values of a and b can be overwritten with positional arguments:

```
[4]: def f(a=1, b=0, *, c=0):
         print(a, b, c)
     f(2)
     f(2, 3)
     f(2, 3, c=4)
     f(2, c=4, b=3)
     f(b=3, a=2, c=4)
     f(2, 3, 4)
    2 0 0
    2 3 0
    2 3 4
    2 3 4
    2 3 4
            TypeError
                                                        Traceback (most recent call
     →last)
            <ipython-input-4-423868e7af4f> in <module>
              7 f(2, c=4, b=3)
              8 f(b=3, a=2, c=4)
        ---> 9 f(2, 3, 4)
```

TypeError: f() takes from 0 to 2 positional arguments but 3 were given

With the version of f() that follows, only the value of a can be overwritten with a positional argument:

```
[5]: def f(a=1, *, b=0, c=0):
         print(a, b, c)
     f(2)
     f(2, b=3)
     f(2, c=4, b=3)
     f(b=3, a=2, c=4)
     f(2, 3)
    2 0 0
    2 3 0
    2 3 4
    2 3 4
            TypeError
                                                       Traceback (most recent call
     →last)
            <ipython-input-5-971756ca1ed0> in <module>
              6 f(2, c=4, b=3)
              7 f(b=3, a=2, c=4)
        ---> 8 f(2, 3)
```

TypeError: f() takes from 0 to 1 positional arguments but 2 were given

With the version of f() that follows, no value can be overwritten with a positional argument:

```
[6]: def f(*, a=1, b=0, c=0):
    print(a, b, c)

f(b=3)
f(c=4, b=3)
f(b=3, a=2, c=4)
f(2)

1 3 0
1 3 4
2 3 4
```

```
TypeError Traceback (most recent callulast)  \begin{array}{l} \text{<ipython-input-6-7560eec60b10> in < module>} \\ & 5 \text{ f(c=4, b=3)} \\ & 6 \text{ f(b=3, a=2, c=4)} \\ & ----> 7 \text{ f(2)} \end{array}
```

TypeError: f() takes 0 positional arguments but 1 was given

The function initialise() below is meant to create a quadratic equation represented as a dictionary with 5 keys, to keep track of the values of a, b and c, but also of the values of the roots, computed by the function compute\_roots() as soon as the former are known. We might think that create() would be a better name; we will soon understand why we opted for initialise():

```
[7]: def initialise(*, a=1, b=0, c=0):
         if a == 0:
             print('a cannot be equal to 0.')
         equation = {'a': a, 'b': b, 'c': c, 'root_1': None, 'root_2': None}
         compute_roots(equation)
         return equation
     def compute_roots(equation):
         a, b, c = equation['a'], equation['b'], equation['c']
         delta = b ** 2 - 4 * a * c
         if delta < 0:</pre>
             equation['root_1'] = equation['root_2'] = None
         elif delta == 0:
             equation['root_1'] = -b / (2 * a)
             equation['root_2'] = None
         else:
             sqrt_delta = sqrt(delta)
             equation['root_1'] = (-b - sqrt_delta) / (2 * a)
             equation['root_2'] = (-b + sqrt_delta) / (2 * a)
```

```
[8]: initialise(a=0, b=1)
```

a cannot be equal to 0.

```
[9]: eq1 = initialise()

eq1['a']
eq1['b']
eq1['c']
```

```
eq1['root_1']
      eq1['root_2'] # None
 [9]: 1
 [9]: 0
 [9]: 0
 [9]: 0.0
[10]: eq2 = initialise(b=4)
      eq2['a']
      eq2['b']
      eq2['c']
      eq2['root_1']
      eq2['root_2']
[10]: 1
[10]: 4
[10]: 0
[10]: -4.0
[10]: 0.0
```

The function that follows allows one to change any number of parameters, that again have to be named even in case the change affects all of them;  $compute_roots()$  recomputes the roots as soon as the possibly new values of a, b and c are known:

```
[11]: def update(equation, *, a=None, b=None, c=None):
    if a == 0:
        print('a cannot be equal to 0.')
        return

if a is not None:
        equation['a'] = a

if b is not None:
        equation['b'] = b

if c is not None:
        equation['c'] = c

compute_roots(equation)
```

```
[12]: eq3 = initialise(a=1, b=3, c=2)
eq3['a']
eq3['b']
```

```
eq3['c']
      eq3['root_1']
      eq3['root_2']
      print()
      update(eq3, a=0)
      print()
      update(eq3, b=-1)
      eq3['a']
      eq3['b']
      eq3['c']
      eq3['root_1'] # None
      eq3['root_2'] # None
      print()
      update(eq3, c=0.3, a=0.5)
      eq3['a']
      eq3['b']
      eq3['c']
      eq3['root_1']
      eq3['root_2']
[12]: 1
[12]: 3
[12]: 2
[12]: -2.0
[12]: -1.0
     a cannot be equal to 0.
[12]: 1
[12]: -1
[12]: 2
[12]: 0.5
```

```
[12]: -1
```

[12]: 0.3

[12]: 0.3675444679663241

[12]: 1.632455532033676

To nicely display an equation, we have to carefully deal with the cases where where a is equal to 1 or -1, b is equal to 1 or -1 or otherwise strictly positive or strictly negative, and c is strictly positive or strictly negative:

```
[13]: def display(equation):
          a, b, c = equation['a'], equation['b'], equation['c']
              displayed_equation = 'x^2'
          elif a == -1:
              displayed_equation = '-x^2'
          else:
              displayed_equation = f'{a}x^2'
          if b == 1:
              displayed_equation += ' + x'
          elif b == -1:
              displayed_equation -= ' - x'
          elif b > 0:
              displayed_equation += f' + {b}x'
          elif b < 0:
              displayed_equation += f'- {-b}x'
          if c > 0:
              displayed_equation += f' + {c}'
          elif c < 0:
              displayed_equation += f' - {-c}'
          print(displayed_equation, 0, sep=' = ')
```

```
[14]: display(initialise())
display(initialise(c=-5, a=2))
display(initialise(b=1, a=-1, c=-1))
```

```
x^2 = 0

2x^2 - 5 = 0

-x^2 + x - 1 = 0
```

That ends the first design. For the second design, we package the functionality associated with quadratic equations; a dictionary offers a simple way to do so. The dictionary QuadraticEquationDict below captures the view that a quadratic equation is an entity that can be created (initialised), displayed, modified (updated) and has roots that can be computed. All of the dictionary's values are functions; they have been previously defined, but two of them are given a slightly different implementation, reflecting the fact that the four functions are now part of the

QuadraticEquationDict "package":

```
[15]: def initialise_variant_1(*, a=1, b=0, c=0):
          if a == 0:
              print('a cannot be equal to 0.')
          equation = {'a': a, 'b': b, 'c': c, 'root_1': None, 'root_2': None}
          QuadraticEquationDict['compute_roots'](equation)
          return equation
      def update_variant_1(equation, *, a=None, b=None, c=None):
          if a == 0:
              print('a cannot be equal to 0.')
              return
          if a is not None:
              equation['a'] = a
          if b is not None:
              equation['b'] = b
          if c is not None:
              equation['c'] = c
          QuadraticEquationDict['compute_roots'](equation)
      QuadraticEquationDict = {'initialise': initialise_variant_1,
                               'display': display,
                               'compute_roots': compute_roots,
                               'update': update_variant_1
                              }
```

The code that tests all four functions is similarly changed and relative to the QuadraticEquationDict "package":

```
[16]: QuadraticEquationDict['initialise'](a=0, b=1)
```

a cannot be equal to 0.

```
[17]: eq1 = QuadraticEquationDict['initialise']()

        eq1['a']
        eq1['b']
        eq1['c']
        eq1['root_1']
        eq1['root_2'] # None
```

[17]: 1

[17]: 0

[17]: 0

```
[17]: 0.0
[18]: eq2 = QuadraticEquationDict['initialise'](b=4)
      eq2['a']
      eq2['b']
      eq2['c']
      eq2['root_1']
      eq2['root_2']
[18]: 1
[18]: 4
[18]: 0
[18]: -4.0
[18]: 0.0
[19]: eq3 = QuadraticEquationDict['initialise'](a=1, b=3, c=2)
      eq3['a']
      eq3['b']
      eq3['c']
      eq3['root_1']
      eq3['root_2']
      print()
      QuadraticEquationDict['update'](eq3, a=0)
      print()
      update(eq3, b=-1)
      eq3['a']
      eq3['b']
      eq3['c']
      eq3['root_1'] # None
      eq3['root_2'] # None
      print()
      QuadraticEquationDict['update'](eq3, c=0.3, a=0.5)
      eq3['a']
      eq3['b']
      eq3['c']
      eq3['root_1']
      eq3['root_2']
```

```
[19]: 1
[19]: 3
[19]: 2
[19]: -2.0
[19]: -1.0
     a cannot be equal to 0.
[19]: 1
[19]: -1
[19]: 2
[19]: 0.5
[19]: -1
[19]: 0.3
[19]: 0.3675444679663241
[19]: 1.632455532033676
[20]: QuadraticEquationDict['display'](QuadraticEquationDict['initialise']())
      QuadraticEquationDict['display'](QuadraticEquationDict['initialise'](c=-5, a=2)
      QuadraticEquationDict['display'](QuadraticEquationDict['initialise'](b=1, a=-1,
                                                                               c = -1
                                                                              )
                                        )
     x^2 = 0
     2x^2 - 5 = 0
     -x^2 + x - 1 = 0
     With the third design, we meet the object oriented paradigm. All four functions are implemented
     slightly differently:
[21]: def initialise_variant_2(equation, *, a=1, b=0, c=0):
```

**if** a == 0:

```
print('a cannot be equal to 0.')
        return
    equation.a = a
    equation.b = b
    equation.c = c
    QuadraticEquationType.compute_roots(equation)
def display_variant_1(equation):
    a, b, c = equation.a, equation.b, equation.c
    if a == 1:
        displayed_equation = 'x^2'
    elif a == -1:
        displayed_equation = '-x^2'
    else:
        displayed_equation = f'{a}x^2'
    if b == 1:
        displayed_equation += ' + x'
    elif b == -1:
        displayed_equation -= ' - x'
    elif b > 0:
        displayed_equation += f' + {b}x'
    elif b < 0:
        displayed_equation += f' - \{-b\}x'
    if c > 0:
        displayed_equation += f' + {c}'
    elif c < 0:
        displayed_equation += f' - {-c}'
    print(displayed_equation, 0, sep=' = ')
def compute_roots_variant_2(equation):
    a, b, c = equation.a, equation.b, equation.c
    delta = b ** 2 - 4 * a * c
    if delta < 0:</pre>
        equation.root_1 = equation.root_2 = None
    elif delta == 0:
        equation.root_1 = -b / (2 * a)
        equation.root_2 = None
    else:
        sqrt_delta = sqrt(delta)
        equation.root_1 = (-b - sqrt_delta) / (2 * a)
        equation.root_2 = (-b + sqrt_delta) / (2 * a)
def update_variant_2(equation, *, a=None, b=None, c=None):
    if a == 0:
        print('a cannot be equal to 0.')
        return
    if a is not None:
```

QuadraticEquationType seems to embed QuadraticEquationDict, with 'initialise' changed to '\_\_init\_\_'; 'initialise' was an arbitrary name, whereas '\_\_init\_\_' is imposed. With 'initialise', we chose a name close enough to '\_\_init\_\_' so as to reflect the similarity of the implementations. QuadraticEquationType is a type, with the name 'QuadraticEquationType', above provided as first argument to type(); another use of type() below shows that QuadraticEquationType is indeed a type:

```
[22]: type(QuadraticEquationType)
QuadraticEquationType.__name__
```

[22]: type

[22]: 'QuadraticEquationType'

The second argument to type() is an empty tuple, making QuadraticEquationType a direct subtype of object, the mother of all types:

```
[23]: QuadraticEquationType.__base__
```

[23]: object

The third argument to type() is a dictionary of attributes, that are all members of \_\_dict\_\_, which itself is another attribute of QuadraticEquationType:

```
'__module__': '__main__',
                    '__dict__': <attribute '__dict__' of 'QuadraticEquationType'
      objects>,
                    '__weakref__': <attribute '__weakref__' of 'QuadraticEquationType'
      objects>,
                    '__doc__': None})
     object also has a __dict__ attribute:
[25]: object.__dict__
[25]: mappingproxy({'__repr__': <slot wrapper '__repr__' of 'object' objects>,
                     __hash__': <slot wrapper '__hash__' of 'object' objects>,
                     __str__': <slot wrapper '__str__' of 'object' objects>,
                    '__getattribute__': <slot wrapper '__getattribute__' of 'object'
      objects>,
                    '__setattr__': <slot wrapper '__setattr__' of 'object' objects>,
                    '__delattr__': <slot wrapper '__delattr__' of 'object' objects>,
                     __lt__': <slot wrapper '__lt__' of 'object' objects>,
                    '__le__': <slot wrapper '__le__' of 'object' objects>,
                     __eq__': <slot wrapper '__eq__' of 'object' objects>,
                    '__ne__': <slot wrapper '__ne__' of 'object' objects>,
                    '__gt__': <slot wrapper '__gt__' of 'object' objects>,
                    '__ge__': <slot wrapper '__ge__' of 'object' objects>,
                    '__init__': <slot wrapper '__init__' of 'object' objects>,
                    '__new__': <function object.__new__(*args, **kwargs)>,
                    '__reduce_ex__': <method '__reduce_ex__' of 'object' objects>,
                     __reduce__': <method '__reduce__' of 'object' objects>,
                    '__subclasshook__': <method '__subclasshook__' of 'object'
      objects>,
                    '__init_subclass__': <method '__init_subclass__' of 'object'
      objects>,
                    '__format__': <method '__format__' of 'object' objects>,
                    '__sizeof__': <method '__sizeof__' of 'object' objects>,
                    '__dir__': <method '__dir__' of 'object' objects>,
                    '__class__': <attribute '__class__' of 'object' objects>,
                    '\_doc\_\_': 'The base class of the class hierarchy.\n\nWhen called,
      it accepts no arguments and returns a new featureless\ninstance that has no
      instance attributes and cannot be given any.\n'})
```

The dir() function returns a list of attributes of its argument; with object as argument, that list consists of nothing but the attributes in object.\_\_dict\_\_:

```
[26]: dir(object)
set(object.__dict__) == set(dir(object))
```

```
[26]: ['__class__',
       '__delattr__',
       '__dir__',
        __doc__',
       '__eq__',
       '__format__',
       '__ge__',
       '__getattribute__',
       '__gt__',
       '__hash__',
       '__init__',
       '__init_subclass__',
       '__le__',
       '__lt__',
       '__ne__',
       '__new__',
       '__reduce__',
       '__reduce_ex__',
       '__repr__',
       '__setattr__',
       '__sizeof__',
       '__str__',
       '__subclasshook__']
```

### [26]: True

With QuadraticEquationType as argument, dir() returns a list of attributes that consists precisely of the attributes in object.\_\_dict\_\_ (or equivalently, the attributes in dir(object)), all inherited by QuadraticEquationType, and the attributes in QuadraticEquationType.\_\_dict\_\_:

```
'__init_subclass__',
'__le__',
'__lt__',
'__module__',
'__ne__',
'__new__',
 __reduce__',
'__reduce_ex__',
'__repr__',
'__setattr__',
'__sizeof__',
'__str__',
'__subclasshook__',
'__weakref__',
'compute_roots',
'display',
'update']
```

### [27]: True

Two attributes belong to both object.\_\_dict\_\_ and QuadraticEquationType.\_\_dict\_\_; they are attributes of object inherited by QuadraticEquationType, but also **overwritten** by QuadraticEquationType:

```
[28]: set(dir(object)) & set(QuadraticEquationType.__dict__)
object.__doc__
QuadraticEquationType.__doc__ # None
object.__init__
QuadraticEquationType.__init__
```

- [28]: {'\_\_doc\_\_', '\_\_init\_\_'}
- [28]: 'The base class of the class hierarchy.\n\m\men called, it accepts no arguments and returns a new featureless\ninstance that has no instance attributes and cannot be given any.\n'
- [28]: <slot wrapper '\_\_init\_\_' of 'object' objects>
- [28]: <function \_\_main\_\_.initialise\_variant\_2(equation, \*, a=1, b=0, c=0)>

With the syntax QuadraticEquationType.compute\_roots, we are trying to access the 'compute\_roots' attribute of QuadraticEquationType, which is equivalent to retrieving the value of the 'compute\_roots' key of the '\_\_dict\_\_' attribute of QuadraticEquationType (this raises the question of how '\_\_dict\_\_' itself is retrieved...):

```
[29]: QuadraticEquationType.compute_roots
QuadraticEquationType.__dict__['compute_roots']
```

```
[29]: <function __main__.compute_roots_variant_2(equation)>
```

[29]: <function \_\_main\_\_.compute\_roots\_variant\_2(equation)>

The key difference between initialise\_variant\_1() and initialise\_variant\_2() is that the latter has an extra argument, equation, and returns None, whereas the former returns a dictionary that is the counterpart to equation. What value is assigned to equation; what provides it? One of QuadraticEquationType's attributes is '\_\_new\_\_', which we know is inherited from and not overwritten by object:

```
[30]: QuadraticEquationType.__new__
QuadraticEquationType.__new__ is object.__new__
```

- [30]: <function object.\_\_new\_\_(\*args, \*\*kwargs)>
- [30]: True

When called with QuadraticEquationType as argument, the function that QuadraticEquationType.\_\_new\_\_, or equivalently, object.\_\_new\_\_, evaluates to, returns an object (not to be confused with object) of type QuadraticEquationType:

```
[31]: QuadraticEquationType.__new__(QuadraticEquationType)
type(QuadraticEquationType.__new__(QuadraticEquationType))
```

- [31]: <\_\_main\_\_.QuadraticEquationType at 0x1106627f0>
- [31]: \_\_main\_\_.QuadraticEquationType

The object returned by QuadraticEquationType.\_\_new\_\_(QuadraticEquationType) can then be passed as an argument to initialise\_variant\_2(), the function that QuadraticEquationType.\_\_init\_\_ evaluates to:

```
[32]: eq = QuadraticEquationType.__new__(QuadraticEquationType)

QuadraticEquationType.__init__(eq, a=0, b=1)
```

a cannot be equal to 0.

The object returned by QuadraticEquationType.\_\_new\_\_(QuadraticEquationType) has a \_\_dict\_\_ attribute, that happens to be empty; the dir() function returns the same list of attributes when it is given either the object or QuadraticEquationType as argument, reflecting the fact that the object inherits all those attributes from QuadraticEquationType:

```
[33]: eq1 = QuadraticEquationType.__new__(QuadraticEquationType)
eq1.__dict__
dir(eq1) == dir(QuadraticEquationType)
```

[33]: {}

#### [33]: True

[34]: QuadraticEquationType.\_\_init\_\_(eq1)

A call to QuadraticEquationType.\_\_init\_\_() provides eq1 with new attributes, which are now in eq1.\_\_dict\_\_ and also part of dir(eq\_1). With the syntax eq1.a, eq1.b, eq1.c, eq1.root\_1 and eq1.root\_2, we are trying to access the 'a', 'b', 'c', 'root\_1' and 'root\_2' attributes of eq1, which is equivalent to retrieving the values of the 'a', 'b', 'c', 'root\_1' and 'root\_2' keys of the '\_\_dict\_\_' attribute of eq1 (this again raises the question of how '\_\_dict\_\_' itself is retrieved):

```
eq1.__dict__
      set(dir(eq1)) - set(dir(QuadraticEquationType))
      eq1.__dict__['a']
      eq1.a
      eq1.__dict__['b']
      eq1.b
      eq1.__dict__['c']
      eq1.c
      eq1.__dict__['root_1']
      eq1.root_1
      eq1.__dict__['root_2'] # None
      eq1.root_2 # None
[34]: {'a': 1, 'b': 0, 'c': 0, 'root_1': 0.0, 'root_2': None}
[34]: {'a', 'b', 'c', 'root_1', 'root_2'}
[34]: 1
[34]: 1
[34]: 0
[34]: 0
[34]: 0
[34]: 0
[34]: 0.0
[34]: 0.0
```

We now understand what value initialise\_variant\_2()'s first argument, equation, receives, and what provides it, but in practice, we do not explicitly call first QuadraticEquationType.\_\_new\_\_() and then QuadraticEquationType.\_\_init\_\_(); instead, we use the following syntax, that in one sweep move, both creates an object and initialises it:

```
[35]: eq2 = QuadraticEquationType(b=4)
      eq2.a
      eq2.b
      eq2.c
      eq2.root_1
      eq2.root_2
[35]: 1
[35]: 4
[35]: 0
[35]: -4.0
[35]: 0.0
     compute_roots, update and display are attributes of both QuadraticEquationType and of ob-
     jects returned by QuadraticEquationType.__new__(QuadraticEquationType), but they evaluate
     to different entities:
[36]: QuadraticEquationType.compute_roots
      QuadraticEquationType. new (QuadraticEquationType).compute_roots
      print()
      QuadraticEquationType.update
      QuadraticEquationType.__new__(QuadraticEquationType).update
      print()
      QuadraticEquationType.display
      QuadraticEquationType.__new__(QuadraticEquationType).display
      eq = QuadraticEquationType.__new__(QuadraticEquationType)
[36]: <function __main__.compute_roots_variant_2(equation)>
[36]: <bound method compute_roots_variant_2 of <__main__.QuadraticEquationType object
      at 0x110662e80>>
[36]: <function __main__.update_variant_2(equation, *, a=None, b=None, c=None)>
[36]: <bound method update_variant_2 of <__main__.QuadraticEquationType object at
      0x10e5747f0>>
```

```
[36]: <function __main__.display_variant_1(equation)>
```

[36]: <bound method display\_variant\_1 of <\_\_main\_\_.QuadraticEquationType object at 0x110662d90>>

These **bound methods** essentially allow one to call <code>compute\_roots\_variant\_2()</code>, update\_variant\_2() and <code>display\_variant\_1()</code> using 'compute\_roots', 'update' and 'display' as object attributes rather than <code>QuadraticEquationType</code> attributes, providing the desired value as first argument. More precisely, one can think of the bound method M of an object o of type <code>QuadraticEquationType</code> as a pair:

- the first member of the pair is a QuadraticEquationType function f, meant to take an object of type QuadraticEquationType as first (and possibly unique) argument;
- the second member of the pair is o, meant to be that first argument.

Having both f and o in hand together with any other arguments for f, if any, f can then be called with o provided as first argument. This can done either as QuadraticEquationType.variable\_referring\_to\_f(variable\_referring\_to\_o, possibly followed by extra arguments), or as variable\_referring\_to\_o.variable\_referring\_to\_f(possibly, extra arguments). This alternative syntax is more compact and the one used in practice:

```
[37]: eq3 = QuadraticEquationType(a=1, b=3, c=2)
      eq3.a
      eq3.b
      eq3.c
      eq3.root_1
      eq3.root_2
      print()
      # update() called as a QuadraticEquationType function
      QuadraticEquationType.update(eq3, a=0)
      print()
      # update() called as a QuadraticEquationType function
      QuadraticEquationType.update(eq3, b=-1)
      eq3.a
      eq3.b
      eq3.c
      eq3.root_1 # None
      eq3.root_2 # None
      print()
      # update() called as an eq3 bound method
      eq3.update(c=0.3, a=0.5)
      eq3.a
      eq3.b
      eq3.c
```

```
eq3.root_1
      eq3.root_2
[37]: 1
[37]: 3
[37]: 2
[37]: -2.0
[37]: -1.0
     a cannot be equal to 0.
[37]: 1
[37]: -1
[37]: 2
[37]: 0.5
[37]: -1
[37]: 0.3
[37]: 0.3675444679663241
[37]: 1.632455532033676
[38]: # display() called as a QuadraticEquationType function
      QuadraticEquationType.display(QuadraticEquationType())
      # display() called as a QuadraticEquationType function
      QuadraticEquationType.display(QuadraticEquationType(c=-5, a=2))
      # display() called as a bound method of the object
      # returned by QuadraticEquationType()
      QuadraticEquationType(c=-5, a=2).display()
     x^2 = 0
     2x^2 - 5 = 0
     2x^2 - 5 = 0
```

The fourth design is essentially nothing but a syntactic variant on the third design, with class followed by the first argument to type() (that we change to QuadraticEquationClass), and with

the functions that are the values of the dictionary provided as third argument to type() now in the body of the class statement. Also, display is renamed \_\_str\_\_, and whereas the former returns None and executes print() statements, the latter returns a string: when print() is given an object as argument, it calls the object's \_\_str\_\_() bound method and displays the returned string:

```
[39]: class QuadraticEquationClass:
          def __init__(equation, *, a=1, b=0, c=0):
              if a == 0:
                  print('a cannot be equal to 0.')
                  return
              equation.a = a
              equation.b = b
              equation.c = c
              equation.compute_roots()
          def __str__(equation):
              if equation.a == 1:
                  displayed_equation = 'x^2'
              elif equation.a == -1:
                  displayed_equation = '-x^2'
              else:
                  displayed_equation = f'{equation.a}x^2'
              if equation.b == 1:
                  displayed equation += ' + x'
              elif equation.b == -1:
                  displayed_equation -= ' - x'
              elif equation.b > 0:
                  displayed_equation += f' + {equation.b}x'
              elif equation.b < 0:</pre>
                  displayed_equation += f'- {-equation.b}x'
              if equation.c > 0:
                  displayed_equation += f' + {equation.c}'
              elif equation.c < 0:</pre>
                  displayed_equation += f' - {-equation.c}'
              return f'{displayed_equation} = 0'
          def compute_roots(equation):
              delta = equation.b ** 2 - 4 * equation.a * equation.c
              if delta < 0:</pre>
                  equation.root_1 = equation.root_2 = None
              elif delta == 0:
                  equation.root_1 = -equation.b / (2 * equation.a)
                  equation.root_2 = None
              else:
                  sqrt_delta = sqrt(delta)
                  equation.root_1 = (-equation.b - sqrt_delta) / (2 * equation.a)
                  equation.root_2 = (-equation.b + sqrt_delta) / (2 * equation.a)
```

```
def update(equation, *, a=None, b=None, c=None):
    if a == 0:
        print('a cannot be equal to 0.')
        return

if a is not None:
        equation.a = a

if b is not None:
        equation.b = b

if c is not None:
        equation.c = c
        equation.compute_roots()
```

The syntax for object creation and initialisation and for calls to compute\_roots() and update() is the same as with the third design:

```
[40]: QuadraticEquationClass(a=0, b=1)
      print()
      eq1 = QuadraticEquationClass.__new__(QuadraticEquationClass)
      QuadraticEquationClass.__init__(eq1)
      eq1.a
      eq1.b
      eq1.c
      eq1.root_1
      eq1.root_2
      print()
      eq2 = QuadraticEquationClass.__new__(QuadraticEquationClass)
      eq2.__init__(b=4)
      eq2.a
      eq2.b
      eq2.c
      eq2.root_1
      eq2.root_2
      print()
      eq3 = QuadraticEquationClass(a=1, b=3, c=2)
      eq3.a
      eq3.b
      eq3.c
      eq3.root_1
      eq3.root_2
```

```
print()
eq3.update(a=0)
print()
QuadraticEquationClass.update(eq3, b=-1)
eq3.a
eq3.b
eq3.c
eq3.root_1
eq3.root_2
print()
eq3.update(c=0.3, a=0.5)
eq3.a
eq3.b
eq3.c
eq3.root_1
eq3.root_2
```

a cannot be equal to 0.

[40]: <\_\_main\_\_.QuadraticEquationClass at 0x10e594370>

[40]: 1

[40]: 0

[40]: 0

[40]: 0.0

[40]: 1

[40]: 4

[40]: 0

[40]: -4.0

[40]: 0.0

```
[40]: 1
[40]: 3
[40]: 2
[40]: -2.0
[40]: -1.0
     a cannot be equal to 0.
[40]: 1
[40]: -1
[40]: 2
[40]: 0.5
[40]: -1
[40]: 0.3
[40]: 0.3675444679663241
[40]: 1.632455532033676
     As previously mentioned, we now display quadratic equations not with calls to display(), but
     with calls directly to print() that behind the scene, calls __str()__:
[41]: print(QuadraticEquationClass())
      print(QuadraticEquationClass(c=-5, a=2))
      print(QuadraticEquationClass(b=1, a=-1, c=-1))
     x^2 = 0
     2x^2 - 5 = 0
```

The fifth design "cleans" the fourth design, changing the first argument of the bound methods to self as always done in practice. Another special bound method, \_\_repr()\_\_, is overwritten: similarly to \_\_str()\_\_, it returns a string, and it is called when the executed statement is just the object name. It has a default implementation, but the output is not particularly insightful:

```
[42]: eq3
```

 $-x^2 + x - 1 = 0$ 

```
[42]: <__main__.QuadraticEquationClass at 0x10e594160>
```

It is standard practice to let \_\_repr()\_\_ output the very statement that creates the object, so for eq3, QuadraticEquationClass(a=1, b=3, c=2), as we will see below.

Finally, note that with the fourth design, QuadraticEquationClass (a=0, b=1) prints out an error message but still returns an ill defined object of type QuadraticEquationClass. It is preferable to raise an error instead. We define a specific exception by defining a class that derives from Exception rather than from object:

Putting things together, here is the final implementation, that abides by the principles of object oriented design in Python:

QuadraticEquationError: a cannot be equal to 0

```
[44]: class QuadraticEquation:
    def __init__(self, *, a=1, b=0, c=0):
        if a == 0:
            raise QuadraticEquationError('a cannot be equal to 0.')
        self.a = a
        self.b = b
        self.c = c
        self.compute_roots()

def __repr__(self):
    return f'QuadraticEquation(a={self.a}, b={self.b}, c={self.c})'
```

```
def __str__(self):
    if self.a == 1:
        displayed_equation = 'x^2'
    elif self.a == -1:
        displayed_equation = '-x^2'
    else:
        displayed_equation = f'{self.a}x^2'
    if self.b == 1:
        displayed equation += ' + x'
    elif self.b == -1:
        displayed_equation -= ' - x'
    elif self.b > 0:
        displayed_equation += f' + {self.b}x'
    elif self.b < 0:</pre>
        displayed_equation += f'- {-self.b}x'
    if self.c > 0:
        displayed_equation += f' + {self.c}'
    elif self.c < 0:</pre>
        displayed_equation += f' - {-self.c}'
    return f'{displayed_equation} = 0'
def compute_roots(self):
    delta = self.b ** 2 - 4 * self.a * self.c
    if delta < 0:</pre>
        self.root_1 = self.root_2 = None
    elif delta == 0:
        self.root_1 = -self.b / (2 * self.a)
        self.root 2 = None
    else:
        sqrt_delta = sqrt(delta)
        self.root_1 = (-self.b - sqrt_delta) / (2 * self.a)
        self.root_2 = (-self.b + sqrt_delta) / (2 * self.a)
def update(self, *, a=None, b=None, c=None):
    if a == 0:
        raise QuadraticEquationError('a cannot be equal to 0.')
    if a is not None:
        self.a = a
    if b is not None:
        self.b = b
    if c is not None:
        self.c = c
    self.compute_roots()
```

An error of type QuadraticEquationError is raised at object creation, or when incorrectly updating an existing object:

```
QuadraticEquationError
                                                   Traceback (most recent call_
     ناهجا ( Jast
            <ipython-input-45-e2cd2f4a7937> in <module>
        ----> 1 QuadraticEquation(a=0, b=1)
            <ipython-input-44-4922cafe3eb8> in __init__(self, a, b, c)
                   def __init__(self, *, a=1, b=0, c=0):
                       if a == 0:
              3
        ---> 4
                           raise QuadraticEquationError('a cannot be equal to 0.')
              5
                      self.a = a
                       self.b = b
            QuadraticEquationError: a cannot be equal to 0.
[46]: eq3 = QuadraticEquation(a=1, b=3, c=2)
     eq3.update(a=0)
      ______
            QuadraticEquationError
                                                   Traceback (most recent call_
     →last)
            <ipython-input-46-ad68ef251222> in <module>
              1 eq3 = QuadraticEquation(a=1, b=3, c=2)
        ---> 2 eq3.update(a=0)
            <ipython-input-44-4922cafe3eb8> in update(self, a, b, c)
                   def update(self, *, a=None, b=None, c=None):
                       if a == 0:
             47
        ---> 48
                           raise QuadraticEquationError('a cannot be equal to 0.')
             49
                       if a is not None:
             50
                          self.a = a
```

[45]: QuadraticEquation(a=0, b=1)

QuadraticEquationError: a cannot be equal to 0.

Otherwise, there is no difference with the 4th design when it comes to creating objects or calling methods:

```
[47]: eq1 = QuadraticEquation.__new__(QuadraticEquation)
      QuadraticEquation.__init__(eq1)
      eq1.a
      eq1.b
      eq1.c
      eq1.root_1
      eq1.root_2
      print()
      eq2 = QuadraticEquation.__new__(QuadraticEquation)
      eq2.__init__(b=4)
      eq2.a
      eq2.b
      eq2.c
      eq2.root_1
      eq2.root_2
      print()
      eq3 = QuadraticEquation(a=1, b=3, c=2)
      eq3.a
      eq3.b
      eq3.c
      eq3.root_1
      eq3.root_2
      QuadraticEquation.update(eq3, b=-1)
      eq3.a
      eq3.b
      eq3.c
      eq3.root_1
      eq3.root_2
      print()
      eq3.update(c=0.3, a=0.5)
      eq3.a
      eq3.b
      eq3.c
      eq3.root_1
      eq3.root_2
```

[47]: 1

[47]: 0

[47]: 0

[47]: 0.0

[47]: 1

[47]: 4

[47]: 0

[47]: -4.0

[47]: 0.0

[47]: 1

[47]: 3

[47]: 2

[47]: -2.0

[47]: -1.0

[47]: 1

[47]: -1

[47]: 2

[47]: 0.5

[47]: -1

[47]: 0.3

[47]: 0.3675444679663241

[47]: 1.632455532033676

Observe the difference between calling either <code>\_\_repr\_\_()</code> or <code>\_\_str\_\_()</code> behind the scene:

```
[48]: eq1 = QuadraticEquation()
    eq1
    print(eq1)

    eq2 = QuadraticEquation(c=-5, a=2)
    eq2
    print(eq2)

    eq3 = QuadraticEquation(b=1, a=-1, c=-1)
    eq3
    print(eq3)

[48]: QuadraticEquation(a=1, b=0, c=0)
    x^2 = 0

[48]: QuadraticEquation(a=2, b=0, c=-5)
    2x^2 - 5 = 0
```

[48]: QuadraticEquation(a=-1, b=1, c=-1)

 $-x^2 + x - 1 = 0$