

Direction-Free In-Air Signature Verification Using WIFI CSI Signal

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Abstract. The abstract should briefly summarize the contents of the paper in 15–250 words.

Keywords: First keyword · Second keyword · Another keyword.

1 Introduction

1.1 Motivation

i. Pros of In-Air WIFI CSI signature system 1) Cheap: Use commercial device 2) Easy: No additional devices is needed 3) Secure: Hard to forgery ii. Cons of In-Air WIFI CSI signature system 1) Setting direction problem a) Different direction -> Different feature is needed b) Hard to set exactly same direction as authentication before Size of signature can varies

1.2 Contribution

- Overcome cons of WIFI signature system - Robust to signal direction, size

2 Related Works

a. WIFI CSI b. Siamese Networks

2.1 WIFI CSI

- An In-Air Signature Verification System Using Wi-Fi Signals

CSI captures signal strength and phase information for OFDM subcarriers and between each pair of transmit-receive antennas. It runs on a commodity 802.11n NIC, and records Channel State Information (CSI) based on the 802.11 standard. The CSI contains information about the channel between sender and receiver at the level of individual data subcarriers, for each pair of transmit and receive antennas.

In a frequency domain, the CSI of sub-carrier \mathbf{c} between transmitter(Tx) and receiver(Rx) can be modeled as $R_c = \mathbf{H}_c T_c + N$ where the R_c and T_c denote the received and the transmitted signal vector of dimension r and t , respectively. The N is the additive channel noise and \mathbf{H}_c is the $r \times t$ channel matrix. The CSI of sub-carrier c can be modeled as follows:

$$h_c = |h_c| e^{j\theta}, \quad (1)$$

where $|h_c|$ and θ represent the amplitude and the phase of the sub-carrier, respectively.

2.2 Siamese Networks

- An In-Air Signature Verification System Using Wi-Fi Signals

3 Proposed System

In this section, we introduce a system for recognition of Wi-Fi based in-air signature which utilizes the Siamese network learning for validation. An overview of the proposed scheme is shown in Fig.1. The main purpose of this system is to receive two csi signals as input, to determine if the two signals are the same signature. Since signals may differ in the direction in which they are entered, our system must be capable of extracting non-direction-related characteristics from two signals.

3.1 Data Preprocessing

In order to be used as an input to a siamese network, the signal must be pre-processed.

First, the signal have to be converted to non-complex form. Since the Wi-Fi signature signals in CSI packets in 2.4Ghz has firmware issues in their phase[ref]. so we used absolute of signal only.

Second, all inputs must be arranged of same size. Since all signals have different length, the gradient operation with respect to the time instance is adopted to measure the short time energy. Data points with the highest short-time energy within the time period are regarded as the starting and the ending points of the in-air signature. And they are re-sampled uniformly based on Fast Fourier Transform (FFT) [16] to normalize the length of the data.

3.2 Siamese Network For Verification

Siamese nets were first introduced in the early 1990s by Bromley and LeCun to solve signature verification as an image matching problem (Bromley et al., 1993) Siamese neural networks employ a unique structure to naturally rank similarity between inputs. It can discriminate between the class-identity of image pairs

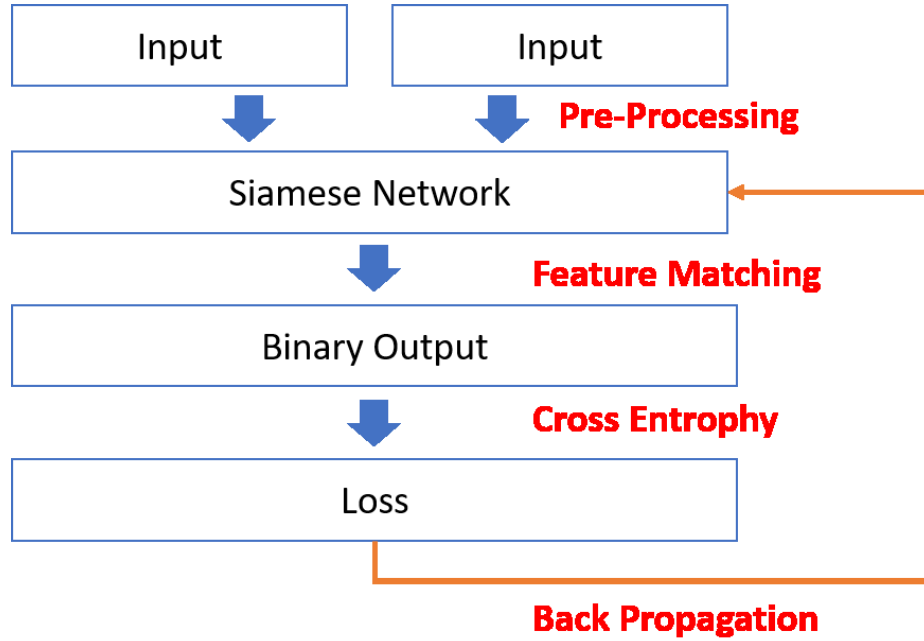


Fig. 1. ...

The verification model learns to identify input pairs according to the probability that they belong to the same class or different classes.[1]

The model receives two processed CSI signals as inputs, and outputs the probability that the two signals are of the same class as the output. The output of the Siamese network is 1 when the distance of the characteristic vector is close, and 0 when it is far. the network is learned by the back-propagation.

Two preprocessed signals enter the Siamese network and the network extracts non-directional characteristics from two signals and calculates how similar the two extracted characteristics are.

Even if a signal belongs to the same class, the shape of the input is very different if the signal is oriented differently. To classify regardless of the direction of the signal, the model shall be capable of extracting features unrelated to the direction.

Feature Extraction When two processed signals come as the input, they are put to 2 symmetric CNN network.

Purpose of CNN is to extract features from signal. By sharing their feature map, this CNN networks is trainin to learn characteristics regardless of the direction only.

To perform the feature extraction, we firstly need to have a convolutional neural networks to serve as the feature extractor Based on the ConvNet struc-

ture [17] the feature extractor of the proposed pretraining model consists of i convolution layers and activation functions followed by i max-pooling layers. Each convolution layer has $f*$ filters to be trained, where $*$ = 1, ..., i . In a similar manner, j fully connected layers constitute the classifier of pretraining model where each layer has $g \bullet$, (\bullet = 1, ..., j) neurons to be trained.

Some of the features CNN extracted are related to the shape of the signature, but CNN's features are not just those that helpful to classify signatures. some may be heavily influenced by the direction in which the signature was entered. We aim to classify the signature in a direction that is not related to the direction in which it was entered. This type of property interferes with the classification of signatures.

To focus on characteristics conducive to classification, The two CNN networks are arranged side by side symmetrically. It was also designed to have the same weight on the symmetrical CNN network as on a symmetrical CNN network.

Feature Matching Let $\mathbf{m} \in \mathbb{R}^{d \times 1}$ and $\mathbf{n} \in \mathbb{R}^{d \times 1}$ be feature vectors extracted from two samples. The L-1 distance between the two features can be calculated as follows: Where \mathbf{p} denotes the L-1 distance. In the Siamese networks, this L-1 distance is utilized to match between two feature vectors.

$$\mathbf{p} = \sigma\left(\sum_j \alpha_j \mid \mathbf{m}_{1,L-1}^{(j)} - \mathbf{n}_{1,L-1}^{(j)} \mid\right) \quad (2)$$

where σ is the sigmoidal activation function. This final layer induces a metric on the learned feature space of the $(L - 1)$ th hidden layer and scores the similarity between the two feature vectors. The α_j are additional parameters that are learned by the model during training, weighting the importance of the component-wise distance. This defines a final Lth fully-connected layer for the network which joins the two siamese twins.

Output of the CNN are feature vectors extracted from two samples. The Euclidean distance between the two features can be calculated. In the proposed system, this Euclidean distance is utilized to match between two feature vectors.

Loss and Backpropagation We impose a regularized cross-entropy objective on our binary classifier. This objective is combined with standard backpropagation algorithm, where the gradient is additive across the twin networks due to the tied weights. We initialized all network weights in the convolutional layers from a normal distribution with zero-mean and a standard deviation of 10^{-2} . Biases were also initialized from a normal distribution, but with mean 0.5 and standard deviation 10^{-2} .

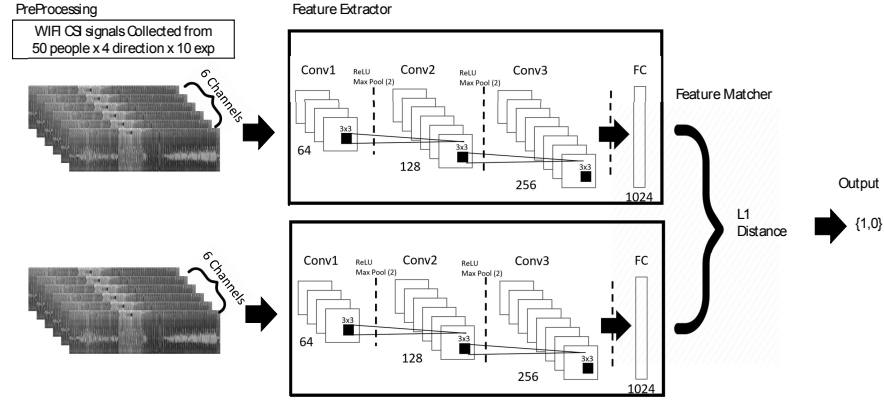


Fig. 2. ...

4 Experiments

5 Conclusion

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