



**Green University of Bangladesh**  
**Department of Computer Science and Engineering (CSE)**  
**Faculty of Sciences and Engineering**  
**Semester: (Summer, Year:2025), B.Sc. in CSE (Day)**

**Lab Report NO #2**  
**Course Title: Artificial Intelligent**  
**Course Code: CSE 316      Section: 221 D12**

**Lab Experiment Name: IDDFS**

**Student Details**

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**Submission Date : 09 MAY 2025**  
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**Lab Report Status**

**Marks: .....**  
**Comments:.....**

**Signature:.....**  
**Date:.....**

## **Title : IDDFS**

### **Objectives :**

#### **1. Maze Representation:**

- The maze is a 2D grid of integers.
- 0 represents an empty cell that can be traversed.
- 1 represents a wall that cannot be traversed.

#### **2. Movement Rules:**

- You can move in four directions: up, down, left, and right.
- You cannot revisit a cell in the same path exploration.
- You cannot pass through walls.

#### **3. Search Algorithm:**

- Use Iterative Deepening Depth-First Search (IDDFS):
  - A hybrid of DFS and BFS.
  - It performs depth-limited DFS repeatedly, increasing the depth limit with each iteration until the target is found or the maximum depth is reached.

### **Problem Analysis :**

IDDFS is a combination of:

- Depth-First Search (DFS) for memory efficiency.
- Breadth-First Search (BFS) in its iterative deepening approach (increasing depth limit).

For each depth limit  $d$ , the algorithm:

- Performs a DFS up to depth  $d$ .
- If the target is not found, it increases the depth and repeats.

### **Complexity Analysis**

Aspect	Complexity
Time (worst-case)	$O(b^d)$ where $b$ is the branching factor and $d$ is the depth of the target node. Repeated exploration makes it slower than BFS/DFS for small graphs.
Space	$O(d)$ because it uses DFS and stores only the current path, not the full tree like BFS.
Optimality	Not optimal — may not return the shortest path unless modified.
Completeness	Yes — it will find a path if one exists.

## Implementation :

```
def is_valid_move(x, y, maze, visited):
    rows, cols = len(maze), len(maze[0])
    return 0 <= x < rows and 0 <= y < cols and maze[x][y] == 0 and not visited[x][y]

def dfs_limited(maze, x, y, target, depth_limit, visited, path, traversal):
    if (x, y) == target:
        path.append((x, y))
        traversal.append((x, y))
        return True
    if depth_limit <= 0:
        return False

    visited[x][y] = True
    traversal.append((x, y))

    for dx, dy in [(-1,0), (1,0), (0,-1), (0,1)]:
        nx, ny = x + dx, y + dy
        if is_valid_move(nx, ny, maze, visited):
            if dfs_limited(maze, nx, ny, target, depth_limit - 1, visited, path, traversal):
                path.append((x, y))
                return True

    return False
```

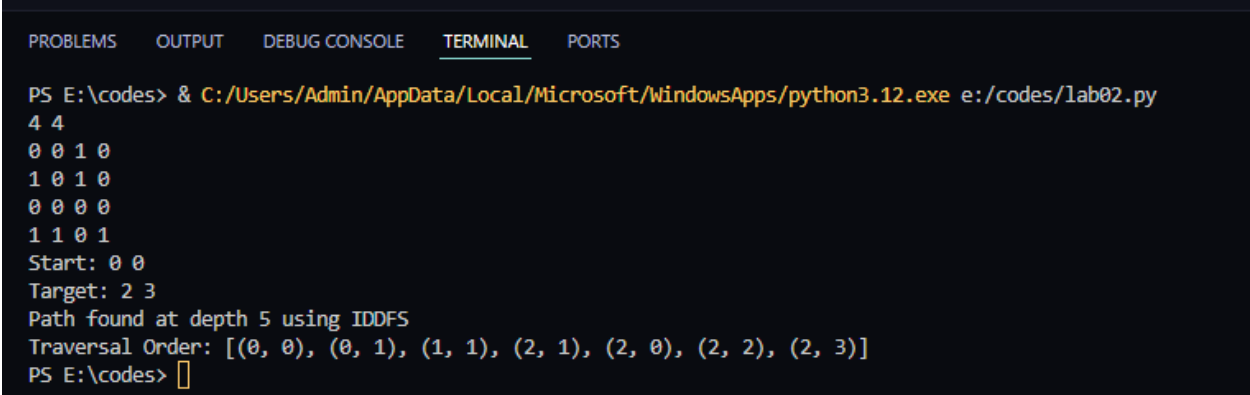
```

def iddfs(maze, start, target):
    max_depth = len(maze) * len(maze[0])
    for depth in range(max_depth):
        visited = [[False for _ in range(len(maze[0]))] for _ in range(len(maze))]
        path = []
        traversal = []
        if dfs_limited(maze, start[0], start[1], target, depth, visited, path, traversal):
            print(f"Path found at depth {depth} using IDDFS")
            print("Traversal Order:", traversal)
            return
    print("No path found using IDDFS")

# ---- Input Parsing ----
def parse_input():
    rows, cols = map(int, input().split())
    maze = []
    for _ in range(rows):
        maze.append(list(map(int, input().split())))
    start_x, start_y = map(int, input().split()[1:])
    target_x, target_y = map(int, input().split()[1:])
    return maze, (start_x, start_y), (target_x, target_y)
maze, start, target = parse_input()
iddfs(maze, start, target)

```

## Output :



```

PROBLEMS  OUTPUT  DEBUG CONSOLE  TERMINAL  PORTS

PS E:\codes> & C:/Users/Admin/AppData/Local/Microsoft/WindowsApps/python3.12.exe e:/codes/lab02.py
4 4
0 0 1 0
1 0 1 0
0 0 0 0
1 1 0 1
Start: 0 0
Target: 2 3
Path found at depth 5 using IDDFS
Traversal Order: [(0, 0), (0, 1), (1, 1), (2, 1), (2, 0), (2, 2), (2, 3)]
PS E:\codes>

```

## **Conclusion :**

The problem effectively demonstrates the application of **Iterative Deepening Depth-First Search (IDDFS)** to solve a maze pathfinding challenge. By combining the space-efficiency of DFS and the completeness of BFS, IDDFS ensures that a solution, if it exists, is eventually found. The approach is particularly useful for large search spaces with unknown solution depth. This method avoids memory-intensive structures like queues used in BFS and avoids infinite loops common in basic DFS. It explores nodes progressively by depth, ensuring thorough and organized traversal. Overall, IDDFS is a powerful technique for problems requiring exhaustive yet memory-efficient search strategies.

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