Lexical alignment: IBM models 1 and 2 MLE via EM for categorical distributions

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Translation data

Let's assume we are confronted with a new language and luckily we managed to obtain some sentence-aligned data

the black dog	□ *
the nice dog	
the black cat	⊡ ⊛
a dog chasing a cat	□⊲□

Translation data

Let's assume we are confronted with a new language and luckily we managed to obtain some sentence-aligned data

Is there anything we could say about this language?

the black dog $\square \otimes$ the nice dog $\square \cup$ the black cat $\square \otimes$ a dog chasing a cat $\square \triangleleft \square$

A few hypotheses:

▶ □ ⇐⇒ dog

the black dog the nice dog the black cat $\odot \$ a dog chasing a cat $\odot \$

- ▶ □ ⇐⇒ dog
- ▶ □ ⇐⇒ cat

the black dog the nice dog the black cat $\odot \$ a dog chasing a cat $\odot \$

- ▶ □ ⇐⇒ dog
- ▶ □ ←⇒ cat
- ▶ ⊛ ⇔ black

the black dog the nice dog the black cat $\odot \$ a dog chasing a cat $\odot \$

- ▶ □ ⇐⇒ dog
- ▶ □ ⇐⇒ cat
- ▶ (*) ⇔ black
- nouns seem to preceed adjectives

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- determines are probably not expressed

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- ▶ □ ⇐⇒ cat
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- chasing may be expressed by and perhaps this language is OVS

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- ▶ □ ⇐⇒ cat
- ▶ * ⇔ black
- nouns seem to preceed adjectives
- determines are probably not expressed
- chasing may be expressed by
 and perhaps this language is OVS
- or perhaps chasing is realised by a verb with swapped arguments

Probabilistic lexical alignment models

This lecture is about operationalising this intuition

- through a probabilistic learning algorithm
- ▶ for a non-probabilistic approach see for example [Lardilleux and Lepage, 2009]

Content

Lexical alignment

Mixture models

IBM model 1

IBM model 2

Remarks

Imagine you are given a text

the black dog o cão preto the nice dog the black cat o gato preto a dog chasing a cat um cão perseguindo um gato

Now imagine the French words were replaced by placeholders

the black dog	$F_1 F_2 F_3$
the nice dog	$F_1 F_2 F_3$
the black cat	$F_1 F_2 F_3$
dog chasing a cat	F_1 F_2 F_3 F_4 F_5

Now imagine the French words were replaced by placeholders

$$\begin{array}{c|cccc} \text{the black dog} & F_1 \ F_2 \ F_3 \\ \text{the nice dog} & F_1 \ F_2 \ F_3 \\ \text{the black cat} & F_1 \ F_2 \ F_3 \\ \text{a dog chasing a cat} & F_1 \ F_2 \ F_3 \ F_4 \ F_5 \end{array}$$

and suppose our task is to have a model explain the original data

Now imagine the French words were replaced by placeholders

$$\begin{array}{c|cccc} \text{the black dog} & F_1 \ F_2 \ F_3 \\ \text{the nice dog} & F_1 \ F_2 \ F_3 \\ \text{the black cat} & F_1 \ F_2 \ F_3 \\ \text{a dog chasing a cat} & F_1 \ F_2 \ F_3 \ F_4 \ F_5 \end{array}$$

and suppose our task is to have a model explain the original data by generating each French word from exactly one English word

Generative story

For each sentence pair independently,

- 1. observe an English sentence e_1, \dots, e_m and a French sentence length n
- 2. for each French word position j from 1 to n
 - 2.1 select an English position a_j
 - 2.2 conditioned on the English word e_{a_j} , generate f_j

Generative story

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- 1. observe an English sentence e_1, \dots, e_m and a French sentence length n
- 2. for each French word position j from 1 to n
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We have introduced an alignment which is not directly visible in the data

Observations:

the black dog | o cão preto

Imagine data is made of pairs: (a_j,f_j) and $e_{a_j} o f_j$

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the black dog o cão preto

Imagine data is made of pairs: (a_j,f_j) and $e_{a_j} o f_j$

the black dog $\mid (A_1, E_{A_1} \to F_1) \ (A_2, E_{A_2} \to F_2) \ (A_3, E_{A_3} \to F_3)$

Observations:

the black dog o cão preto

Imagine data is made of pairs: (a_j,f_j) and $e_{a_j} o f_j$

the black dog $| (1, E_{A_1} \to F_1) (A_2, E_{A_2} \to F_2) (A_3, E_{A_3} \to F_3)$

Observations:

Imagine data is made of pairs: (a_j, f_j) and $e_{a_j} o f_j$

the black dog
$$\mid (1, \text{the} \rightarrow \text{o}) \ (A_2, E_{A_2} \rightarrow F_2) \ (A_3, E_{A_3} \rightarrow F_3)$$

Observations:

the black dog o cão preto

Imagine data is made of pairs: (a_j,f_j) and $e_{a_j} o f_j$

the black dog \mid $(1, {\rm the} \to {\rm o}) \ (3, E_{A_2} \to F_2) \ (A_3, E_{A_3} \to F_3)$

Observations:

Imagine data is made of pairs: (a_j, f_j) and $e_{a_j} o f_j$

the black dog
$$\mid$$
 $(1, \text{the} \rightarrow \text{o}) \ (3, \text{dog} \rightarrow \text{cão}) \ (A_3, E_{A_3} \rightarrow F_3)$

Observations:

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the black dog
$$\mid$$
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Observations:

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Imagine data is made of pairs: (a_j, f_j) and $e_{a_j} o f_j$

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Observations:

Imagine data is made of pairs:
$$(a_j,f_j)$$
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Content

Lexical alignment

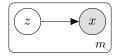
Mixture models

IBM model 1

IBM model 2

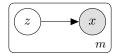
Remarks

Mixture models



- c mixture components
- lacktriangle each defines a distribution over the same data space ${\mathcal X}$
- plus a distribution over components themselves

Mixture models

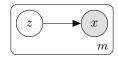


- c mixture components
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Generative story

- 1. select a mixture component $z \sim P(Z)$
- 2. generate an observation from it $x \sim P(X|Z=z)$

Mixture models



- c mixture components
- lacktriangle each defines a distribution over the same data space ${\mathcal X}$
- plus a distribution over components themselves

Marginal likelihood

$$P(x_1^m) = \prod_{\substack{i=1 \ m \ c}}^m \sum_{z=1}^c P(X = x_i, Z = z)$$
 (1)

$$= \prod_{i=1}^{m} \sum_{z=1}^{c} P(Z=z)P(X=x_i|Z=z)$$
 (2)

Interpretation

Missing data

- lackbox Let Z take one of c mixture components
- Assume data consists of pairs (x, z)
- x is always observed
- ightharpoonup y is always missing

Interpretation

Missing data

- ▶ Let Z take one of c mixture components
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- x is always observed
- y is always missing

Inference: posterior distribution over possible Z for each x

$$P(Z=z|X=x) = \frac{P(Z=z, X=x)}{\sum_{z'=1}^{c} P(Z=z', X=x)}$$
(3)

$$= \frac{P(Z=z)P(X=x|Z=z)}{\sum_{z'=1}^{c} P(Z=z')P(X=x|Z=z')}$$
 (4)

Non-identifiability

Different parameter settings, same distribution

Suppose
$$\mathcal{X}=\{a,b\}$$
 and $c=2$ and let $P(Z=1)=P(Z=2)=0.5$

Z	X = a	X = b
1	0.2	0.8
2	0.7	0.3
P(X)	0.45	0.55

Z	X = a	X = b
1	0.7	0.3
2	0.2	8.0
P(X)	0.45	0.55

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Problem for parameter estimation by hillclimbing

Suppose a dataset
$$\mathcal{D} = \{x^{(1)}, x^{(2)}, \cdots, x^{(m)}\}$$

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then we choose

$$\theta^{\star} = \arg\max_{\theta} l(\theta)$$

MLE for categorical: estimation from fully observed data

Suppose we have complete data

$$ightharpoonup \mathcal{D}_{\mathsf{complete}} = \{(x^{(1)}, z^{(1)}), \dots, (x^{(m)}, z^{(m)})\}$$

MLE for categorical: estimation from fully observed data

Suppose we have complete data

$$ightharpoonup \mathcal{D}_{complete} = \{(x^{(1)}, z^{(1)}), \dots, (x^{(m)}, z^{(m)})\}$$

Then, for a categorical distribution

$$P(X = x | Z = z) = \theta_{z,x}$$

and
$$n(z, x | \mathcal{D}_{\mathsf{complete}}) = \mathit{count} \ \mathit{of} \ (z, x) \ \mathit{in} \ \mathcal{D}_{\mathsf{complete}}$$

MLE solution:

$$P(X = x | Z = z) = \theta_{z,x} = \frac{n(z, x | \mathcal{D}_{\text{complete}})}{\sum_{x'} n(z, x' | \mathcal{D}_{\text{complete}})}$$

MLE for categorical: estimation from incomplete data

Expectation-Maximisation algorithm [Dempster et al., 1977]

E-step:

• for every observation x, imagine that every possible latent assignment z happened with probability $P_{\theta}(Z=z|X=x)$

$$\mathcal{D}_{\mathsf{completed}} = \{(x, Z = 1), \dots, (x, Z = c) : x \in \mathcal{D}\}\$$

MLE for categorical: estimation from incomplete data

Expectation-Maximisation algorithm [Dempster et al., 1977]

M-step:

- \blacktriangleright reestimate θ as to climb the likelihood surface
- for categorical distributions $P(X=x|Z=z)=\theta_{z,x}$ z and x are categorical $0 \le \theta_{z,x} \le 1$ and $\sum_{x \in X} \theta_{z,x} = 1$

$$\theta_{z,x} = \frac{\mathbb{E}[n(z \to x | \mathcal{D}_{\mathsf{completed}})]}{\sum_{x'} \mathbb{E}[n(z \to x' | \mathcal{D}_{\mathsf{completed}})]}$$
(5)

$$= \frac{\sum_{i=1}^{m} \sum_{z'} P(z'|x^{(i)}) \mathbb{1}_{z}(z') \mathbb{1}_{x}(x^{(i)})}{\sum_{i=1}^{m} \sum_{x'} \sum_{z'} P(z'|x^{(i)}) \mathbb{1}_{z}(z') \mathbb{1}_{x'}(x^{(i)})}$$
(6)

$$= \frac{\sum_{i=1}^{m} P(z|x^{(i)}) \mathbb{1}_{x}(x^{(i)})}{\sum_{i=1}^{m} \sum_{x'} P(z|x^{(i)}) \mathbb{1}_{x'}(x^{(i)})}$$
(7)

Content

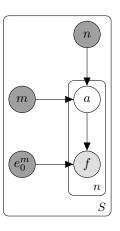
Lexical alignment

Mixture models

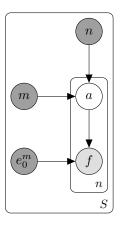
IBM model 1

IBM model 2

Remarks

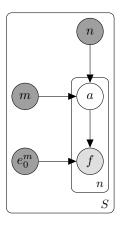


Constrained mixture model



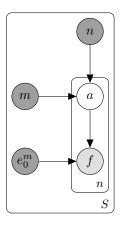
Constrained mixture model

mixture components are English words



Constrained mixture model

- mixture components are English words
- but only English words that appear in the English sentence can be assigned



Constrained mixture model

- mixture components are English words
- but only English words that appear in the English sentence can be assigned
- a_j acts as an indicator for the mixture component that generates French word f_j
- $ightharpoonup e_0$ is occupied by a special m NULL component

Parameterisation

Alignment distribution: uniform

$$P(A|M = m, N = n) = \frac{1}{m+1}$$
 (8)

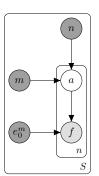
Lexical distribution: categorical

$$P(F|E=e) = \operatorname{Cat}(F|\theta_e) \tag{9}$$

- where $\theta_e \in \mathbb{R}^{v_F}$
- \bullet $0 \le \theta_{e,f} \le 1$
- $\blacktriangleright \sum_{f} \theta_{e,f} = 1$

IBM1: marginal likelihood

Marginal likelihood



$$P(f_1^n|e_0^m) = \sum_{a_1=0}^m \cdots \sum_{a_n=0}^m P(f_1^n, a_1^n|e_{a_j})$$

$$= \sum_{a_1=0}^m \cdots \sum_{a_n=0}^m \prod_{j=1}^n P(a_j|m, n) P(f_j|e_{a_j})$$

$$= \prod_{j=1}^n \sum_{a_j=0}^m P(a_j|m, n) P(f_j|e_{a_j})$$

$$= (10)$$

IBM1: posterior

Posterior

$$P(a_1^n|f_1^n, e_0^m) = \frac{P(f_1^n, a_1^n|e_0^m)}{P(f_1^n|e_0^m)}$$
(13)

Factorised

$$P(a_j|f_1^n, e_0^m) = \frac{P(a_j|m, n)P(f_j|e_{a_j})}{\sum_{i=0}^m P(i|m, n)P(f_j|e_i)}$$
(14)

MLE via EM

E-step:

$$\mathbb{E}[n(\mathsf{e} \to \mathsf{f}|A_1^n)] = \sum_{a_1=0}^m \cdots \sum_{a_n=0}^m P(a_1^n|f_1^n, e_0^m) n(\mathsf{e} \to \mathsf{f}|A_1^n)$$

$$= \sum_{a_1=0}^m \cdots \sum_{A_n=0}^m \prod_{j=1}^n P(a_j|f_1^n, e_0^m) \mathbb{1}_{\mathsf{e}}(e_{a_j}) \mathbb{1}_{\mathsf{f}}(f_j)$$

$$= \prod_{j=1}^n \sum_{i=0}^m P(A_j = i|f_1^n, e_0^m) \mathbb{1}_{\mathsf{e}}(e_i) \mathbb{1}_{\mathsf{f}}(f_j)$$

$$(15)$$

M-step:

$$\theta_{e,f} = \frac{\mathbb{E}[n(e \to f|A_1^n)]}{\sum_{f'} \mathbb{E}[n(e \to f'|A_1^n)]}$$
(18)

EM algorithm

Repeat until convergence to a local optimum

- 1. For each sentence pair
 - 1.1 compute posterior per alignment link
 - 1.2 accumulate fractional counts
- 2. Normalise counts for each English word

Content

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Alignment distribution

Positional distribution

$$P(A_i|M=m, N=n) = \operatorname{Cat}(A|\lambda_{i,m,n})$$

- lacktriangle one distribution for each tuple (j,m,n)
- support must include length of longest English sentence
- extremely over-parameterised!

Alignment distribution

Positional distribution

$$P(A_j|M=m, N=n) = \operatorname{Cat}(A|\lambda_{j,m,n})$$

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- support must include length of longest English sentence
- extremely over-parameterised!

Jump distribution

[Vogel et al., 1996]

- ▶ define a jump function $\delta(a_j, j, m, n) = a_j \lfloor j \frac{m}{n} \rfloor$
- $P(A_j|m,n) = \operatorname{Cat}(\Delta|\lambda)$
- lacktriangle Δ takes values from -longest to +longest

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Note on terminology

Source/Target vs English/French

From an alignment model perspective all that matters is

- we condition on one language and generate the other
- ▶ in IBM models terminology, we condition on *English* and generate *French*

From a noisy channel perspective, where we want to translate a source sentence f_1^n into some target sentence e_1^m

- \blacktriangleright Bayes rule decomposes $p(e_1^m|f_1^n) \propto p(f_1^n|e_1^m)p(e_1^m)$
- train $p(e_1^m)$ and $p(f_1^n|e_1^m)$ independently
- ▶ language model: $p(e_1^m)$
- ▶ alignment model: $p(f_1^n|e_1^m)$
- ▶ note that the alignment model conditions on the target sentence (English) and generates the source sentence (French)

Limitations of IBM1-2

- too strong independence assumptions
- categorical parameterisation suffers from data sparsity
- EM suffers from local optima

Extensions

Fertility, distortion, and concepts [Brown et al., 1993]

Dirichlet priors and posterior inference [Mermer and Saraclar, 2011]

- ► + no NULL words [Schulz et al., 2016]
- + HMM and efficient sampler [Schulz and Aziz, 2016]

Log-linear distortion parameters and variational Bayes [Dyer et al., 2013]

First-order dependency (HMM) [Vogel et al., 1996]

E-step requires dynamic programming [Baum and Petrie, 1966]

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