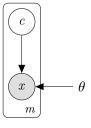
Variational Auto-Encoders

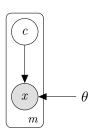
Wilker Aziz

Universiteit van Amsterdam w.aziz@uva.nl

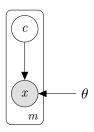
May 18, 2017



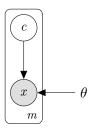
Mixture model



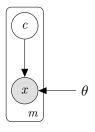
 \blacktriangleright sample a latent class $c \in \{1, \dots, K\}$ $c \sim U(\frac{1}{K})$



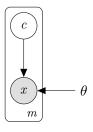
- ▶ sample a latent class $c \in \{1, ..., K\}$ $c \sim U(\frac{1}{K})$
- generate categorical observation x from c $x \sim P(X|C=c)$



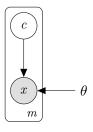
- ▶ sample a latent class $c \in \{1, \dots, K\}$ $c \sim U(\frac{1}{K})$
- ▶ generate categorical observation x from c $x \sim P(X|C=c)$
- where $P(X|C=c) = \operatorname{Cat}(f_{\theta}(c))$



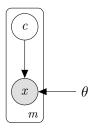
- ▶ sample a latent class $c \in \{1, ..., K\}$ $c \sim U(\frac{1}{K})$
- ▶ generate categorical observation x from c $x \sim P(X|C=c)$
- where $P(X|C=c) = \operatorname{Cat}(f_{\theta}(c))$
 - e.g. $f_{\theta}(c) = \operatorname{softmax}(g_{\theta}(c))$



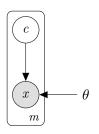
- ▶ sample a latent class $c \in \{1, ..., K\}$ $c \sim U(\frac{1}{K})$
- ▶ generate categorical observation x from c $x \sim P(X|C=c)$
- where $P(X|C=c) = \operatorname{Cat}(f_{\theta}(c))$
 - e.g. $f_{\theta}(c) = \operatorname{softmax}(g_{\theta}(c))$ and $g_{\theta}(c) = \tanh(Wr(c) + b)$



- ▶ sample a latent class $c \in \{1, ..., K\}$ $c \sim U(\frac{1}{K})$
- generate categorical observation x from c $x \sim P(X|C=c)$
- where $P(X|C=c) = \operatorname{Cat}(f_{\theta}(c))$
 - e.g. $f_{\theta}(c) = \operatorname{softmax}(g_{\theta}(c))$ and $g_{\theta}(c) = \tanh(Wr(c) + b)$ and r(c) = Ec



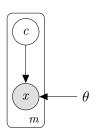
- ▶ sample a latent class $c \in \{1, \dots, K\}$ $c \sim U(\frac{1}{K})$
- generate categorical observation x from c $x \sim P(X|C=c)$
- where $P(X|C=c) = \operatorname{Cat}(f_{\theta}(c))$
 - e.g. $f_{\theta}(c) = \operatorname{softmax}(g_{\theta}(c))$ and $g_{\theta}(c) = \tanh(Wr(c) + b)$ and r(c) = Ec
- with $\theta = (E, W, b)$



- ▶ sample a latent class $c \in \{1, ..., K\}$ $c \sim U(\frac{1}{K})$
- ▶ generate categorical observation x from c $x \sim P(X|C=c)$
- where $P(X|C=c) = \operatorname{Cat}(f_{\theta}(c))$
 - e.g. $f_{\theta}(c) = \operatorname{softmax}(g_{\theta}(c))$ and $g_{\theta}(c) = \operatorname{tanh}(Wr(c) + b)$ and r(c) = Ec
- with $\theta = (E, W, b)$

$$P(x) = \sum_{c=1}^{K} \underbrace{P(c)P(x|c)}_{\text{differentiable function of } \ell}$$
tractable for small K

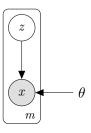
Mixture model



- ▶ sample a latent class $c \in \{1, ..., K\}$ $c \sim U(\frac{1}{K})$
- ▶ generate categorical observation x from c $x \sim P(X|C=c)$
- where $P(X|C=c) = \operatorname{Cat}(f_{\theta}(c))$
 - e.g. $f_{\theta}(c) = \operatorname{softmax}(g_{\theta}(c))$ and $g_{\theta}(c) = \tanh(Wr(c) + b)$ and r(c) = Ec
- with $\theta = (E, W, b)$

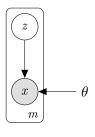
$$P(x) = \sum_{c=1}^{K} \underbrace{P(c)P(x|c)}_{\text{differentiable function of } \theta}$$
tractable for small K

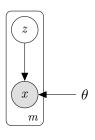
Gradient-based optimisation! $\nabla_{\theta} \log P_{\theta}(x)$



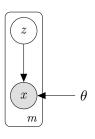
Continuous mixture model

• sample a latent embedding $z \in \mathbb{R}^d$ $z \sim \mathcal{N}(0,1)$

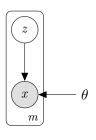




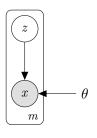
- sample a latent embedding $z \in \mathbb{R}^d$ $z \sim \mathcal{N}(0,1)$
- generate categorical observation x from z $x \sim P(X|Z=z)$



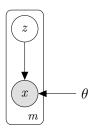
- sample a latent embedding $z \in \mathbb{R}^d$ $z \sim \mathcal{N}(0, 1)$
- generate categorical observation x from z $x \sim P(X|Z=z)$
- where $P(X|Z=z) = \operatorname{Cat}(f_{\theta}(z))$



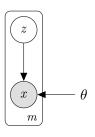
- ▶ sample a latent embedding $z \in \mathbb{R}^d$ $z \sim \mathcal{N}(0,1)$
- generate categorical observation x from z $x \sim P(X|Z=z)$
- where $P(X|Z=z) = \operatorname{Cat}(f_{\theta}(z))$
 - e.g. $f_{\theta}(z) = \operatorname{softmax}(g_{\theta}(z))$



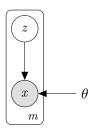
- ▶ sample a latent embedding $z \in \mathbb{R}^d$ $z \sim \mathcal{N}(0,1)$
- generate categorical observation x from z $x \sim P(X|Z=z)$
- where $P(X|Z=z) = \operatorname{Cat}(f_{\theta}(z))$
 - e.g. $f_{\theta}(z) = \operatorname{softmax}(g_{\theta}(z))$ and $g_{\theta}(z) = \tanh(Wz + b)$



- ▶ sample a latent embedding $z \in \mathbb{R}^d$ $z \sim \mathcal{N}(0,1)$
- generate categorical observation x from z $x \sim P(X|Z=z)$
- where $P(X|Z=z) = \operatorname{Cat}(f_{\theta}(z))$
 - e.g. $f_{\theta}(z) = \operatorname{softmax}(g_{\theta}(z))$ and $g_{\theta}(z) = \tanh(Wz + b)$
- with $\theta = (E, W, b)$

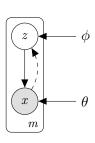


- ▶ sample a latent embedding $z \in \mathbb{R}^d$ $z \sim \mathcal{N}(0,1)$
- generate categorical observation x from z $x \sim P(X|Z=z)$
- where $P(X|Z=z) = \operatorname{Cat}(f_{\theta}(z))$
 - e.g. $f_{\theta}(z) = \operatorname{softmax}(g_{\theta}(z))$ and $g_{\theta}(z) = \tanh(Wz + b)$
- with $\theta = (E, W, b)$
- Intractability

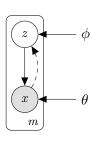


- ▶ sample a latent embedding $z \in \mathbb{R}^d$ $z \sim \mathcal{N}(0,1)$
- generate categorical observation x from z $x \sim P(X|Z=z)$
- where $P(X|Z=z) = \operatorname{Cat}(f_{\theta}(z))$
 - e.g. $f_{\theta}(z) = \operatorname{softmax}(g_{\theta}(z))$ and $g_{\theta}(z) = \tanh(Wz + b)$
- with $\theta = (E, W, b)$
- Intractability
 - $P(x) = \int p(z)P(x|z)dz$
 - $P(z|x) = \frac{p(z)P(x|z)}{\int p(z')P(x|z')dz'}$

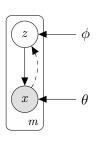
but we know VI:D



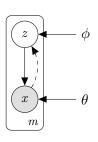
▶ approximate the posterior with $q_{\phi}(Z|x) = \mathcal{N}(\mu_{\phi}(x), I\sigma_{\phi}^2(x))$



- ▶ approximate the posterior with $q_{\phi}(Z|x) = \mathcal{N}(\mu_{\phi}(x), I\sigma_{\phi}^2(x))$
- where
 - $\begin{array}{ll} & \mu_{\phi}(x) = u_{\phi}(r_{\phi}(x)) \\ & \text{e.g. } r_{\phi}(x) = E_{\mathbf{u}}x \\ & \text{and } u_{\phi}(r) = \tanh \big(W_{\mathbf{u}}r + b_{\mathbf{u}} \big) \end{array}$

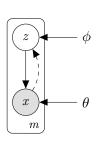


- ▶ approximate the posterior with $q_{\phi}(Z|x) = \mathcal{N}(\mu_{\phi}(x), I\sigma_{\phi}^{2}(x))$
- where
 - $\begin{array}{ll} \blacktriangleright & \mu_{\phi}(x) = u_{\phi}(r_{\phi}(x)) \\ \text{e.g.} & r_{\phi}(x) = E_{\mathbf{u}}x \\ \text{and} & u_{\phi}(r) = \tanh(W_{\mathbf{u}}r + b_{\mathbf{u}}) \end{array}$
 - $\sigma_{\phi}^{2}(x) = \exp(v_{\phi}(r_{\phi}'(x)))$ e.g. $r_{\phi}'(x) = E_{\mathbf{v}}x$ and $v_{\phi}(r) = \tanh(W_{\mathbf{v}}r + b_{\mathbf{v}})$



- ▶ approximate the posterior with $q_{\phi}(Z|x) = \mathcal{N}(\mu_{\phi}(x), I\sigma_{\phi}^2(x))$
- where
 - $\begin{array}{ll} & \mu_{\phi}(x) = u_{\phi}(r_{\phi}(x)) \\ & \text{e.g. } r_{\phi}(x) = E_{\mathbf{u}}x \\ & \text{and } u_{\phi}(r) = \tanh(W_{\mathbf{u}}r + b_{\mathbf{u}}) \end{array}$
 - $\sigma_{\phi}^{2}(x) = \exp(v_{\phi}(r'_{\phi}(x)))$ e.g. $r'_{\phi}(x) = E_{\mathbf{v}}x$ and $v_{\phi}(r) = \tanh(W_{\mathbf{v}}r + b_{\mathbf{v}})$
- with $\phi = (E_{\mathsf{u}}, E_{\mathsf{v}}, W_{\mathsf{u}}, W_{\mathsf{v}}, b_{\mathsf{u}}, b_{\mathsf{v}})$

but we know VI:D



- ▶ approximate the posterior with $q_{\phi}(Z|x) = \mathcal{N}(\mu_{\phi}(x), I\sigma_{\phi}^2(x))$
- where
 - $\begin{array}{ll} & \mu_{\phi}(x) = u_{\phi}(r_{\phi}(x)) \\ & \text{e.g. } r_{\phi}(x) = E_{\mathbf{u}}x \\ & \text{and } u_{\phi}(r) = \tanh(W_{\mathbf{u}}r + b_{\mathbf{u}}) \end{array}$
 - $\sigma_{\phi}^{2}(x) = \exp(v_{\phi}(r_{\phi}'(x)))$ e.g. $r_{\phi}'(x) = E_{\mathbf{v}}x$ and $v_{\phi}(r) = \tanh(W_{\mathbf{v}}r + b_{\mathbf{v}})$
- ightharpoonup with $\phi = (E_{\mathsf{u}}, E_{\mathsf{v}}, W_{\mathsf{u}}, W_{\mathsf{v}}, b_{\mathsf{u}}, b_{\mathsf{v}})$

Mean field assumption

• $q_{\phi_i}(Z|x_i)$ is specified for each observation x_i by locally predicting its mean and variance

Approximate inference by optimisation

Maximise ELBO

$$\log P_{\theta}(x) \ge \underbrace{\mathbb{E}_{q_{\phi}(Z|x)} \left[\log \frac{q_{\phi}(Z|x)}{p_{\theta}(Z)} \right]}_{-\mathrm{KL}(q_{\theta}(Z|x)||p_{\theta}(Z))} + \underbrace{\mathbb{E}_{q_{\phi}(Z|x)} \left[\log P_{\theta}(X=x|Z) \right]}_{\text{intractable!}}$$

Approximate inference by optimisation

Maximise ELBO

$$\log P_{\theta}(x) \ge \underbrace{\mathbb{E}_{q_{\phi}(Z|x)} \left[\log \frac{q_{\phi}(Z|x)}{p_{\theta}(Z)} \right]}_{-\mathrm{KL}(q_{\theta}(Z|x)||p_{\theta}(Z))} + \underbrace{\mathbb{E}_{q_{\phi}(Z|x)} \left[\log P_{\theta}(X=x|Z) \right]}_{\text{intractable!}}$$

Prior term

$$KL(q_{\phi}(Z|x)||p_{\theta}(Z)) = -\frac{1}{2} \sum_{j=1}^{d} (1 + \log \sigma_{\phi}^{2}(x)_{j} - \mu_{\phi}^{2}(x)_{j} - \sigma_{\phi}^{2}(x)_{j})$$

Approximate inference by optimisation

Maximise ELBO

$$\log P_{\theta}(x) \ge \underbrace{\mathbb{E}_{q_{\phi}(Z|x)} \left[\log \frac{q_{\phi}(Z|x)}{p_{\theta}(Z)} \right]}_{-\mathrm{KL}(q_{\theta}(Z|x)||p_{\theta}(Z))} + \underbrace{\mathbb{E}_{q_{\phi}(Z|x)} \left[\log P_{\theta}(X=x|Z) \right]}_{\text{intractable!}}$$

Prior term

$$KL(q_{\phi}(Z|x)||p_{\theta}(Z)) = -\frac{1}{2} \sum_{j=1}^{d} (1 + \log \sigma_{\phi}^{2}(x)_{j} - \mu_{\phi}^{2}(x)_{j} - \sigma_{\phi}^{2}(x)_{j})$$

Likelihood term is intractable

the Categorical likelihood is not conjugate with the Normal approximate posterior

Change of variable for location-scale distributions

For $Z \sim \mathcal{N}(\mu, \sigma^2)$ we can re-express Z in terms of $E \sim \mathcal{N}(0, I)$

$$ightharpoonup Z = \mu + \sigma E$$

Change of variable for location-scale distributions

For $Z \sim \mathcal{N}(\mu, \sigma^2)$ we can re-express Z in terms of $E \sim \mathcal{N}(0, I)$

$$ightharpoonup Z = \mu + \sigma E$$

then we can re-express expectations

$$\mathbb{E}_{\mathcal{N}(\mu,\sigma^2)}[f(Z)] = \mathbb{E}_{\mathcal{N}(0,I)}[f(\mu+\sigma E)]$$

Change of variable for location-scale distributions

For $Z \sim \mathcal{N}(\mu, \sigma^2)$ we can re-express Z in terms of $E \sim \mathcal{N}(0, I)$

$$ightharpoonup Z = \mu + \sigma E$$

then we can re-express expectations

$$\mathbb{E}_{\mathcal{N}(\mu,\sigma^2)}[f(Z)] = \mathbb{E}_{\mathcal{N}(0,I)}[f(\mu + \sigma E)]$$

back to the ELBO

$$\mathbb{E}_{q_{\phi}(Z|x)}\left[\log P(x|Z)\right] = \mathbb{E}_{\epsilon \sim N(0,I)}\left[\log P(x|Z = \mu_{\phi}(x) + \sigma_{\phi}(x)\epsilon)\right]$$

Monte Carlo estimate

$$\mathbb{E}_{q_{\phi}(Z|x)} \left[\log P(x|Z) \right] = \mathbb{E}_{\epsilon \sim N(0,I)} \left[\log P(x|Z = \mu_{\phi}(x) + \sigma_{\phi}(x)\epsilon) \right]$$

$$\approx \frac{1}{N} \sum_{n=1}^{N} \log P \left(x | \mu_{\phi}(x) + \sigma_{\phi}(x)\epsilon^{(n)} \right)$$

MC estimate of the ELBO

$$\begin{split} \log P_{\theta}(x) &\geq \underbrace{\mathbb{E}_{q_{\phi}(Z|x)} \left[\log \frac{q_{\phi}(Z|x)}{p_{\theta}(Z)} \right]}_{-\mathrm{KL}(q_{\theta}(Z|x)||p_{\theta}(Z))} + \underbrace{\mathbb{E}_{q_{\phi}(Z|x)} \left[\log P_{\theta}(X=x|Z) \right]}_{\text{intractable!}} \\ &\approx \underbrace{\frac{1}{2} \sum_{j=1}^{d} \left(1 + \log \sigma_{\phi}^{2}(x)_{j} - \mu_{\phi}^{2}(x)_{j} - \sigma_{\phi}^{2}(x)_{j} \right)}_{-\mathrm{KL}(q_{\theta}(Z|x)||p_{\theta}(Z))} \\ &\quad + \underbrace{\log P_{\theta}\left(x | \mu_{\phi}(x) + \sigma_{\phi}(x) \epsilon \right)}_{\text{single-sample estimate}} \end{split}$$

Gradient-based optimisation

Let $\mathcal{L}(\theta, \phi|x)$ be our objective function

$$\mathcal{L}(\theta,\phi|x) = \underbrace{\frac{1}{2} \sum_{j=1}^{d} \left(1 + \log \sigma_{\phi}^{2}(x)_{j} - \mu_{\phi}^{2}(x)_{j} - \sigma_{\phi}^{2}(x)_{j}\right)}_{\text{differentiable function of } \phi} \\ + \underbrace{\log P_{\theta}\left(x | \mu_{\phi}(x) + \sigma_{\phi}(x)\epsilon\right)}_{\text{differentiable function of } \theta \text{ and } \phi}$$

Gradient-based optimisation

Let $\mathcal{L}(\theta, \phi|x)$ be our objective function

$$\mathcal{L}(\theta,\phi|x) = \underbrace{\frac{1}{2} \sum_{j=1}^{d} \left(1 + \log \sigma_{\phi}^{2}(x)_{j} - \mu_{\phi}^{2}(x)_{j} - \sigma_{\phi}^{2}(x)_{j} \right)}_{\text{differentiable function of } \phi} \\ + \underbrace{\log P_{\theta} \left(x | \mu_{\phi}(x) + \sigma_{\phi}(x) \epsilon \right)}_{\text{differentiable function of } \theta \text{ and } \phi}$$

We can update θ and ϕ using stochastic gradient steps

- we know chain rule (thus we can get a gradient)
- we have a noisy though unbiased estimate
- guaranteed convergence to a local optimum of L
 (with appropriate learning rate schedule)

Further reading

► Auto-Encoding variational Bayes [Kingma and Welling, 2014]

References I

Diederik P. Kingma and Max Welling. Auto-encoding variational bayes. In *International Conference on Learning Representations*, 2014.