SN-GIMBAL



The image shown here is indicative only. If there is inconsistency between the image and the actual product, the actual product shall govern.

1. INTERFACE

CAMERA CONTROL			
Con2 (PWM signal)	FIREFLY2 REC video		
Pitch(PWM signal)	Camera pitch angle		
Con1 (PWM signal)	FIREFLY2 take photo		
-	GND		
UART (upgrade FW & set parameter, 115200 8N1)			
TX	/		
RX	/		
-	GND		
POWER			
-	/		
+	8-12v		
video	Video out		
CAMERA BOARD INTERFACE			
video	Connect to camera video out		
Tape	Camera Video record		
Photo	Camera photo		
5V	Camera power		
Batt	Battery power		
GND	/		

➢ WORK WITH SN_L FC

- ① Make sure your OSD back-level is 125.
- 2) If OSD can not work normally please connect the video conditioner.
- (3) Check your firmware version is support aat; The latest firmware v6.0 can open the aat function directly in the OSD setting menu.

CONNECT CAMERA CONDITIONER



2. HOW TO WORK

① work vol: 8-12V

② pitch angle range: ±45° roll angle range: ±45°

*Camera shake if it exceeds the angle range

3 check C.G(center of gravity)

SN GIMBAL support FIREFLY2, if you use other camera, please Re-weighting.



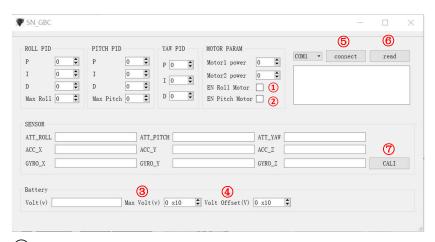
(4) LED status

	FLASH	ON	0FF
RED LED	sensor ok	sensor error	/
GREEN LED	voltage ok	voltage exceeds threshold	/
BLUE LED	/	Camera power ok	Camera power error

3. HOW TO CONTROLL

- ① Control the FIREFLY2 to take photo, video
 Connect a RC channel to <CON1> and <CON2>, then you can control it by flip a switch channel.
- ② Connect to mavlink port
 Gimbal will enter follow mode when you connect to mavlink port. Will follow the attitude change of the aircraft.

4. HOW TO USE GCS



- 1 Enable Roll Motor power.
- 2 Enable Pitch Motor power.
- ③ Voltage Threshold: if you set 120, it means that max input voltage is 12.0v.

- 4 Calibrate voltage value.
- ⑤ Connect button.
- 6 Read button, read param from gimbal.
- 7 Calibrate level.

When calibrating the level, please disable the motor power and then place the camera platform horizontally.