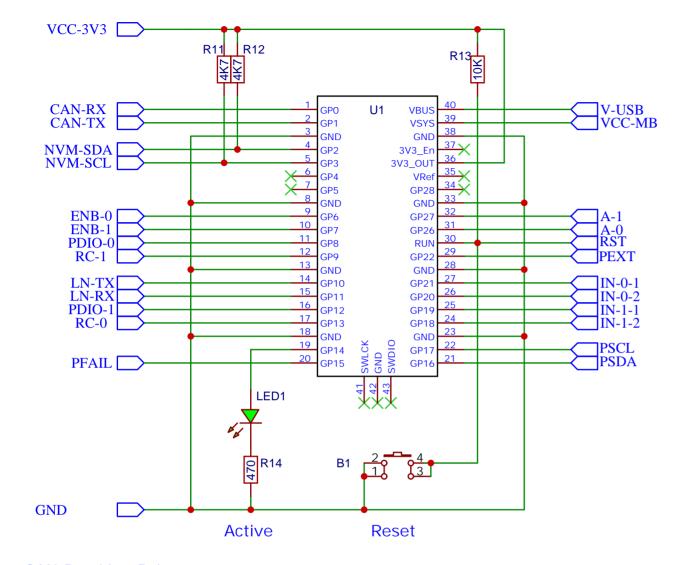
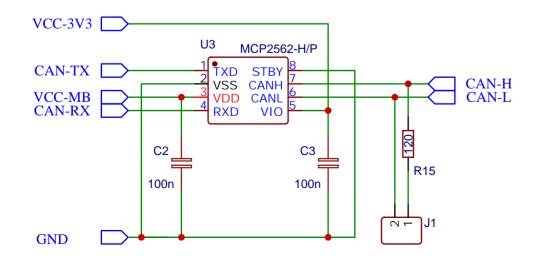


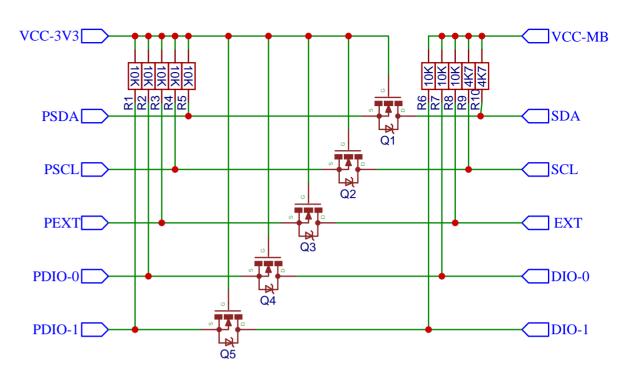
## Main controller - RASPBERRY Pi Pico



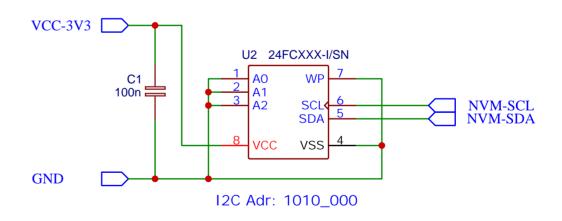
## **CAN Bus Line Driver**

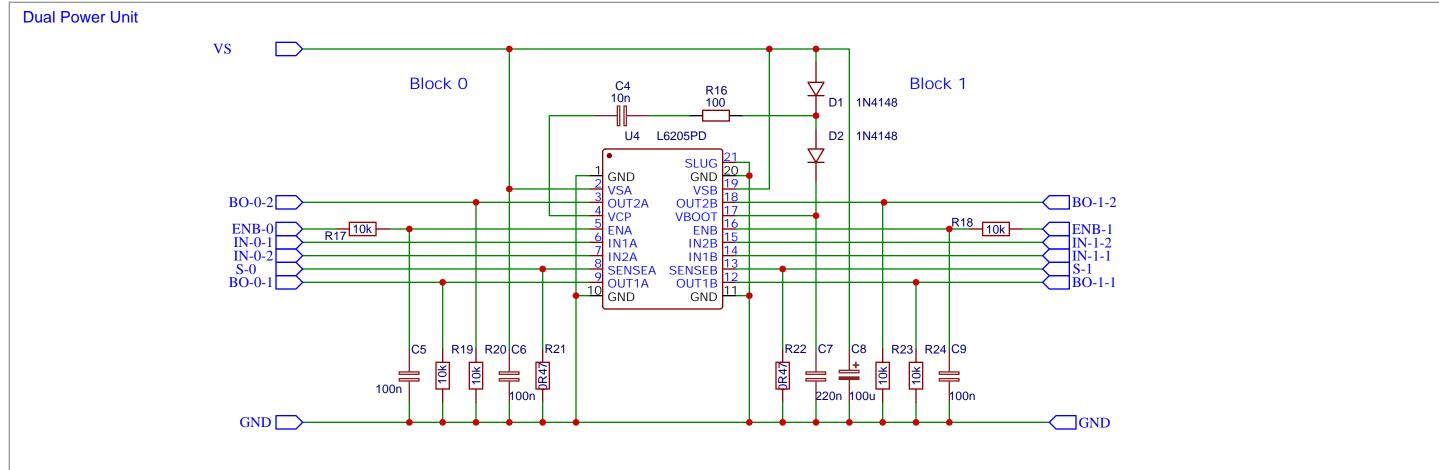


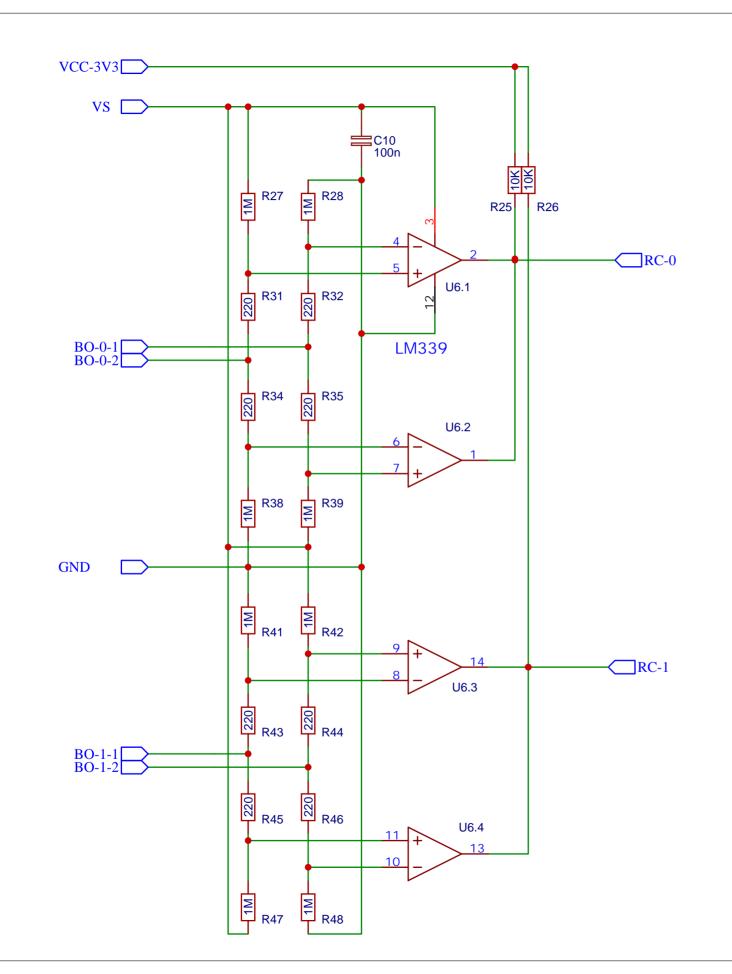
## Level shifters

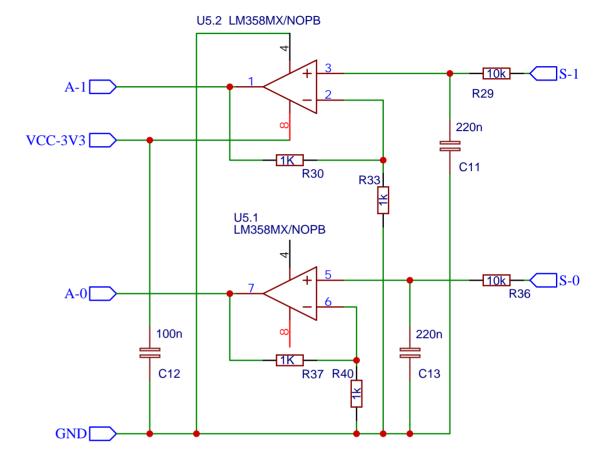


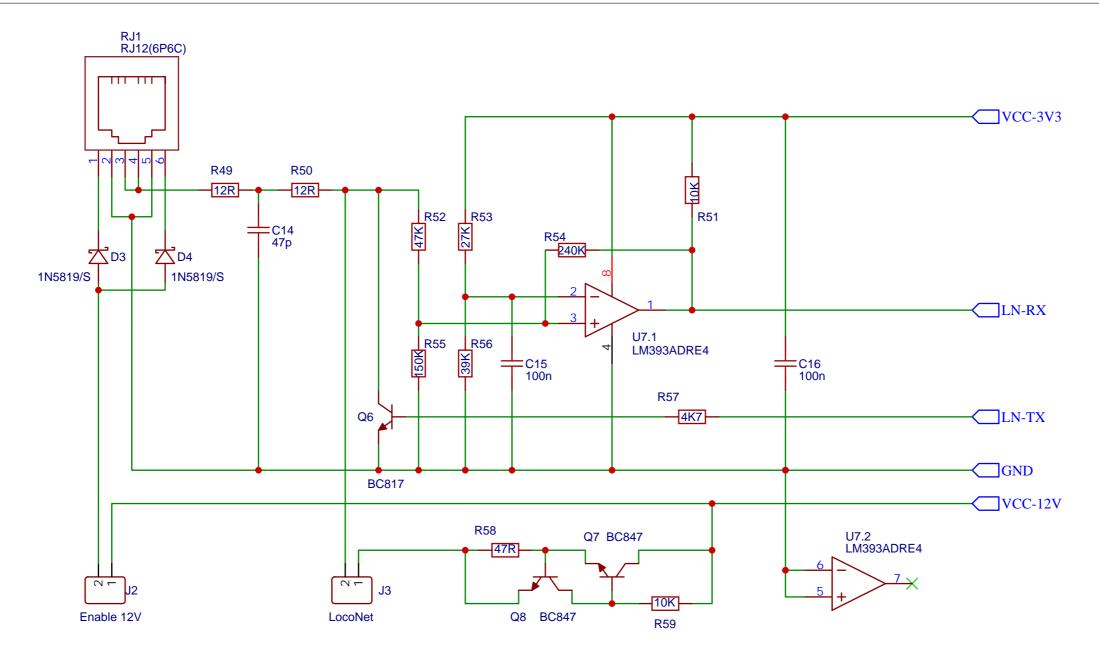
## Non-Volatile Memory



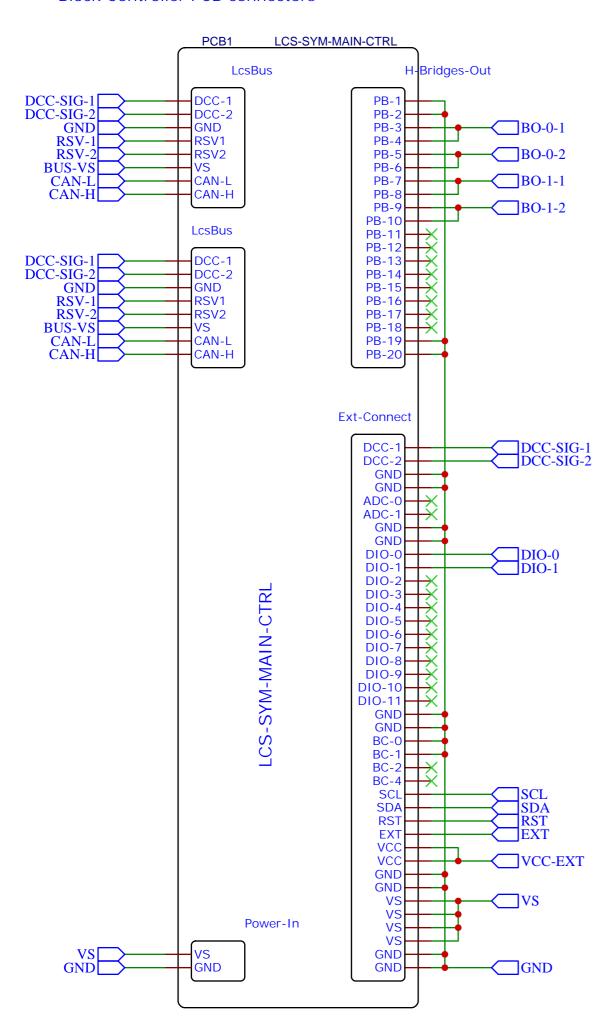


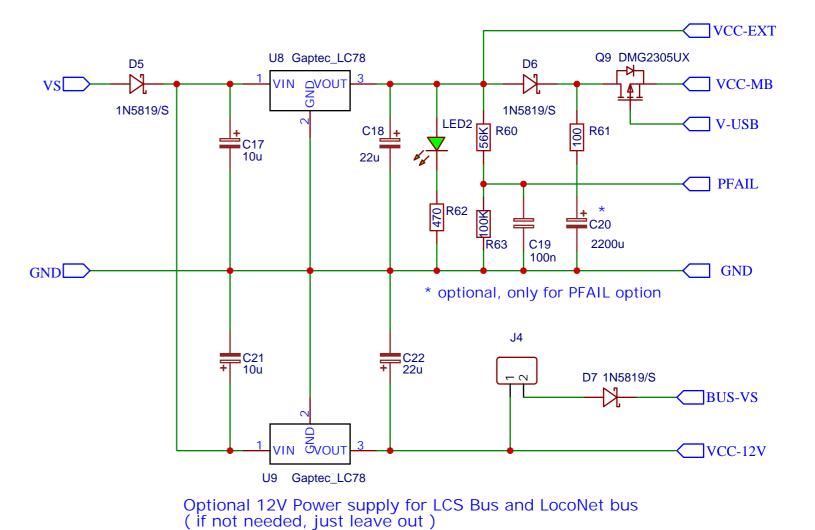






The LocNet interface is an optional component. If not used, just leave the PCB board empty for this function.





Jumper for DCC Signal enable on LCS Bus

