Developing Zynq Software with Xilinx SDK

Lab 5 Connecting SDK to Hardware



November 2013 Version 03



Lab 5 Overview

At last we will now be able to power up the Zynq hardware. Using the example application projects and the SDK, we will connect to the hardware through a JTAG connection. The bitstream will be programmed into the PL, the ARM processor configured, and the code bootloaded to the appropriate memory. SDK can be used to simply run the application or use a full-featured application debugger to step through the code.

Lab 5 Objectives

When you have completed Lab 5, you will know how to:

- Set up the hardware for operation
- Program a bitstream to the PL
- Configure the ARM PS over JTAG using TCL
- Run an application
- Debug an application



Experiment 1: Setup Hardware and Download Bitstream

Xilinx Zynq SoCs are SRAM-based devices, meaning they are volatile. The PL is volatile and the ARM registers are also volatile. In production, the PL hardware definition (or bitstream) and the ARM PS configuration code (or First-Stage Boot Loader FSBL) are stored in Flash on the board, such as a Quad-SPI Flash or SD Card.

Before storing a hardware/software design to Flash, developers will want to experiment with the code – both PL hardware code as well as software application code. In this experiment, we will focus on software application code experimentation directly from SDK. Making use of a JTAG connection to the hardware, SDK will be able to perform all the functions that would normally be performed from Flash.

The SDK-SoC JTAG interface may be used to accomplish all these things:

- Read and write ARM registers
- Configure the PL with a bitstream
- Program attached QSPI Flash
- Upload application code to on-chip RAM or DDR3
- Application debug



Experiment 1 General Instruction:

Setup the hardware and connect all cables. Determine the COM Port assignment on your PC. Configure the SoC PL with a bitstream.

Experiment 1 Step-by-Step Instructions:

- 1. Connect the power cable to the ZedBoard, but leave ZedBoard OFF for now.
- 2. Connect two micro-USB cables between the Windows Host machine and the ZedBoard connectors J17 (JTAG) and J14 (UART).
- 3. Set the Boot Mode jumpers to Cascaded JTAG Mode MIO[6:2] = GND



Figure 1 – PLL Used, JTAG Boot, Cascaded JTAG: MIO[6:2] = 00000

4. Slide the ZedBoard power switch to ON. You should see the Green Power Good LED (LD13light.

If this is the first time you've connected the ZedBoard to this computer, you may see Windows install device drivers for the USB-UART and/or the JTAG cable. You should have previously installed the driver for the Cypress USB-UART. The Platform Cable and Digilent HS2/HS1 USB-JTAG drivers were installed during the Xilinx tool installation.





Figure 2 – ZedBoard Powered with micro-USB Cables Connected to JTAG and UART

- 5. Use Device Manager to determine the COM port for the Cypress USB-UART. In Windows 7, click Start → Control Panel, and then click Device Manager. Click Yes to confirm.
- 6. Expand *Ports*. Note the COM port number for the Cypress Serial device. This example shows COM6.

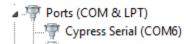


Figure 3 – Find the COM port number for the Cypress Serial device

- 7. In SDK, select **Xilinx Tools** → **Program FPGA** or click the discon.
- 8. SDK will already know the correct .bit file (and .bmm if your future hardware platform includes that) since this was imported with the hardware platform. Click **Program**. When LD12 lights blue, the PL has configured successfully. Look for the message "FPGA configured successfully with bitstream" in the Console window.



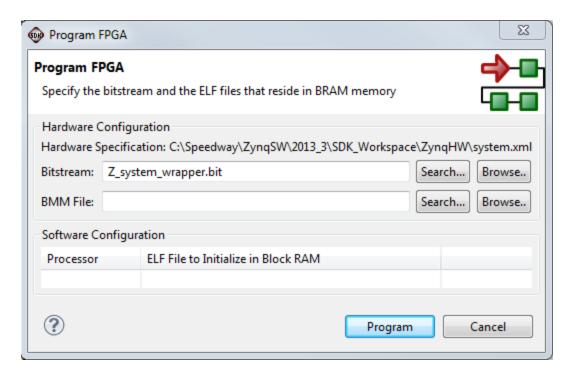


Figure 4 - Program FPGA

Ouestions:

Ans	ver the following questions:
•	For what can the JTAG interface be used?
	1
	2
	3
	4
	Under what conditions must the hardware platform first be downloaded into the PL?



Experiment 2: Running an Application

SDK is now ready to run or debug an application. In this experiment, the previous Hello World and Memory Tests will be run.

Experiment 2 General Instruction:

Run the Hello_Zynq and Test_Memory applications on the hardware, viewing the results on the stdout Terminal. Run the edited Test_Memory to see the expanded test window.

Experiment 2 Step-by-Step Instructions:

Since we previously setup the hardware and configured the hardware platform to FPGA, the blue DONE LED (D2) should be lit, and the hardware should be ready to accept an application to run.

- Right-click on the Hello_Zynq application and select Run As → Run Configurations...
- 2. Select Xilinx C/C++ Application (GDB) and then click the 'New' icon .

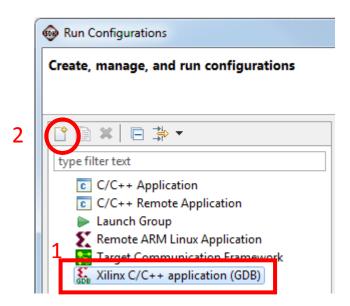


Figure 5 – Create a New Xilinx C/C++ Application Run Configuration

SDK creates the new Run Configuration and automatically assigns a name to the configuration <application_name> <active_configuration>, which in this case is Hello Zynq Debug.



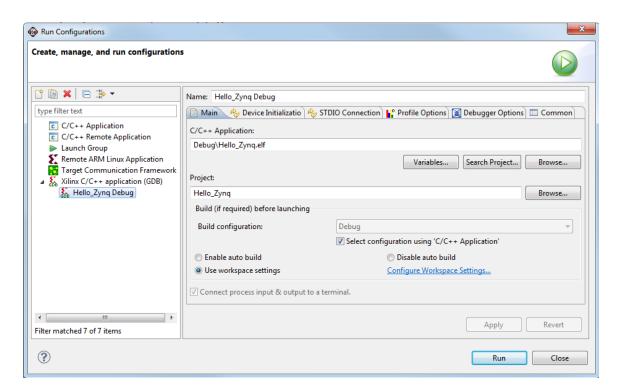


Figure 6 – New Run Configuration

Recall that the example code copied over for the Hello_Zynq application was quite simple. Other than the UART statements, there wasn't much else. There was nothing in Hello_Zynq to set up the ARM registers for the designed clocking, peripherals, and I/O connections. If the Hello_Zynq application doesn't configure the ARM processing system, then how will it get done?

3. Switch to the *Device Initialization* tab. Note that by default, the ps7_init.tcl will be sourced prior to running your application. That is how the ARM gets initialized for proper operation. Recall that this ps7_init.tcl was one of the outputs reviewed in Lab 1.

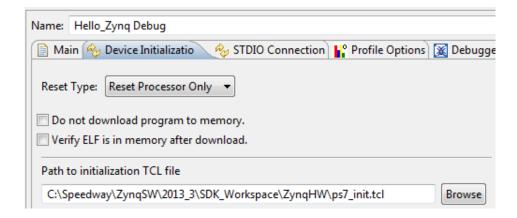


Figure 7 – ps7 init.tcl Script to Source



4. SDK provides a simple terminal. It is sufficient for simple text output, but otherwise use a different terminal like Tera Term. For now, we'll show you how to make use of the SDK terminal.

Switch to the *STDIO Connection* tab. Check the box for *Connect STDIO to Console*. Select the PORT for the USB to UART Bridge previously seen in Device Manager. Set the BAUD Rate to 115200. This is a fixed hardware setting determined by the hardware platform. Click **Apply** and then **Run**.



Figure 8 – STDIO Connection

You can monitor the progress of the download in the lower right-hand corner.

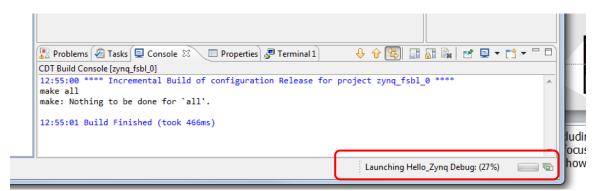


Figure 9 - Download Progress

SDK will download the Hello_Zynq ELF to the on-chip RAM (because this is what we set in the linker script in Lab 4) and begin executing the code.



Figure 10 - Hello World



5. Repeat steps 1 through 4 for application Test_Memory, including setting up a new Run Configuration, confirming the Device Initialization, and setting up the STDIO Connection. This test completes very quickly as it only tests the first 4 KB in the three tested memory spaces. When finished, click the Terminate icon.

```
🖳 Problems 🙆 Tasks 🖳 Console 🖾 🔪 🗏 Properties 🧬 Terminal
Test_Memory Debug [Xilinx C/C++ application (GDB)] C:\Speedway\ZynqSW\2013_3\SDK_Workspace\Test_Memory\Debug\Test_Memory
--Starting Memory Test Application-
NOTE: This application runs with D-Cache disabled.As a result, cacheline requests will not be generated
Testing memory region: ps7_ddr_0
   Memory Controller: ps7_ddr
         Base Address: 0x00100000
                Size: 0x1ff00000 bytes
          32-bit test: PASSED!
          16-bit test: PASSED!
          8-bit test: PASSED!
Testing memory region: ps7_ram_0
   Memory Controller: ps7_ram
        Base Address: 0x00000000
                Size: 0x00030000 bytes
          32-bit test: PASSED!
          16-bit test: PASSED!
          8-bit test: PASSED!
Testing memory region: ps7_ram_1
   Memory Controller: ps7_ram
         Base Address: 0xffff0000
                Size: 0x0000fe00 bytes
          32-bit test: PASSED!
          16-bit test: PASSED!
          8-bit test: PASSED!
--Memory Test Application Complete--
```

Figure 11 - Memory Tests Complete



6. Repeat the run again using the previously edited application Test_Memory_FullDDR to see if you successfully edited the Memory Test code to test 1MB of DDR3. If the Run Configuration does not show a targeted ELF in the C/C++ Application field, it may be because you didn't delete the old ELF after copying the project. If that happens, click **Search Project...** and then select Test Memory FullDDR.elf.

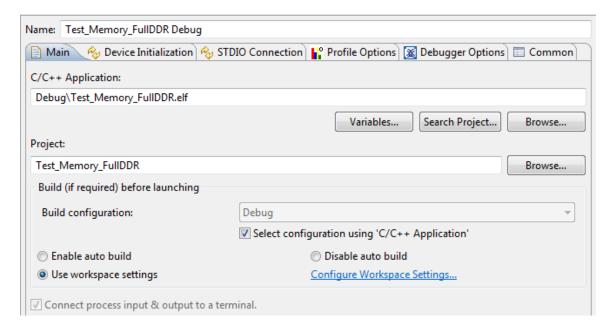


Figure 12 - Run Configuration for Test Memory FullDDR

```
Problems Tasks Console Console
```

Figure 13 – 1MB of DDR3 Tested

The same test runs as before. However, this time it takes slightly longer since a larger space is being tested.



Questions:

Answer the following questions:			
•	How does the ARM get initialized when running an application from SDK over the JTAG connection?		
•	How much memory is tested by default?		



Experiment 3: Debug an Application

Debugging applications is a very important part of the software development process. During this experiment, we will exercise the debugger with the Peripheral Test application.

Xilinx recently introduced the SDK System Debugger, based on the Target Communications Framework (TCF). According to Xilinx, System Debugger delivers true multi-processor SoC design and debug. For example, in a Zynq-based design, System Debugger displays both ARM CPUs and multiple Zynq soft-processors, in the same debug session, through a single JTAG cable; for an unprecedented level of insight between the hardened processing system, and any additional processing that you've added to the programmable logic.

- Based on the Target Communication Framework (TCF)
- Homogenous and heterogeneous multi-processor support
- New in 2013.3 Linux application debug on the target
- Hierarchical Profiling
- Bare-metal and Linux development
- Supporting both SMP and AMP designs
- Associate hardware and software breakpoints per core
- NEON™ library support

The traditional XMD/GDB Debugger continues to work with Zynq applications as well.



Experiment 3 General Instruction:

Launch the Peripheral Test application in the Debugger. Step through a few lines of code. Set breakpoints. Observe memory.

Experiment 3 Step-by-Step Instructions:

Right-click on the Test_Peripherals application and choose Debug As to view the options. Notice that we have two Launch on Hardware options – GDB and System Debugger. Don't select either of these now. Rather select Debug Configurations...

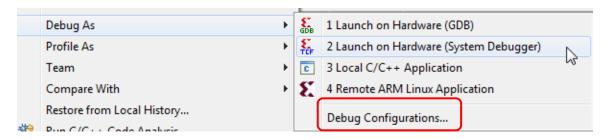


Figure 14 - Debug As Option

2. Notice that the Configurations menu remembers the previous Run Configurations from the previous labs. Select **Xilinx C/C++ application (System Debugger)** then click the new icon.

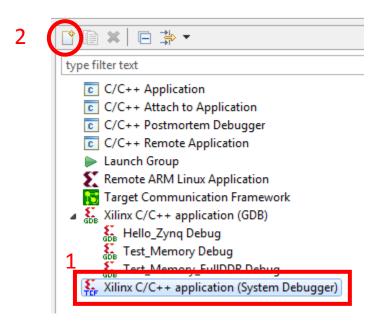


Figure 15 – Create New System Debugger Configuration



3. If you hadn't previously programmed the PL, you could check the **Reset entire** system and **Program FPGA** checkboxes. However, we have already programmed the PL so we will leave these unchecked.

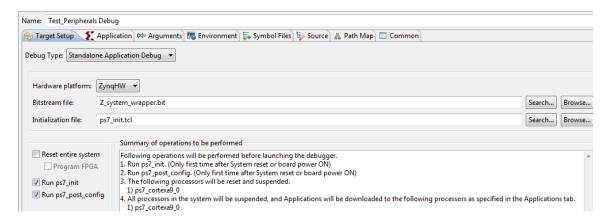


Figure 16 - Target Setup

- 4. Feel free to explore the other tabs, but we will not make any other changes. Click **Debug**.
- 5. The code will be downloaded to the target memory, which in this case is DDR3. However, the application will not be run. Instead, the SDK's windows will be reconfigured to show you what is known as the "debugging perspective." Click **Yes** to confirm the perspective switch.

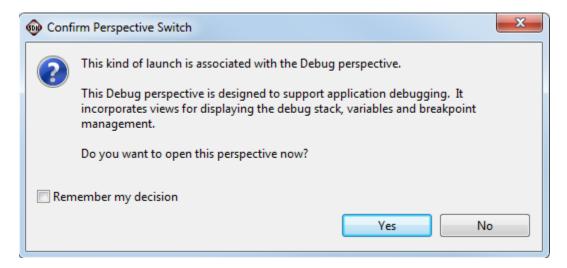


Figure 17 – Confirm Perspective Switch



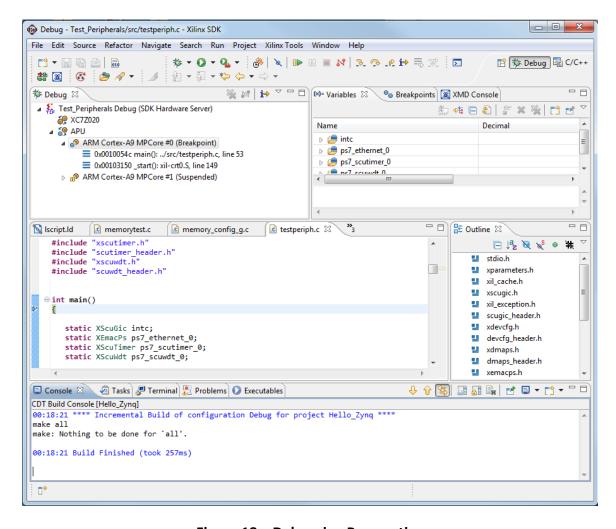


Figure 18 – Debugging Perspective

It is important to note that the Zynq processor is now in a halted state; therefore the application is not being executed. In the code editing window, you will now see a green bar (very small in this case, surrounding the '{'), which shows the line of code which will be executed next.

```
sint main()

static XScuGic intc;
static XEmacPs ps7_ethernet_0;
static XScuTimer ps7_scutimer_0;
static XScuWdt ps7_scuwdt_0;
```

Figure 19 – Debug Waiting for User Input



The System Debugger did not give us the option to setup the STDIO terminal. This time you'll see how to connect the terminal with an alternative method.

6. At the bottom of the SDK screen, select the *Terminal 1* tab. Click the yellow "Settings" icon , and change the *Connection Type* to **Serial**. Change the *Settings* for 115200 baud, 8 data bits, 1 stop bit, no parity and no flow control. Choose the COM port identified previously. Click **OK**.

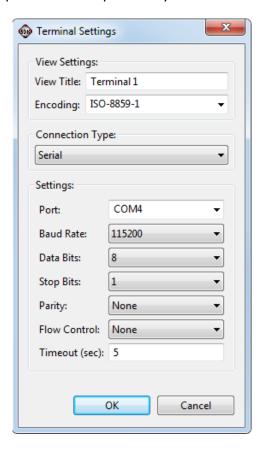
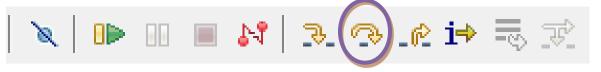


Figure 20 – Terminal Settings

- 7. If it is not already connected, click the green "Connect" icon on the right hand side of the *Terminal 1* tab header. (The icon is represented by two circles connected by a 'z' shaped wire)
- 8. In the header of the Debug pane at the top of the screen, you should see a number of icons. We shall use the "Step Over" icon to advance the application by one line of code. Click this icon four times and observe the effect on the code editing window and the UART Terminal.





As you can see, the processor has executed the first four lines of code. The green bar indicates the next line of code waiting to be executed. The line of printed text should have appeared in the UART terminal window.

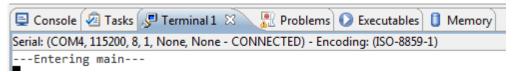


Figure 21 - First Line of Text in UART

Each time the green bar is shown in the code window, the Zynq processor has advanced but then stopped executing again. Next, we'll set a breakpoint. For ease of explanation, it would be useful to have the editor show line numbers.

 Select Window → Preferences. Within the Preferences dialog, browse to General → Editors → Text Editors. Click the checkbox for Show line numbers. Click OK.

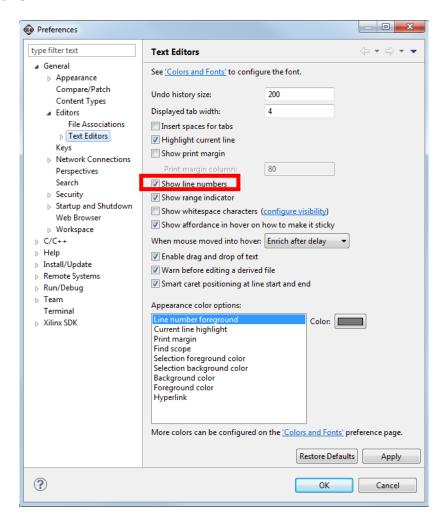


Figure 22 – Show Line Numbers in the Text Editor



10. Browse to Line 148 in testperiph.c, where the code is beginning the QSPI test. Set a breakpoint on Line 148 by double-clicking in the blue column to the left of the line number.

```
int Status;
int Status;

print("\r\n Running QspiSelfTestExample() for ps7_qspi_0...\r\n");

fint Status;

print("\r\n Running QspiSelfTestExample() for ps7_qspi_0...\r\n");

Status = QspiPsSelfTestExample(XPAR_PS7_QSPI_0_DEVICE_ID);

if (Status == 0) {
    print("QspiPsSelfTestExample PASSED\r\n");

for print("QspiPsSelfTestExample FAILED\r\n");

lower between the print("QspiPsSelfTestExample FAILED\r\n");

for print("QspiPsSelfTestExample FAILED\r\n")
```

Figure 23 – Setting a Breakpoint

11. In the upper right hand area of the perspective, select the *Breakpoints* tab. This area allows you to disable or delete breakpoints. Breakpoints can also be deleted by double-clicking again to the left of the line number.

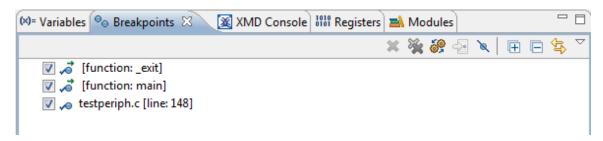


Figure 24 – Breakpoints

12. Click the "Resume" icon which is depicted by the Green arrow.



13. A few tests have now passed, as indicated by the results in the *Terminal 1* window. The next sequence of code will test the QSPI. Click the Resume icon again.

Since this application is not in a loop, the application has finished. The complete results from the Peripheral Test application are shown below.



```
🖳 Console 🙆 Tasks 🐶 Terminal 1 🖂
                                   Problems Decentables
                                                             Memory
Serial: (COM4, 115200, 8, 1, None, None - CONNECTED) - Encoding: (ISO-8859-1)
---Entering main---
Running ScuGicSelfTestExample() for ps7_scugic_0...
ScuGicSelfTestExample PASSED
ScuGic Interrupt Setup PASSED
Running DcfgSelfTestExample() for ps7_dev_cfg_0...
DcfgSelfTestExample PASSED
Running XDmaPs_Example_W_Intr() for ps7_dma_s...
Test round 0
XDmaPs Example W Intr PASSED
Running Interrupt Test for ps7_ethernet_0...
EmacPsDmaIntrExample PASSED
Running QspiSelfTestExample() for ps7_qspi_0...
QspiPsSelfTestExample PASSED
Running ScuTimerPolledExample() for ps7_scutimer_0...
ScuTimerPolledExample PASSED
Running Interrupt Test for ps7_scutimer_0...
ScuTimerIntrExample PASSED
Running Interrupt Test for ps7_scuwdt_0...
ScuWdtIntrExample PASSED
---Exiting main---
```

Figure 25 – Complete Peripheral Test

14. Under the *Debug* tab in the upper left-hand corner, right-click on **Test_Peripherals Debug (SDK Hardware Server)** and select **Relaunch**. Click **Yes**.

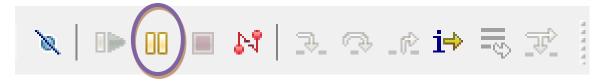


Figure 26 - Relaunch Test_Peripherals Debug

15. Use the *Breakpoints* tab to disable the breakpoint at Line 148. Simply uncheck the box.



16. This time, click Resume, wait a few moments, and then click the Suspend icon, which is the yellow "pause" icon.



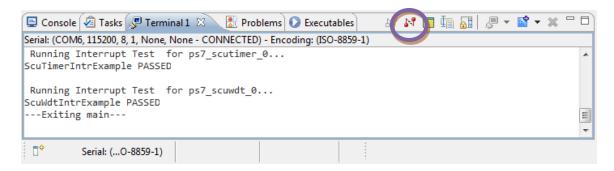
17. If you end up suspended inside one of the other functions, the SDK debugger will open the function with the green bar showing exactly where you are paused. Click the Step Return icon to get back to the testperiph.c. Depending on where you suspended execution, you may have to click the Step Return several times. Click Resume to continue the test.



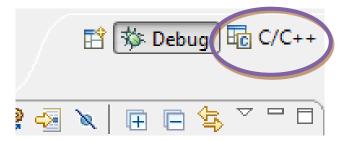
18. Click the Disconnect icon to end the debugging session.



19. Switch to the Terminal tab, and click the Disconnect icon for the COM port.



20. Finally, in the top-right corner of the screen, click the "C/C++" icon to return the SDK to the code editing perspective. Alternatively, to close the Debug perspective, right-click on Debug and select **Close**.





Exploring Further

If you have more time and would like to investigate more...

- Debug the Test_Memory application. Make use of the following debugger features from the **Window** → **Show View** menu.
 - Memory
 - Variables
 - o Registers
- The first Test_Memory application targets the application code at RAM_0. Then, the application also runs a destructive memory test on RAM_0. How is that possible? Can you prove it?

This concludes Lab 5.

Revision History

Date	Version	Revision
12 Nov 13	01	Initial release
23 Nov 13	02	Revisions after pilot
01 May 14	03	ZedBoard.org Training Course Release



Answers

Experiment 1

- For what can the JTAG interface be used?
 - 1. Read and write ARM registers
 - 2. Configure the PL with a bitstream
 - 3. Program attached QSPI Flash
 - 4. Upload application code to on-chip RAM or DDR3
 - 5. Application debug
- Under what conditions must the hardware platform first be downloaded into the PL?

If the application only uses the Zynq PS, then programming the PL is not necessary. If the application makes use of something in the PL, then the PL must be programmed first. Unlike an off-the-shelf microprocessor with all built-in peripherals, the Zynq SoC starts out with the PL as a blank hardware device. The hardware identity, or bitstream, must be first downloaded to the PL. Any PL peripherals or co-processors don't exist in the PL until after the hardware platform bitstream is configured to the PL.

Experiment 2

- How does the ARM get initialized when running an application from SDK?
 ps7 init.tcl that was provided with the hardware platform
- How much memory is tested by default?

4 KB



Troubleshooting

Any Windows Security Alerts will cause issues. Click Allow Access, reboot, then retry. Hopefully this will not affect anyone since we are covering this in Lab 0.

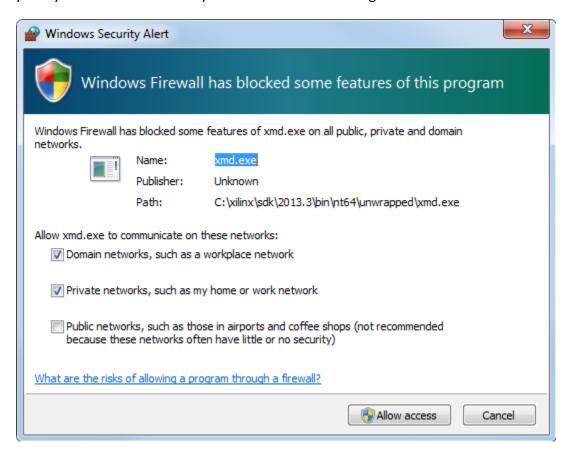


Figure 27 – Windows Security Alert

