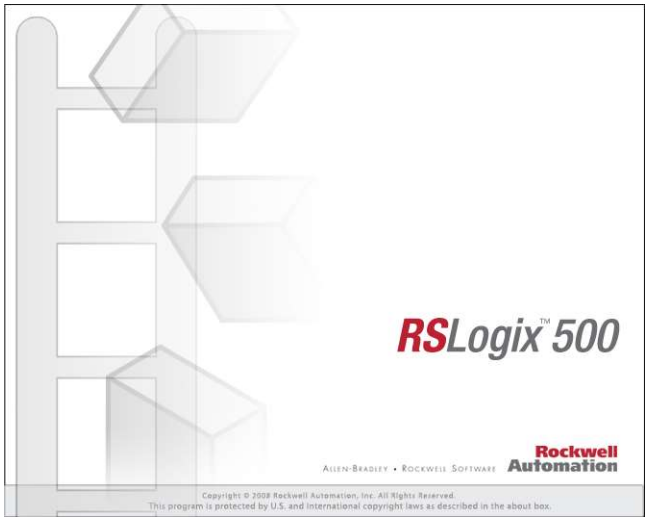
RSLogix Micro Project Report



Processor Information

Processor Type: Bul.1763 MicroLogix 1100 Series B

Processor Name: UNTITLED

Total Memory Used: 279 Instruction Words Used - 52 Data Table Words Used

Total Memory Left: 6377 Instruction Words Left

Program Files: 6

Data Files: 9

Program ID: 3187

I/O Configuration

0	Bul.1763	MicroLogix 1100 Series B
1		
2		
3		
4		

Channel Configuration

CHANNEL 0 (SYSTEM) - Driver: DF1 Full Duplex
CHANNEL 0 (SYSTEM) - Driver: DF1 Full Duplex Edit Resource/Owner Timeout: 60
CHANNEL 0 (SYSTEM) - Driver: DF1 Full Duplex Passthru Link ID: 1
CHANNEL 0 (SYSTEM) - Driver: DF1 Full Duplex Write Protected: No
CHANNEL 0 (SYSTEM) - Driver: DF1 Full Duplex Comms Servicing Selection: Yes
CHANNEL 0 (SYSTEM) - Driver: DF1 Full Duplex Message Servicing Selection: Yes
CHANNEL 0 (SYSTEM) - Driver: DF1 Full Duplex 1st AWA Append Character: \d
CHANNEL 0 (SYSTEM) - Driver: DF1 Full Duplex 2nd AWA Append Character: \a

Source ID: 1 (decimal)
Baud: 19200
Parity: NONE
Control Line : No Handshaking
Error Detection: CRC
Embedded Responses: Auto Detect
Duplicate Packet Detect: Yes
ACK Timeout(x20 ms): 50
NAK Retries: 3
ENQ Retries: 3

CHANNEL 1 (SYSTEM) - Driver: Ethernet
CHANNEL 1 (SYSTEM) - Driver: Ethernet Edit Resource/Owner Timeout: 60
CHANNEL 1 (SYSTEM) - Driver: Ethernet Passthru Link ID: 1
CHANNEL 1 (SYSTEM) - Driver: Ethernet Write Protected: No
CHANNEL 1 (SYSTEM) - Driver: Ethernet Comms Servicing Selection: Yes
CHANNEL 1 (SYSTEM) - Driver: Ethernet Message Servicing Selection: Yes

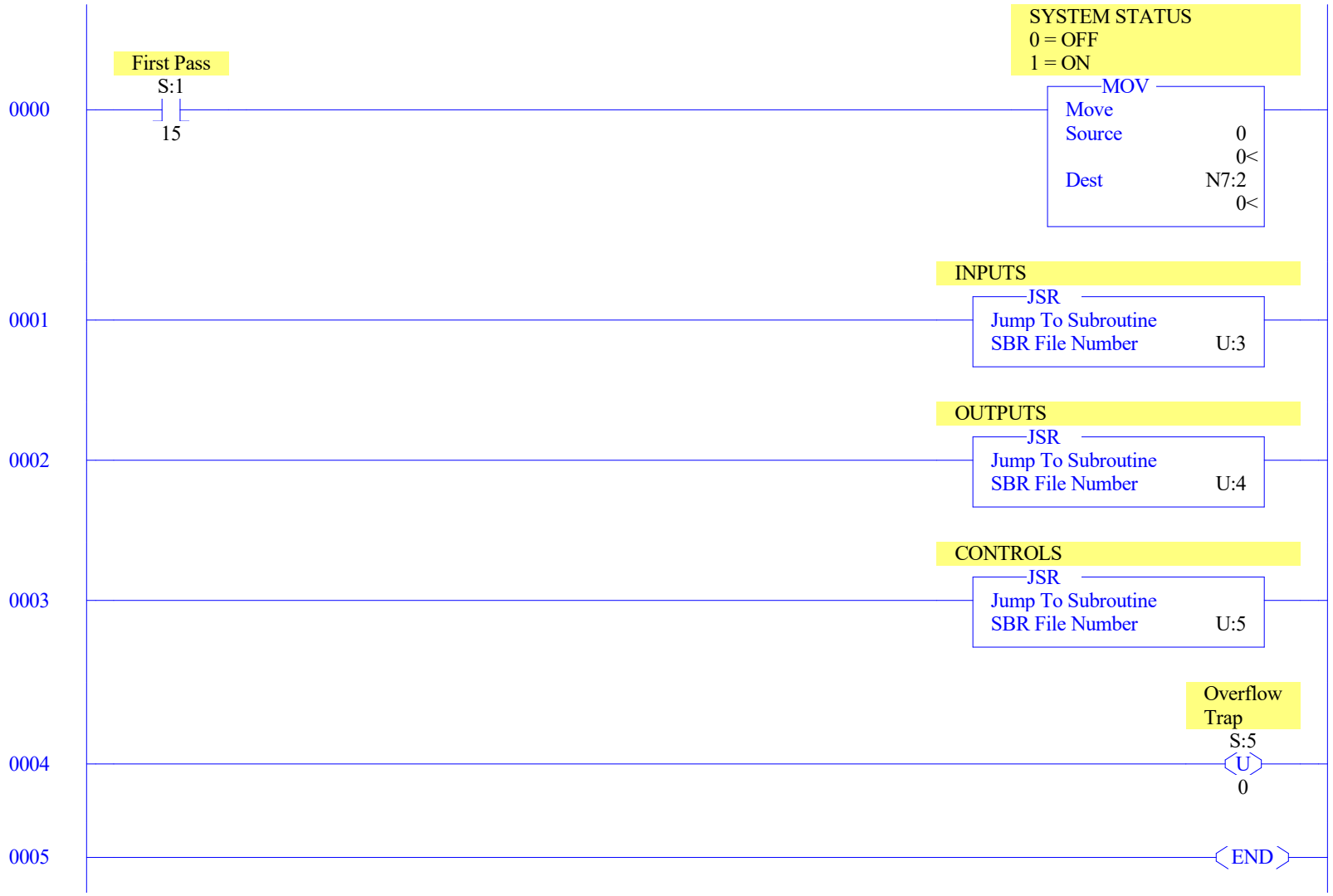
Hardware Address: 00:00:00:00:00:00
IP Address: 0.0.0.0
Subnet Mask: 0.0.0.0
Gateway Address: 0.0.0.0
Msg Connection Timeout (x 1mS): 15000
Msg Reply Timeout (x mS): 3000
Inactivity Timeout (x Min): 30
Bootp Enable: Yes
Dhcp Enable No
SNMP Enable: No
HTTP Enable: Yes
Auto Negotiate Enable: Yes
Port Speed Enable: 10/100 Mbps Full Duplex/Half Duplex
Contact:
Location:

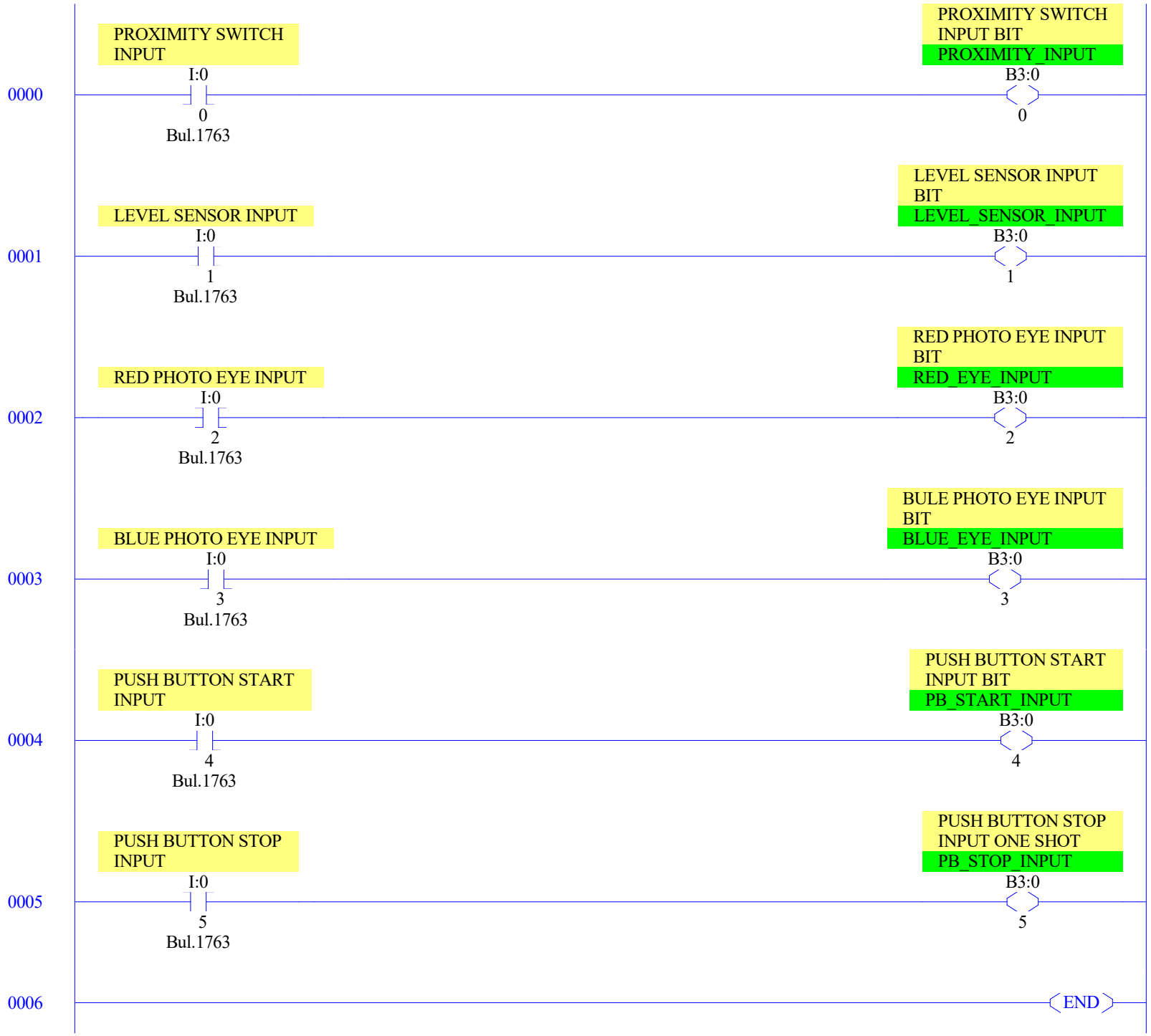
Program File List

Name	Number	Type	Rungs	Debug	Bytes
[SYSTEM]	0	SYS	0	No	0
	1	SYS	0	No	0
MAIN	2	LADDER	6	No	61
INPUTS	3	LADDER	7	No	99
OUTPUTS	4	LADDER	4	No	51
CONTROLS	5	LADDER	16	No	894

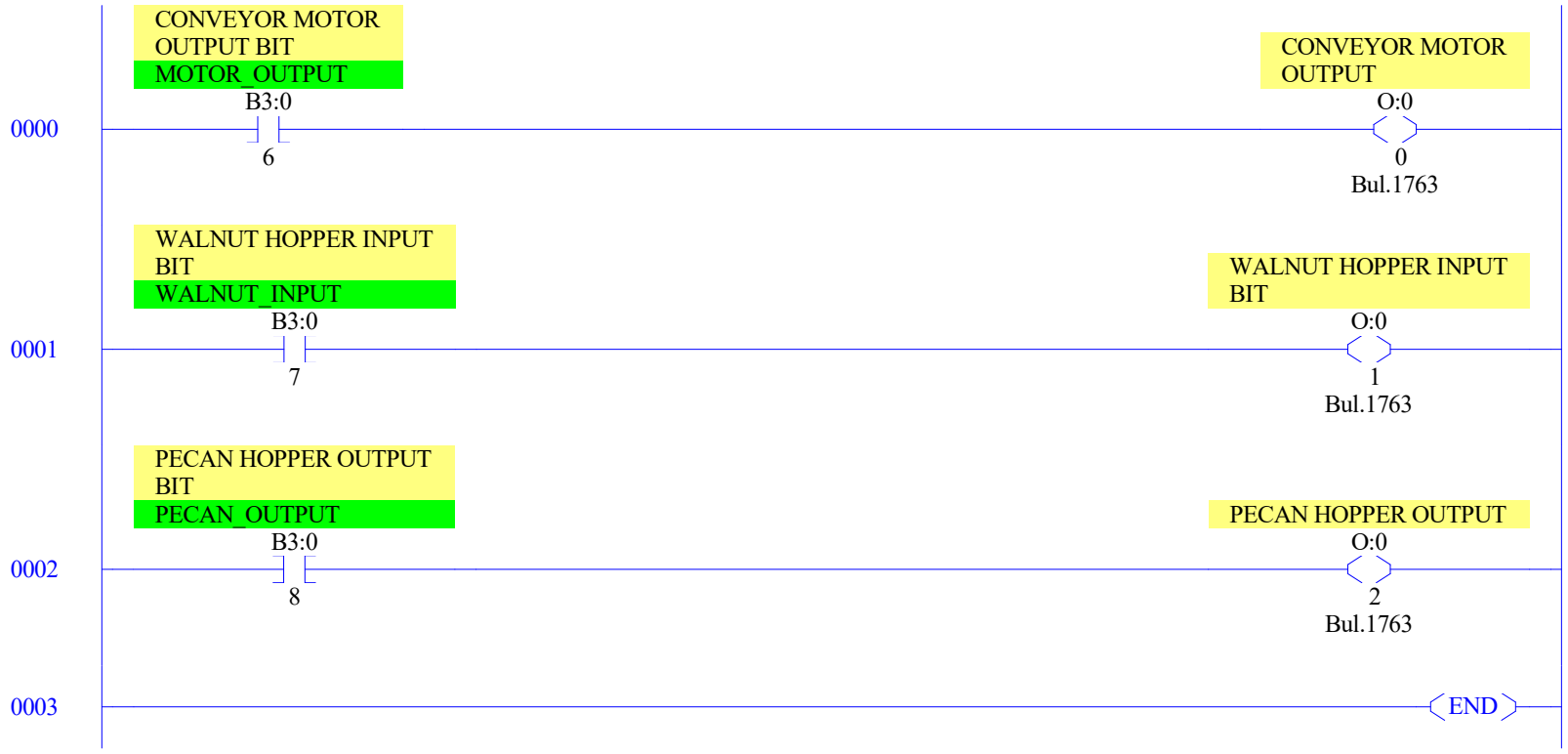
Data File List

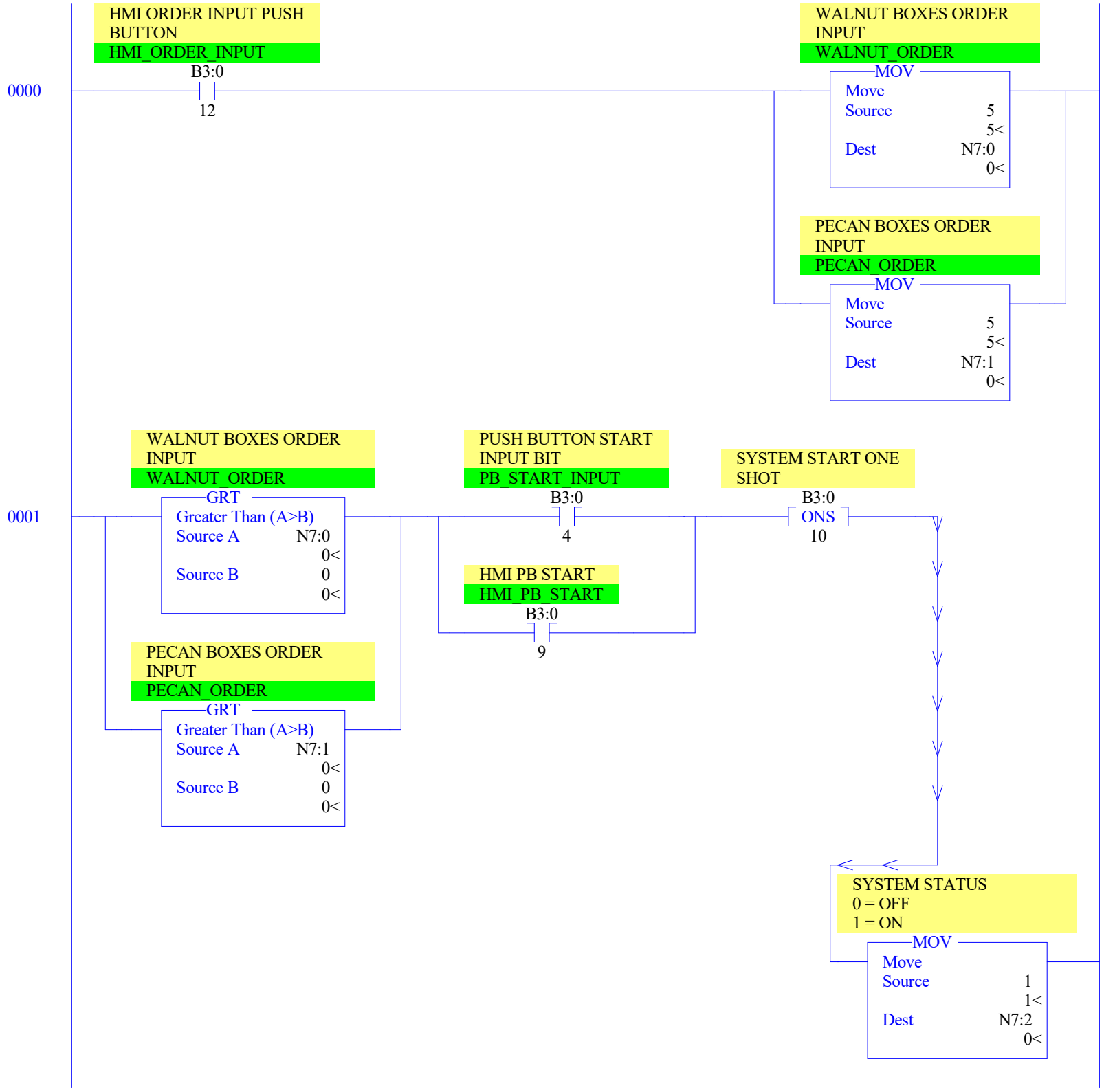
Name	Number	Type	Scope	Debug	Words	Elements	Last
OUTPUT	0	O	Global	No	12	4	O:3
INPUT	1	I	Global	No	18	6	I:5
STATUS	2	S	Global	No	0	66	S:65
BINARY	3	B	Global	No	2	2	B3:1
TIMER	4	T	Global	No	9	3	T4:2
COUNTER	5	C	Global	No	3	1	C5:0
CONTROL	6	R	Global	No	3	1	R6:0
INTEGER	7	N	Global	No	3	3	N7:2
FLOAT	8	F	Global	No	2	1	F8:0

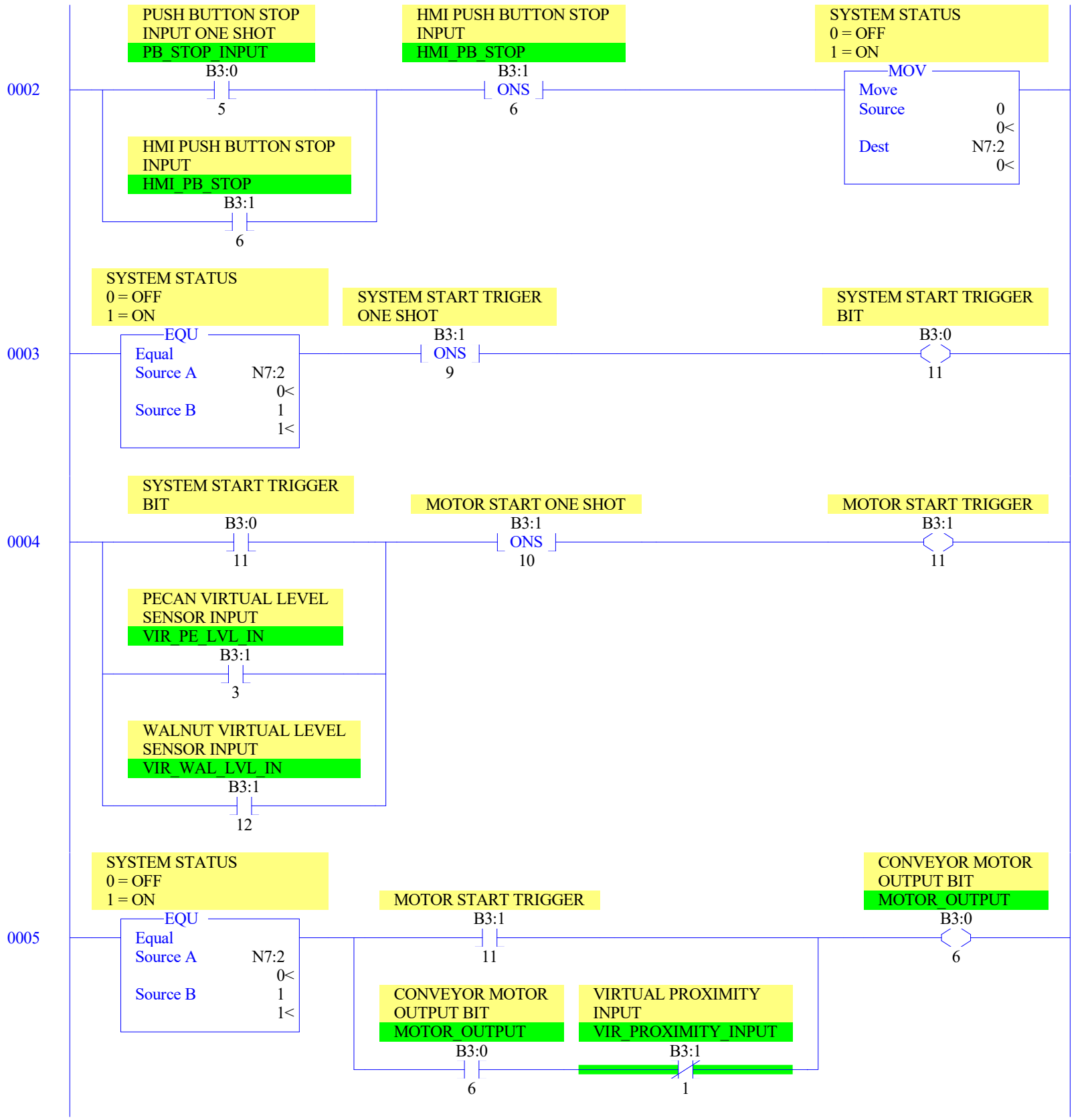

SYSTEM STATUS
0 = OFF
1 = ON
First Pass
S:1
15
0000
MOV
Move
Source 0
0<
Dest N7:2
0<
INPUTS
0001
JSR
Jump To Subroutine
SBR File Number U:3
OUTPUTS
0002
JSR
Jump To Subroutine
SBR File Number U:4
CONTROLS
0003
JSR
Jump To Subroutine
SBR File Number U:5
Overflow
Trap
S:5
0004
U
0
0005
END

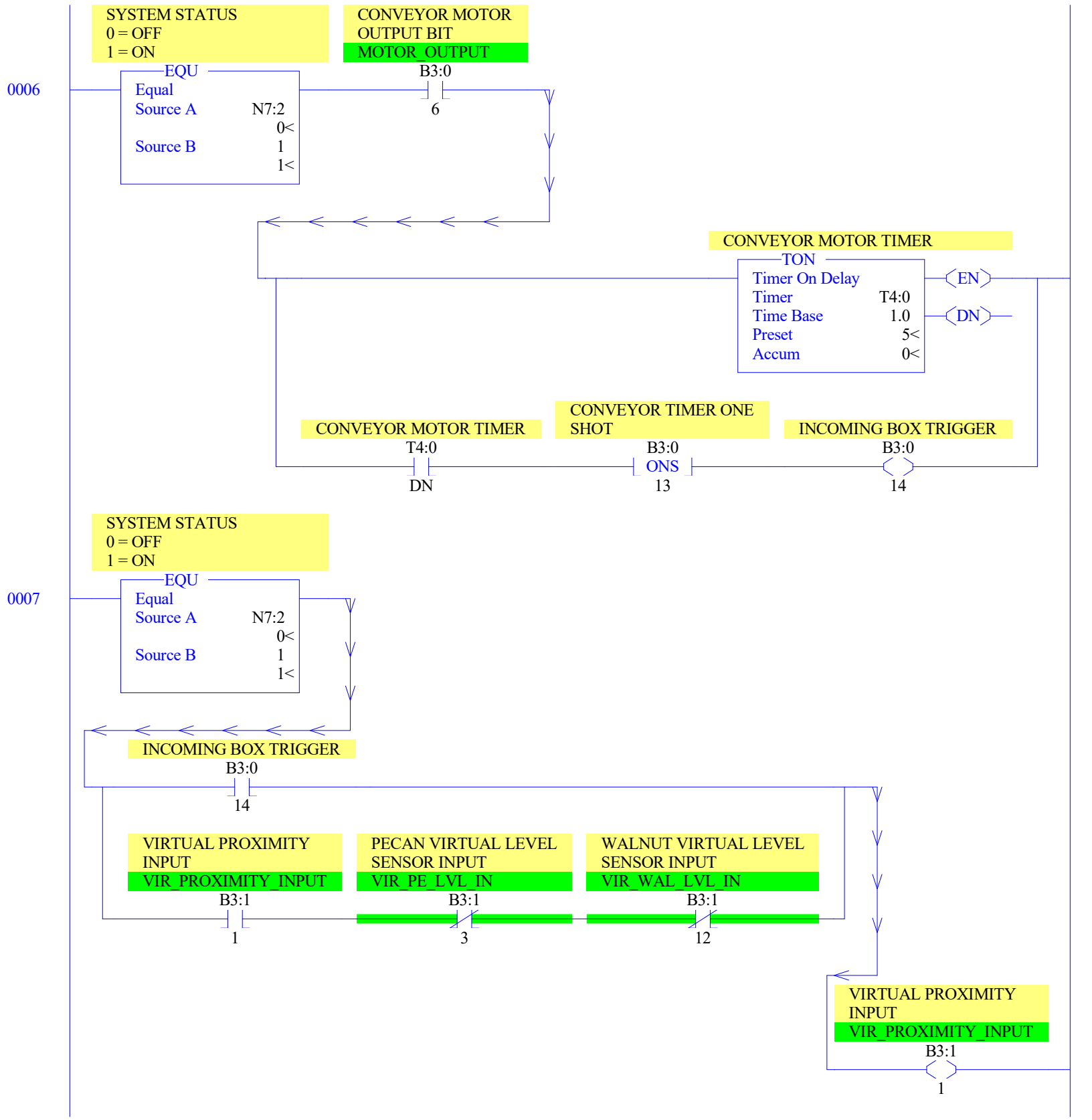

PROXIMITY SWITCH INPUT
I:0
0
Bul.1763
PROXIMITY SWITCH INPUT BIT
PROXIMITY_INPUT
B3:0
0
0000
LEVEL SENSOR INPUT
I:0
1
Bul.1763
LEVEL SENSOR INPUT BIT
LEVEL_SENSOR_INPUT
B3:0
1
0001
RED PHOTO EYE INPUT
I:0
2
Bul.1763
RED PHOTO EYE INPUT BIT
RED_EYE_INPUT
B3:0
2
0002
BLUE PHOTO EYE INPUT
I:0
3
Bul.1763
BULE PHOTO EYE INPUT BIT
BLUE_EYE_INPUT
B3:0
3
0003
PUSH BUTTON START INPUT
I:0
4
Bul.1763
PUSH BUTTON START INPUT BIT
PB_START_INPUT
B3:0
4
0004
PUSH BUTTON STOP INPUT
I:0
5
Bul.1763
PUSH BUTTON STOP INPUT ONE SHOT
PB_STOP_INPUT
B3:0
5
0005
END
0006

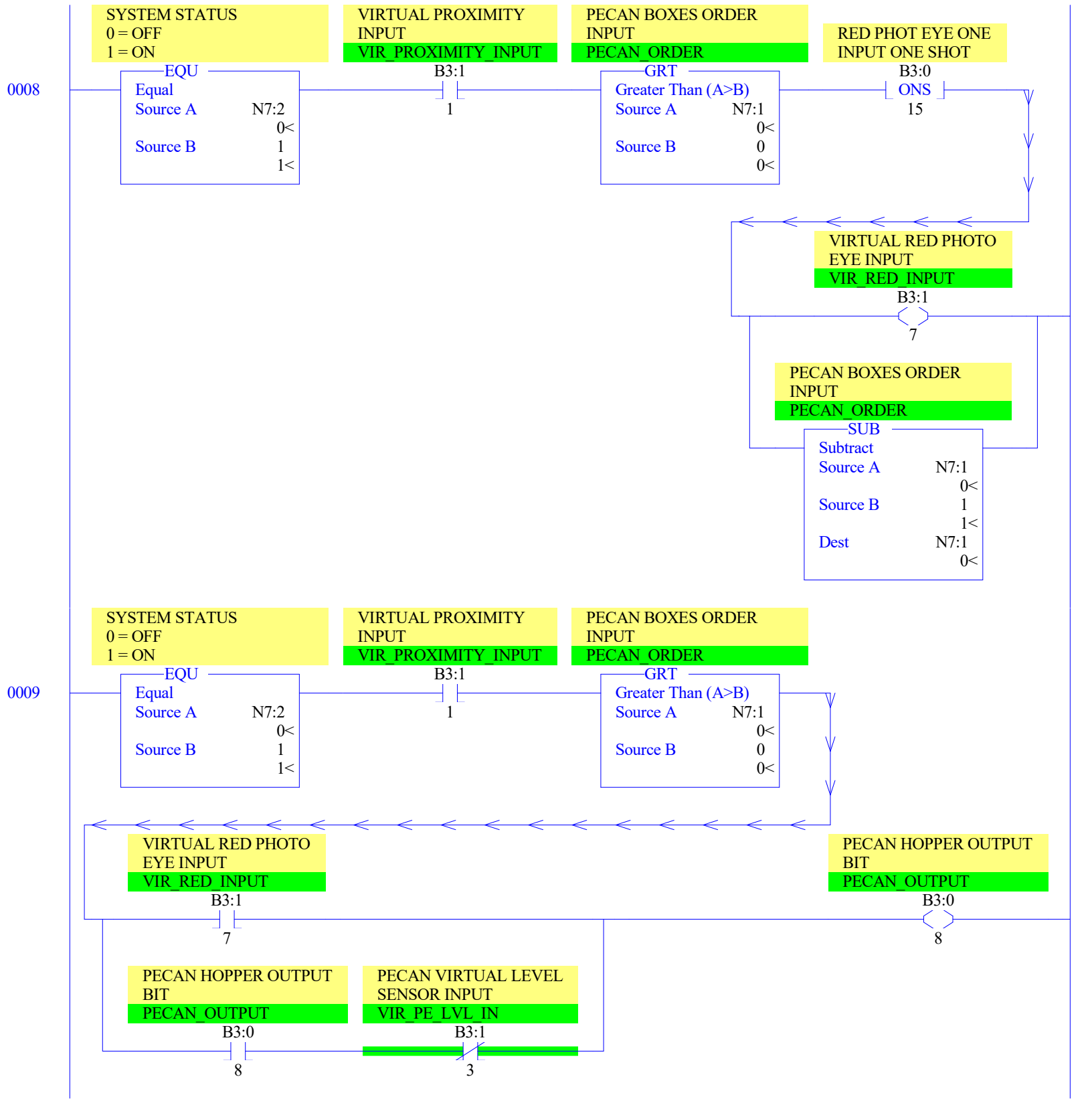
LAD 4 - OUTPUTS --- Total Rungs in File = 4

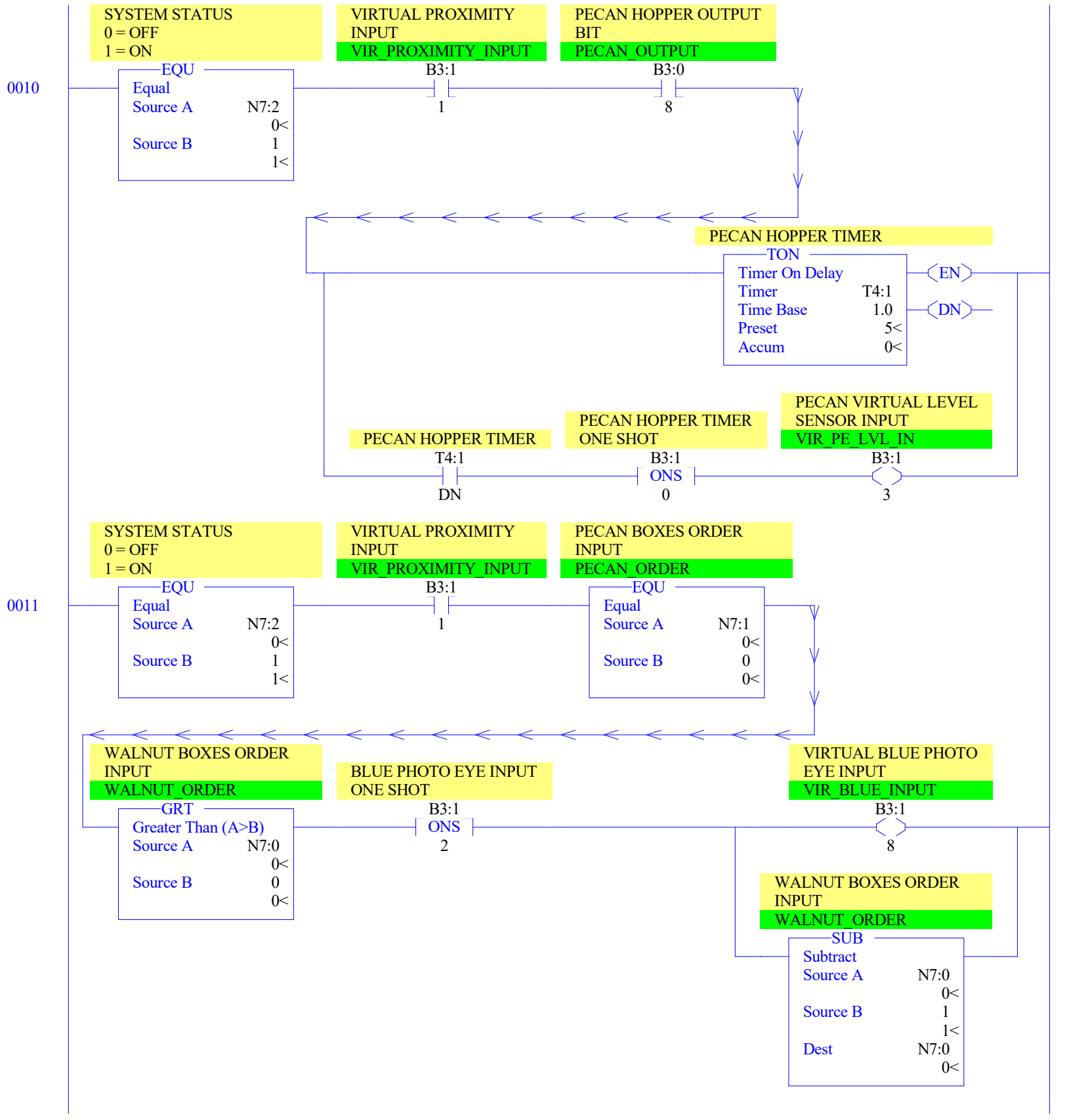


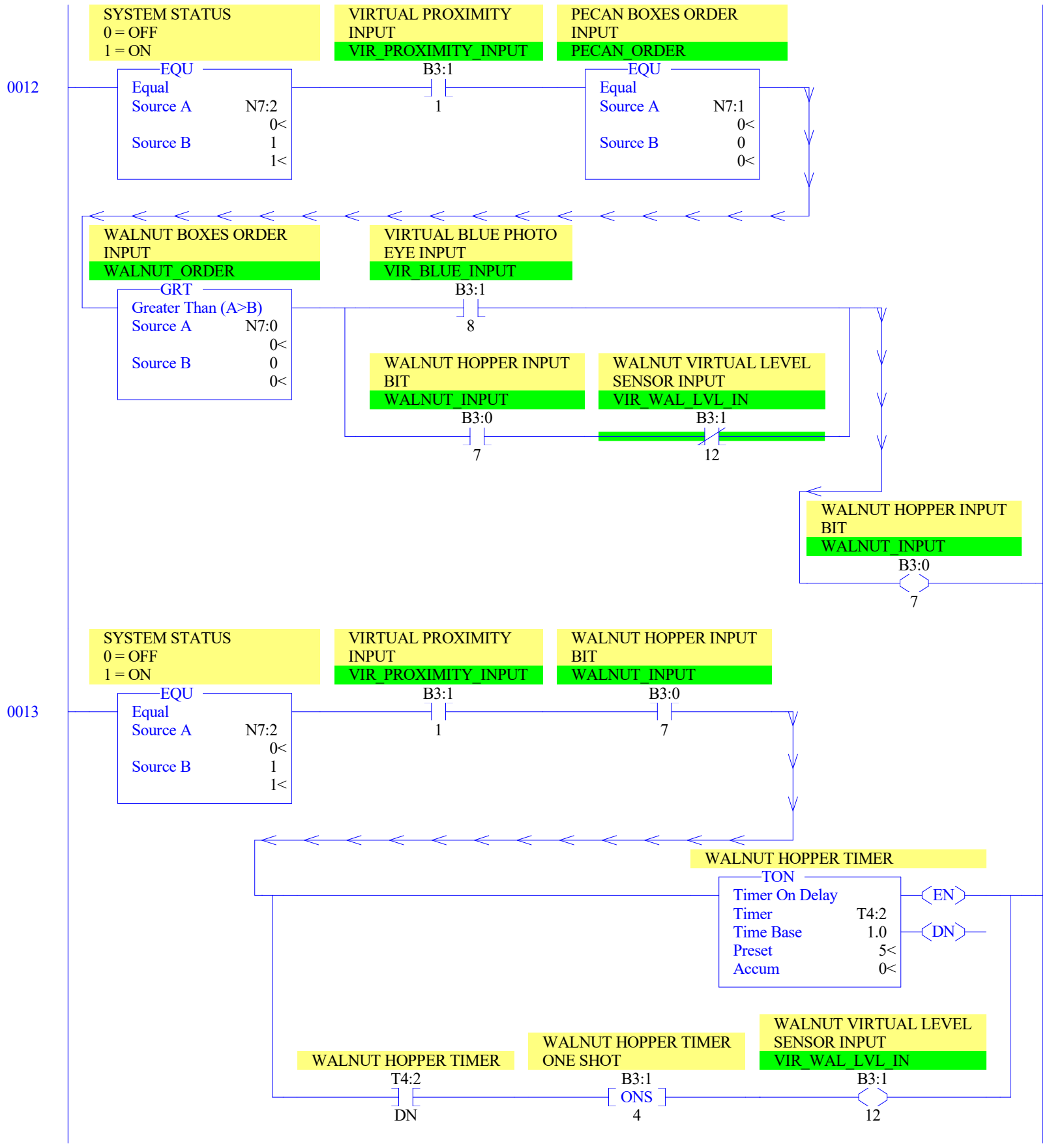

HMI ORDER INPUT PUSH BUTTON
HMI_ORDER_INPUT
B3:0
12
0000
WALNUT BOXES ORDER INPUT
WALNUT_ORDER
MOV
Move
Source 5
5<
Dest N7:0
0<
PECAN BOXES ORDER INPUT
PECAN_ORDER
MOV
Move
Source 5
5<
Dest N7:1
0<
WALNUT BOXES ORDER INPUT
WALNUT_ORDER
GRT
Greater Than (A>B)
Source A N7:0
0<
Source B 0
0<
PECAN BOXES ORDER INPUT
PECAN_ORDER
GRT
Greater Than (A>B)
Source A N7:1
0<
Source B 0
0<
0001
PUSH BUTTON START INPUT BIT
PB_START_INPUT
B3:0
4
HMI PB START
HMI_PB_START
B3:0
9
SYSTEM START ONE SHOT
B3:0
ONS
10
SYSTEM STATUS
0 = OFF
1 = ON
MOV
Move
Source 1
1<
Dest N7:2
0<

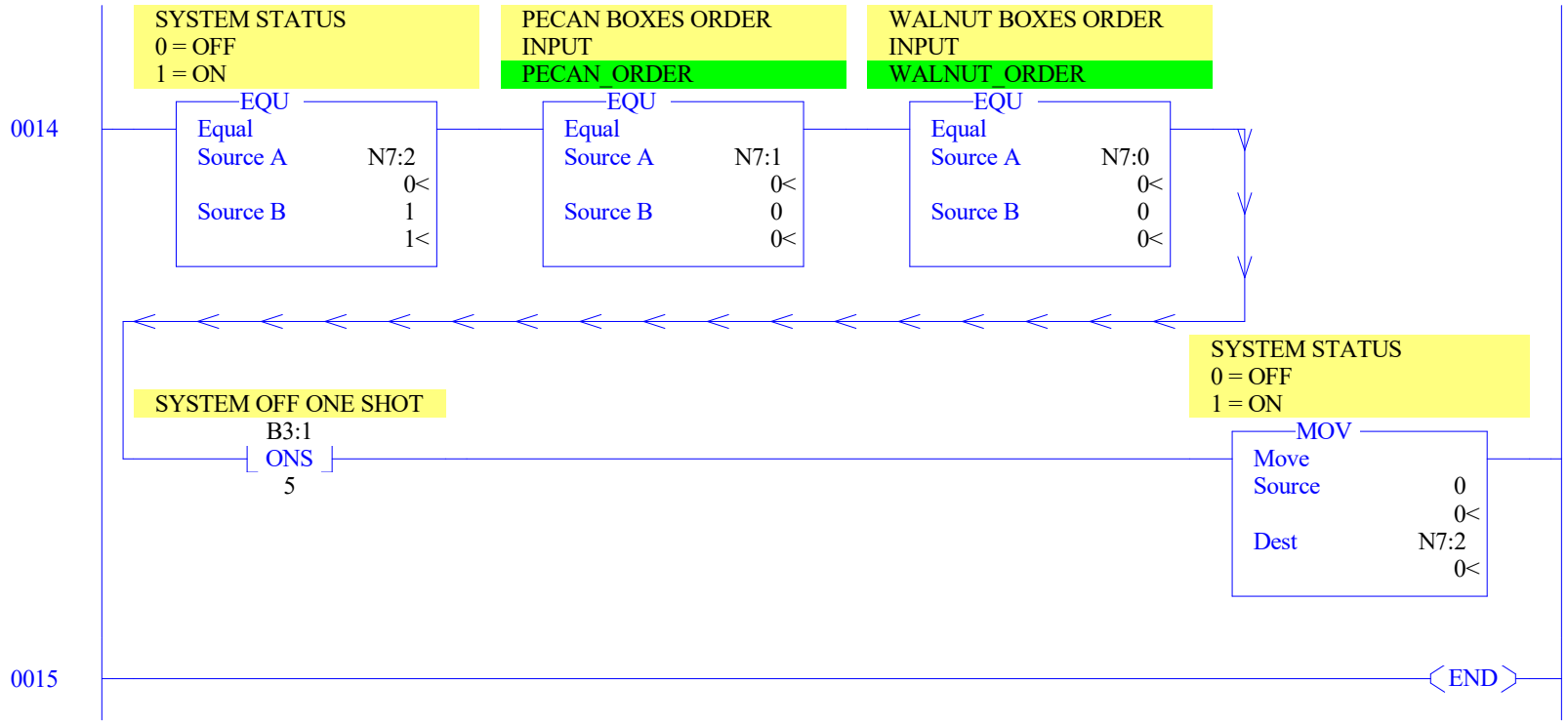

PUSH BUTTON STOP INPUT ONE SHOT
PB_STOP_INPUT
B3:0
5
HMI PUSH BUTTON STOP INPUT
HMI_PB_STOP
B3:1
ONS
6
SYSTEM STATUS
0 = OFF
1 = ON
MOV
Move
Source 0
0<
Dest N7:2
0<
0002
HMI PUSH BUTTON STOP INPUT
HMI_PB_STOP
B3:1
6
SYSTEM STATUS
0 = OFF
1 = ON
EQU
Equal
Source A N7:2
0<
Source B 1
1<
SYSTEM START TRIGER ONE SHOT
B3:1
ONS
9
SYSTEM START TRIGGER BIT
B3:0
11
0003
SYSTEM START TRIGGER BIT
B3:0
11
MOTOR START ONE SHOT
B3:1
ONS
10
MOTOR START TRIGGER
B3:1
11
0004
PECAN VIRTUAL LEVEL SENSOR INPUT
VIR_PE_LVL_IN
B3:1
3
WALNUT VIRTUAL LEVEL SENSOR INPUT
VIR_WAL_LVL_IN
B3:1
12
SYSTEM STATUS
0 = OFF
1 = ON
EQU
Equal
Source A N7:2
0<
Source B 1
1<
MOTOR START TRIGGER
B3:1
11
CONVEYOR MOTOR OUTPUT BIT
MOTOR_OUTPUT
B3:0
6
0005
CONVEYOR MOTOR OUTPUT BIT
MOTOR_OUTPUT
B3:0
6
VIRTUAL PROXIMITY INPUT
VIR_PROXIMITY_INPUT
B3:1
1


SYSTEM STATUS
0 = OFF
1 = ON
EQU
Equal
Source A N7:2
0<
Source B 1
1<
CONVEYOR MOTOR OUTPUT BIT
MOTOR_OUTPUT
B3:0
6
0006
CONVEYOR MOTOR TIMER
TON
Timer On Delay
Timer T4:0
Time Base 1.0
Preset 5<
Accum 0<
EN
DN
CONVEYOR MOTOR TIMER
T4:0
DN
CONVEYOR TIMER ONE SHOT
B3:0
ONS
13
INCOMING BOX TRIGGER
B3:0
14
SYSTEM STATUS
0 = OFF
1 = ON
EQU
Equal
Source A N7:2
0<
Source B 1
1<
0007
INCOMING BOX TRIGGER
B3:0
14
VIRTUAL PROXIMITY INPUT
VIR_PROXIMITY_INPUT
B3:1
1
PECAN VIRTUAL LEVEL SENSOR INPUT
VIR_PE_LVL_IN
B3:1
3
WALNUT VIRTUAL LEVEL SENSOR INPUT
VIR_WAL_LVL_IN
B3:1
12
VIRTUAL PROXIMITY INPUT
VIR_PROXIMITY_INPUT
B3:1
1


SYSTEM STATUS
0 = OFF
1 = ON
EQU
Equal
Source A N7:2 0<
Source B 1 1<
VIRTUAL PROXIMITY INPUT
VIR_PROXIMITY_INPUT
B3:1
1
PECAN BOXES ORDER INPUT
PECAN_ORDER
GRT
Greater Than (A>B)
Source A N7:1 0<
Source B 0 0<
RED PHOT EYE ONE INPUT ONE SHOT
B3:0
ONS
15
0008
VIRTUAL RED PHOTO EYE INPUT
VIR_RED_INPUT
B3:1
7
PECAN BOXES ORDER INPUT
PECAN_ORDER
SUB
Subtract
Source A N7:1 0<
Source B 1 1<
Dest N7:1 0<
SYSTEM STATUS
0 = OFF
1 = ON
EQU
Equal
Source A N7:2 0<
Source B 1 1<
VIRTUAL PROXIMITY INPUT
VIR_PROXIMITY_INPUT
B3:1
1
PECAN BOXES ORDER INPUT
PECAN_ORDER
GRT
Greater Than (A>B)
Source A N7:1 0<
Source B 0 0<
0009
VIRTUAL RED PHOTO EYE INPUT
VIR_RED_INPUT
B3:1
7
PECAN HOPPER OUTPUT BIT
PECAN_OUTPUT
B3:0
8
PECAN HOPPER OUTPUT BIT
PECAN_OUTPUT
B3:0
8
PECAN VIRTUAL LEVEL SENSOR INPUT
VIR_PE_LVL_IN
B3:1
3


SYSTEM STATUS
0 = OFF
1 = ON
EQU
Equal
Source A N7:2
0<
Source B 1
1<
VIRTUAL PROXIMITY INPUT
VIR_PROXIMITY_INPUT
B3:1
1
PECAN HOPPER OUTPUT BIT
PECAN_OUTPUT
B3:0
8
0010
PECAN HOPPER TIMER
TON
Timer On Delay
Timer T4:1
Time Base 1.0
Preset 5<
Accum 0<
EN
DN
PECAN HOPPER TIMER
T4:1
DN
PECAN HOPPER TIMER ONE SHOT
B3:1
ONS
0
PECAN VIRTUAL LEVEL SENSOR INPUT
VIR_PE_LVL_IN
B3:1
3
SYSTEM STATUS
0 = OFF
1 = ON
EQU
Equal
Source A N7:2
0<
Source B 1
1<
VIRTUAL PROXIMITY INPUT
VIR_PROXIMITY_INPUT
B3:1
1
PECAN BOXES ORDER INPUT
PECAN_ORDER
EQU
Equal
Source A N7:1
0<
Source B 0
0<
0011
WALNUT BOXES ORDER INPUT
WALNUT_ORDER
GRT
Greater Than (A>B)
Source A N7:0
0<
Source B 0
0<
BLUE PHOTO EYE INPUT ONE SHOT
B3:1
ONS
2
VIRTUAL BLUE PHOTO EYE INPUT
VIR_BLUE_INPUT
B3:1
8
WALNUT BOXES ORDER INPUT
WALNUT_ORDER
SUB
Subtract
Source A N7:0
0<
Source B 1
1<
Dest N7:0
0<


SYSTEM STATUS
0 = OFF
1 = ON
EQU
Equal
Source A N7:2
0<
Source B 1
1<
VIRTUAL PROXIMITY INPUT
VIR_PROXIMITY_INPUT
B3:1
1
PECAN BOXES ORDER INPUT
PECAN_ORDER
EQU
Equal
Source A N7:1
0<
Source B 0
0<
0012
WALNUT BOXES ORDER INPUT
WALNUT_ORDER
GRT
Greater Than (A>B)
Source A N7:0
0<
Source B 0
0<
VIRTUAL BLUE PHOTO EYE INPUT
VIR_BLUE_INPUT
B3:1
8
WALNUT HOPPER INPUT BIT
WALNUT_INPUT
B3:0
7
WALNUT VIRTUAL LEVEL SENSOR INPUT
VIR_WAL_LVL_IN
B3:1
12
WALNUT HOPPER INPUT BIT
WALNUT_INPUT
B3:0
7
SYSTEM STATUS
0 = OFF
1 = ON
EQU
Equal
Source A N7:2
0<
Source B 1
1<
VIRTUAL PROXIMITY INPUT
VIR_PROXIMITY_INPUT
B3:1
1
WALNUT HOPPER INPUT BIT
WALNUT_INPUT
B3:0
7
0013
WALNUT HOPPER TIMER
TON
Timer On Delay
Timer T4:2
Time Base 1.0
Preset 5<
Accum 0<
EN
DN
WALNUT HOPPER TIMER
T4:2
DN
WALNUT HOPPER TIMER ONE SHOT
B3:1
ONS
4
WALNUT VIRTUAL LEVEL SENSOR INPUT
VIR_WAL_LVL_IN
B3:1
12


SYSTEM STATUS
0 = OFF
1 = ON
PECAN BOXES ORDER INPUT
PECAN_ORDER
WALNUT BOXES ORDER INPUT
WALNUT_ORDER
0014
EQU
Equal
Source A N7:2 0<
Source B 1 1<
EQU
Equal
Source A N7:1 0<
Source B 0 0<
EQU
Equal
Source A N7:0 0<
Source B 0 0<
SYSTEM OFF ONE SHOT
B3:1
ONS
5
SYSTEM STATUS
0 = OFF
1 = ON
MOV
Move
Source 0 0<
Dest N7:2 0<
0015
END

Data File O0 (bin) -- OUTPUT

Offset	15	14	13	12	11	10	9	8	7	6	5	4	3	2	1	0		
O:0.0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	Bul.1763	MicroLogix 1100 Series B
O:0.1	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	Bul.1763	MicroLogix 1100 Series B
O:0.2	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	Bul.1763	MicroLogix 1100 Series B
O:0.3	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	Bul.1763	MicroLogix 1100 Series B

Data File I1 (bin) -- INPUT

Offset	15	14	13	12	11	10	9	8	7	6	5	4	3	2	1	0		
I:0.0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	Bul.1763	MicroLogix 1100 Series B
I:0.1	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	Bul.1763	MicroLogix 1100 Series B
I:0.2	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	Bul.1763	MicroLogix 1100 Series B
I:0.3	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	Bul.1763	MicroLogix 1100 Series B
I:0.4	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	Bul.1763	MicroLogix 1100 Series B-Analog
I:0.5	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	Bul.1763	MicroLogix 1100 Series B-Analog

Main

Processor Mode S:1/0 - S:1/4 = Remote Program Mode
On Power up Go To Run (Mode Behavior) S:1/12 = 0
First Pass S:1/15 = No
Free Running Clock S:4 = 0000-0000-0000-0000

Proc

OS Catalog Number S:57 = 1100 User Program Type S:63 = 8001h
OS Series S:58 = A Compiler Revision Number S:64 =
OS FRS S:59 =
Processor Catalog Number S:60 =
Processor Series S:61 = A
Processor FRN S:62 =

Scan Times

Maximum (x10 ms) S:22 = 0
Watchdog (x10 ms) S:3 (high byte) = 10
Last 100 uSec Scan Time S:35 = 0
Scan Toggle Bit S:33/9 = 0

Math

Math Overflow Selected S:2/14 = 0 Math Register (lo word) S:13 = 0
Overflow Trap S:5/0 = 0 Math Register (high word) S:14-S:13 = 0
Carry S:0/0 = 0 Math Register (32 Bit) S:14-S:13 = 0
Overflow S:0/1 = 0
Zero Bit S:0/2 = 0
Sign Bit S:0/3 = 0

Chan 0

Processor Mode S:1/0- S:1/4 = Remote Program Mode
Node Address S:15 (low byte) = 0 Outgoing Msg Cmd Pending S:33/2 = 0
Baud Rate S:15 (high byte) = ?
Channel Mode S:33/3 = 0
Comms Active S:33/4 = 0
Incoming Cmd Pending S:33/0 = 0
Msg Reply Pending S:33/1 = 0

Debug

Suspend Code S:7 = 0
Suspend File S:8 = 0

Errors

Fault Override At Power Up S:1/8 = 0 Fault Routine S:29 = 0
Startup Protection Fault S:1/9 = 0 Major Error S:6 = 0h
Major Error Halt S:1/13 = 0
Overflow Trap S:5/0 = 0 Error Description:
Control Register Error S:5/2 = 0
Major Error Executing User Fault Rtn. S:5/3 = 0
Battery Low S:5/11 = 0
Input Filter Selection Modified S:5/13 = 0
ASCII String Manipulation error S:5/15 = 0

Protection

Deny Future Access S:1/14 = No
Data File Overwrite Protection Lost S:36/10 = False

Mem Module

Memory Module Loaded On Boot S:5/8 = 0
Password Mismatch S:5/9 = 0
Load Memory Module On Memory Error S:1/10 = 0
Load Memory Module Always S:1/11 = 0
On Power up Go To Run (Mode Behavior) S:1/12 = 0
Program Compare S:2/9 = 0
Data File Overwrite Protection Lost S:36/10 = 0

Forces

Forces Enabled S:1/5 = Yes
Forces Installed S:1/6 = No

Data File B3 (bin) -- BINARY

Offset	15	14	13	12	11	10	9	8	7	6	5	4	3	2	1	0	(Symbol) Description
B3:0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	
B3:1	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	

Data File T4 -- TIMER

Offset	EN	TT	DN	BASE	PRE	ACC	(Symbol) Description
T4:0	0	0	0	1.0 sec	5	0	CONVEYOR MOTOR TIMER
T4:1	0	0	0	1.0 sec	5	0	PECAN HOPPER TIMER
T4:2	0	0	0	1.0 sec	5	0	WALNUT HOPPER TIMER

Data File C5 -- COUNTER

Offset	CU	CD	DN	OV	UN	UA	PRE	ACC	(Symbol)	Description
C5:0	0	0	0	0	0	0	0	0		

Data File R6 -- CONTROL

Offset	EN	EU	DN	EM	ER	UL	IN	FD	LEN	POS	(Symbol)	Description
R6:0	0	0	0	0	0	0	0	0	0	0		

Data File N7 (dec) -- INTEGER

Offset	0	1	2	3	4	5	6	7	8	9
N7:0	0	0	0							

Data File F8 -- FLOAT

Offset	0	1	2	3	4
F8:0	0				

Address/Symbol Database

Address	Symbol	Scope	Description	Sym Group	Dev. Code	ABV
B3:0/0	PROXIMITY_INPUT	Global	PROXIMITY SWITCH INPUT BIT			
B3:0/1	LEVEL_SENSOR_INPUT	Global	LEVEL SENSOR INPUT BIT			
B3:0/2	RED_EYE_INPUT	Global	RED PHOTO EYE INPUT BIT			
B3:0/3	BLUE_EYE_INPUT	Global	BULE PHOTO EYE INPUT BIT			
B3:0/4	PB_START_INPUT	Global	PUSH BUTTON START INPUT BIT			
B3:0/5	PB_STOP_INPUT	Global	PUSH BUTTON STOP INPUT ONE SHOT			
B3:0/6	MOTOR_OUTPUT	Global	CONVEYOR MOTOR OUTPUT BIT			
B3:0/7	WALNUT_INPUT	Global	WALNUT HOPPER INPUT BIT			
B3:0/8	PECAN_OUTPUT	Global	PECAN HOPPER OUTPUT BIT			
B3:0/9	HMI_PB_START	Global	HMI PB START			
B3:0/10			SYSTEM START ONE SHOT			
B3:0/11			SYSTEM START TRIGGER BIT			
B3:0/12	HMI_ORDER_INPUT	Global	HMI ORDER INPUT PUSH BUTTON			
B3:0/13			CONVEYOR TIMER ONE SHOT			
B3:0/14			INCOMING BOX TRIGGER			
B3:0/15			RED PHOT EYE ONE INPUT ONE SHOT			
B3:1/0			PECAN HOPPER TIMER ONE SHOT			
B3:1/1	VIR_PROXIMITY_INPUT	Global	VIRTUAL PROXIMITY INPUT			
B3:1/2			BLUE PHOTO EYE INPUT ONE SHOT			
B3:1/3	VIR_PE_LVL_IN	Global	PECAN VIRTUAL LEVEL SENSOR INPUT			
B3:1/4			WALNUT HOPPER TIMER ONE SHOT			
B3:1/5			SYSTEM OFF ONE SHOT			
B3:1/6	HMI_PB_STOP	Global	HMI PUSH BUTTON STOP INPUT			
B3:1/7	VIR_RED_INPUT	Global	VIRTUAL RED PHOTO EYE INPUT			
B3:1/8	VIR_BLUE_INPUT	Global	VIRTUAL BLUE PHOTO EYE INPUT			
B3:1/9			SYSTEM START TRIGER ONE SHOT			
B3:1/10			MOTOR START ONE SHOT			
B3:1/11			MOTOR START TRIGGER			
B3:1/12	VIR_WAL_LVL_IN	Global	WALNUT VIRTUAL LEVEL SENSOR INPUT			
I:0/0			PROXIMITY SWITCH INPUT			
I:0/1			LEVEL SENSOR INPUT			
I:0/2			RED PHOTO EYE INPUT			
I:0/3			BLUE PHOTO EYE INPUT			
I:0/4			PUSH BUTTON START INPUT			
I:0/5			PUSH BUTTON STOP INPUT			
N7:0	WALNUT_ORDER	Global	WALNUT BOXES ORDER INPUT			
N7:1	PECAN_ORDER	Global	PECAN BOXES ORDER INPUT			
N7:2			SYSTEM STATUS 0 = OFF 1 = ON			
O:0/0			CONVEYOR MOTOR OUTPUT			
O:0/1			WALNUT HOPPER INPUT BIT			
O:0/2			PECAN HOPPER OUTPUT			
S:0			Arithmetic Flags			
S:0/0			Processor Arithmetic Carry Flag			
S:0/1			Processor Arithmetic Underflow/ Overflow Flag			
S:0/2			Processor Arithmetic Zero Flag			
S:0/3			Processor Arithmetic Sign Flag			
S:1			Processor Mode Status/ Control			
S:1/0			Processor Mode Bit 0			
S:1/1			Processor Mode Bit 1			
S:1/2			Processor Mode Bit 2			
S:1/3			Processor Mode Bit 3			
S:1/4			Processor Mode Bit 4			
S:1/5			Forces Enabled			
S:1/6			Forces Present			
S:1/7			Comms Active			
S:1/8			Fault Override at Powerup			
S:1/9			Startup Protection Fault			
S:1/10			Load Memory Module on Memory Error			
S:1/11			Load Memory Module Always			
S:1/12			Load Memory Module and RUN			
S:1/13			Major Error Halted			
S:1/14			Access Denied			
S:1/15			First Pass			
S:2/0			STI Pending			
S:2/1			STI Enabled			
S:2/2			STI Executing			
S:2/3			Index Addressing File Range			
S:2/4			Saved with Debug Single Step			
S:2/5			DH-485 Incoming Command Pending			
S:2/6			DH-485 Message Reply Pending			
S:2/7			DH-485 Outgoing Message Command Pending			
S:2/15			Comms Servicing Selection			
S:3			Current Scan Time/ Watchdog Scan Time			
S:4			Time Base			
S:5/0			Overflow Trap			
S:5/2			Control Register Error			
S:5/3			Major Err Detected Executing UserFault Routine			
S:5/4			M0-M1 Referenced on Disabled Slot			
S:5/8			Memory Module Boot			
S:5/9			Memory Module Password Mismatch			
S:5/10			STI Overflow			
S:5/11			Battery Low			
S:6			Major Error Fault Code			
S:7			Suspend Code			

Address/Symbol Database

Address	Symbol	Scope	Description	Sym Group	Dev. Code	ABV
S:8			Suspend File			
S:9			Active Nodes			
S:10			Active Nodes			
S:11			I/O Slot Enables			
S:12			I/O Slot Enables			
S:13			Math Register			
S:14			Math Register			
S:15			Node Address/ Baud Rate			
S:16			Debug Single Step Rung			
S:17			Debug Single Step File			
S:18			Debug Single Step Breakpoint Rung			
S:19			Debug Single Step Breakpoint File			
S:20			Debug Fault/ Powerdown Rung			
S:21			Debug Fault/ Powerdown File			
S:22			Maximum Observed Scan Time			
S:23			Average Scan Time			
S:24			Index Register			
S:25			I/O Interrupt Pending			
S:26			I/O Interrupt Pending			
S:27			I/O Interrupt Enabled			
S:28			I/O Interrupt Enabled			
S:29			User Fault Routine File Number			
S:30			STI Setpoint			
S:31			STI File Number			
S:32			I/O Interrupt Executing			
S:33			Extended Proc Status Control Word			
S:33/0			Incoming Command Pending			
S:33/1			Message Reply Pending			
S:33/2			Outgoing Message Command Pending			
S:33/3			Selection Status User/DF1			
S:33/4			Communicat Active			
S:33/5			Communicat Servicing Selection			
S:33/6			Message Servicing Selection Channel 0			
S:33/7			Message Servicing Selection Channel 1			
S:33/8			Interrupt Latency Control Flag			
S:33/9			Scan Toggle Flag			
S:33/10			Discrete Input Interrupt Reconfigur Flag			
S:33/11			Online Edit Status			
S:33/12			Online Edit Status			
S:33/13			Scan Time Timebase Selection			
S:33/14			DTR Control Bit			
S:33/15			DTR Force Bit			
S:34			Pass-thru Disabled			
S:34/0			Pass-Thru Disabled Flag			
S:34/1			DH+ Active Node Table Enable Flag			
S:34/2			Floating Point Math Flag Disable,Fl			
S:35			Last 1 ms Scan Time			
S:36			Extended Minor Error Bits			
S:36/8			DII Lost			
S:36/9			STI Lost			
S:36/10			Memory Module Data File Overwrite Protection			
S:37			Clock Calendar Year			
S:38			Clock Calendar Month			
S:39			Clock Calendar Day			
S:40			Clock Calendar Hours			
S:41			Clock Calendar Minutes			
S:42			Clock Calendar Seconds			
S:43			STI Interrupt Time			
S:44			I/O Event Interrupt Time			
S:45			DII Interrupt Time			
S:46			Discrete Input Interrupt- File Number			
S:47			Discrete Input Interrupt- Slot Number			
S:48			Discrete Input Interrupt- Bit Mask			
S:49			Discrete Input Interrupt- Compare Value			
S:50			Processor Catalog Number			
S:51			Discrete Input Interrupt- Return Number			
S:52			Discrete Input Interrupt- Accumulat			
S:53			Reserved/ Clock Calendar Day of the Week			
S:55			Last DII Scan Time			
S:56			Maximum Observed DII Scan Time			
S:57			Operating System Catalog Number			
S:58			Operating System Series			
S:59			Operating System FRN			
S:61			Processor Series			
S:62			Processor Revision			
S:63			User Program Type			
S:64			User Program Functional Index			
S:65			User RAM Size			
S:66			Flash EEPROM Size			
S:67			Channel 0 Active Nodes			
S:68			Channel 0 Active Nodes			
S:69			Channel 0 Active Nodes			
S:70			Channel 0 Active Nodes			
S:71			Channel 0 Active Nodes			

Address/Symbol Database

Address	Symbol	Scope	Description	Sym Group	Dev. Code	ABV
S:72			Channel 0 Active Nodes			
S:73			Channel 0 Active Nodes			
S:74			Channel 0 Active Nodes			
S:75			Channel 0 Active Nodes			
S:76			Channel 0 Active Nodes			
S:77			Channel 0 Active Nodes			
S:78			Channel 0 Active Nodes			
S:79			Channel 0 Active Nodes			
S:80			Channel 0 Active Nodes			
S:81			Channel 0 Active Nodes			
S:82			Channel 0 Active Nodes			
S:83			DH+ Active Nodes			
S:84			DH+ Active Nodes			
S:85			DH+ Active Nodes			
S:86			DH+ Active Nodes			
T4:0			CONVEYOR MOTOR TIMER			
T4:1			PECAN HOPPER TIMER			
T4:2			WALNUT HOPPER TIMER			
T4:3						
U:3			INPUTS			
U:4			OUTPUTS			
U:5			CONTROLS			
U:6			ALARMS			

Instruction Comment Database

Address	Instruction	Description

Symbol Group Database

Group_Name	Description