

# Uncertainty Modelling for Intelligent Systems

Lecture Notes

jerakrs

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## Abstract

This document is the lecture note of *Uncertainty Modelling for Intelligent Systems*. The course code is *EMATM1120* and the unit director is *Jonathan Lawry*.

## 1 Quantitative Measures of Uncertainty

### Certainty vs. Uncertainty

- Certainty: Given a number of inference rules we are then able to deduce other propositions as being certainty true.
- Uncertainty: Our knowledge consists of proposition in which we have some level of belief but about which we are not certain.

Aim: investigate frameworks according to which a rational intelligent agent could reason under uncertainty.

### 1.1 Inductive Logic Rudolf Carnap

There are  $N$  unary predicates  $Q_1, Q_2, \dots, Q_N$  which can be applied to  $M$  objects  $a_1, a_2, \dots, a_M$ , any object must satisfy exactly one of the formula:

$$\alpha(x) = \pm Q_1(x) \wedge \pm Q_2(x) \wedge \dots \wedge \pm Q_n(x) \quad (1)$$

and  $\pm Q_i(x) = Q_i(x)$  or  $\neg Q_i(x)$ , then for any event  $p$ , have:

$$p = \alpha(a_1) \wedge \alpha(a_2) \wedge \dots \wedge \alpha(a_M) \quad (2)$$

### 1.2 Uncertainty Measures

- $W$ : the set of all possible worlds which is assumed be finite.
- $\mu : 2^W \rightarrow [0, 1]$  is a function mapping subsets of  $W$  into the interval.

e.g. four student, each bit represent that it is present or not:

$$\mu(\{< 1, 0, 0, 1 >\}) = 1$$

### 1.3 Random Variables

$X : W \rightarrow \Omega$  is a function from  $W$  into some measurement domain  $\Omega$ .

- $\mu(X = x) = \mu(\{w : X(w) = x\})$
- For  $S \subseteq \Omega$ ,  $\mu(X \in S) = \mu(\{w : X(w) \in S\})$

e.g.  $X$  is the number of male students present, then:

$$\mu(X = 2) = \mu(\{< 1, 0, 0, 1 >, < 1, 0, 1, 1 >, < 1, 1, 0, 1 >, < 1, 1, 1, 1 >\})$$

### 1.4 Random Sets

$R : W \rightarrow 2^\Omega$ : measurements which are imprecise so that  $R(w) = S$  when  $S \subseteq \Omega$ .

$$\mu(R = S) = \mu(\{w : R(w) = S\}) \quad (3)$$

e.g. Let  $R$  denote the lecturer's estimate of the number of people present:

$$R(< 1, 0, 1, 1 >) = \{3, 4\}$$

### 1.5 Attribute of Measures

- **Additive**
  - For uncertainty measures: If  $A \cap B = \emptyset$  then  $\mu(A \cup B) = \mu(A) + \mu(B)$
  - General form: For any  $A$  and  $B$ ,  $\mu(A \cup B) = \mu(A) + \mu(B) - \mu(A \cap B)$
- **Sub-Additive**
  - For uncertainty measures: If  $A \cap B = \emptyset$  then  $\mu(A \cup B) \leq \mu(A) + \mu(B)$
  - General form: For any  $A$  and  $B$ ,  $\mu(A \cup B) \leq \mu(A) + \mu(B) - \mu(A \cap B)$
- **Super-Additive**
  - For uncertainty measures: If  $A \cap B = \emptyset$  then  $\mu(A \cup B) \geq \mu(A) + \mu(B)$
  - General form: For any  $A$  and  $B$ ,  $\mu(A \cup B) \geq \mu(A) + \mu(B) - \mu(A \cap B)$
- **Maxitive**
  - For any  $A$  and  $B$ ,  $\mu(A \cup B) = \max(\mu(A), \mu(B))$ : Special case of sub-additive measure.
- **Minimal**
  - For any  $A$  and  $B$ ,  $\mu(A \cup B) = \min(\mu(A), \mu(B))$ : Special case of super-additive measure.

## 2 Probability Theory

### 2.1 Axioms

For probability measures we denote the uncertainty measure  $\mu = P$

- **P1:**  $P(W) = 1, P(\emptyset) = 0$ ,  $W$  is the all possible world.
- **P2:**  $A \cap B = \emptyset$  then  $P(A \cup B) = P(A) + P(B)$  to general additivity  
 $P(A \cup B) = P(A) + P(B) - P(A \cap B)$

**Complement:**  $P(A^c) = 1 - P(A)$

*Proof:*

$$\because P1, A \cup A^c = W$$

$$\therefore 1 = P(W) = P(A \cup A^c)$$

$$\because P2, A \cap A^c = \emptyset$$

$$\therefore P(A \cup A^c) = P(A) + P(A^c)$$

$$\text{Therefore : } P(A) + P(A^c) = 1$$

**Probability Distributions:**  $A = \{w_1, \dots, w_k\}$  so that  $A = \{w_1\} \cup \dots \cup \{w_k\}$ , then  $P(A) = P(w_1) + P(w_2) + \dots + P(w_k)$

- For uncertainty measure: if  $W$  has  $n$  elements, agent needs to specify  $2^n - 2$  values ( $\mu(W) = 1, \mu(\emptyset) = 0$ ).
- For probability measure: if  $W$  has  $n$  elements, agent needs to specify  $n - 1$  values (Probability distribution must sum to 1).

### 2.2 Probabilities Distributions

- **Joint Probability:**  $P(X_1, X_2, \dots, X_n)$ , if  $X_i$  has  $k_i$  values then specifying the joint distribution requires  $(\prod_{i=1}^n k_i) - 1$ .
- **Marginal Probability:**  $P(X_1) = \sum_{x_2 \in \Omega} \dots \sum_{x_n \in \Omega} P(X_1 = x_1, X_2 = x_2, \dots, X_n = x_n)$
- **Conditional Distribution:**  $P(X_1 = x_1 | X_2 = x_2) = \frac{P(X_1 = x_1, X_2 = x_2)}{P(X_2 = x_2)}$

#### Independence

- Random variable  $X_1$  is independent of  $X_2$  if  $P(X_1 = x_1 | X_2 = x_2) = P(X_1 = x_1)$
- Random variables  $X_1, \dots, X_n$  are independent if  $P(X_1 = x_1, \dots, X_n = x_n) = \prod_{i=1}^n P(X_i = x_i)$

The number of values which must be specified in order to define the joint distribution is:

- the independent case requires  $\sum_{i=1}^n (k_i - 1)$  values.
- the fully dependent case requires  $\prod_{i=1}^n (k_i) - 1$  values.

**Conditional Independence:** Let  $U, V, W$  be exclusive subsets of  $\{X_1, \dots, X_n\}$ , then the variables in  $U$  are said to be conditionally independent of variables in  $V$  given the variables in  $W$  if  $P(U|V, W) = P(U|W)$ .

## 2.3 Conditional Probability

For  $A, B \subseteq W$  the conditional probability of  $A$  given  $B$  is defined by:

$$P(A|B) = \frac{P(A \cap B)}{P(B)} \quad (4)$$

Notice that if  $P(B) = 0$  then  $P(A|B)$  is undefined.

**Bayes Theorem**

$$P(H|E) = \frac{P(H \cap E)}{P(E)} = \frac{P(E|H)P(H)}{P(E)} \quad (5)$$

$P(E|H)$  is called the likelihood,  $P(H)$  is called a prior probability, and

$$P(E) = P(E|H)P(H) + P(E|H^c)P(H^c) \quad (6)$$

**Laplace's principle of insufficient reason**

In the absence of any other information all possible worlds should be assumed to be equally probable, i.e. the probability distribution should be uniform.

Sometimes assuming a uniform prior gives you different answers if you transform the problem:

- Let  $W = \{w1, w2, w3\}$  and  $X$  be a random variable with values in  $\{1, 2\}$
- By insufficient reason, then  $p(w1) = p(w2) = p(w3) = \frac{1}{3}$  and  $P(X = 1) = P(X = 2) = \frac{1}{2}$
- However,  $P(X = 1) = P(\{w : X(w) = 1\}) = 0$  or  $= \frac{1}{3}$  or  $= \frac{2}{3}$  or  $= 1$

## 2.4 Betting Justification

**Notation:** Let  $w^*$  denote the true world, so  $\chi_A(w^*) = 1$  when  $A$  is true and  $\chi_A(w^*) = 0$  when  $A$  is false.

$$\chi_A : W \rightarrow \{0, 1\} \begin{cases} 1, w^* \in A \\ 0, w^* \notin A \end{cases} \quad (7)$$

**Betting Rules:**

- $0 \leq p \leq 1$  and  $S > 0$
- **Bet 1:** Gain  $S(1 - p)$  if  $A$  is true and lose  $Sp$  if  $A$  is false.
- **Bet 2:** Lose  $S(1 - p)$  if  $A$  is false and gain  $Sp$  if  $A$  is true.

**Gain for bet 1 and bet 2**

- gain for bet 1 =  $S(1 - p)\chi_A(w^*) - Sp(1 - \chi_A(w^*)) = S(\chi_A(w^*) - p)$
- gain for bet 2 =  $-S(1 - p)\chi_A(w^*) + Sp(1 - \chi_A(w^*)) = -S(\chi_A(w^*) - p)$

When the expectation of gain for bet 1 and bet 2 is equal, we have:

$$\begin{aligned}\mu(A)S(1 - p) &= -(1 - \mu(A))S(0 - p) \\ \mu(A)(1 - p) + (\mu(A) - 1)p &= 0 \\ \mu(A) &= p\end{aligned}$$

therefore when  $p < \mu$ , the agent pick bet 1 and when  $p > \mu$ , the agent pick bet 2.

**Dutch Book Problem:** A Dutch book is a sequence of bets the outcome of which is a sure loss no matter what the actual state of the world. The gain from two bets is  $S(\chi_A(w^*) - p) + S(\chi_{A^c}(w^*) - p)$  where  $w^*$  is the actual state of the world. Simplifying gives

$$\begin{aligned}& S(\chi_A(w^*) - p) + S(\chi_{A^c}(w^*) - p) \\ &= S(\chi_A(w^*) + \chi_{A^c}(w^*) - 2p) = S(1 - 2p) < 0\end{aligned}$$

since  $S > 0$  and  $p > \frac{1}{2}$ .

## 2.5 Bayesian Networks

A Bayesian network is a directed graph  $(V, E)$  where  $V = \{X_1, \dots, X_n\}$  enumerated such that  $(X_j, X_i) \in E$  only if  $j < i$  together with a probability distribution on  $V$  satisfying:

$$P(X_i | X_1, \dots, X_{i-1}) = P(X_i | \Pi(X_i)) \quad (8)$$

where  $\Pi(X_i) = \{X_j : (X_j, X_i) \in E\}$  are the parents of  $X_i$ .

- Full dependent: for any  $1 \leq i \leq N$  and  $\Pi(X_i) = \{X_j | j < i\}$ .
- Full independent: for any  $1 \leq i \leq N$ ,  $\Pi(X_i) = \emptyset$ .

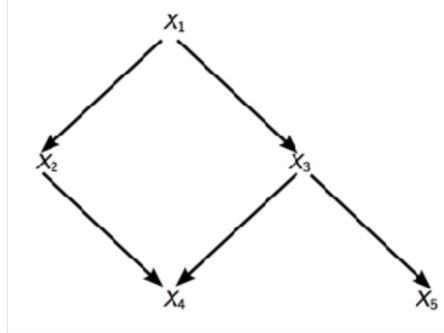


Figure 1: The example of Bayesian Network

*PS: The graph not exist cycles since it is illegal for one thing dependent its self.*

**The Chain Rule:**

$$\begin{aligned}
 P(X_1, \dots, X_n) &= P(X_1) \frac{P(X_1, X_2)}{P(X_1)} \frac{P(X_1, X_2, X_3)}{P(X_1, X_2)} \cdots \frac{P(X_1, \dots, X_n)}{P(X_1, \dots, X_{n-1})} \\
 &= P(X_1) P(X_2|X_1) \dots P(X_n|X_1, \dots, X_{n-1}) = \prod_{i=1}^n P(X_i | \Pi(X_i)) \quad (9)
 \end{aligned}$$

**Possible Values:** Suppose that  $X_1, X_2, \dots, X_n$  is a binary distribution, the total number of possible values is  $\sum_{i=1}^n 2^{|\Pi(X_i)|}$ , since  $0 \leq |\Pi(X_i)| \leq i-1$ , we have

$$\left( \sum_{i=1}^n 2^0 = n \right) \leq \sum_{i=1}^n 2^{|\Pi(X_i)|} \leq \left( \sum_{i=1}^n 2^{i-1} = 2^n - 1 \right) \quad (10)$$

which means the possible values satisfy *independent*  $\leq$  *BayesianNetwork*  $\leq$  *fullydependent*.

### 3 Information and Inference

#### 3.1 Linear Knowledge

A base knowledge can be represented by a set of linear equations on a probability measure  $P$ :

$$K = \sum_{i=1}^{n_j} a_{i,j} P(A_{i,j}) = b_j : j = 1, \dots, m \quad (11)$$

*Example of Knowledge:* Supposing there are three sections, red(r), blue(b) and green(g). And our knowledge base is the probability of red is twice to probability of blue,  $K = \{P(r) = 2P(b)\}$ .

- Let denotes  $P(r) = p_1, P(b) = p_2, P(g) = p_3$ .
- From  $K$  we have that  $p_1 = 2p_2$  also we know hint  $p_1 + p_2 + p_3 = 1 \rightarrow p_3 = 1 - 3p_2$
- The  $V(K) \subseteq V$  corresponding to all probability distributions which satisfy  $K$
- $V(K) = \{< 2p_2, p_2, 1 - 3p_2 >: 0 \leq p_2 \leq \frac{1}{3}\}$
- Notice  $p_2 \leq \frac{1}{3}$  since we require  $3p_2 \leq 1$  and  $2p_2 \leq 1$

*Recall some basic maths:*

- $\log_2 x = \frac{\ln x}{\ln 2}$ , let  $y = \log_a x \Rightarrow a^y = x \Rightarrow \ln a^y = \ln x \Rightarrow y = \frac{\ln x}{\ln a}$
- $\frac{d \ln x}{dx} = \frac{1}{x}$
- $\frac{d(-x \log_2 x)}{dx} = \frac{d(-x \frac{\ln x}{\ln 2})}{dx} = -\frac{1}{\ln 2} \frac{d(x \ln x)}{dx} = -\frac{1}{\ln 2} (\ln x + x \frac{1}{x}) = -\log_2 x - \frac{1}{\ln 2}$

### 3.2 Information and Entropy

**Shannon's Entropy Measure:** Let  $W = \{w_1, \dots, w_n\}$  and  $P(w_i) = p_i$  then the information content of this distribution is

$$H := - \sum_{i=1}^N p_i \log_2(p_i) \quad (12)$$

- $H$  is minimal when  $p_j = 1$  and for some  $j \in \{1, \dots, n\}$  and  $p_i = 0$  for all  $i \neq j$
- $H$  is maximal when  $p_i = \frac{1}{n}$  for  $i = \{1, \dots, n\}$

*Proof Maximal Entropy:* Let  $p_n = 1 - \sum_{i=1}^{n-1} p_i$  and  $H = \sum_{i=1}^n -p_i \log_2 p_i$

$$\frac{dH}{dp_i} = \frac{d(-p_i \log_2 p_i)}{dp_i} + \frac{d(-p_n \log_2 p_n)}{dp_i} = -\log_2 p_i - \frac{1}{\ln 2} + \log_2(1 - \sum_{i=1}^{n-1} p_i) + \frac{1}{\ln 2}$$

$$\frac{dH}{dp_i} = -\log_2 p_i + \log_2(1 - \sum_{i=1}^{n-1} p_i)$$

$$\frac{dH}{dp_i} = 0 \Rightarrow \log_2 p_i = \log_2 1 - \sum_{i=1}^{n-1} p_i \Rightarrow p_i = p_n$$

$$1 = \sum_{i=1}^n p_i \Rightarrow p_i = \frac{1}{n}$$

**Center of Mass:** Suppose we give every element of  $V(K)$  equal probability, then we obtain the probability distribution

$$\hat{p}_i = \frac{\int_{V(K)} p_i dV(K)}{\int_{V(K)} dV(K)} \quad (13)$$

$\langle \hat{p}_1, \dots, \hat{p}_n \rangle$  is the centre of mass of  $V(K)$ .

*Example of CM:* For  $V(K) = \{ \langle p_1, 0.8 - p_1, 0.7 - p_1, p_1 - 0.5 \rangle : 0.5 \leq p_1 \leq 0.7 \}$ ,

$$\hat{p}_1 = \int_{V(K)} p_1 dV(K) = \frac{\int_{0.5}^{0.7} p_1 dp_1}{\int_{0.5}^{0.7} dp_1} = \frac{0.12}{0.2} = 0.6$$

## 4 Dempster-Shafer Theory

### 4.1 Mass Assignments

Shafer-Dempster belief functions are defined by a probability distribution on the power set of  $W$ .

$$m : 2^W \rightarrow [0, 1], m(\emptyset) = 0, \sum_{A \subseteq W} m(A) = 1 \quad (14)$$

#### Belief and Plausibility

- Belief  $Bel : 2^W \rightarrow [0, 1]$  is a measure of the total amount of evidence in favor of a proposition

$$Bel(A) = \sum_{B \subseteq A} m(B) \quad (15)$$

- Plausibility  $Pl : 2^W \rightarrow [0, 1]$  is a measure of the total amount of evidence not against a proposition.

$$Pl(A) = \sum_{B: B \cap A \neq \emptyset} m(B) \quad (16)$$

- $\forall A \subseteq W$ ,  $Bel(A) \leq Pl(A)$  and  $Pl(A) - Bel(A)$  provides a direct measure of ignorance about the proposition  $A$
- $Bel(A) + Bel(A^c) \leq 1$
- $Pl(A) = 1 - Bel(A^c)$



- Belief is sub-additive:  $Bel(A \cup B) \geq Bel(A) + Bel(B)$

$$\begin{aligned} Bel(A \cup B) &= \sum_{C \subseteq A \cup B} m(C) = \sum_{C \subseteq A} m(C) + \sum_{C \subseteq B} m(C) + \sum_{C \subseteq A \cup B, C \not\subseteq A, C \not\subseteq B} m(C) \\ &\geq \sum_{C \subseteq A} m(C) + \sum_{C \subseteq B} m(C) = Bel(A) + Bel(B) \end{aligned}$$

- Plausibility is super-additive:  $Pl(A \cup B) \leq Pl(A) + Pl(B)$

$$\begin{aligned} Pl(A \cup B) &= \sum_{C \cap (A \cup B) \neq \emptyset} m(C) = \sum_{C \cap A \neq \emptyset} m(C) + \sum_{C \cap B \neq \emptyset} m(C) \\ &- \sum_{C \cap A \neq \emptyset, C \cap B \neq \emptyset} m(C) \leq \sum_{C \cap A \neq \emptyset} m(C) + \sum_{C \cap B \neq \emptyset} m(C) = Pl(A) + Pl(B) \end{aligned}$$

**Belief Inversion:** If we already have the Belief and we want to know the Mass, we can consider different levels of each elements.

$$m(A) = \sum_{B \subseteq A} (-1)^{|A-B|} Bel(B) \quad (17)$$

$$m(A) = \sum_{B \subseteq A} (-1)^{|A-B|} (1 - Pl(B^c)) \quad (18)$$

**Lower and Upper Probabilities:** A lower probability  $\underline{P} : 2^W \rightarrow [0, 1]$  and an upper probability  $\overline{P} : 2^W \rightarrow [0, 1]$

- $\forall A \subseteq W \quad \underline{P}(A) \leq \overline{P}(A)$
- $\forall A \subseteq W \quad \overline{P}(A^c) = 1 - \underline{P}(A)$

$\mathbb{P}$  is a set of probability measures on  $2^W$ , then  $\underline{P}(A) = \inf\{P(A) : P \in \mathbb{P}\}$  and  $\overline{P}(A) = \sup\{P(A) : P \in \mathbb{P}\}$ .

## 4.2 Updating Probabilities

Suppose we have a prior probability measure  $P$  and evidence about the true state of the world is given by mass assignment  $m$ . To get a single probability measure we could then take the expected value:

$$P(\bullet|m) = \sum_{B \subseteq W} P(\bullet|B)m(B) \quad (19)$$

*Example for Updating Probabilities:*

$$P(w_1) = 0.5, \quad P(w_2) = 0.3, \quad P(w_3) = 0.2$$

$$P(w_1|\{w_1, w_2\}) = \frac{P(w_1)}{P(w_1) + P(w_2)} = \frac{5}{8}$$

$$P(w_2|\{w_1, w_2\}) = \frac{P(w_2)}{P(w_1) + P(w_2)} = \frac{3}{8}$$

$$P(w_3|\{w_1, w_2\}) = \frac{P(w_3)}{P(w_1) + P(w_2)} = 0 \text{ since } \{w_3\} \cap \{w_1, w_2\} = \emptyset$$

**Pignistic Distribution:** Take to be the uniform measure so that

$$P_u(A|m) = \sum_{B \subseteq W} \frac{|A \cap B|}{|B|} m(B) \quad (20)$$

where  $|A|$  means the number of elements in set  $A$ .

### 4.3 Nested Evidence

**Nested hierarchy:** There exists  $F_1 \subseteq F_2 \subseteq \dots \subseteq F_n \subseteq W$  such that  $\sum_{i=1}^n m(F_i) = 1$ ,  $F_1 \subseteq F_2 \subseteq \dots \subseteq F_n \subseteq W$  are called the **focal sets** of  $m$ .

*Example for Nested hierarchy:* There are  $W = \{d_1, d_2, h\}$ , suppose all doctors agree that the patient may have disease  $d_2$ , a subset of doctors think that he may have disease  $d_1$ , some doctors in this subset also believe it is possible that he is healthy.

**Possibility and Necessity Measures:** For a nested mass assignment the corresponding belief measure is called a **necessity measure** and the plausibility measure is called a **possibility measure**.

- Let  $F_j$  be the largest focal set for which  $F_j \subseteq A$  then:

$$Bel(A) = Nec(A) = \sum_{B \subseteq A} m(B) = \sum_{i=1}^j m(F_i) \quad (21)$$

- Let  $F_k$  be the smallest focal set for which  $A \cap F_k \neq \emptyset$  then:

$$Pl(A) = Pos(A) = \sum_{B: B \cap A \neq \emptyset} m(B) = \sum_{i=k}^n m(F_i) \quad (22)$$

#### Possibility and Necessity Axioms

- **Pos1:**  $Pos(W) = 1, Pos(\emptyset) = 0$
- **Pos2:**  $Pos(A \cup B) = \max(Pos(A), Pos(B))$
- **Nec1:**  $Nec(W) = 1, Nec(\emptyset) = 0$
- **Nec2:**  $Nec(A \cap B) = \min(Nec(A), Nec(B))$
- **Consequences1:**  $\forall A \subseteq W, Pos(A) = 1$  or  $Pos(A^c) = 1$ . Notice that

$$1 = Pos(W) = Pos(A \cup A^c) = \max(Pos(A), Pos(A^c))$$

- **Consequences2:**  $\forall A \subseteq W, Nec(A) = 0$  or  $Nec(A^c) = 0$ . Notice that

$$0 = Nec(\emptyset) = Nec(A \cap A^c) = \min(Nec(A), Nec(A^c))$$

- Either  $[Nec(A), Pos(A)] = [x, 1]$  or  $[0, y]$  where  $0 < x \leq 1$  and  $0 \leq y < 1$ .

*Proof if  $Nec(A) > 0$  then  $Pos(A) = 1$ :*

- $Pos(A^c) = 1 - Nec(A)$  therefore  $Nec(A) > 0 \Rightarrow Pos(A^c) < 1$ .
- Now  $1 = Pos(W) = Pos(A \cup A^c) = \max(Pos(A), Pos(A^c))$ .
- Hence, since  $Pos(A^c) < 1$  so that  $Pos(A) = 1$ .

**Possibility Distribution:** For any  $A \subseteq W$ ,  $Pos(A) = \max\{Pos(\{w_i\}) : w_i \in A\}$ . Let  $Pos(\{w_i\}) = \pi(w_i)$  and  $\max\{\pi(w_i) : w_i \in W\} = 1$ .

**Possibility Inversion:** Suppose  $W = \{w_1, \dots, w_n\}$  ordered, then

$$\begin{aligned} 1 &= \pi(w_1) \geq \pi(w_2) \geq \dots \geq \pi(w_n) \\ m(\{w_1, \dots, w_n\}) &= \pi(w_n) \\ m(\{w_1, \dots, w_{n-1}\}) &= \pi(w_{n-1}) - \pi(w_n) \\ m(\{w_1, \dots, w_i\}) &= \pi(w_i) - \pi(w_{i+1}) \\ m(\{w_1\}) &= 1 - \pi(w_2) \end{aligned}$$

#### 4.4 Dempster's Rule of Combination

Suppose we have two mass assignments provided by two independent sources of evidence.

$$\forall A \subseteq W \quad m_1 \oplus m_2(A) = \frac{\sum_{(B,C): B \cap C = A} m_1(B)m_2(C)}{1 - \sum_{(B,C): B \cap C = \emptyset} m_1(B)m_2(C)} \quad (23)$$

**Conditional Belief Functions:** Suppose that  $Pl$  is a plausibility:

$$Pl(A|B) = \sum_{C \subseteq W; C \cap A \neq \emptyset} m \oplus m_B(C) = \frac{Pl(A \cap B)}{Pl(B)} \quad (24)$$

$$\text{Notice that } m \oplus m_B(C) = \frac{\sum_{D: C \cap A \neq \emptyset} m(D)}{1 - \sum_{D: D \cap B = \emptyset} m(D)}$$

$$Pl(A|B) = \frac{\sum_{D: (D \cap B) \cap A \neq \emptyset} m(D)}{1 - \sum_{D: D \cap B = \emptyset} m(D)} = \frac{\sum_{D: (D \cap B) \cap A \neq \emptyset} m(D)}{\sum_{D: D \cap B \neq \emptyset} m(D)} = \frac{Pl(A \cap B)}{Pl(B)}$$

Also

$$\begin{aligned} Bel(A|B) &= 1 - Pl(A^c|B) = 1 - \frac{Pl(A^c \cap B)}{Pl(B)} = \frac{Pl(B) - Pl(A^c \cap B)}{Pl(B)} = \\ &= \frac{(1 - Bel(B^c)) - (1 - Bel(A \cup B^c))}{1 - Bel(B^c)} = \frac{Bel(A \cup B^c) - Bel(B^c)}{1 - Bel(B^c)} \quad (25) \end{aligned}$$

## 5 Fuzzy Set Theory

Fuzzy sets are sets to which elements can belong to some partial degree. A (crisp) set  $A \subseteq W$  can be characterised by a membership function  $\chi_A : W \rightarrow \{0, 1\}$  so that

$$\chi_A = \begin{cases} 1 & w \in A \\ 0 & w \notin A \end{cases} \quad (26)$$

The support of a fuzzy set  $\tilde{A}$  is given by  $Sup(\tilde{A}) = \{w \in W : \chi_{\tilde{A}}(w) > 0\}$  and the fuzzy set is

$$\tilde{A} = \sum_{w \in Sup(\tilde{A})} w / \chi_{\tilde{A}}(w) \quad (27)$$

**Sorites Paradox:** Consider a man with a lot of hair on his head. One hair is plucked at a time until he is bald. It follows that there must be a hair pluck at which the man switches from being not bald to being bald. However, this is counter intuitive since the difference of one hair cannot induce a category change from not bald to bald. This or an alternative version of sorites.

### 5.1 T-norm

**T-norm** are function  $T : [0, 1]^2 \rightarrow [0, 1]$  which satisfy the following properties:

- **T1:**  $\forall x \in [0, 1] \quad T(x, 1) = x$
- **T2:**  $\forall x, y, z \in [0, 1], \text{ if } y \leq z \text{ then } T(x, y) \leq T(x, z)$
- **T3:**  $\forall x, y \in [0, 1], T(x, y) = T(y, x)$
- **T4:**  $\forall x, y, z \in [0, 1], T(x, T(y, z)) = T(T(x, y), z)$

$$\varphi_{(A \cap B) \cap C} = \varphi_{A \cap (B \cap C)} \Rightarrow T(T(A, B), C) = T(A, T(B, C))$$

- **T5:**  $\forall x \in [0, 1] \quad T(x, x) = x$

**Theorem:** For any t-norm  $T$ ,  $drastic \leq T \leq min$ , where

$$drastic(x, y) = \begin{cases} x & : y = 1 \\ y & : x = 1 \\ 0 & : otherwise \end{cases} \quad (28)$$

- Show that  $T \leq min(x, y)$

$$T(x, y) \leq T(x, 1) = x$$

$$T(x, y) = T(y, x) \leq T(y, 1) = y$$

$$T(x, y) \leq min(x, y)$$

- Show that  $T \geq \text{drastic}(x, y)$

$$T(x, 1) = x$$

$$T(1, y) = T(y, 1) = y$$

$$T(x, y) \geq 0$$

$$T(x, y) \geq \text{drastic}$$

### Families of T-norms

- **Frank's t-norms:**  $T_s(x, y) = \log_s[1 + \frac{(s^x - 1)(s^y - 1)}{s - 1}]$  where  $s > 0$  and  $s \neq 1$
- **Dombi Family:**  $T_\lambda(x, y) = \{1 + [(\frac{1}{x} - 1)^\lambda + (\frac{1}{y} - 1)^\lambda]^{\frac{1}{\lambda}}\}^{-1}$ , where  $\lambda > 0$

## 5.2 T-conorms

**T-conorms** are function  $S : [0, 1]^2 \rightarrow [0, 1]$ , it equal to  $1 - T(1 - x, 1 - y)$  and satisfy the following properties:

- **S1:**  $\forall x \in [0, 1] S(x, 0) = x$
- **S2:**  $\forall x, y, z \in [0, 1]$  if  $y \leq z$  then  $S(x, y) \leq S(x, z)$
- **S3:**  $\forall x, y \in [0, 1] S(x, y) = S(y, x)$
- **S4:**  $\forall x, y, z \in [0, 1] S(x, S(y, z)) = S(S(x, y), z)$
- **S5:**  $\forall x \in [0, 1] S(x, x) = x$

## 5.3 Fuzzy Set

$\alpha$ -**cuts** provide a way of representing fuzzy sets as a nested sequence of crisp sets, Fuzzy set  $\tilde{A}_\alpha = \{w \in W : \chi_{\tilde{A}}(w) \geq \alpha\}$  so  $\chi_{\tilde{A}}(w) = \int_{\alpha: w \in \tilde{A}_\alpha} d\alpha$ .

Notice that  $w \in \tilde{A}_\alpha$  if and only if  $\varphi_{\tilde{A}}(w) \geq \alpha$ , therefore  $\{\alpha : w \in \tilde{A}_\alpha\} = (0, \chi_{\tilde{A}}(w)]$ .

*Example for Fuzzy Set:* There are  $\tilde{A} = 5/1 + 6/0.8 + 7/0.5$  and  $\tilde{B} = 1/1 + 2/0.5 + 3/0.2$ , use the  $\alpha$ -cut method to determine  $\frac{\tilde{A}}{\tilde{B}}$ .

$\frac{\tilde{A}}{\tilde{B}}$	$\{5, 6, 7\} : (0, 0.5]$	$\{5, 6\} : (0.5, 0.8]$	$\{5\} : (0.8, 1]$
$\{1, 2, 3\} : (0, 0.2]$	$\{5, 6, 7, \frac{5}{2}, 3, \frac{7}{2}, \frac{5}{3}, 2, \frac{7}{3}\} : (0, 0.2]$	$\emptyset$	$\emptyset$
$\{1, 2\} : (0.2, 0.5]$	$\{5, 6, 7, \frac{5}{2}, 3, \frac{7}{2}\} : (0.2, 0.5]$	$\emptyset$	$\emptyset$
$\{1\} : (0.5, 1]$	$\emptyset$	$\{5, 6\} : (0.5, 0.8]$	$\{5\} : (0.8, 1]$

$$\tilde{A}_\alpha = \begin{cases} \{5, 6, 7\} & : \alpha \in (0, 0.5] \\ \{5, 6\} & : \alpha \in (0.5, 0.8] \\ \{5\} & : \alpha \in (0.8, 1] \end{cases} \text{ and } \tilde{B}_\alpha = \begin{cases} \{1, 2, 3\} & : \alpha \in (0, 0.2] \\ \{1, 2\} & : \alpha \in (0.2, 0.5] \\ \{1\} & : \alpha \in (0.5, 1] \end{cases}$$

$$(\frac{\tilde{A}}{\tilde{B}})_\alpha = \begin{cases} \{5, 6, 7, \frac{5}{2}, 3, \frac{7}{2}, \frac{5}{3}, 2, \frac{7}{3}\} & : \alpha \in (0, 0.2] \\ \{5, 6, 7, \frac{5}{2}, 3, \frac{7}{2}\} & : \alpha \in (0.2, 0.5] \\ \{5, 6\} & : \alpha \in (0.5, 0.8] \\ \{5\} & : \alpha \in (0.8, 1] \end{cases}$$

$$\frac{\tilde{A}}{\tilde{B}} = 5/1 + 6/0.8 + 7/0.5 + \frac{5}{2}/0.5 + 3/0.5 + \frac{7}{2}/0.5 + 5/0.2 + 6/0.2 + 7/0.2$$

## 6 Model Logic

The idea is to directly incorporate the notions of possibly the case and necessarily the case directly in to a formal logic.

**Proposition:**  $w \models A$  denote that proposition  $A$  is true in world  $w$ .

$$W(A) = \{w \in W : w \models A\} \quad (29)$$

### Well-Formed Formula

- standard connectives:  $\neg$  (not),  $\wedge$  (and),  $\vee$  (or)
- modal operators:  $\Box$  (necessarily),  $\Diamond$  (possibly)
  - $\Box\theta$  means  $\theta$  is necessarily the case.
  - $\Diamond\theta$  means  $\theta$  is possibly the case.

### Semantics of Modal Logic

- $w \models \Box\theta$ : for all  $w'$  such that  $Edge(w, w')$ ,  $w' \models \theta$
- $w \models \Diamond\theta$ : if  $\theta$  is true in every world accessible from  $w$ , there exists  $w'$  such that  $Edge(w, w')$ ,  $w' \models \theta$
- $W(\Box B) \subseteq W(B) \subseteq W(\Diamond B)$
- $\theta \models \varphi$  ( $\theta$  entails  $\varphi$  or  $\varphi$  follows  $\theta$ ) if and only if  $w \models \theta$  implies that  $w \models \varphi$
- $\neg\Box\neg\theta \equiv \Diamond\theta$  and  $\neg\Diamond\neg\theta \equiv \Box\theta$

### Properties of Relations

- Reflexive:  $E(w, w)$  for all  $w \in W$
- Symmetric: If  $E(w, w')$  then  $E(w', w)$
- Transitive: If  $E(w_1, w_2)$  and  $E(w_2, w_3)$  then  $E(w_1, w_3)$
- Dense: If  $E(w_1, w_3)$  then there exists  $w_2$  such that  $E(w_1, w_2)$  and  $E(w_2, w_3)$
- Serial: For all  $w$ , there exists  $w'$  such that  $E(w, w')$

- Identity Relation:  $E(w, w')$  if and only if  $w = w'$

**Probability, Model Logic and DS-Theory:**  $P$  is a probability measure on  $2^W$ ;  $R(w)$  is the set of worlds which are reachable from  $w$  denoted as  $R(w) = \{w' : E(w, w')\}$ . Notice that  $w \models \theta$  if and only if  $R(w) \subseteq W(\theta)$ ,  $w \models \diamond\theta$  if and only if  $R(w) \cap W(\theta) \neq \emptyset$ .

Mass function:  $m(F) = P(\{w : R(w) = F\}) = \sum_{w: R(w)=F} P(w)$

If  $E$  is serial then for all  $w$ ,  $R(w) \neq \emptyset$  and hence  $m(\emptyset) = 0$ ,  $P(\Box\theta) = Bel(\theta)$  and  $P(\diamond\theta) = Pl(\theta)$ .

$$\begin{aligned} P(\Box\theta) &= P(W(\Box\theta)) = \sum_{w: R(w) \subseteq W(\theta)} P(w) \\ &= \sum_{F \subseteq W(\theta)} \sum_{w: R(w)=F} P(w) = \sum_{F \subseteq W(\theta)} m(F) = Bel(W(\theta)) = Bel(\theta) \end{aligned}$$

and also  $P(\diamond\theta) = P(\neg\Box\neg\theta) = 1 - P(\Box\neg\theta) = 1 - Bel(\neg\theta) = Pl(\theta)$ .

*Web page Example:* Consider the probability distribution  $\{w_1, w_2, w_3, w_4, w_5\}$

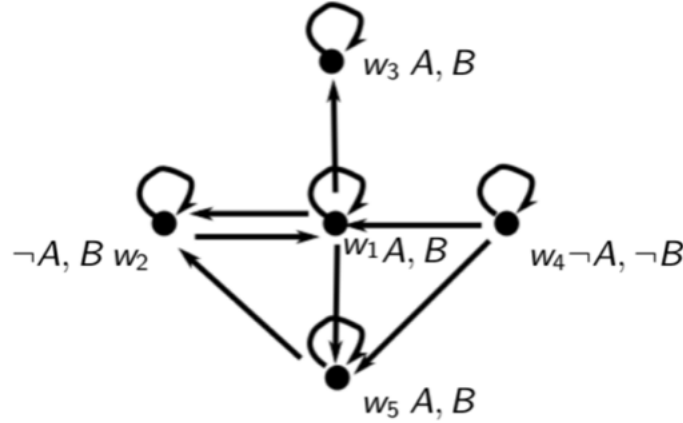


Figure 2: Web Page

$$P(w_1) = 0.1, P(w_2) = 0.2, P(w_3) = 0.2, P(w_4) = 0.4, P(w_5) = 0.1$$

$$R(w_1) = \{w_1, w_2, w_3, w_5\}, R(w_2) = \{w_1, w_2\}, R(w_3) = \{w_3\}$$

$$R(w_4) = \{w_1, w_4, w_5\}, R(w_5) = \{w_2, w_5\}$$

$$W(B) = \{w_1, w_2, w_3, w_5\}$$

$$Bel(B) = m(\{w_1, w_2, w_3, w_5\}) + m(\{w_1, w_2\}) + m(\{w_3\}) + m(\{w_2, w_5\}) = 0.6$$