SparseGPT: Massive Language Models Can be Accurately Pruned in One-Shot

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Large-scale generative pretrained transformer (GPT) family models can be pruned to at least 50% sparsity in one-shot at minimal loss of accuracy.

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Introduction

- The best-performing pruning methods so far require extensive retraining of the model to recover accuracy.
- SparseGPT is efficient enough to execute in a few hours on the largest openly-available GPT models (175B parameters), on a single GPU.
- SparseGPT is accurate enough to drop negligible accuracy post-pruning,
 without any fine-tuning.

Introduction

SparseGPT can induce uniform layerwise sparsity of up to 60%

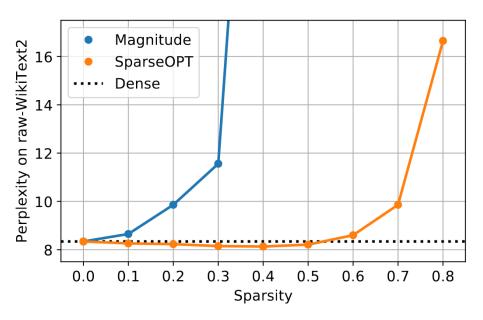


Figure 1. Sparsity-vs-perplexity comparison of SparseGPT against magnitude pruning on OPT-175B, when pruning to different *uniform* per-layer sparsities.

Introduction

•SparseGPT can also accurately impose sparsity in the more stringent, but hardware-friendly, 2:4 and 4:8 semistructured sparsity patterns, although this comes at an accuracy loss relative to the dense baseline for smaller models.

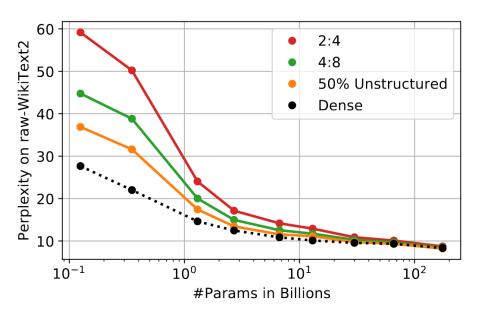


Figure 2. Perplexity vs. model and sparsity type when compressing the entire OPT model family (135M, 350M, ..., 66B, 175B) to different sparsity patterns using SparseGPT.

Background

Layer-Wise Pruning:

- Post-training compression is usually done by splitting the full-model compression problem into layer-wise subproblems, whose solution quality is measured in terms of the $\ell_2-error$ between the output, for given inputs X_ℓ , of the uncompressed layer with weights W_ℓ and that of the compressed one.
- The overall compressed model is then obtained by "stitching together" the individually compressed layers.

$$\operatorname{argmin}_{\operatorname{mask} \mathbf{M}_{\ell}, \widehat{\mathbf{W}}_{\ell}} || \mathbf{W}_{\ell} \mathbf{X}_{\ell} - (\mathbf{M}_{\ell} \odot \widehat{\mathbf{W}}_{\ell}) \mathbf{X}_{\ell} ||_{2}^{2}. \tag{1}$$

NP-Hard Optimization problem

Background

Mask Selection & Weight Reconstruction

- A particularly popular approach is to separate the problem into mask selection and weight reconstruction
- First choose a pruning mask M according to some saliency criterion, like the weight magnitude, and then optimize the remaining unpruned weights while keeping the mask unchanged. Importantly, once the mask is fixed, (1) turns into a linear squared error problem that is easily optimized.
- Existing solvers have difficulty of scaling to 100+ billion parameters.

Fast Approximate Reconstruction

Motivation

$$\mathbf{w^{i}_{M_{i}}} = (\mathbf{X_{M_{i}}X_{M_{i}}^{\top}})^{-1}\mathbf{X_{M_{i}}}(\mathbf{w_{M_{i}}X_{M_{i}}})^{\top}, \qquad (2)$$

- The optimal values of all weights in the mask can be calculated exactly by solving the sparse reconstruction problem
- $^{\circ}$ This requires inverting the Hessian matrix $\mathbf{H_{M_i}} = \mathbf{X_{M_i}} \mathbf{X_{M_i}^{ op}}$
- For a Transformer model, this means that the overall runtime is $O(d_{hidden}^4)$
- We need a speedup by at least a full factor of d_{hidden} to arrive at a practical algorithm.

Fast Approximate Reconstruction

Different Row-Hessian Challenge

$$\mathbf{w^{i}_{M_{i}}} = (\mathbf{X_{M_{i}}X_{M_{i}}^{\top}})^{-1}\mathbf{X_{M_{i}}}(\mathbf{w_{M_{i}}X_{M_{i}}})^{\top}, \qquad (2)$$

- Solving each row requires the individual inversion of a $O(d_{col} \times d_{col})$ matrix.
- The key towards designing an approximation algorithm that is both accurate and efficient lies in enabling the reuse of Hessians between rows with distinct pruning masks.

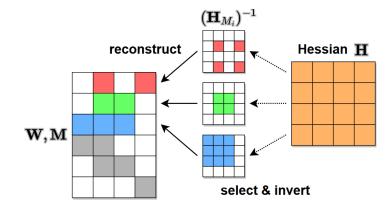


Figure 3. Illustration of the row-Hessian challenge: rows are sparsified independently, pruned weights are in white.

Fast Approximate Reconstruction

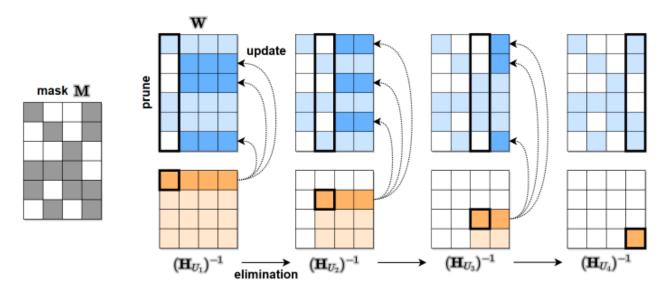
- Equivalent Iterative Perspective
- Row-wise weight reconstruction from a different iterative perspective, using the classic
 OBS(Optimal Brain Surgeon) update.
 - Assuming the current weights w are optimal, the OBS update δ_m provides the optimal adjustment of the remaining weights to compensate for the removal of the weight at index m, incurring error ε_m :

$$\boldsymbol{\delta_m} = -\frac{w_m}{[\mathbf{H}^{-1}]_{mm}} \cdot \mathbf{H}_{:,m}^{-1}, \quad \varepsilon_m = \frac{w_m^2}{[\mathbf{H}^{-1}]_{mm}}. \quad (3)$$

Hence, $w + \delta_m$ is the optimal weight reconstruction corresponding to mask $\{m\}^C$.

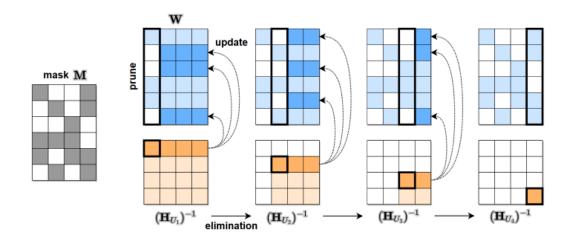
Fast Approximate Reconstruction

- Equivalent Iterative Perspective
- For solving for a full mask $M = \{m_1, \dots, m_p\}^c$, we could iteratively apply OBS to individually prune the weights m_1 up until, m_p in order, one-at-a-time, and will ultimately arrive at the same optimal solution as applying the closed-form regression reconstruction with the full M directly.



Fast Approximate Reconstruction

- Optimal Partial Updates
- Only update the weights in a subset $U \subseteq M$ among remaining unpruned weights
- The restriction to U does not incur any extra approximation error by itself, only the error compensation might not be as effective, as less weights are available for adjustment. At the same time, if |U| < |M|, then inverting H_U will be a lot faster than inverting H_M .



Fast Approximate Reconstruction

- Hessian Synchronization
 - $^{\circ}$ Asuming a fixed ordering of the input features $j=1,\ldots,d_{col}$
 - ullet Define a sequence of d_{col} index subsets U_{j} recursively as:

$$U_{j+1} = U_j - \{j\} \text{ with } U_1 = \{1, \dots, d_{\text{col}}\}.$$
 (4)

• These subsets also impose a sequence of inverse Hessians $(\mathbf{H}_{U_j})^{-1} = ((\mathbf{X}\mathbf{X}^{\top})_{U_j})^{-1}$ which we are going to share across all rows of W.

Fast Approximate Reconstruction

- Hessian Synchronization
- The updated inverse $(\mathbf{H}_{U_{j+1}})^{-1}$ can be calculated efficiently by removing the first row and column, corresponding to j in the original H, from $\mathbf{B} = (\mathbf{H}_{U_j})^{-1}$ in $O(\mathbf{d}_{\operatorname{col}}^2)$ time via one step of Gaussian elimination:

$$(\mathbf{H}_{U_{j+1}})^{-1} = \left(\mathbf{B} - \frac{1}{[\mathbf{B}]_{11}} \cdot \mathbf{B}_{:,1} \mathbf{B}_{1,:}\right)_{2:,2:}, \quad (5)$$

• Hence, the entire sequence of d_{col} inverse Hessians can be calculated recursively in $O(d_{col}^3)$ time, i.e. at similar cost to a single extra matrix inversion on top of the initial one for H^{-1} .

Fast Approximate Reconstruction

Hessian Synchronization

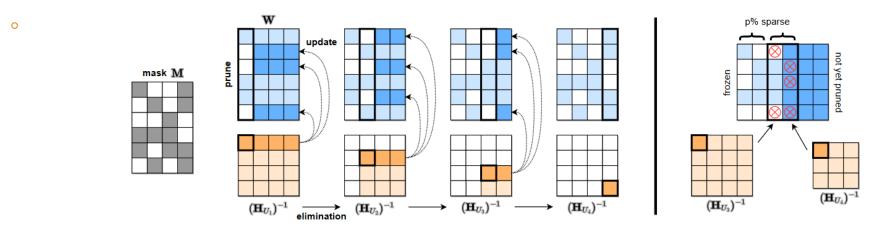


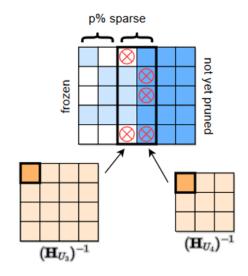
Figure 4. [Left] Visualization of the SparseGPT reconstruction algorithm. Given a fixed pruning mask M, we incrementally prune weights in each column of the weight matrix W, using a sequence of Hessian inverses $(H_{U_j})^{-1}$, and updating the remainder of the weights in those rows, located to the "right" of the column being processed. Specifically, the weights to the "right" of a pruned weight (dark blue) will be updated to compensate for the pruning error, whereas the unpruned weights do not generate updates (light blue). [Right] Illustration of the adaptive mask selection via iterative blocking.

Fast Approximate Reconstruction

- Computational Complexity
 - a) The initial Hessian, which takes time $\Theta(n + d_{col}^2)$ where n is the number of input samples used
 - b) Iterating through the inverse Hessian sequence in time $O(d_{col}^3)$
 - c) The reconstruction/pruning itself $O(d_{col}d_{row}d_{col})$
- In total, $O(d_{col}^3 + d_{row}d_{col}^2)$
- For Transformer models $O(d_{hidden}^3)$

Adaptive Mask Selection

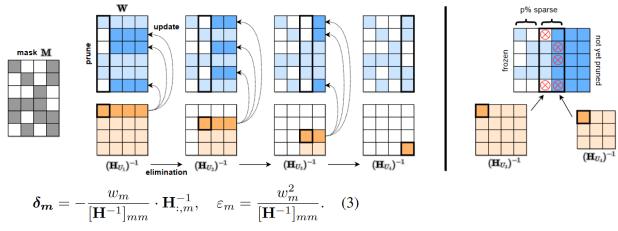
- So far, we have assumed a fixed pruning mask M.
- Recent work (Frantar et al., 2022b) shows that updates during pruning change weights significantly due to correlations, and that taking this into account in the mask selection yields better results.
- Adaptively choosing the mask while running the reconstruction.
- Select the pruning mask for $B_s=128$ columns at a time.
- Based on the OBS reconstruction error ε from Equation (3), using the diagonal values in our Hessian sequence. We then perform the next B_s weight updates, before selecting the mask for the next block, and so on.



Extended to Semi-Structured Sparsity

Algorithm 1 The SparseGPT algorithm. We prune the layer matrix \mathbf{W} to p% unstructured sparsity given inverse Hessian $\mathbf{H}^{-1} = (\mathbf{X}\mathbf{X}^{\top} + \lambda \mathbf{I})^{-1}$, lazy batch-update blocksize B and adaptive mask selection blocksize B_s ; each B_s consecutive columns will be p% sparse.

```
\mathbf{M} \leftarrow \mathbf{1}_{d_{row} \times d_{col}} // binary pruning mask
\mathbf{E} \leftarrow \mathbf{0}_{d_{\text{row}} \times B} // block quantization errors
\mathbf{H}^{-1} \leftarrow \text{Cholesky}(\mathbf{H}^{-1})^{\top} // Hessian inverse information
for i = 0, B, 2B, \dots do For each block
   if i \mod B_s = 0 then
           \mathbf{M}_{:,i:(i+B_c)} \leftarrow \text{mask of } (1-p)\% \text{ weights } w_c \in
           \mathbf{W}_{:,j:(j+B_s)} with largest w_c^2/[\mathbf{H}^{-1}]_{cc}^2
       end if
       \mathbf{E}_{:,j-i} \leftarrow \mathbf{W}_{:,j} / [\mathbf{H}^{-1}]_{jj} // pruning error
       \mathbf{E}_{:,j-i} \leftarrow (\mathbf{1} - \mathbf{M}_{:,j}) \cdot \mathbf{E}_{:,j-i} // freeze weights
       \mathbf{W}_{:,j:(i+B)} \leftarrow \mathbf{W}_{:,j:(i+B)} - \mathbf{E}_{:,j-i} \cdot \mathbf{H}_{j,j:(i+B)}^{-1} "update \rightarrow
   end for
   \mathbf{W}_{:,(i+B):} \leftarrow \mathbf{W}_{:,(i+B):} - \mathbf{E} \cdot \mathbf{H}_{i:(i+B),(i+B):}^{-1} // update
end for
\mathbf{W} \leftarrow \mathbf{W} \cdot \mathbf{M} // set pruned weights to 0
```



Select the mask for current block according to the error information

Only updates the weights in some specific rows

 $w+\delta_m$ is the optimal weight reconstruction corresponding to mask $\{m\}^{\mathcal{C}}$

Perform the next B_S weight updates, before selecting the mask for the next block.

Experiments

Setup

- Single NVIDIA A100 GPU, 80GB memory
- Focus on 175-billion-parameter models
- In approximately 4 hours
- Compressing Transformer layers sequentially in order, which significantly reduces memory requirements.

Models, Datasets & Evaluation

- Models: OPT family, 176B BLOOM
- Evaluation on perplexity
- **Test sets:** raw-WikiText2, PTB, C4 validation subset
- ZeroShot accuracy benchmarks: Lambada, ARC, PIQA, StoryCloze

Results

Pruning vs. Model Size

Table 1. OPT perplexity results on raw-WikiText2.

OPT - 50%	125M	350M	1.3B
Dense	27.66	22.00	14.62
Magnitude	193.	97.80	1.7e4
AdaPrune	58.66	48.46	32.52
SparseGPT	36.85	31.58	17.46

OPT	Sparsity	2.7B	6.7B	13B	30B	66B	175B
Dense	0%	12.47	10.86	10.13	9.56	9.34	8.35
Magnitude	50%	265.	969.	1.2e4	168.	4.2e3	4.3e4
SparseGPT	50%	13.48	11.55	11.17	9.79	9.32	8.21
SparseGPT	4:8	14.98	12.56	11.77	10.30	9.65	8.45
SparseGPT	2:4	17.18	14.20	12.96	10.90		8.74

Larger Models Are More Compressible

Results

Pruning vs. Model Size

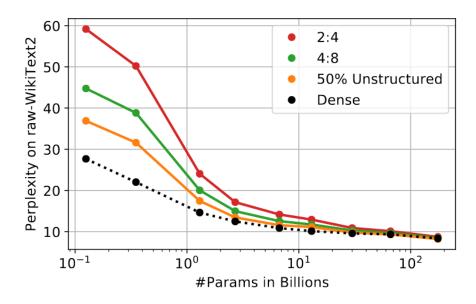


Figure 2. Perplexity vs. model and sparsity type when compressing the entire OPT model family (135M, 350M, ..., 66B, 175B) to different sparsity patterns using SparseGPT.

Larger Models Are More Compressible

Results

ZeroShot Experiments

Table 2. ZeroShot results on several datasets for sparsified variants of OPT-175B.

Method	Spars.	Lamb.	PIQA	ARC-e	ARC-c	Story.	Avg.
Dense	0%	75.59	81.07	71.04	43.94	79.82	70.29
Magnitude	50%	00.02	54.73	28.03	25.60	47.10	31.10
SparseGPT	50%	78.47	80.63	70.45	43.94	79.12	70.52
SparseGPT	4:8	80.30	79.54	68.85	41.30	78.10	69.62
SparseGPT	2:4	80.92	79.54	68.77	39.25	77.08	69.11

SparseGPT models maintained close to original accuracy in ZeroShot tasks, while magnitude-pruned models showed a significant drop in performance. Interestingly, 2:4 pruning sometimes achieved higher accuracy than the dense model.

Results

Joint Sparsification & Quantization

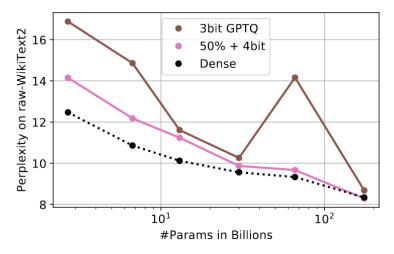


Figure 6. Comparing joint 50% sparsity + 4-bit quantization with size-equivalent 3-bit on the OPT family for \geq 2.7B params.

Combining sparsity and quantization, SparseGPT with 50% sparsity + 4-bit quantization outperformed the 3-bit versions for models larger than 2.7B parameters, including the 175B model

Results

Sensitivity & Partial N:M Sparsity

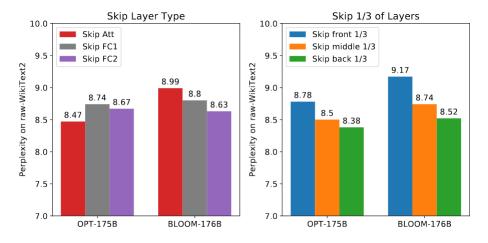


Figure 7. Sensitivity results for partial 2:4 pruning.

Full sparsity is not accurate enough and how to choose a subset of layers for n:m sparsification. It was found that skipping the last third of the model layers yields the best accuracy, indicating that later layers are more sensitive than earlier ones.

Dicussion:

- This paper focus primarily on uniform per-layer sparsity but non-uniform distributions are a promising topic for future work.
- SparseGPT is currently not quite as accurate on smaller and medium sized variants as on the very largest ones.