机器视觉-第八次作业

实现思路

- 观察目标图片们,为两个主要直线区域设置ROI。并观察主要直线,根据它们的倾角设置采样方向。
- 在每条采样线上间隔做差,以近似一阶导数,选其中大于阈值且最大的差值对应的点作为目标边缘像素。
- 对边缘像素进行最小二乘拟合,并根据拟合结果算出各点到直线的距离,利用这个距离来计算出 ε^2 、并计算点的权重。
- 根据权重,重新拟合,并计算出 ε^2 、更新权重,若此次计算出的 ε^2 与上一次 ε^2 的差值过大,可以认为没有收敛,重复该步。
- 对两条直线拟合完后, 计算它们的交点, 并绘制出来, 输出图片结果。对每个图片, 重复。

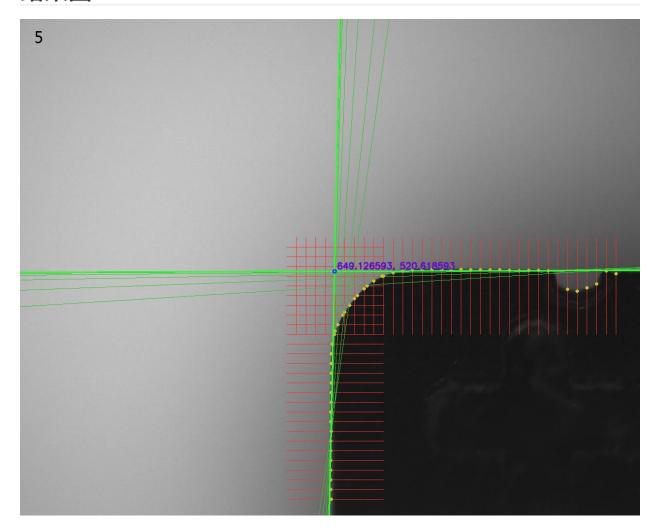
代码

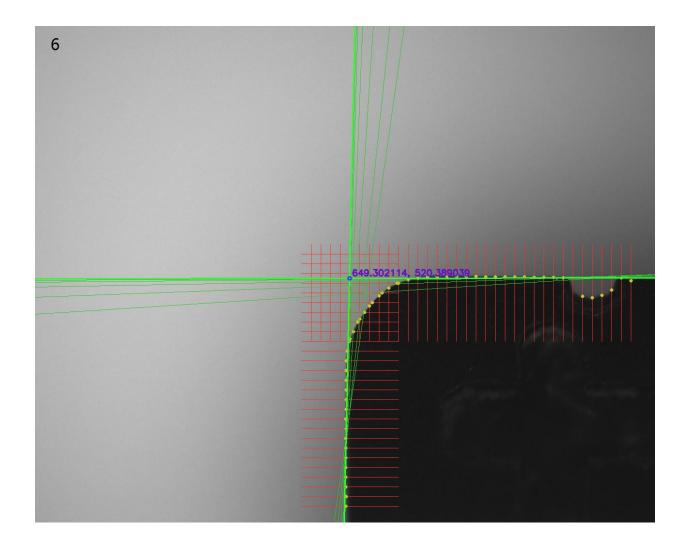
```
#include <vector>
#include <string>
#include "opencv2/opencv.hpp"
using namespace std;
using namespace cv;
#define DIR HOR 1
#define DIR VER 2
#define DIV THRES 15
void findEdgePixel(Mat& img, vector<Point>& points, Mat& canvasimg, Rect& roi,
int sampleinterval, int direction);
void fitLineMinSqr(vector<Point>& points, Point3d& linearg, Mat& canvasimg, int
weight thres);
void drawMyLine(Point3d& linearg, Mat& canvasimg, Scalar color, int thick);
void drawCrossPoint(Point3d& line1, Point3d& line2, Mat& canvasimg);
int main(){
    for (int i=5; i <= 19; ++i) {
        char filename[8];
```

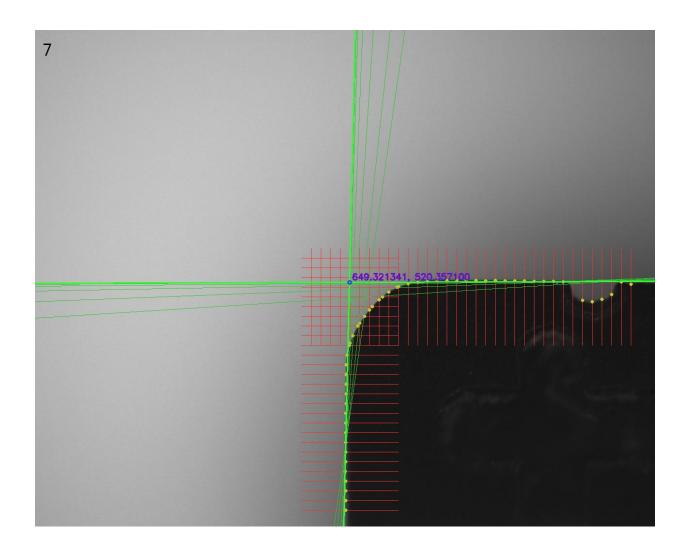
```
sprintf(filename, "%02d.jpg", i);
       Mat img = imread(string("../image/")+filename);
       Mat gray;
       Rect roi1(550, 450, 700, 200), roi2(550, 450, 200, 550);
       vector<Point> points1, points2;
        Point3d line1, line2;
        cvtColor(img, gray, COLOR_BGR2GRAY);
        findEdgePixel(gray, points1, img, roi1, 20, DIR VER);
        findEdgePixel(gray, points2, img, roi2, 20, DIR_HOR);
        fitLineMinSqr(points1, line1, img, 40);
        fitLineMinSqr(points2, line2, img, 25);
        drawCrossPoint(line1, line2, img);
        imwrite(string("../outimg/out")+filename, img);
    }
   return 0;
}
void findEdgePixel(Mat& img, vector<Point>& points, Mat& canvasimg, Rect& roi,
int sampleinterval, int direction){
   if (direction == DIR HOR) {
        /** 请自行补充 **/
    else if (direction == DIR VER){
       /** 请自行补充 **/
    }
}
void fitLineMinSqr(vector<Point>& points, Point3d& linearg, Mat& canvasimg, int
weight_thres){
  /** 请自行补充 **/
}
void drawMyLine(Point3d& linearg, Mat& canvasimg, Scalar color, int thick){
   /** 请自行补充 **/
}
```

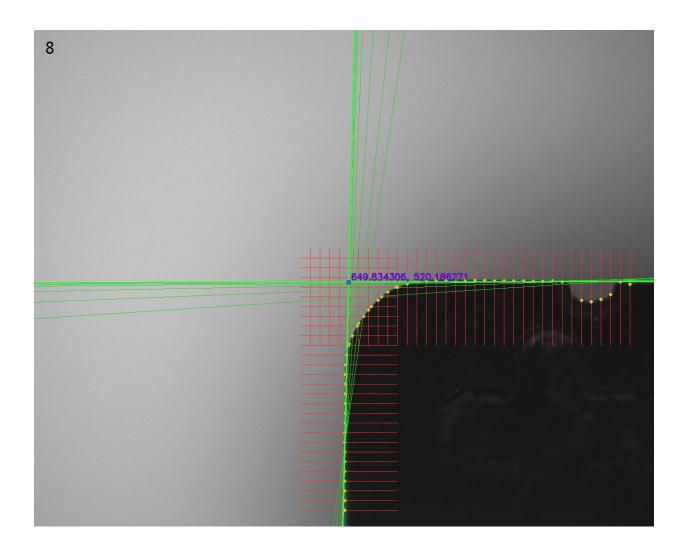
```
void drawCrossPoint(Point3d& line1, Point3d& line2, Mat& canvasimg){
   /** 请自行补充 **/
}
```

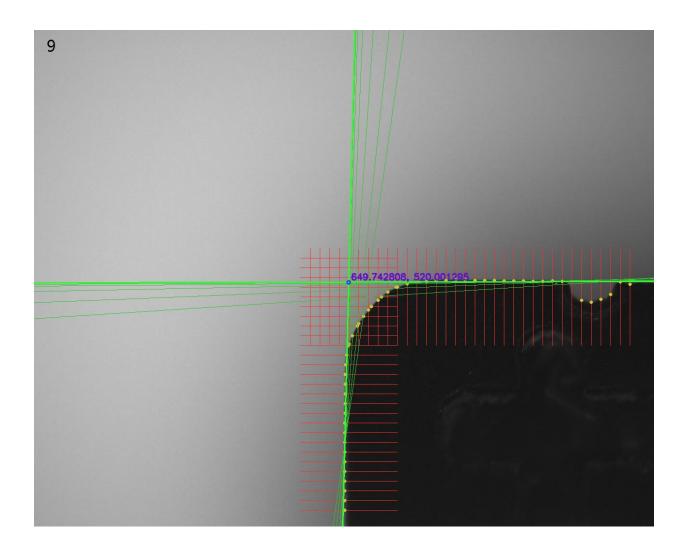
结果图

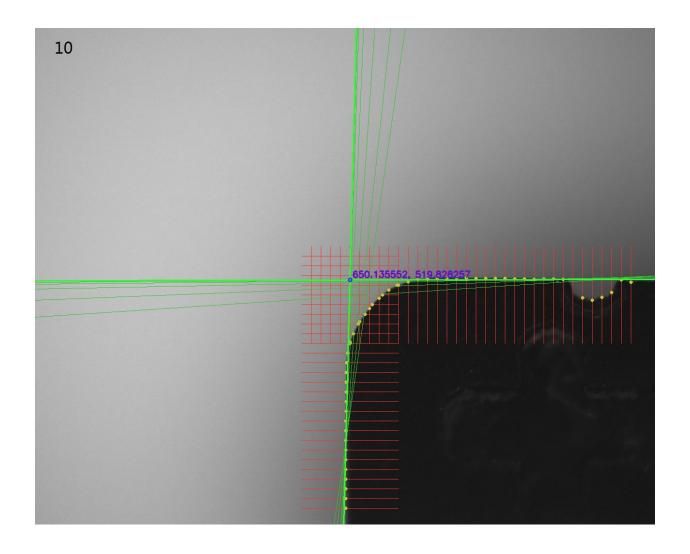


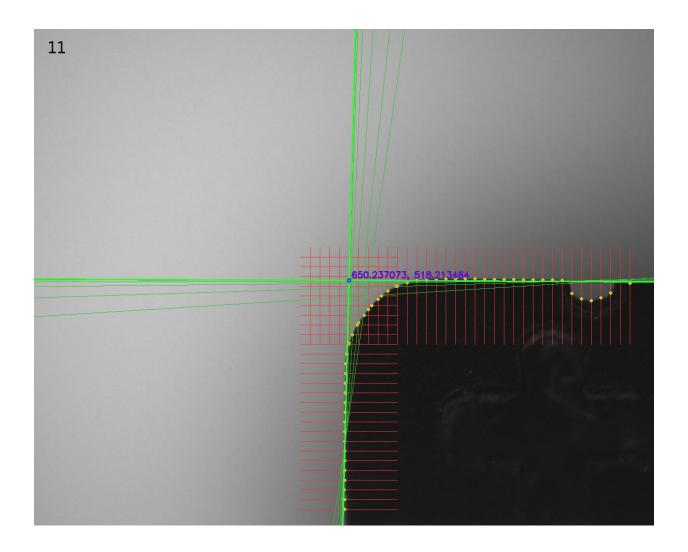


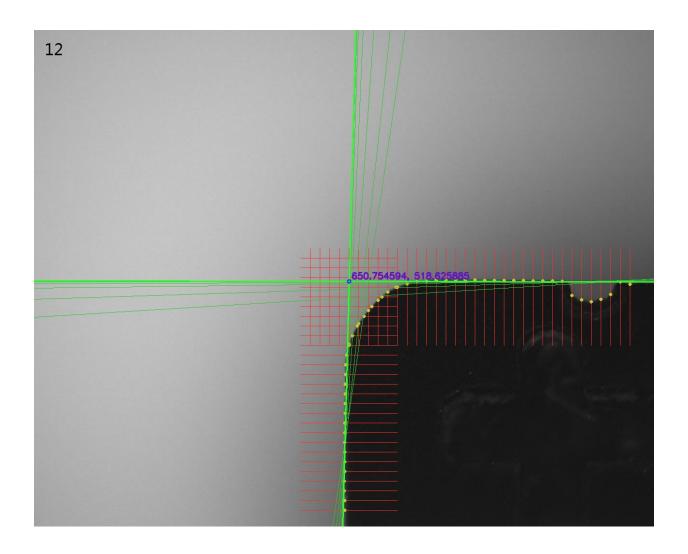


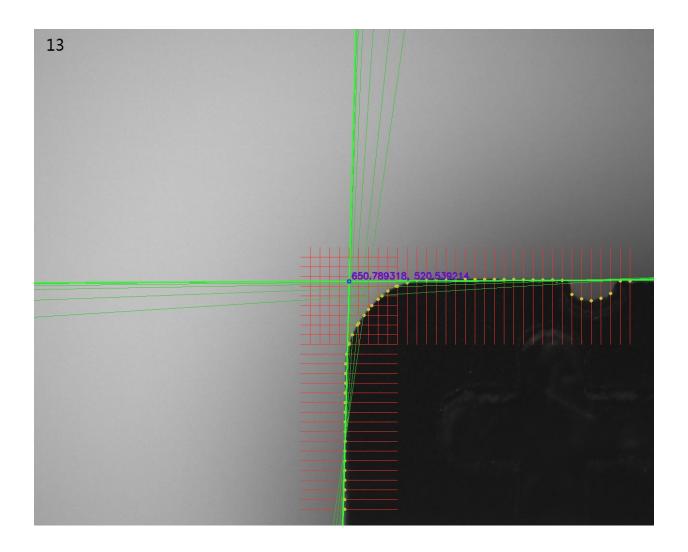


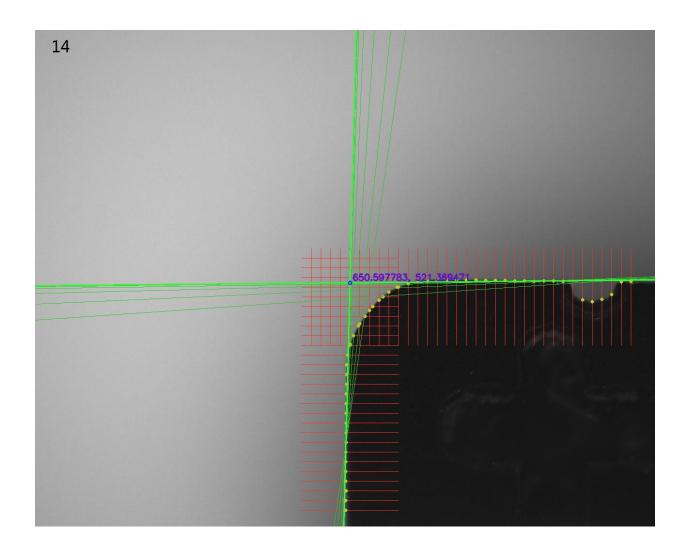


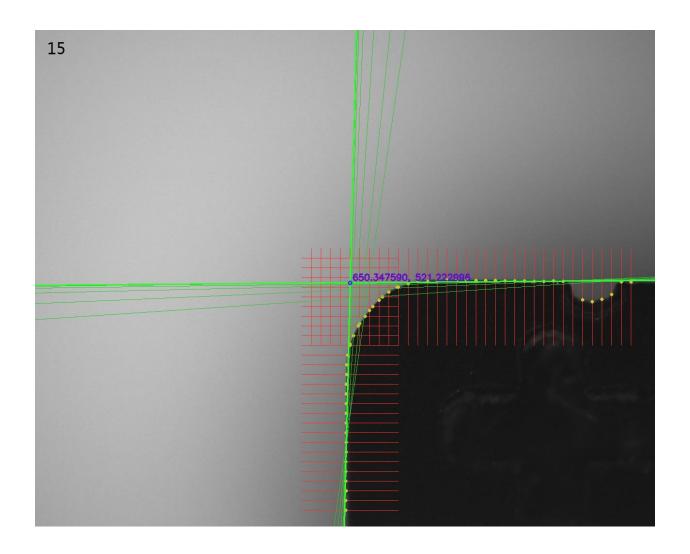


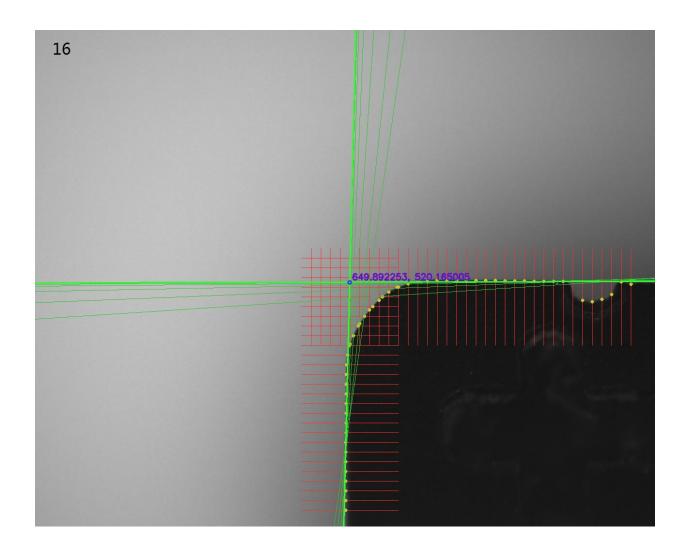


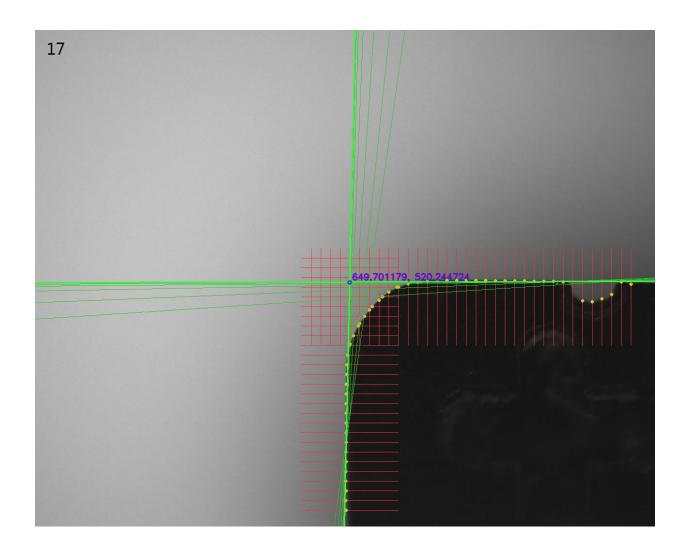


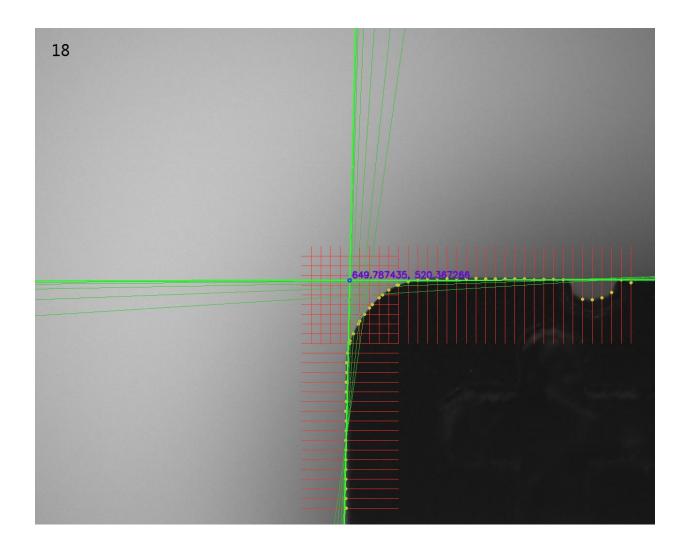


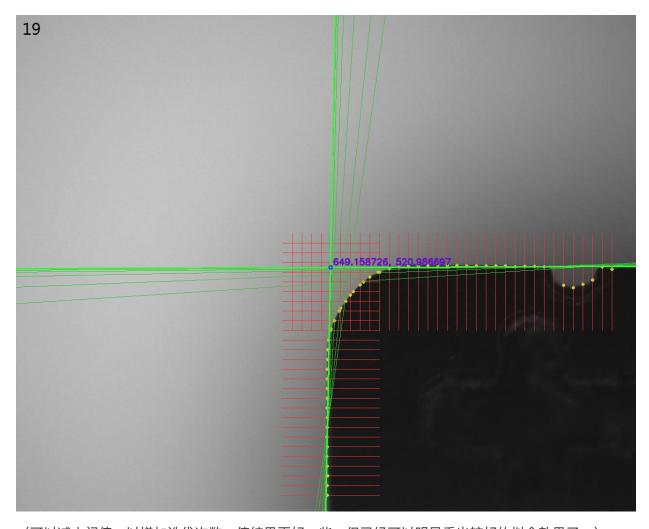












(可以减小阈值,以增加迭代次数,使结果更好一些。但已经可以明显看出较好的拟合效果了。)