



CMSC 5743

Efficient Computing of Deep Neural Networks

Implementation 01: GEMM

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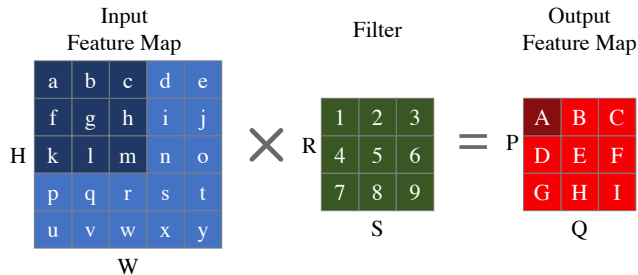
2024 Fall



- ① Convolution Basis
- ② Im2Col
- ③ Memory-efficient Convolution
- ④ Memory Layout

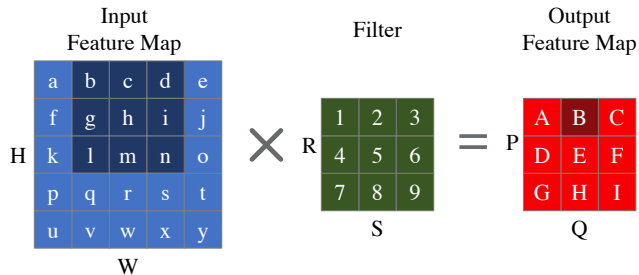


Convolution Basis

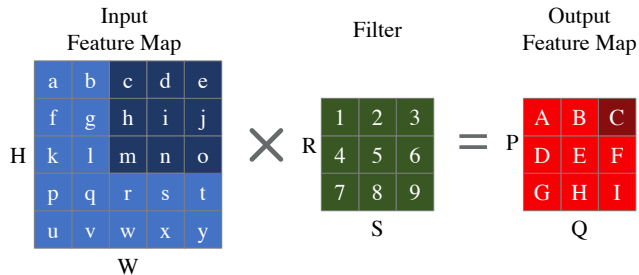


$$\begin{aligned} A &= a \cdot 1 + b \cdot 2 + c \cdot 3 \\ &\quad + f \cdot 4 + g \cdot 5 + h \cdot 6 \\ &\quad + k \cdot 7 + l \cdot 8 + m \cdot 9 \end{aligned}$$

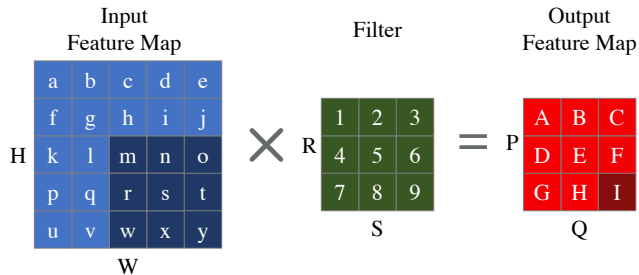
- **H**: Height of input feature map
- **W**: Width of input feature map
- **R**: Height of filter
- **S**: Width of filter
- **P**: Height of output feature map
- **Q**: Width of output feature map



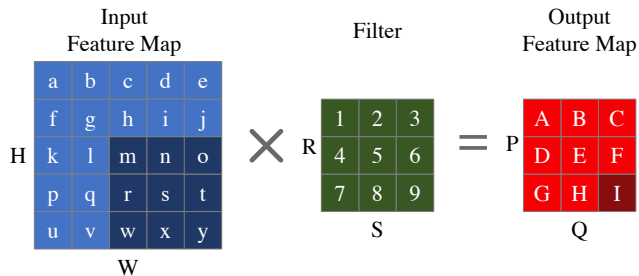
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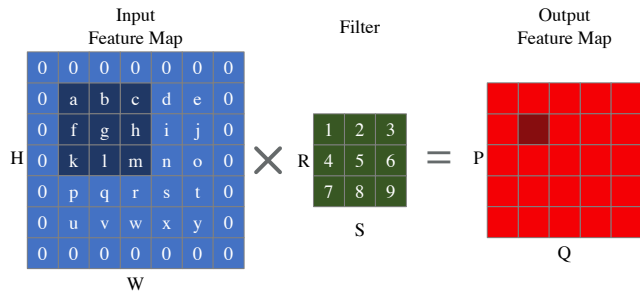


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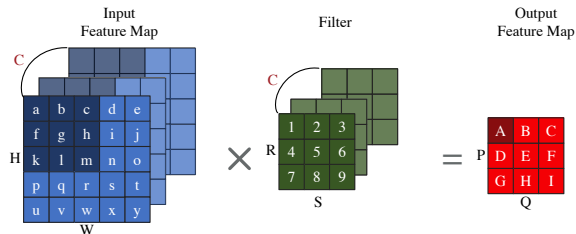
$$P = \frac{(H - R)}{\text{stride}} + 1;$$
$$Q = \frac{(W - S)}{\text{stride}} + 1.$$



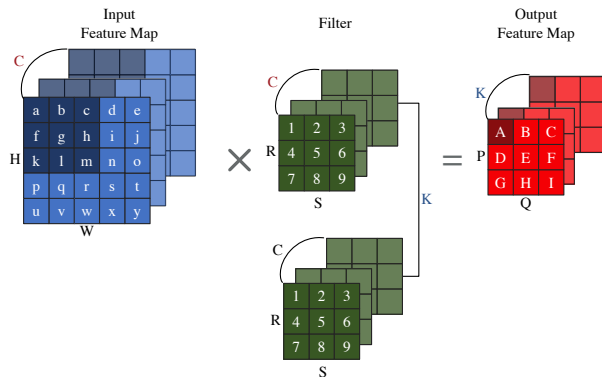
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- **padding**: # of zero rows/columns added

$$P = \frac{(H - R + 2 \cdot \text{padding})}{\text{stride}} + 1;$$

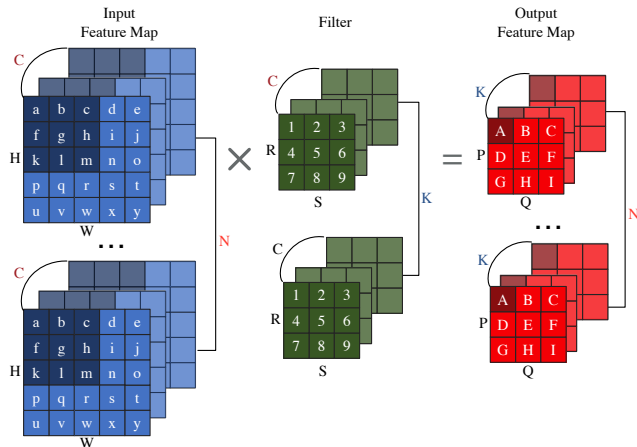
$$Q = \frac{(W - S + 2 \cdot \text{padding})}{\text{stride}} + 1.$$



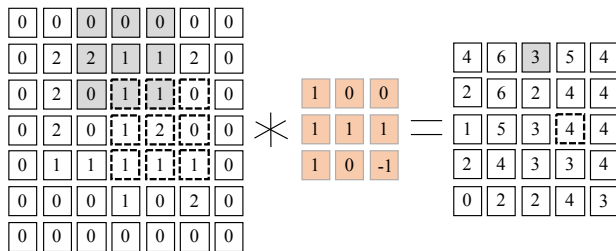
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- **C**: # of input channels



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- **K**: # of output channels

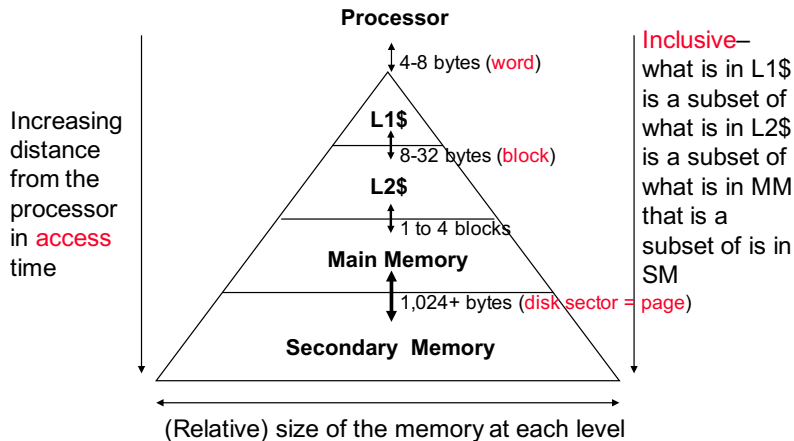


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- C : # of input channels
- K : # of output channels
- N : Batch size



Direct convolution: No extra memory overhead

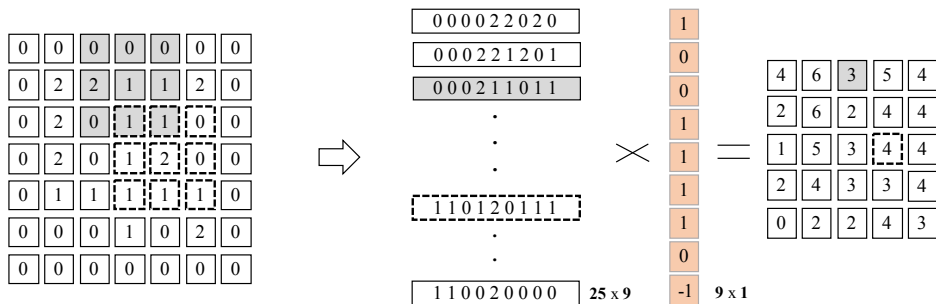
- Low performance
- Poor memory access pattern due to geometry-specific constraint
- Relatively short dot product



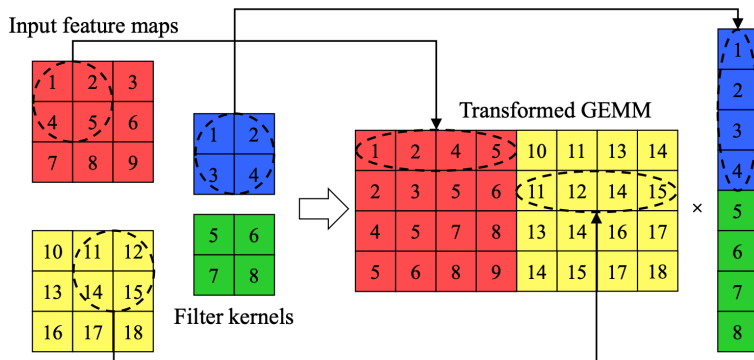
- Spatial locality
- Temporal Locality



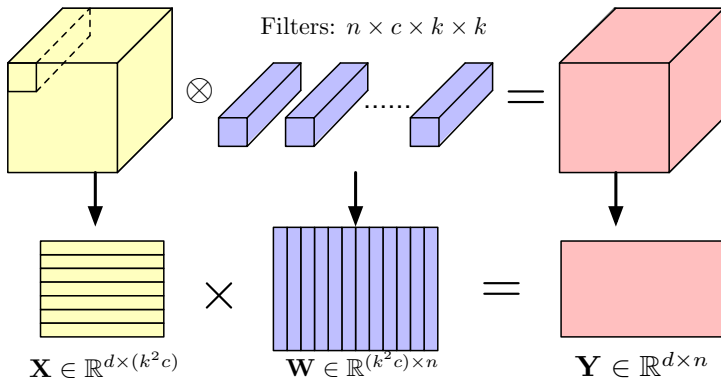
Im2Col



- Large extra memory overhead
- **Good** performance
- BLAS-friendly memory layout to enjoy SIMD/locality/parallelism
- Applicable for any convolution configuration on any platform



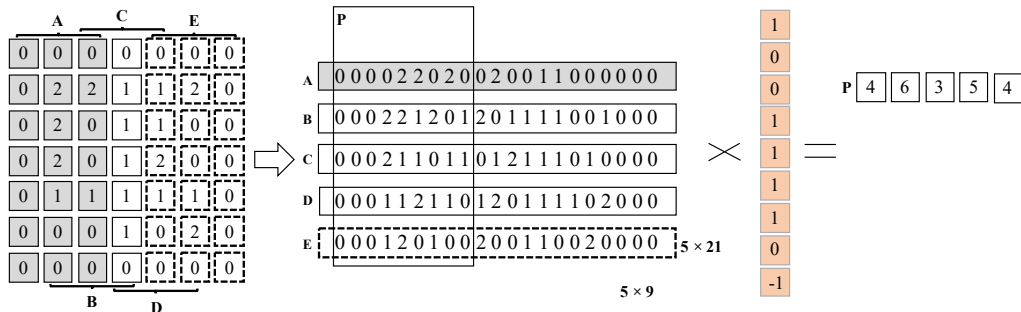
- Input channel #: 2
- Output channel #: 1



- Transform convolution to **matrix multiplication**
- **Unified** calculation for both convolution and fully-connected layers



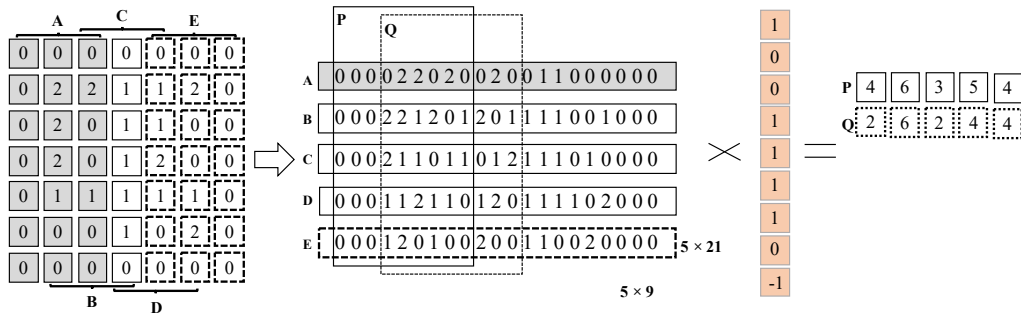
Memory-efficient Convolution



1

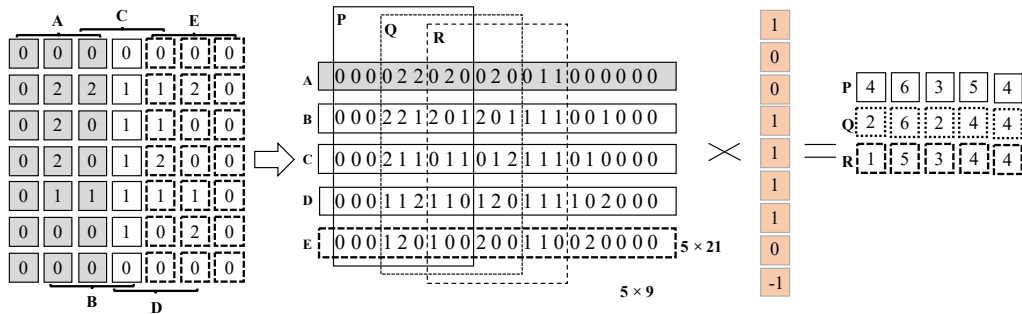
- Sub matrices in the lowered matrix will be “sgemm” ed in parallel
- Smaller memory foot print, cache locality, and explicit parallelism

¹Minsik Cho and Daniel Brand (2017). “MEC: memory-efficient convolution for deep neural network”. In: *Proc. ICML*.



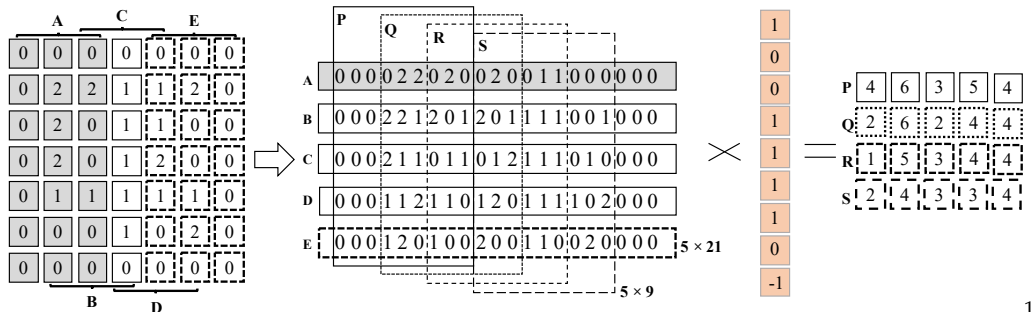
1

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1

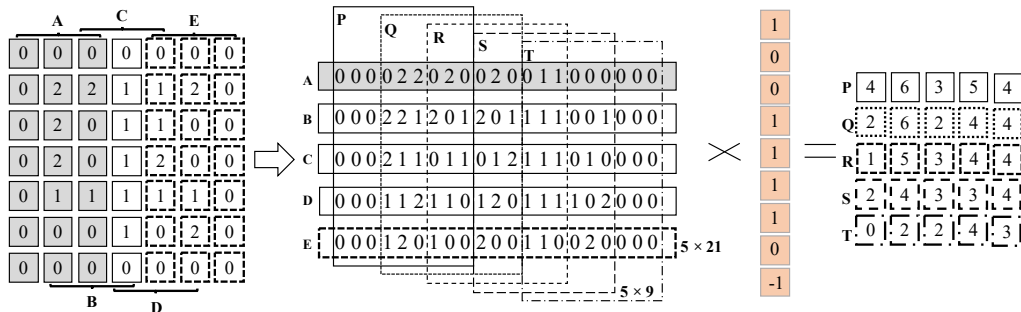
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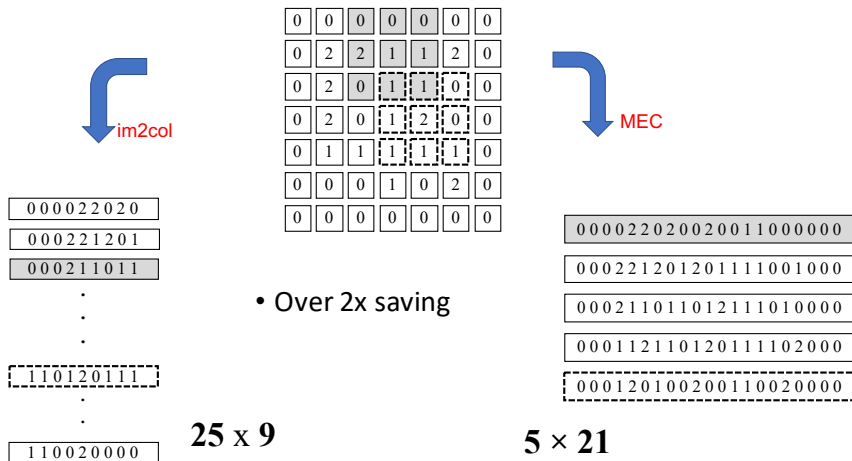
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1

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Over $2\times$ memory saving²:



²Minsik Cho and Daniel Brand (2017). "MEC: memory-efficient convolution for deep neural network". In: *Proc. ICML*.



Memory Layout



- **N** is the batch size
- **C** is the number of feature maps
- **H** is the image height
- **W** is the image width

EXAMPLE**N = 1****C = 64****H = 5****W = 4****c = 0**

0	1	2	3
4	5	6	7
8	9	10	11
12	13	14	15
16	17	18	19

c = 1

20	21	22	23
24	25	26	27
28	29	30	31
32	33	34	35
36	37	38	39

c = 2

40	41	42	43
44	45	46	47
48	49	50	51
52	53	54	55
56	57	58	59

...

c = 30

600	601	602	603
604	605	606	607
608	609	610	611
612	613	614	615
616	617	618	619

c = 31

620	621	622	623
624	625	626	627
628	629	630	631
632	633	634	635
636	637	638	639

c = 32

640	641	642	643
644	645	646	647
648	649	650	651
652	653	654	655
656	657	658	659

...

c = 62

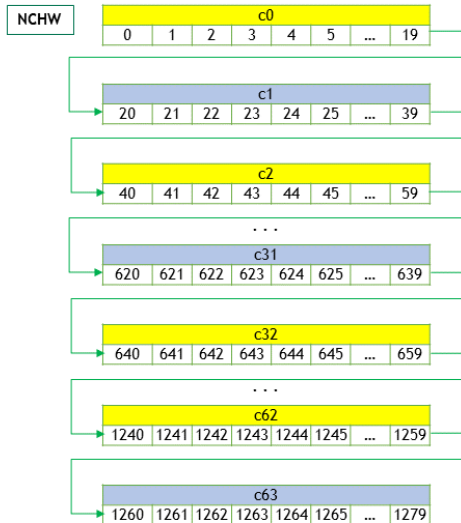
1240	1241	1242	1243
1244	1245	1246	1247
1248	1249	1250	1251
1252	1253	1254	1255
1256	1257	1258	1259

c = 63

1260	1261	1262	1263
1264	1265	1266	1267
1268	1269	1270	1271
1272	1273	1274	1275
1276	1277	1278	1279

...

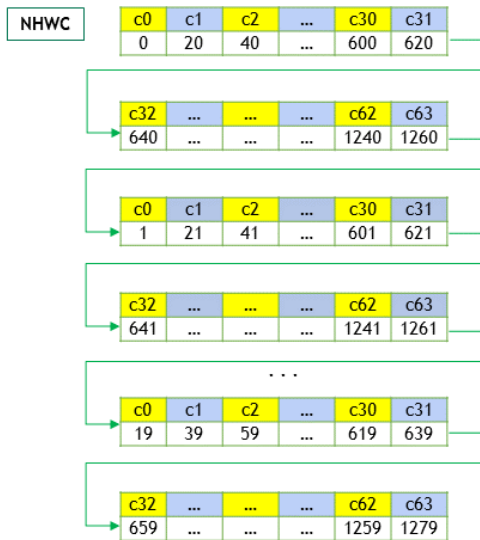
- Begin with first channel ($c=0$), elements arranged contiguously in row-major order
- Continue with second and subsequent channels until all channels are laid out





- Begin with the first element of channel 0, then proceed to the first element of channel 1, and so on, until the first elements of all the C channels are laid out
- Next, select the second element of channel 0, then proceed to the second element of channel 1, and so on, until the second element of all the channels are laid out
- Follow the row-major order of channel 0 and complete all the elements
- Proceed to the next batch (if N is > 1)

NHWC Memory Layout

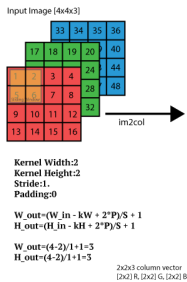


Memory Layout in Im2col

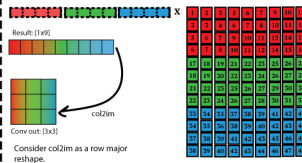


Image to column operation (im2col)

Slide the input image like a convolution but each patch become a column vector.

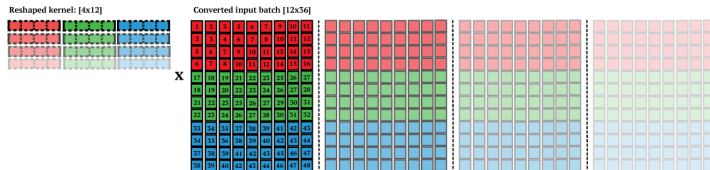


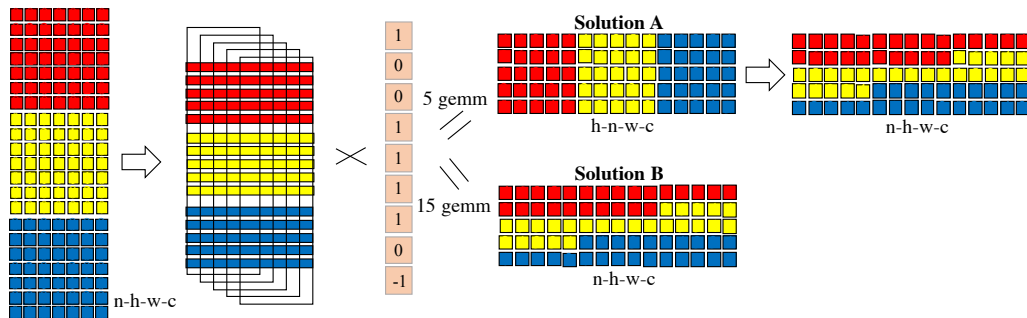
We can multiply this result matrix [12x9] with a kernel [1x12].
result = kernel x matrix
The result would be a row vector [1x9].
We need another operation that will convert this row vector into a image [3x3].



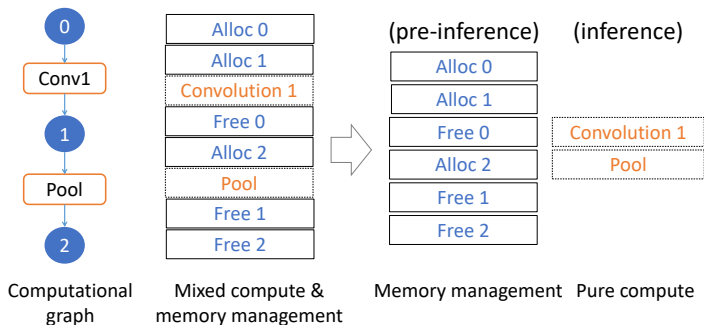
We get true performance gain

when the kernel has a large number of filters, ie: F=4
and/or you have a batch of images (N=4). Example for the input batch [4x4x3x4], convolved with 4 filters [2x2x3x2].
The only problem with this approach is the amount of memory





- MEC w. mini-batch: can use $n-h-w-c$ format
- Fusing convolution+pooling can be another solution



- MNN can infer the exact required memory for the entire graph:
 - virtually walking through all operations
 - summing up all allocation and freeing