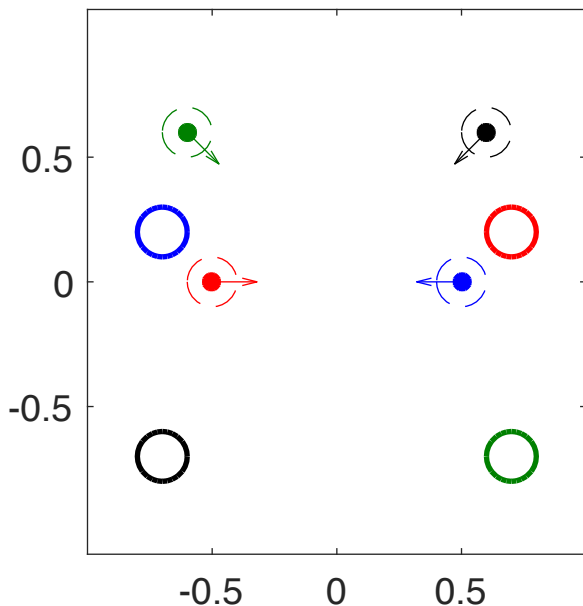
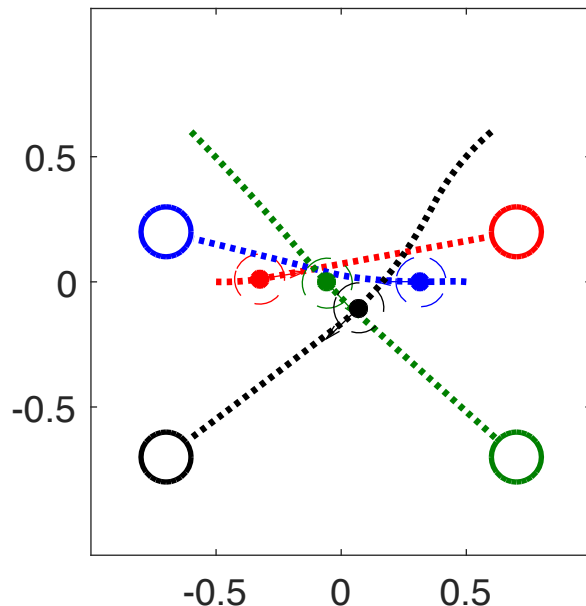


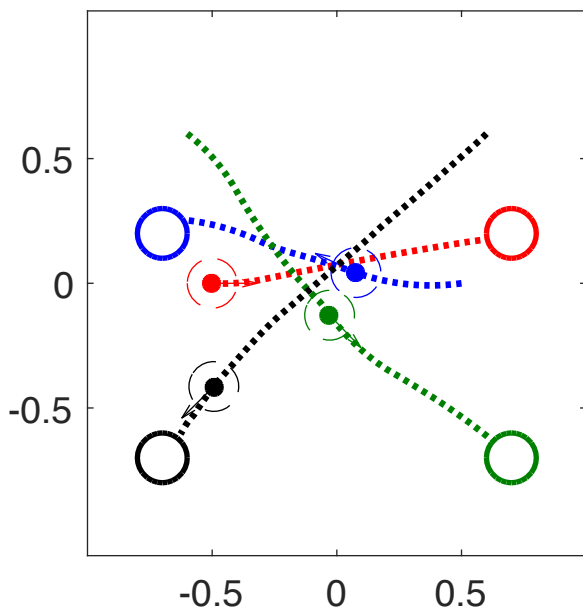
Initial setup



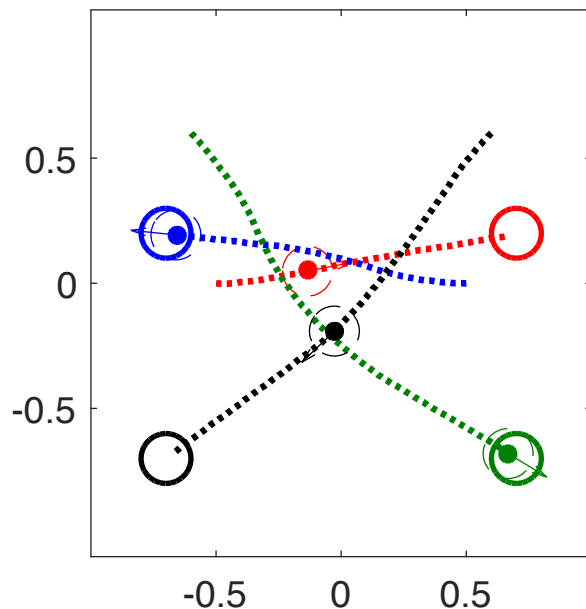
Centralized control



Least restrictive control



Robust trajectory tracking



—●— Vehicle 1 —●— Vehicle 2 —●— Vehicle 3 —●— Vehicle 4

— Targets —●— Positions, Headings *—> Danger Zones - - Trajectories