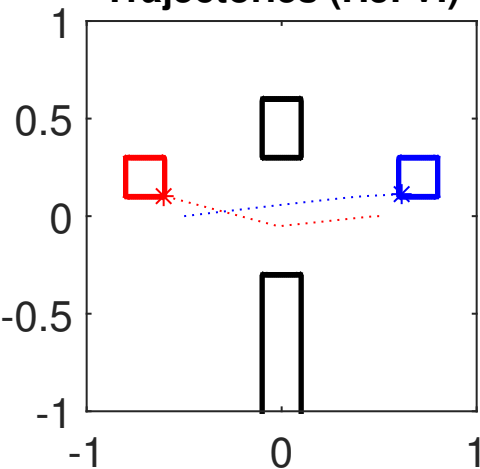
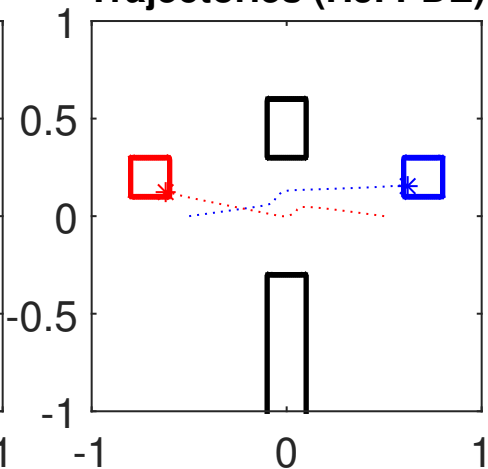


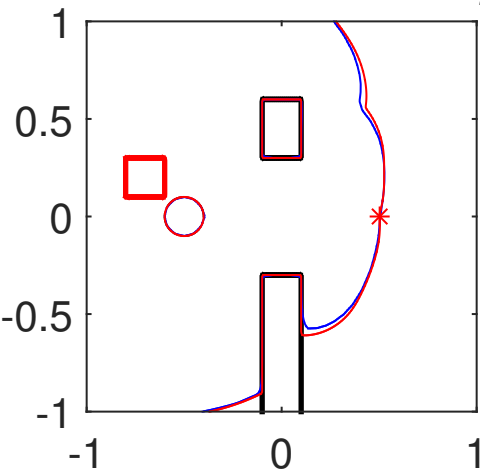
Trajectories (HJI VI)



Trajectories (HJI PDE)



Reach-avoid sets at $t=t_2^i$



- Obstacle
- Target
- ... Trajectory
- * Position
- Reach-avoid set (HJI PDE)
- Reach-avoid set (HJI VI)
- - - Danger zone