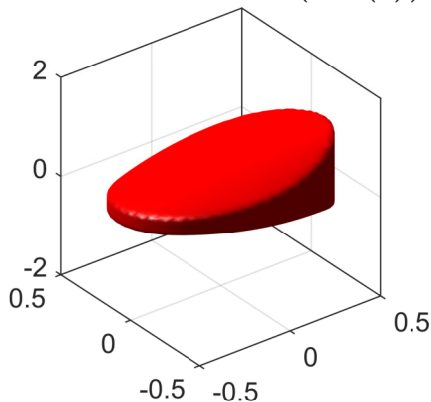
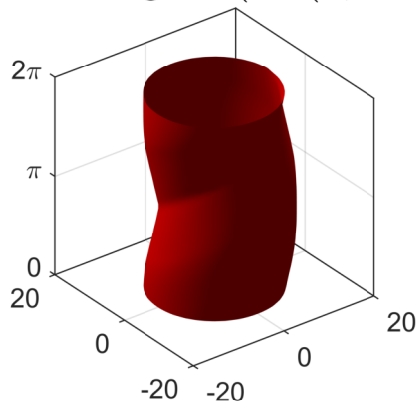


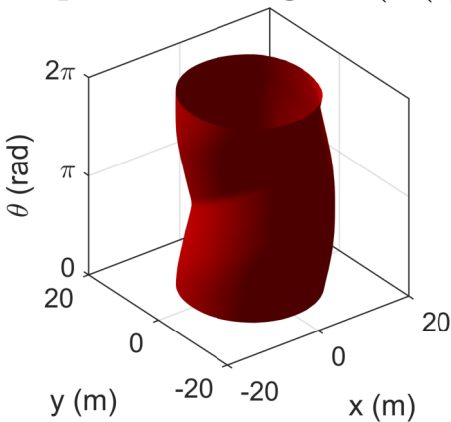
Base Obstacle ( $\mathcal{M}(\underline{t})$ )



Avoid Region ( $\mathcal{V}^A(0, t^{\text{IAT}})$ )



Separation Region ( $\mathcal{S}(\underline{t})$ )



(Relative) Buffer Region ( $\mathcal{V}^B(0, t^{\text{BRD}})$ )

