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1 Basic

1.1 Run

```
1 #use -> sh run.sh {name}
2 g++ -O2 -std=c++14 -Wall -Wextra -Wshadow -o $1 $1.cpp
3 ./ $1 < t.in > t.out
```

1.2 Black Magic

```
1 #include <bits/stdc++.h>
2 #include <ext/pb_ds/assoc_container.hpp>
3 #include <ext/pb_ds/tree_policy.hpp>
4 #include <ext/pb_ds/priority_queue.hpp>
5 using namespace std;
6 using namespace __gnu_pbds;
7 using set_t =
8     tree<int, null_type, less<int>, rb_tree_tag,
9     tree_order_statistics_node_update>;
10 using map_t =
11     tree<int, int, less<int>, rb_tree_tag,
12     tree_order_statistics_node_update>;
13 using heap_t =
14     __gnu_pbds::priority_queue<int>;
15 using ht_t =
16     gp_hash_table<int, int>;
17 int main() {
18     //set-----
19     set_t st;
20     st.insert(5); st.insert(6);
21     st.insert(3); st.insert(1);
22
23     // the smallest is (0), biggest is (n-1), kth small
24     // is (k-1)
25     int num = *st.find_by_order(0);
26     cout << num << '\n'; // print 1
27
28     num = *st.find_by_order(st.size() - 1);
29     cout << num << '\n'; // print 6
30
31     // find the index
32     int index = st.order_of_key(6);
33     cout << index << '\n'; // print 3
```

```
33
34 // check if there exists x
35 int x = 5;
36 int check = st.erase(x);
37 if (check == 0) printf("st not contain 5\n");
38 else if (check == 1) printf("st contain 5\n");
39
40 //tree policy like set
41 st.insert(5); st.insert(5);
42 cout << st.size() << '\n'; // print 4
43
44 //map-----
45 map_t mp;
46 mp[1] = 2;
47 cout << mp[1] << '\n';
48 auto tmp = *mp.find_by_order(0); // pair
49 cout << tmp.first << " " << tmp.second << '\n';
50
51 //heap-----
52 heap_t h1, h2;
53 h1.push(1); h1.push(3);
54 h2.push(2); h2.push(4);
55 h1.join(h2);
56 cout << h1.size() << h2.size() << h1.top() << '\n';
57 // 404
58
59 //hash-table-----
60 ht_t ht;
61 ht[85] = 5;
62 ht[89975] = 234;
63 for (auto i : ht) {
64     cout << i.first << " " << i.second << '\n';
65 }
66 }
```

1.3 Ternary Search

```
1 const double EPS = 1e-6;
2 // target function
3 double f(double x) { return x * x; }
4 double ternarySearch() {
5     double L = -1e5, R = 1e5;
6     while (R - L > EPS) {
7         double mr = (L + R) / 2.0;
8         double ml = (L + mr) / 2.0;
9         if (f(ml) < f(mr)) {
10             R = mr;
11         } else {
12             L = ml;
13         }
14     }
15     return L;
16 }
```

2 Data Structure

2.1 BIT RARSQ

```
1 // 1-base
2 #define lowbit(k) (k & -k)
3
4 int n;
5 vector<int> B1, B2;
6
7 void add(vector<int> &tr, int id, int val) {
8     for (; id <= n; id += lowbit(id)) {
9         tr[id] += val;
10     }
11 }
12 void range_add(int l, int r, int val) {
13     add(B1, l, val);
14     add(B1, r + 1, -val);
```

```

15 add(B2, l, val * (1 - 1));
16 add(B2, r + 1, -val * r);
17 }
18 int sum(vector<int> &tr, int id) {
19     int ret = 0;
20     for (; id >= 1; id -= lowbit(id)) {
21         ret += tr[id];
22     }
23     return ret;
24 }
25 int prefix_sum(int id) {
26     return sum(B1, id) * id - sum(B2, id);
27 }
28 int range_sum(int l, int r) {
29     return prefix_sum(r) - prefix_sum(l - 1);
30 }

```

2.2 zkw RMQ

```

1 // 0-base
2 const int INF = 1e9;
3 const int MAXN = ;
4
5 int n;
6 int a[MAXN], tr[MAXN << 1];
7
8 // !!! remember to call this function
9 void build() {
10     for (int i = 0; i < n; i++) {
11         tr[i + n] = a[i];
12     }
13     for (int i = n - 1; i > 0; i--) {
14         tr[i] = max(tr[i << 1], tr[i << 1 | 1]);
15     }
16 }
17 void update(int id, int val) {
18     for (tr[id += n] = val; id > 1; id >>= 1) {
19         tr[id >> 1] = max(tr[id], tr[id ^ 1]);
20     }
21 }
22 int query(int l, int r) { // [l, r)
23     int ret = -INF;
24     for (l += n, r += n; l < r; l >>= 1, r >>= 1) {
25         if (l & 1) {
26             ret = max(ret, tr[l++]);
27         }
28         if (r & 1) {
29             ret = max(ret, tr[--r]);
30         }
31     }
32     return ret;
33 }

```

2.3 Segment Tree RARMQ

```

1 struct Node {
2     int val, tag;
3     Node *lc, *rc;
4     Node() : lc(nullptr), rc(nullptr), tag(0) {}
5     void pull() {
6         if (!lc) {
7             val = rc->val;
8         } else if (!rc) {
9             val = lc->val;
10        } else {
11            val = max(lc->val, rc->val);
12        }
13    }
14    void push() {
15        if (lc) {
16            lc->tag += tag;
17            lc->val += tag;
18        }

```

```

19        if (rc) {
20            rc->tag += tag;
21            rc->val += tag;
22        }
23        tag = 0;
24    }
25 };
26 struct SegmentTree {
27     Node *root;
28     SegmentTree() : root(nullptr) {}
29     void build(Node* &T, int l, int r, const
30         vector<int> &o) {
31         T = new Node();
32         if (l == r) {
33             T->val = o[l];
34             return;
35         }
36         int mid = (l + r) / 2;
37         build(T->lc, l, mid, o);
38         build(T->rc, mid + 1, r, o);
39         T->pull();
40     }
41     void update(Node* &T, int l, int r, int ql, int qr,
42         int v) {
43         if (ql <= l && r <= qr) {
44             T->val += v;
45             T->tag += v;
46             return;
47         }
48         T->push();
49         int mid = (l + r) / 2;
50         if (qr <= mid) {
51             update(T->lc, l, mid, ql, qr, v);
52         } else if (mid < ql) {
53             update(T->rc, mid + 1, r, ql, qr, v);
54         } else {
55             update(T->lc, l, mid, ql, mid, v);
56             update(T->rc, mid + 1, r, mid + 1, qr, v);
57         }
58         T->pull();
59     }
60     int query(Node* &T, int l, int r, int ql, int qr) {
61         if (ql <= l && r <= qr) {
62             return T->val;
63         }
64         T->push();
65         int mid = (l + r) / 2;
66         if (qr <= mid) {
67             return query(T->lc, l, mid, ql, qr);
68         } else if (mid < ql) {
69             return query(T->rc, mid + 1, r, ql, qr);
70         } else {
71             return max(query(T->lc, l, mid, ql, mid),
72                 query(T->rc, mid + 1, r, mid + 1, qr));
73         }
74     }
75 };

```

2.4 Treap

```

1 struct Treap {
2     int val, pri, sz;
3     Treap *lc, *rc;
4     Treap() {}
5     Treap(int _val) {
6         val = _val;
7         pri = rand();
8         sz = 1;
9         lc = rc = NULL;
10    }
11 };
12 int getSize(Treap *a) { return (a == NULL ? 0 :
13     a->sz); }
14 void split(Treap *t, Treap *&a, Treap *&b, int k) {
15     if (t == NULL) {
16         a = b = NULL;

```

```

16     return;
17 }
18 if (getSize(t->lc) < k) {
19     a = t;
20     split(t->rc, a->rc, b, k - getSize(t->lc) - 1);
21 } else {
22     b = t;
23     split(t->lc, a, b->lc, k);
24 }
25 }
26 Treap *merge(Treap *a, Treap *b) {
27     if (!a || !b) {
28         return (a ? a : b);
29     }
30     if (a->pri > b->pri) {
31         a->rc = merge(a->rc, b);
32         return a;
33     } else {
34         b->lc = merge(a, b->lc);
35         return b;
36     }
37 }
38 void Insert(Treap *&t, int x, int p) {
39     Treap *a, *b;
40     split(t, a, b, x);
41     t = merge(a, merge(new Treap(p), b));
42 }
43 void Delete(Treap *&t, int x) {
44     Treap *a, *b, *c;
45     split(t, b, c, x);
46     split(b, a, b, x - 1);
47     t = merge(a, c);
48 }
49
50 /*
51 Usage
52 Treap *root = NULL; // declare
53 root = merge(root, new Treap(val)); // push back
54 Insert(root, x, y); // insert y after x-th element
55 Delete(root, x); // delete x-th element
56 */

```

3 Graph

3.1 Directed MST

```

1 // 0-base
2 const LL INF = 1e18;
3 const int MAXN = ;
4
5 struct Edge {
6     int from;
7     int to;
8     LL cost;
9     Edge(int u, int v, LL c) : from(u), to(v), cost(c) {}
10 };
11
12 struct DMST {
13     int n;
14     int vis[MAXN], pre[MAXN], id[MAXN];
15     LL in[MAXN];
16     vector<Edge> edges;
17     void init(int _n) {
18         n = _n;
19         edges.clear();
20     }
21     void add_edge(int from, int to, LL cost) {
22         edges.eb(from, to, cost);
23     }
24     LL run(int root) {
25         LL ret = 0;
26         while (true) {
27             for (int i = 0; i < n; i++) {

```

```

28         in[i] = INF;
29     }
30
31     // find in edge
32     for (auto &e : edges) {
33         if (e.cost < in[e.to] && e.from != e.to) {
34             pre[e.to] = e.from;
35             in[e.to] = e.cost;
36         }
37     }
38
39     // check in edge
40     for (int i = 0; i < n; i++) {
41         if (i == root) {
42             continue;
43         }
44         if (in[i] == INF) {
45             return -1;
46         }
47     }
48
49     int nodenum = 0;
50     memset(id, -1, sizeof(id));
51     memset(vis, -1, sizeof(vis));
52     in[root] = 0;
53
54     // find cycles
55     for (int i = 0; i < n; i++) {
56         ret += in[i];
57         int v = i;
58         while (vis[v] != i && id[v] == -1 && v != root) {
59             vis[v] = i;
60             v = pre[v];
61         }
62         if (id[v] == -1 && v != root) {
63             for (int j = pre[v]; j != v; j = pre[j]) {
64                 id[j] = nodenum;
65             }
66             id[v] = nodenum++;
67         }
68     }
69
70     // no cycle
71     if (nodenum == 0) {
72         break;
73     }
74
75     for (int i = 0; i < n; i++) {
76         if (id[i] == -1) {
77             id[i] = nodenum++;
78         }
79     }
80
81     // grouping the vertices
82     for (auto &e : edges) {
83         int to = e.to;
84         e.from = id[e.from];
85         e.to = id[e.to];
86         if (e.from != e.to) {
87             e.cost -= in[to]; //!!!
88         }
89     }
90
91     n = nodenum;
92     root = id[root];
93 }
94 return ret;
95 }
96 };

```

3.2 LCA

```

1 const int LOG = 20;
2 vector<int> tin(MAXN), tout(MAXN), depth(MAXN);
3 int par[MAXN][LOG];

```

```

4 int timer = 0;
5 vector<int> G[MAXN];
6
7 void dfs(int u, int f) {
8     tin[u] = ++timer;
9     par[u][0] = f;
10    for (int v : G[u]) {
11        if (v != f) {
12            depth[v] = depth[u] + 1;
13            dfs(v, u);
14        }
15    }
16    tout[u] = ++timer;
17 }
18
19 void Doubling(int n) {
20     for (int j = 1; j < LOG; ++j) {
21         for (int i = 1; i <= n; ++i) {
22             par[i][j] = par[par[i][j - 1]][j - 1];
23         }
24     }
25 }
26
27 bool anc(int u, int v) { return tin[u] <= tin[v] &&
    tout[v] <= tout[u]; }
28
29 int LCA(int u, int v) {
30     if (depth[u] > depth[v]) {
31         swap(u, v);
32     }
33     if (anc(u, v)) {
34         return u;
35     }
36     for (int j = LOG - 1; j >= 0; --j) {
37         if (!anc(par[u][j], v)) u = par[u][j];
38     }
39     return par[u][0];
40 }
41
42 int dis(int u, int v) {
43     int lca = LCA(u, v);
44     return depth[u] + depth[v] - 2 * depth[lca];
45 }
46
47 /*
48 dfs(root, root);
49 Doubling(n);
50 */

```

3.3 Euler Circuit

七橋問題根據起點與終點是否相同，分成 Euler path (不同) 及 Euler circuit (相同)。

- 判斷法
 - 無向圖部分，將點分成奇點（度數為奇數）和偶點（度數為偶數）。
 - Euler path：奇點數為 0 或 2
 - Euler circuit：沒有奇點
 - 有向圖部分，將點分成出點（出度 - 入度 = 1）和入點（入度 - 出度 = 1）還有平衡點（出度 = 入度）。
 - Euler path：出點和入點個數同時為 0 或 1。
 - Euler circuit：只有平衡點。
- 求出一組解
- 用 DFS 遍歷整張圖，設 S 為離開的順序，無向圖的答案為 S ，有向圖的答案為反向的 S 。
- DFS 起點選定：
 - Euler path：無向圖選擇任意一個奇點，有向圖選擇出點。
 - Euler circuit：任意一點。

```

1 // Code from Eric
2 #define ll long long
3 #define PB push_back
4 #define EB emplace_back
5 #define PII pair<int, int>
6 #define MP make_pair
7 #define all(x) x.begin(), x.end()
8 #define maxn 50000+5
9
10 //structure
11 struct Euler {
12     vector<PII> adj[maxn];
13     vector<bool> edges;
14     vector<PII> path;
15     int chk[maxn];
16     int n;
17
18     void init(int _n) {
19         n = _n;
20         for (int i = 0; i <= n; i++) adj[i].clear();
21         edges.clear();
22         path.clear();
23         memset(chk, 0, sizeof(chk));
24     }
25
26     void dfs(int v) {
27         for (auto i : adj[v]) {
28             if (edges[i.first] == true) {
29                 edges[i.first] = false;
30                 dfs(i.second);
31                 path.EB(MP(i.second, v));
32             }
33         }
34     }
35
36     void add_Edge(int from, int to) {
37         edges.PB(true);
38
39         // for bi-directed graph
40         adj[from].PB(MP(edges.size() - 1, to));
41         adj[to].PB(MP(edges.size() - 1, from));
42         chk[from]++;
43         chk[to]++;
44
45         // for directed graph
46         // adj[from].PB(MP(edges.size()-1, to));
47         // check[from]++;
48     }
49
50     bool euler_path() {
51         int st = -1;
52         for (int i = 1; i <= n; i++) {
53             if (chk[i] % 2 == 1) {
54                 st = i;
55                 break;
56             }
57         }
58         if (st == -1) {
59             return false;
60         }
61         dfs(st);
62         return true;
63     }
64
65     void print_path(void) {
66         for (auto i : path) {
67             printf("%d %d\n", i.first, i.second);
68         }
69     }
70 };
71
72 // Code from allen(lexicographic order)
73 #include <bits/stdc++.h>
74 using namespace std;
75 const int ALP = 30;
76 const int MXN = 1005;
77 int n;
78 int din[ALP], dout[ALP];

```

```

8  int par[ALP];
9  vector<string> vs[MXN], ans;
10 bitset<MXN> vis, used[ALP];
11
12 void djsInit() {
13     for (int i = 0; i != ALP; ++i) {
14         par[i] = i;
15     }
16 }
17
18 int Find(int x) { return (x == par[x] ? (x) : (par[x]
    = Find(par[x]))); }
19
20 void init() {
21     djsInit();
22     memset(din, 0, sizeof(din));
23     memset(dout, 0, sizeof(dout));
24     vis.reset();
25     for (int i = 0; i != ALP; ++i) {
26         vs[i].clear();
27         used[i].reset();
28     }
29     return;
30 }
31
32 void dfs(int u) {
33     for (int i = 0; i != (int)vs[u].size(); ++i) {
34         if (used[u][i]) {
35             continue;
36         }
37         used[u][i] = 1;
38         string s = vs[u][i];
39         int v = s[s.size() - 1] - 'a';
40         dfs(v);
41         ans.push_back(s);
42     }
43 }
44
45 bool solve() {
46     int cnt = 1;
47     for (int i = 0; i != n; ++i) {
48         string s;
49         cin >> s;
50         int from = s[0] - 'a', to = s.back() - 'a';
51         ++din[to];
52         ++dout[from];
53         vs[from].push_back(s);
54         vis[from] = vis[to] = true;
55         if ((from = Find(from)) != (to = Find(to))) {
56             par[from] = to;
57             ++cnt;
58         }
59     }
60     if ((int)vis.count() != cnt) {
61         return false;
62     }
63     int root, st, pin = 0, pout = 0;
64     for (int i = ALP - 1; i >= 0; --i) {
65         sort(vs[i].begin(), vs[i].end());
66         if (vs[i].size()) root = i;
67         int d = dout[i] - din[i];
68         if (d == 1) {
69             ++pout;
70             st = i;
71         } else if (d == -1) {
72             ++pin;
73         } else if (d != 0) {
74             return false;
75         }
76     }
77     if (pin != pout || pin > 1) {
78         return false;
79     }
80     ans.clear();
81     dfs((pin ? st : root));
82     return true;
83 }

```

```

84
85 int main() {
86     int t;
87     cin >> t;
88     while (t--) {
89         cin >> n;
90         init();
91         if (!solve()) {
92             cout << "***\n";
93             continue;
94         }
95         for (int i = ans.size() - 1; i >= 0; --i) {
96             cout << ans[i] << ".\n"[i == 0];
97         }
98     }
99 }

```

4 Connectivity

4.1 Articulation Point

```

1  // from aizu
2  typedef long long int ll;
3  typedef unsigned long long int ull;
4  #define BIG_SIZE 200000000
5  #define MOD 1000000007
6  #define EPS 0.000000001
7  using namespace std;
8
9  #define SIZE 100000
10
11 vector<int> G[SIZE];
12 int N;
13 bool visited[SIZE];
14 int visited_order[SIZE], parent[SIZE], lowest[SIZE],
    number;
15
16 void dfs(int cur, int pre_node) {
17     visited_order[cur] = lowest[cur] = number;
18     number++;
19
20     visited[cur] = true;
21
22     int next;
23
24     for (int i = 0; i < G[cur].size(); i++) {
25         next = G[cur][i];
26         if (!visited[next]) {
27             parent[next] = cur;
28             dfs(next, cur);
29             lowest[cur] = min(lowest[cur], lowest[next]);
30         } else if (visited[next] == true && next !=
            pre_node) {
31             lowest[cur] = min(lowest[cur],
                visited_order[next]);
32         }
33     }
34 }
35
36 void art_points() {
37     for (int i = 0; i < N; i++) visited[i] = false;
38
39     number = 1;
40     dfs(0, -1);
41
42     int tmp_parent, root_num = 0;
43
44     vector<int> V;
45
46     for (int i = 1; i < N; i++) {
47         tmp_parent = parent[i];
48         if (tmp_parent == 0) {
49             root_num++;

```

```

50     } else if (visited_order[tmp_parent] <=
        lowest[i]) {
51         V.push_back(tmp_parent);
52     }
53 }
54 if (root_num >= 2) {
55     V.push_back(0);
56 }
57 sort(V.begin(), V.end());
58 V.erase(unique(V.begin(), V.end()), V.end());
59
60 for (int i = 0; i < V.size(); i++) {
61     printf("%d\n", V[i]);
62 }
63 }
64
65 int main() {
66     int E;
67     scanf("%d %d", &N, &E);
68     int from, to;
69     for (int i = 0; i < E; i++) {
70         scanf("%d %d", &from, &to);
71         G[from].push_back(to);
72         G[to].push_back(from);
73     }
74     art_points();
75 }

```

4.2 Bridges

```

1 // from aizu
2 typedef long long int ll;
3 typedef unsigned long long int ull;
4 #define BIG_NUM 2000000000
5 #define MOD 1000000007
6 #define EPS 0.000000001
7 using namespace std;
8
9 struct Edge {
10     bool operator<(const struct Edge &arg) const {
11         if (s != arg.s) {
12             return s < arg.s;
13         } else {
14             return t < arg.t;
15         }
16     }
17     int s, t;
18 };
19 struct Info {
20     Info(int arg_to, int arg_edge_id) {
21         to = arg_to;
22         edge_id = arg_edge_id;
23     }
24     int to, edge_id;
25 };
26
27 int V, E, number;
28 int order[100000], lowlink[100000];
29 bool visited[100000];
30 Edge edge[100000];
31 vector<Info> G[100000];
32
33 void recursive(int cur) {
34     order[cur] = number++;
35     lowlink[cur] = order[cur];
36
37     int next;
38
39     for (int i = 0; i < G[cur].size(); i++) {
40         next = G[cur][i].to;
41
42         if (order[next] == -1) {
43             visited[G[cur][i].edge_id] = true;
44             recursive(next);
45             lowlink[cur] = min(lowlink[cur], lowlink[next]);
46

```

```

47     } else if (visited[G[cur][i].edge_id] == false) {
48         lowlink[cur] = min(lowlink[cur], order[next]);
49     }
50 }
51 }
52
53 int main() {
54     scanf("%d %d", &V, &E);
55     for (int i = 0; i < E; i++) {
56         scanf("%d %d", &edge[i].s, &edge[i].t);
57         if (edge[i].s > edge[i].t) {
58             swap(edge[i].s, edge[i].t);
59         }
60         G[edge[i].s].push_back(Info(edge[i].t, i));
61         G[edge[i].t].push_back(Info(edge[i].s, i));
62     }
63
64     sort(edge, edge + E);
65
66     number = 0;
67     for (int i = 0; i < V; i++) {
68         order[i] = -1;
69         lowlink[i] = -1;
70     }
71     for (int i = 0; i < E; i++) {
72         visited[i] = false;
73     }
74
75     recursive(0);
76
77     int from, to;
78     for (int i = 0; i < E; i++) {
79         from = edge[i].s;
80         to = edge[i].t;
81         if (order[edge[i].s] > order[edge[i].t]) {
82             swap(from, to);
83         }
84         if (order[from] < lowlink[to]) {
85             printf("%d %d\n", edge[i].s, edge[i].t);
86         }
87     }
88     return 0;
89 }

```

5 Flow & Matching

5.1 Relation

```

1 1. 一般圖
2 |最大匹配| + |最小邊覆蓋| = |V|
3 |最大獨立集| + |最小點覆蓋| = |V|
4 |最大圖| = |補圖的最大獨立集|
5 2. 二分圖
6 |最大匹配| = |最小點覆蓋|
7 |最大獨立集| = |最小邊覆蓋|
8 |最大獨立集| = |V| - |最大匹配|
9 |最大圖| = |補圖的最大獨立集|

```

5.2 Bipartite Matching

```

1 // 0-base
2 const int MAXN = ;
3 int n;
4 vector<int> G[MAXN];
5 int vy[MAXN], my[MAXN];
6
7 bool match(int u) {
8     for (int v : G[u]) {
9         if (vy[v]) {
10             continue;
11         }

```

```

12     vy[v] = true;
13     if (my[v] == -1 || match(my[v])) {
14         my[v] = u;
15         return true;
16     }
17 }
18 return false;
19 }
20 int sol() {
21     int cnt = 0;
22     memset(my, -1, sizeof(my));
23     for (int i = 0; i < n; i++) {
24         memset(vy, 0, sizeof(vy));
25         if (match(i)) {
26             cnt++;
27         }
28     }
29     return cnt;
30 }

```

5.3 KM

```

1 const int INF = 1e9;
2 const int MAXN = ;
3 struct KM { //1-base
4     int n, G[MAXN][MAXN];
5     int lx[MAXN], ly[MAXN], my[MAXN];
6     bool vx[MAXN], vy[MAXN];
7     void init(int _n) {
8         n = _n;
9         for (int i = 1; i <= n; i++) {
10             for (int j = 1; j <= n; j++) {
11                 G[i][j] = 0;
12             }
13         }
14     }
15     bool match(int i) {
16         vx[i] = true;
17         for (int j = 1; j <= n; j++) {
18             if (lx[i] + ly[j] == G[i][j] && !vy[j]) {
19                 vy[j] = true;
20                 if (!my[j] || match(my[j])) {
21                     my[j] = i;
22                     return true;
23                 }
24             }
25         }
26         return false;
27     }
28     void update() {
29         int delta = INF;
30         for (int i = 1; i <= n; i++) {
31             if (vx[i]) {
32                 for (int j = 1; j <= n; j++) {
33                     if (!vy[j]) {
34                         delta = min(delta, lx[i] + ly[j] -
35                             G[i][j]);
36                     }
37                 }
38             }
39             for (int i = 1; i <= n; i++) {
40                 if (vx[i]) {
41                     lx[i] -= delta;
42                 }
43                 if (vy[i]) {
44                     ly[i] += delta;
45                 }
46             }
47         }
48     }
49     int run() {
50         for (int i = 1; i <= n; i++) {
51             lx[i] = ly[i] = my[i] = 0;
52             for (int j = 1; j <= n; j++) {
53                 lx[i] = max(lx[i], G[i][j]);
54             }
55         }
56     }
57 }

```

```

54 }
55 for (int i = 1; i <= n; i++) {
56     while (true) {
57         for (int i = 1; i <= n; i++) {
58             vx[i] = vy[i] = 0;
59         }
60         if (match(i)) {
61             break;
62         } else {
63             update();
64         }
65     }
66 }
67 int ans = 0;
68 for (int i = 1; i <= n; i++) {
69     ans += lx[i] + ly[i];
70 }
71 return ans;
72 }
73 };

```

5.4 Dinic

```

1 #define eb emplace_back
2 const LL INF = 1e18;
3 const int MAXN = ;
4 struct Edge {
5     int to;
6     LL cap;
7     int rev;
8     Edge(int v, LL c, int r) : to(v), cap(c), rev(r) {}
9 };
10 struct Dinic {
11     int n;
12     int level[MAXN], now[MAXN];
13     vector<Edge> G[MAXN];
14     void init(int _n) {
15         n = _n;
16         for (int i = 0; i <= n; i++) {
17             G[i].clear();
18         }
19     }
20     void add_edge(int u, int v, LL c) {
21         G[u].eb(v, c, G[v].size());
22         // directed graph
23         G[v].eb(u, 0, G[u].size() - 1);
24         // undirected graph
25         // G[v].eb(u, c, G[u].size() - 1);
26     }
27     bool bfs(int st, int ed) {
28         fill(level, level + n + 1, -1);
29         queue<int> q;
30         q.push(st);
31         level[st] = 0;
32         while (!q.empty()) {
33             int u = q.front();
34             q.pop();
35             for (const auto &e : G[u]) {
36                 if (e.cap > 0 && level[e.to] == -1) {
37                     level[e.to] = level[u] + 1;
38                     q.push(e.to);
39                 }
40             }
41         }
42         return level[ed] != -1;
43     }
44     LL dfs(int u, int ed, LL limit) {
45         if (u == ed) {
46             return limit;
47         }
48         LL ret = 0;
49         for (int &i = now[u]; i < G[u].size(); i++) {
50             auto &e = G[u][i];
51             if (e.cap > 0 && level[e.to] == level[u] + 1) {
52                 LL f = dfs(e.to, ed, min(limit, e.cap));
53                 ret += f;
54             }
55         }
56         now[u] = i;
57         return ret;
58     }
59 }

```

```

54     limit -= f;
55     e.cap -= f;
56     G[e.to][e.rev].cap += f;
57     if (!limit) {
58         return ret;
59     }
60 }
61 }
62 if (!ret) {
63     level[u] = -1;
64 }
65 return ret;
66 }
67 LL flow(int st, int ed) {
68     LL ret = 0;
69     while (bfs(st, ed)) {
70         fill(now, now + n + 1, 0);
71         ret += dfs(st, ed, INF);
72     }
73     return ret;
74 }
75 };

```

5.5 MCMF

```

1 // 0-base
2 const LL INF = 1e18;
3 const int MAXN = ;
4 struct Edge {
5     int u, v;
6     LL cost;
7     LL cap;
8     Edge(int _u, int _v, LL _c, LL _cap) : u(_u),
9         v(_v), cost(_c), cap(_cap) {}
10 };
11 struct MCMF { // inq times
12     int n, pre[MAXN], cnt[MAXN];
13     LL ans_flow, ans_cost, dis[MAXN];
14     bool inq[MAXN];
15     vector<int> G[MAXN];
16     vector<Edge> edges;
17     void init(int _n) {
18         n = _n;
19         edges.clear();
20         for (int i = 0; i < n; i++) {
21             G[i].clear();
22         }
23     }
24     void add_edge(int u, int v, LL c, LL cap) {
25         // directed
26         G[u].pb(edges.size());
27         edges.pb(u, v, c, cap);
28         G[v].pb(edges.size());
29         edges.pb(v, u, -c, 0);
30     }
31     bool SPFA(int st, int ed) {
32         for (int i = 0; i < n; i++) {
33             pre[i] = -1;
34             dis[i] = INF;
35             cnt[i] = 0;
36             inq[i] = false;
37         }
38         queue<int> q;
39         bool negcycle = false;
40
41         dis[st] = 0;
42         cnt[st] = 1;
43         inq[st] = true;
44         q.push(st);
45
46         while (!q.empty() && !negcycle) {
47             int u = q.front();
48             q.pop();
49             inq[u] = false;
50             for (int i : G[u]) {
51                 int v = edges[i].v;

```

```

51         LL cost = edges[i].cost;
52         LL cap = edges[i].cap;
53
54         if (dis[v] > dis[u] + cost && cap > 0) {
55             dis[v] = dis[u] + cost;
56             pre[v] = i;
57             if (!inq[v]) {
58                 q.push(v);
59                 cnt[v]++;
60                 inq[v] = true;
61
62                 if (cnt[v] == n + 2) {
63                     negcycle = true;
64                     break;
65                 }
66             }
67         }
68     }
69 }
70
71 return dis[ed] != INF;
72 }
73 LL sendFlow(int v, LL curFlow) {
74     if (pre[v] == -1) {
75         return curFlow;
76     }
77     int i = pre[v];
78     int u = edges[i].u;
79     LL cost = edges[i].cost;
80
81     LL f = sendFlow(u, min(curFlow, edges[i].cap));
82
83     ans_cost += f * cost;
84     edges[i].cap -= f;
85     edges[i ^ 1].cap += f;
86     return f;
87 }
88 pair<LL, LL> run(int st, int ed) {
89     ans_flow = ans_cost = 0;
90     while (SPFA(st, ed)) {
91         ans_flow += sendFlow(ed, INF);
92     }
93     return make_pair(ans_flow, ans_cost);
94 }
95 };

```

6 String

6.1 Manacher

```

1 int p[2 * MAXN];
2 int Manacher(const string &s) {
3     string st = "@#";
4     for (char c : s) {
5         st += c;
6         st += '#';
7     }
8     st += '$';
9     int id = 0, mx = 0, ans = 0;
10    for (int i = 1; i < st.length() - 1; i++) {
11        p[i] = (mx > i ? min(p[2 * id - i], mx - i) : 1);
12        for (; st[i - p[i]] == st[i + p[i]]; p[i]++);
13        if (mx < i + p[i]) {
14            mx = i + p[i];
15            id = i;
16        }
17        ans = max(ans, p[i] - 1);
18    }
19    return ans;
20 }

```

6.2 Trie


```
1 const int MAXL = ;
2 const int MAXC = ;
3 struct Trie {
4     int nex[MAXL][MAXC];
5     int len[MAXL];
6     int sz;
7     void init() {
8         memset(nex, 0, sizeof(nex));
9         memset(len, 0, sizeof(len));
10        sz = 0;
11    }
12    void insert(const string &str) {
13        int p = 0;
14        for (char c : str) {
15            int id = c - 'a';
16            if (!nex[p][id]) {
17                nex[p][id] = ++sz;
18            }
19            p = nex[p][id];
20        }
21        len[p] = str.length();
22    }
23    vector<int> find(const string &str, int i) {
24        int p = 0;
25        vector<int> ans;
26        for (; i < str.length(); i++) {
27            int id = str[i] - 'a';
28            if (!nex[p][id]) {
29                return ans;
30            }
31            p = nex[p][id];
32            if (len[p]) {
33                ans.pb(len[p]);
34            }
35        }
36        return ans;
37    }
38 };
```