EKFMONOSLAM FOR THE INTELLITABLE ROBOT

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1. Introduction

The EKFmonoSLAM uses a EKF SLAM algorithm originally designed by Joan Sola [1]

2. Quick Setup

References

[1] Joan Sola, Teresa Vidal-Calleja, Javier Civera, and Jos'e Mar'ia Mart'inez Montiel. Impact of land-mark parametrization on monocular ekf-slam with points and lines. *International journal of computer vision*, 97(3):339–368, 2012.