
Indirect Evidence of Network Effects in a System of Cities

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Abstract

This paper is the application of a theoretical paper developing a theory of co-evolutive networked territorial systems. We apply simple models of urban growth for systems of cities, which include in particular the role of physical networks.

Keywords

Urban Systems, Urban Growth, Spatial Interactions

1 Introduction

1.1 Modeling Urban Growth

Understanding processes driving urban growth is more crucial than ever, as urban population recently crossed the symbolic proportion of half world population .Future of world economies and sustainability of future societies seem to be deeply interlinked with the dynamics of urban systems.A better knowledge of how cities differentiate, interact and grow is thus a relevant topic both theoretically and for application. Many disciplines have studied models of urban growth with different objectives and taking different aspects into account. Economics still have a difficulty to consider spatial interactions in their models **Krugman (1998)**, whereas geography fails to embrace a certain level of complexity. The example of this two disciplines shows how it is difficult to make bridges, as it needed exceptional minds to translate from one to the other (as P. Hall did for Von Thunen work **Taylor (2016)**)

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1.2 Urban Growth and Spatial Interaction

Bretagnolle et al. (2000) already proposed a spatial extension of the Gibrat model. Later, Favaro and Pumain (2011) developed a more refined extension with economic cycles and innovation waves, yielding a system dynamics version of the core of Simpop models.

1.3 Urban Growth and Networks

We work on simple territorial systems that are country-wide city systems, and more particularly French cities, on a time scale corresponding to that spatial scale, i.e. two last centuries. Taking into account physical networks can improve the understanding of city growth within that system in two ways : a qualitative one, for which the extended model would exhibit qualitative features corresponding to stylized facts empirically observed but that more basic models do not manage to reproduce, and a quantitative way, in the sense that model extension improves explained variance further than the mechanic improvement due to the introduction of supplementary degrees of freedom. If at least one of these is unveiled in our particular case, the evidence will support the theory at these scale and in this context.

The rest of this paper is organized as follows : our model is introduced and formally described in next section ; we then describe results obtained through exploration and calibration of our model on data for french cities, in particular the unveiling of network effects significantly influencing growth processes. We finally discuss interpretations of these results and implications for planning.

2 Model Description

2.1 From Gibrat to Marius : the dilemma of formulation

2.2 Model description

We choose to work on a deterministic extension of the Gibrat model, what is equivalent to consider only expectancies in time as detailed before. Let $\vec{P}(t) = (P_i(t))_i$ be the population of cities in time. Under Gibrat independence assumptions, we have $\text{Cov}[P_i(t), P_j(t)] = 0$. If $\vec{P}(t+1) = \mathbf{R} \cdot \vec{P}(t)$ where \mathbf{R} is also independent, then $\mathbb{E}[\vec{P}(t+1)] = \mathbf{R} \cdot \mathbb{E}[\vec{P}(t)]$. With $\vec{\mu}(t) = \mathbb{E}[\vec{P}(t)]$, we generalize this approach by taking $\vec{\mu}(t+1) = f(\vec{\mu}(t))$. In our case, we take

$$f(\vec{\mu}) = r_0 \cdot \mathbf{Id} \cdot \vec{\mu} + \mathbf{G} \cdot \mathbf{1} + \mathbf{N} \cdot$$

with

- $G_{ij} = w_G \cdot \frac{V_{ij}}{\langle V_{ij} \rangle}$ and $V_{ij} = \left(\frac{\mu_i \mu_j}{\sum \mu_k^2} \right)^{\gamma_G} \exp(-d_{ij}/d_G)$
- $N_i = w_N \cdot \sum_{kl} \left(\frac{\mu_k \mu_l}{\sum \mu} \right)^{\gamma_N} \exp(-d_{kl,i}/d_N)$ where $d_{kl,i}$ is distance to shortest path between k, l computed with slope impedance ($Z = (1 + \alpha/\alpha_0)^{n_0}$ with $\alpha_0 \simeq 3$)

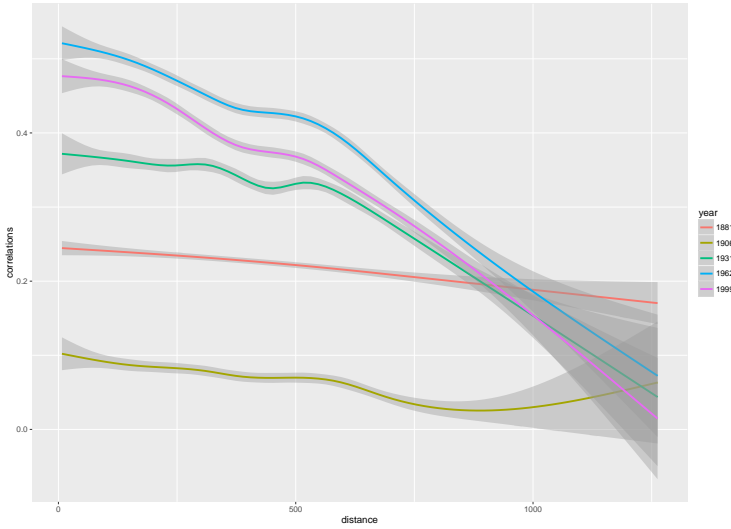


Figure 1. Time-series correlations as a function of distance. Solid line correspond to smoothed correlations, computed between each normalized population time-series, on successive periods.

The first component is the pure Gibrat model, that we obtain by setting the weights $w_G = w_N = 0$. The second component captures interdependencies between

3 Results

3.1 Data

Population data

Physical flows As stated above, this modeling exercise focuses on exploring the role of physical flows, whatever the effective shape of the network. We do not need for this reason network data which is furthermore not easily available at different time periods, and physical flows are assumed to take the geographical shortest path that include terrain slope (to avoid geographical absurdities such as cities with a difficult access having an overestimated growth rate). Using the 1km resolution Digital Elevation Model openly available from IGN , we construct an impedance field of the form

$$Z = \left(1 + \frac{\alpha}{\alpha_0} \right)^{n_0}$$

We took fixed parameter values $\alpha_0 = 3$ (corresponding to approximatively a 5% slope) and $n_0 = 3$

Figure 2. Example of output of the model. The graphical interface allows to explore interactively on which cities changes operate after a parameter change, what is necessary to interpret raw calibration results.

3.2 Implementation

Data preprocessing, result processing and models profiling are implemented in R. For performances reasons and an easier integration into the OpenMole software for model exploration [Reuillon et al. \(2013\)](#), a `scala` version was also developed. The typical question of trade-off between implementation performance and interoperability appeared quickly as an issue, as a blind exploration and calibration can difficultly provide useful thematic conclusions for that kind of model. Finding an improvement in model fit among one parameter dimension is significant if the geographical situation is visualized and the improvement is confirmed as reasonable and not an absurdity.

3.3 Model Exploration

3.4 Model Calibration

4 Discussion

We propose to support our hypothesis that *physical transportation networks are necessary to explain the morphogenesis of territorial systems* (aka *Network Necessity*) by showing on a relatively simple case that the integration of physical networks into some models effectively increase their explanative power (being careful on the precise definition of model improvement to avoid overfitting).

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