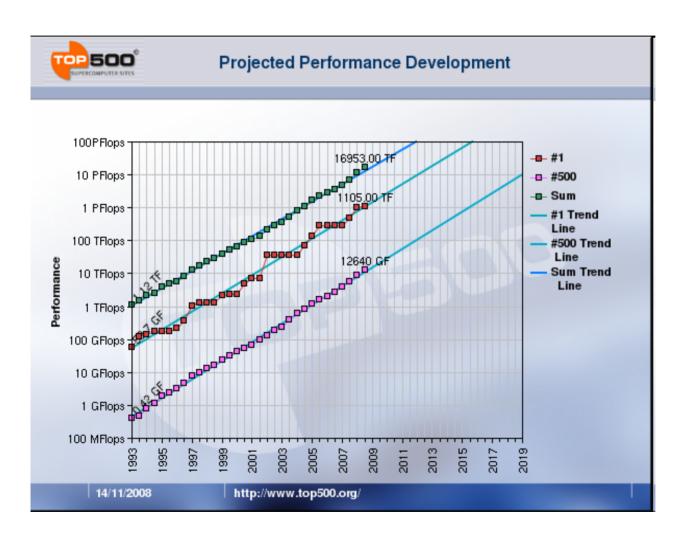
A crash course on MPI



Performance of laptop is only 12-14 years behind ... which is about the time it takes to complete PhD

Parallel computing: a few things everyone should be familiar with...

Amdahl's law:

 S_P – speed-up factor P - # of processors ξ - non parallelizable portion of a code

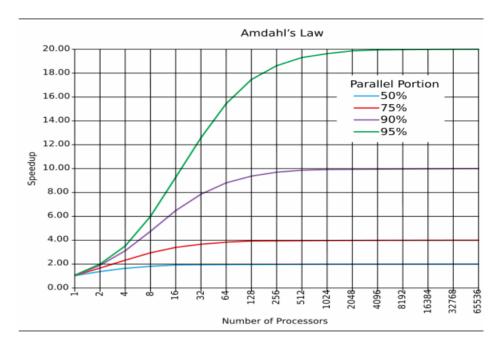
$$S_P = \frac{1}{\xi + (1 - \xi) \frac{1}{P}} < \frac{T_1}{T_P}$$



$$\eta_{P} = \frac{P - 1}{P \log_{2} P}$$

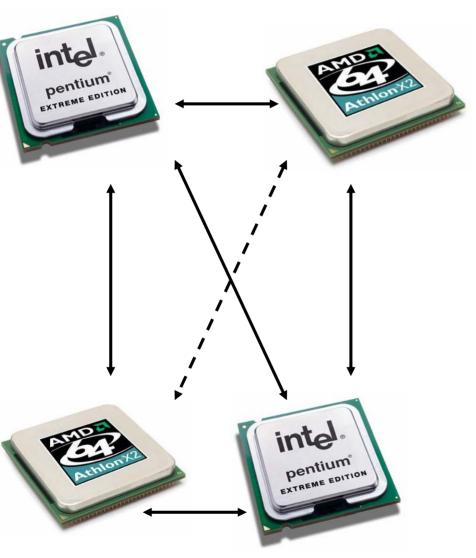
Communication cost

$$C = L + \beta l$$



$$L$$
 – latency, I – message size, β^{-1} - bandwidth

Message Passing Interface - MPI: what do we need it for?







The minimal MPI subset

- 1. MPI_Init()
- 2. MPI_Finalize()
- 3. MPI_Comm_size()
- 4. MPI_Comm_rank()
- 5. MPI_Send()
- 6. MPI_Recv()

```
#include <stdio.h>
#include <mpi.h>
int main (argc, *argv[]){
int rank, size:
MPI_Init (&argc, &argv);
/* starts MPI */
MPI_Comm_rank (MPI_COMM_WORLD, &rank);
/* get current process id */
MPI_Comm_size (MPI_COMM_WORLD, &size);
/* get number of processes */
printf( "Hello world from process %d of %d\n",
      rank, size );
MPI Finalize();
return 0;
```

MPI Communications

Point-to-point communications

- Involves a sender and a receiver
- Only the two processors participate in communication

Collective communications

- All processors within a communicator participate in communication (by calling same routine, may pass different arguments);
- Barrier, reduction operations, gather, scatter...

Blocking point-to-point communication











```
int MPI_Send(
    void *buf, /* initial address of send buffer */
    int count, /* number of elements in send buffer (nonnegative integer) */
    MPI_Datatype datatype, /* datatype of each send buffer element */
    int dest, /* rank of destination (integer) */
    int tag, /* message tag (integer) */
    MPI_Comm comm /* communicator */
);
```

```
int MPI_Recv(
    void *buf, /* initial address of receive buffer */
    int count, /* number of elements in receive buffer (nonnegative integer) */
    MPI_Datatype datatype, /* datatype of each receive buffer element */
    int dest, /* rank of source (integer) */
    int tag, /* message tag (integer) */
    MPI_Comm comm, /* communicator */
    MPI_Status *status /* status object */
);
```

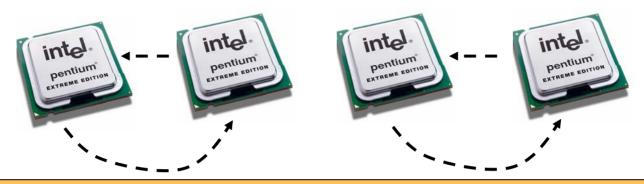
Deadlock

```
MPI_Comm_rank(MPI_COMM_WORLD,&rank);
If(rank==0)
{
    MPI_Recv(buf1,count,MPI_DOUBLE,1,tag,comm);
    MPI_Send(buf2,count,MPI_DOUBLE,1,tag,comm);
}
else if (rank==1)
{
    MPI_Recv(buf1,count,MPI_DOUBLE,0,tag,comm);
    MPI_Send(buf2,count,MPI_DOUBLE,0,tag,comm);
}
```

```
P0 - P1 - -
```

```
MPI_Comm_rank(MPI_COMM_WORLD,&rank);
If(rank==0)
{
    MPI_Recv(buf1,count,MPI_DOUBLE,1,tag,comm);
    MPI_Send(buf2,count,MPI_DOUBLE,1,tag,comm);
}
else if (rank==1)
{
    MPI_Send(buf2,count,MPI_DOUBLE,0,tag,comm);
    MPI_Recv(buf1,count,MPI_DOUBLE,0,tag,comm);
}
```

Blocking point-to-point communication



```
int MPI_Sendrecv(
   void *sendbuf,
   int sendcount,
   MPI_Datatype sendtype,
   int dest,
   int sendtag,
   void *recvbuf,
   int recvcount,
   MPI_Datatype recvtype,
   int source,
   int recytag,
   MPI_Comm comm,
   MPI_Status *status
```

Example

```
#include <mpi.h>
#include <stdio.h>
int main(int argc, char **argv)
  int my rank, ncpus;
  int left neighbor, right neighbor;
 int data received;
  int send_tag = 101, recv tag=101;
 MPI Status status;
 MPI Init(&argc, &argv);
 MPI_Comm_rank(MPI_COMM_WORLD, &my_rank);
 MPI Comm size(MPI COMM WORLD, &ncpus);
 left_neighbor = (my_rank-1 + ncpus)%ncpus;
 right_neighbor = (my_rank+1)%ncpus;
 MPI_Sendrecv(&my_rank, 1, MPI_INT, left_neighbor, send_tag,
               &data_received, 1, MPI_INT, right_neighbor, recv_tag,
              MPI COMM WORLD, &status);
 printf("P%d received from right neighbor: P%d\n",
         my rank, data received);
  // clean up
 MPI Finalize();
 return 0;
```

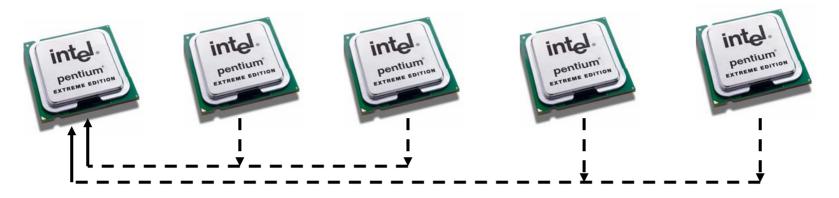
Output:

P3 received from right neighbor: P0 P2 received from right neighbor: P3 P0 received from right neighbor: P1 P1 received from right neighbor: P2

Non-blocking point-to-point communication

What should we use?

```
MPI_Send + MPI_Recv
MPI_Send + MPI_Irecv
MPI_Isend + MPI_Recv
MPI_Isend + MPI_Irecv
MPI_Sendrecv
MPI_Alltoall
```



MPI function

MPI MAX maximum.

```
int MPI_Reduce (
void *sendbuf,
void *recvbuf,
int count,
MPI_Datatype datatype,
MPI_Op op,
int root,
MPI_Comm comm
);
```

_	
MPI_MIN minimum,	min
MPI_MAXLOC	maximum and location of maximum
MPI_MINLOC	minimum and location of minimum
MPI_SUM	sum
MPI_PROD	product
MPI_LAND	logical and
MPI LOR	logical or

logical exclusive or

Math Meaning

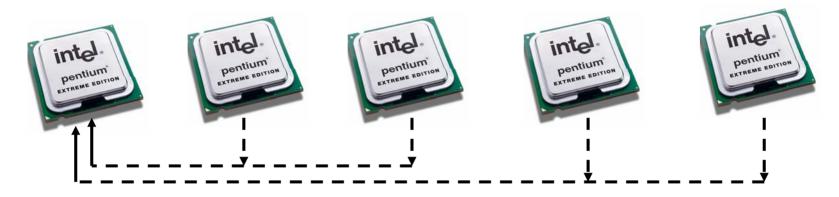
max

MPI_BAND bitwise and MPI_BOR bitwise or

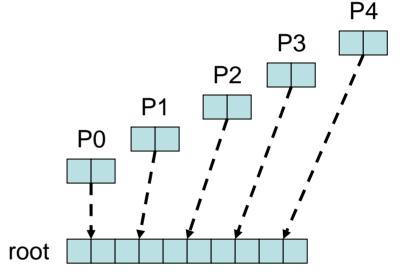
MPI_BXOR bitwise exclusive or

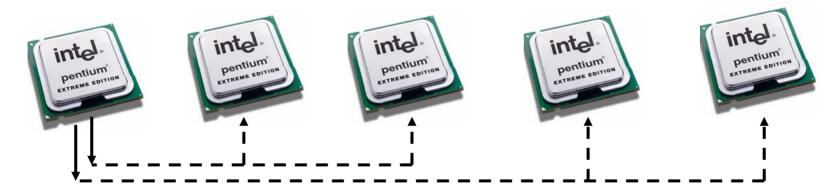
Implemented in integration, dot products, finding maxima or minima

MPI LXOR

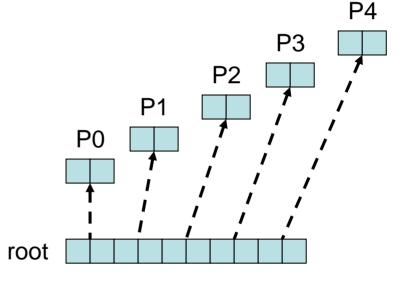


```
int MPI_Gather (
 void
               *sendbuf,
 int
                sendont,
 MPI_Datatype sendtype,
 void
               *recvbuf,
 int
                recvcount,
 MPI_Datatype recvtype,
 int
                root,
 MPI_Comm
                comm
);
```





```
int MPI_Scatter (
void *sendbuf,
int sendcnt,
MPI_Datatype sendtype,
void *recvbuf,
int recvcount,
MPI_Datatype recvtype,
int root,
MPI_Comm comm
);
```



To operate on messages of <u>unequal</u> length:

- MPI_Scatterv
- MPI_Gatherv

To obtain results on <u>all</u> processors:

- MPI_Allreduce
- MPI_Allgather (v)

To Send data from all to all processes

MPI_Alltoall(v)

To broadcast message

MPI_Bcast

To synchronize between processors

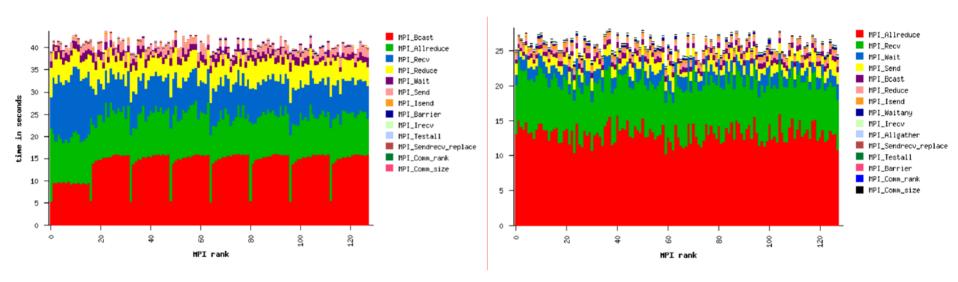
MPI_Barrier

Good programming

- Reliability The code does not have errors and can be trusted to compute what it is supposed to compute.
- Robustness, which is closely related to reliability The code has a
 wide range of applicability as well as the ability to detect bad data,
 "singular" or other problems that it can not be expected to handle,
 and other abnormal situations, and deal with them in a way that is
 satisfactory to user.
- Portability The code can be transferred from one computer to another with a minimum effort and without loosing reliability. Usually this means that the code has been written in a general high-level language like FORTRAN (C++) and uses no "tricks" that are dependent on the characteristic of a particular computer. Any machine characteristics that must be used are clearly delineated.
- Maintainability Any code will necessary need to be changed from time to time, either to make corrections or to add enhancements, and this should be possible with minimum effort.

Gene Golub, James M. Ortega, **Scientific computing**: an introduction with **parallel computing**, 1993.

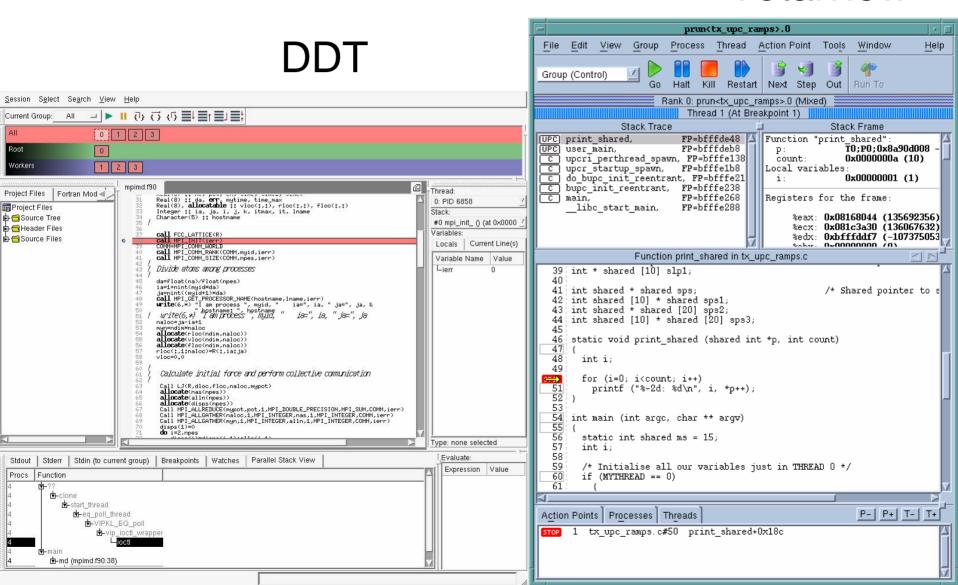
Code optimization through code profiling



Difference: 40 sec → 25 sec

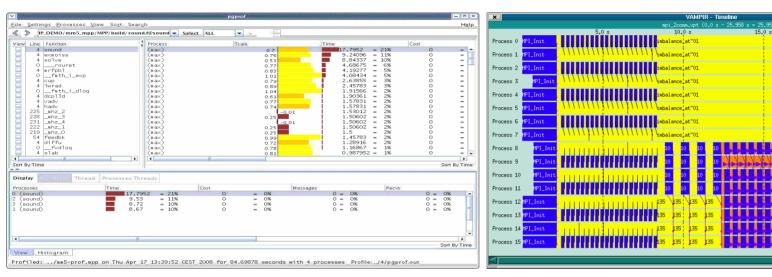
Debugging parallel code

Totalview



Performance analysis tools

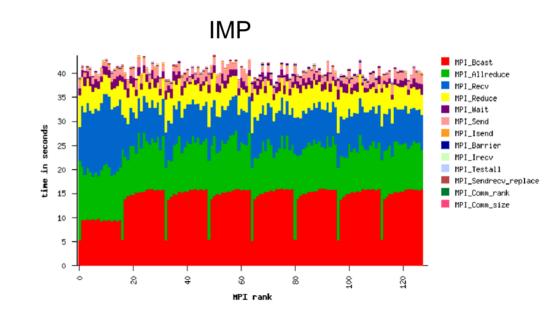
pgprof vampire





100.0% | 100.0% | 512 | Total

59.8%	59.8%	306	stepfx_
17.6%	77.3%	90	getrusage
8.0%	85.4%	41	stepfy_
6.2%	91.6%	32	integr_
2.0%	93.6%	10	gradco_
1.0%	94.5%	5	write
0.8%	95.3%	4	filerx_



How to learn MPI programming?

Just do it!