1 Objective  
The objective of this exercise is to make a direction controller and a line  
follower to the square program  
When you have finished this exercise you will be able to:  
● Drive straight lines with the square program  
● Follow a line with the square program  
2 Direction control.  
Implement a angular controller in the square program, where  
Δ V =K∗(θref −θodo)

First, we define a K value.

#define K 10