Data Structure: Sorting

sorting

sorting is putting the elements into a list in which the elements are in increasing order

insertion sort

34, 8, 64, 51, 32, 21

0	I	2	3	4	5	
34	8	64	51	32	21	
8	34	64	51	32	21	after p=I
8	34	64	51	32	21	after p=2
8	34	51	64	32	21	after p=3
8	32	34	51	64	21	after p=4
8	21	32	34	51	64	after p=5

insertion sort

- For each pass P = 1 through n 1, insertion sort ensures that elements in position 0 through P are in sorted order
- In pass P, move the element in position P left until its correct place is found among the first P elements
- $O(n^2)$ comparisons required on average
- any algorithm that sorts by exchanging adjacent elements requires $O(n^2)$ time on average
 - average number of swapping in an array of n distinct numbers is n(n-1)/4 since total number of pairs to be compared is n(n-1)/2

34, 8, 64, 51, 32, 21

0	l	2	3	4	5	
34	8	64	51	32	21	
8	34	64	51	32	21	after p=I
8	34	64	51	32	21	after p=2
8	34	51	64	32	21	after p=3
8	32	34	51	64	21	after p=4
8	21	32	34	51	64	after p=5

insertion sort

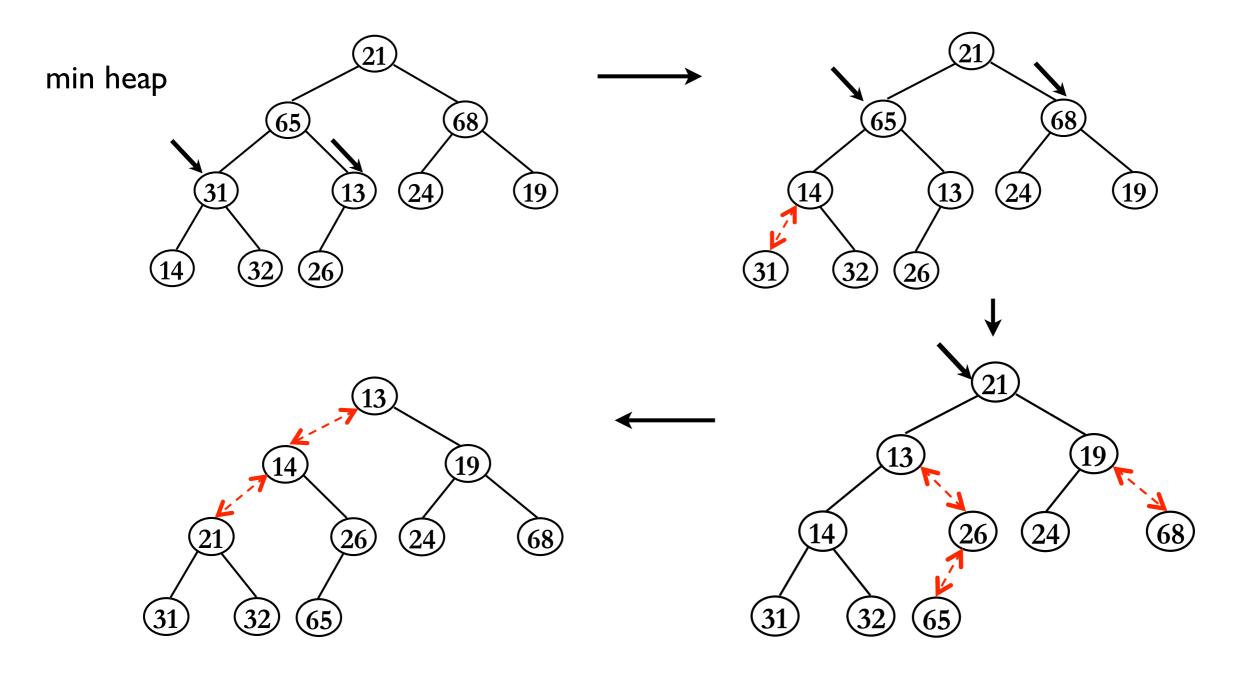
0	l	2	3	4	5	
34	8	64	51	32	21	
8	34	64	51	32	21	after p=I
8	34	64	51	32	21	after p=2
8	34	51	64	32	21	after p=3
8	32	34	51	64	21	after p=4
8	21	32	34	51	64	after p=5

heap sort

- building binary heap of n elements: O(n)
- DeleteMin operation n times: O(n log n)
- use the last cell in the previous heap to save the noted list (in-place algorithm)

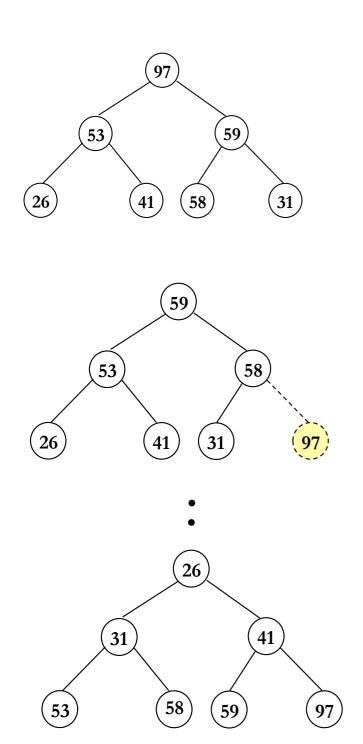
BuildHeap

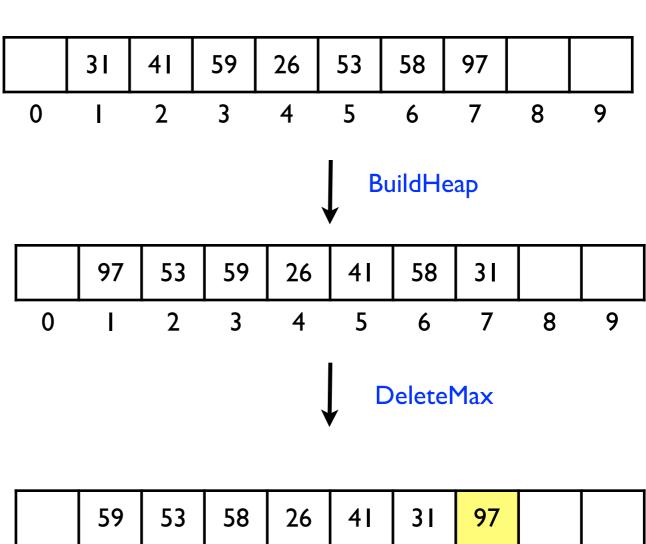
- Build a Heap containing n keys takes $O(n \log n)$ with consecutive insertions
- But it can take O(n) if they are already in array.
- Starting with the lowest non-leaf node, working back towards root, perform percolating-down on each node of the tree.

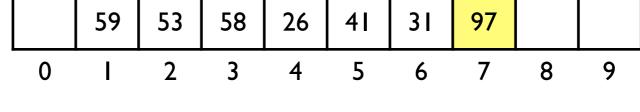


heap sort

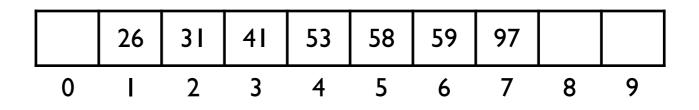
Increasing order using Max heap



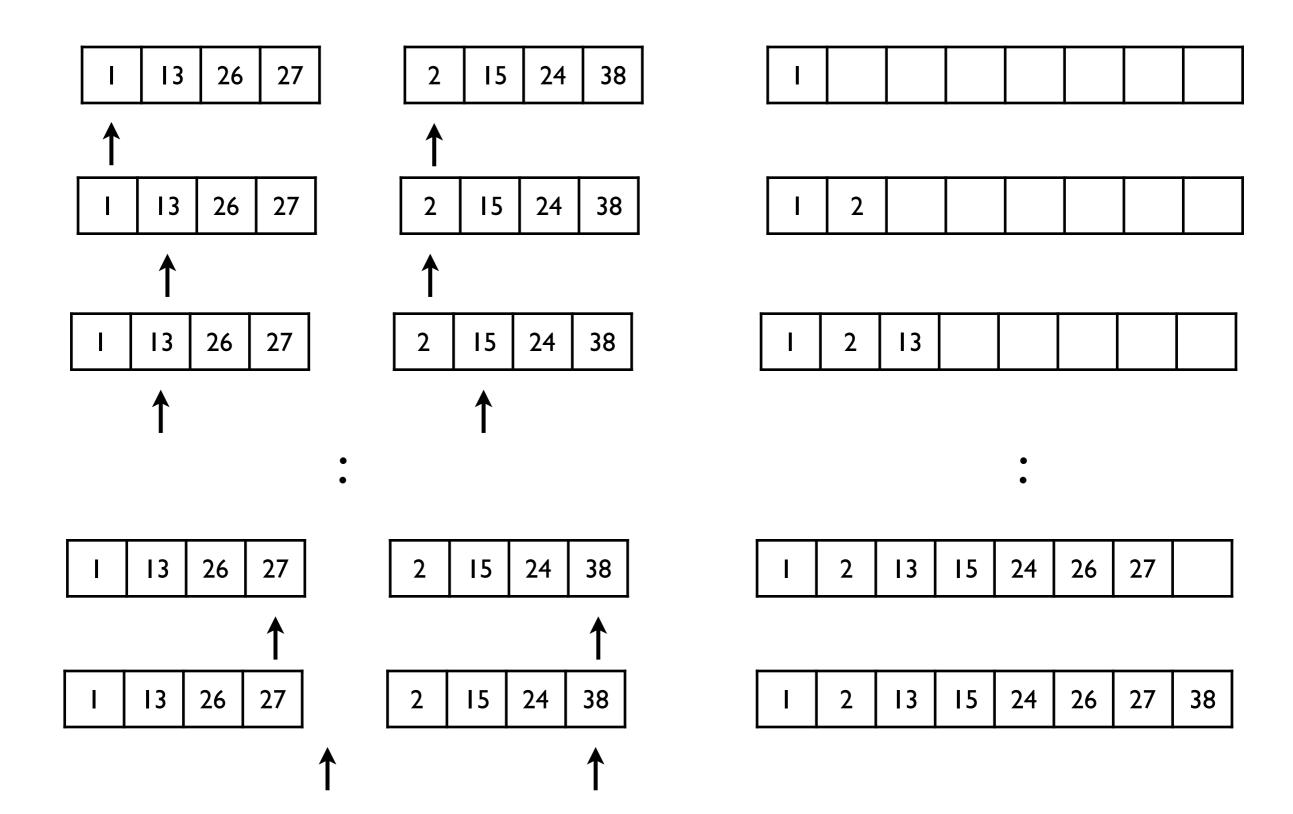




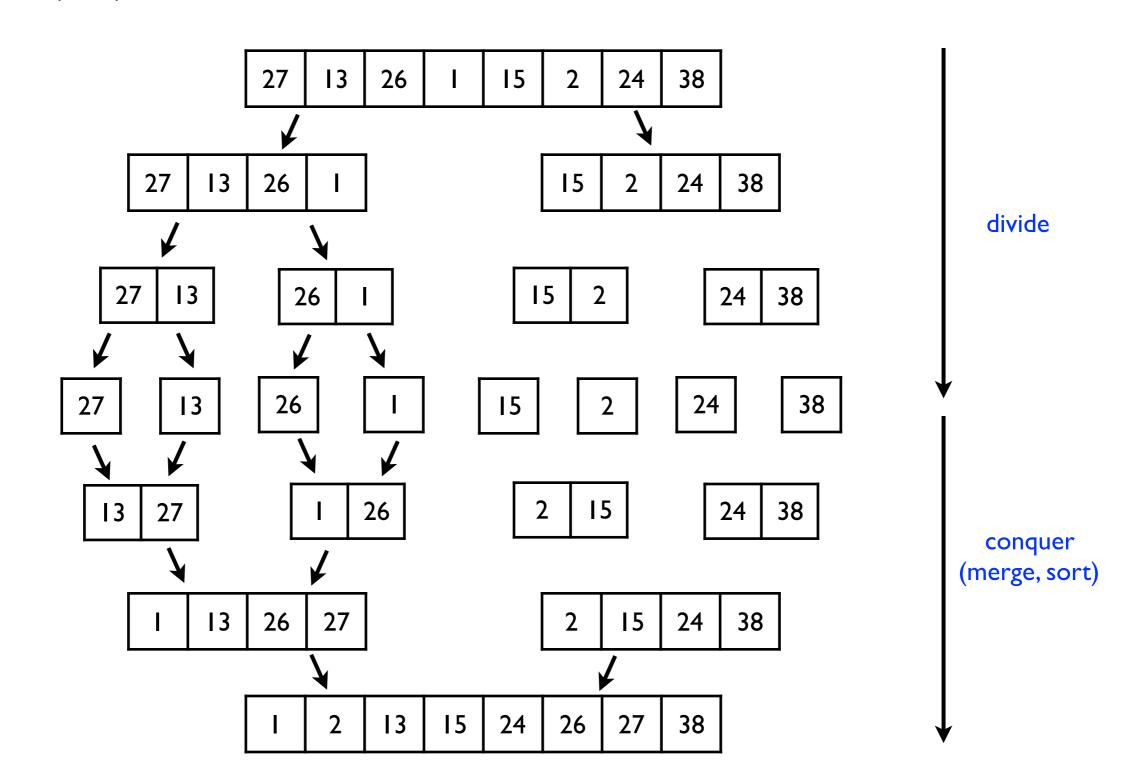
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merge two sorted sublists using temporary array

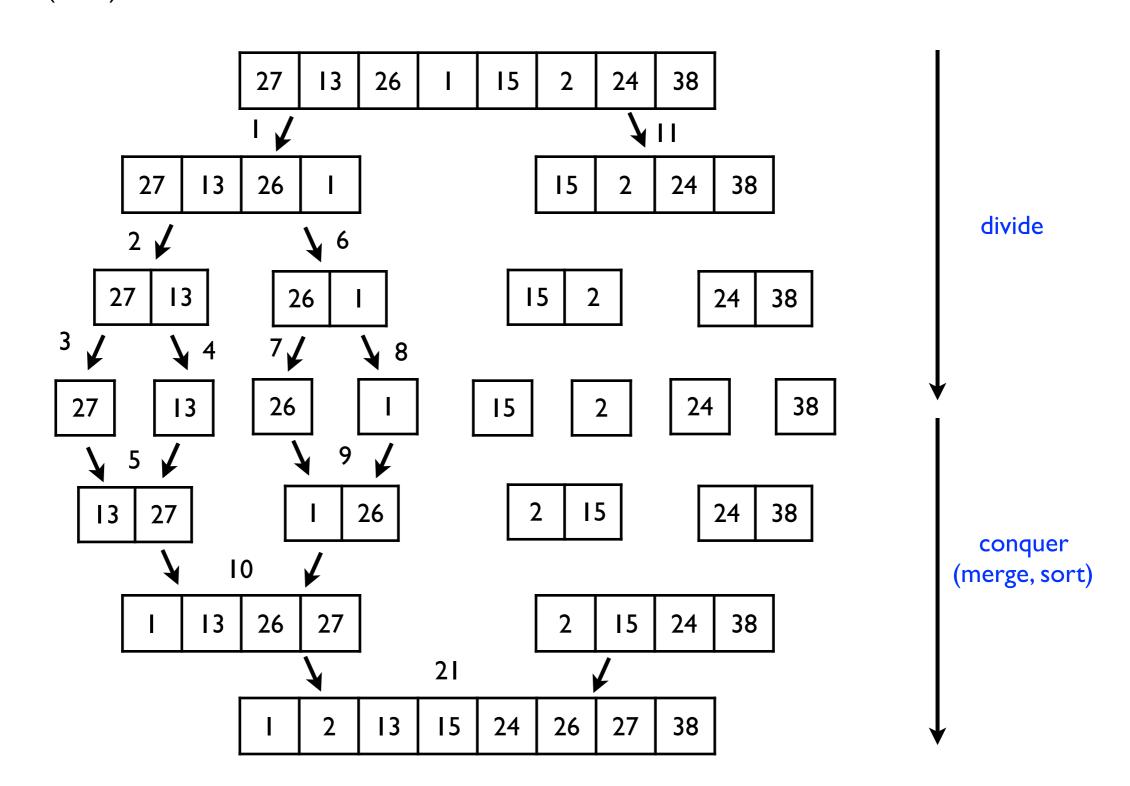


- divide a list into two sublists
- conquer (sort) the sorted sublist into the list



```
void MSort (ElementType A[], ElementType TmpArray[], int Left, int Right)
{
    int Center;
    if (Left < Right){
        Center = (Left + Right) / 2;
        MSort (A,TmpArray, Left, Center);
        MSort (A,TmpArray, Center+I, Right);
        Merge (A,TmpArray, Left, Center+I, Right);
    }
}</pre>
```

- divide a list into two sublists
- conquer (sort) the sorted sublist into the list



```
void Merge (ElementType A[], ElementType TmpArray[], int Lpos, int Rpos, int RightEnd)
     int i, LeftEnd, NumElements, TmpPos;
     LeftEnd = Rpos - I;
     TmpPos = Lpos;
     NumElements = RightEnd - Lpos + I;
     while (Lpos <= LeftEnd && Rpos <= RightEnd)
          if (A[Lpos] \le A[Rpos])
               TmpArray[TmpPos++] = A[Lpos++];
          else
               TmpArray[TmpPos++] = A[Rpos++];
     while (Lpos <= LeftEnd)
          TmpArray[TmpPos++] = A[Lpos++];
     while (Rpos <= RightEnd)
          TmpArray[TmpPos++] = A[Rpos++];
     for(i=0; i<NumElements; i++, RightEnd--)</pre>
          A[RightEnd] = TmpArray[RightEnd];
```

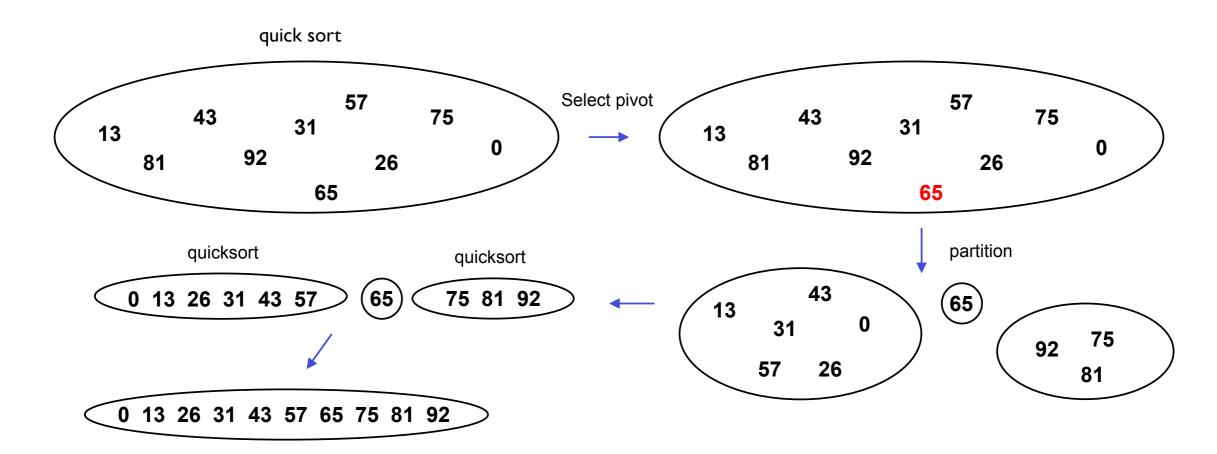
merge sort: analysis of time complexity

$$T(I) = I$$

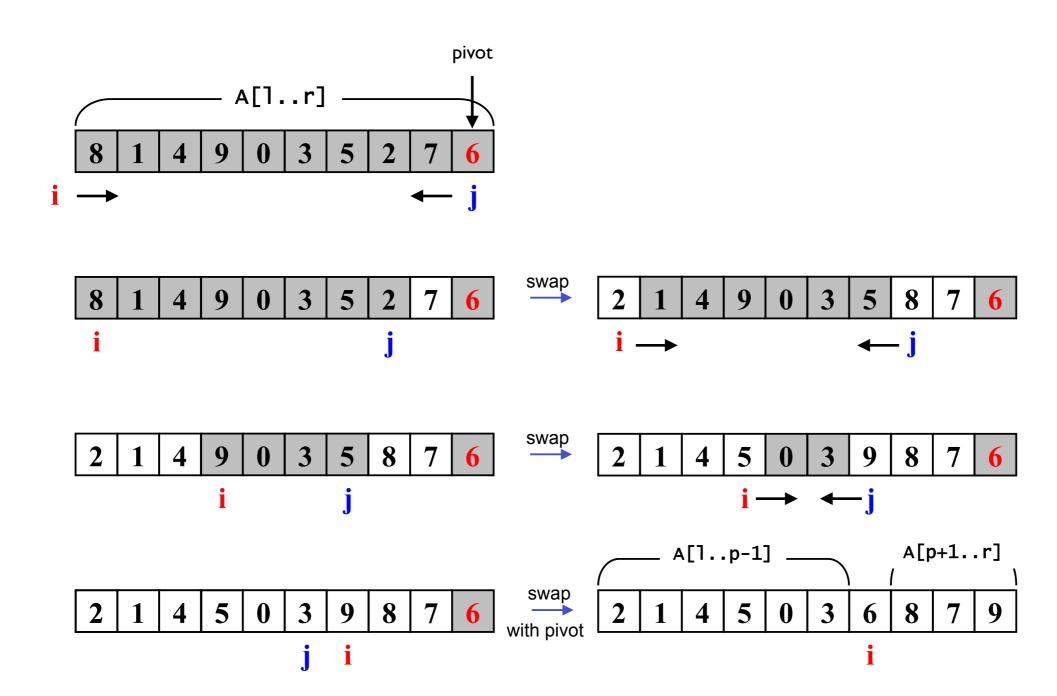
 $T(N) = 2T(N/2) + N$
 $T(N)/N = T(N/2) / (N/2) + I$
 $T(N/2) / (N/2) = T(N/4) / (N/4) + I$
 $T(N/4) / (N/4) = T(N/8) / (N/8) + I$
:
 $T(2) / (2) = T(I) / (I) + I$
 $T(N)/N = T(I)/I + log N$
 $T(N) = N log N + N = O(N log N)$

quick sort

- \blacksquare divide: partition the array A[I..r] into two subarrays A[I..p-I] and A[p+I..r]
 - all elements in A[l..p-I] are less than or equal to a pivot element A[p]
 - all elements in A[p+1..r] are greater than pivot element A[p].
- \blacksquare conquer: sort the two subarrays A[I..p-I] and A[p+I..r] by recursive calls to quicksort.
 - -> since the subarrays are sorted in place, no work is needed.



quick sort



quick sort

```
void Quicksort(A, I, r)
       if (l >= r)
                    return;
        p = Partition(A, I, r);
        Quicksort(A, I, p-I);
        Quicksort(A, p+I, r);
}
int Partition(A, I, r)
        pivot = select_pivot(A, I, r);
        i = I - I;
        j = r;
        for(;;) {
            while (A[--j] > pivot);
            while (A[++i] \le pivot);
            if (i < j) swap(&A[i], &A[j]);
            else {
                  swap(&A[i], &A[r]);
                  return i;
```

quick sort: picking the pivot

- use the first element or the last element
 - worst if the input is presorted or in reverse order
- choose the pivot randomly
 - safe, but does not reduce the average running time
 - median-of-three choose the median of the leftmost, rightmost, and center elements

quick sort: picking the pivot

$$T(0) = T(1) = 0$$

 $T(n) = T(i) + T(n - i - 1) + n$

- performance depends on the selection of pivot
 - worst-case partitioning: divide n 1 and pivot

$$T(n) = T(n-1) + n$$

$$= T(n-2) + n - 1 + n$$

$$= :$$

$$= T(1) + 2 + 3 + ... + n$$

$$= O(n^{2})$$

best-case partitioning: divide n/2 and n/2 elements

$$T(n) = 2T(n/2) + n$$

= $4T(n/4) + 2n$ $\leftarrow 2(2T(n/4) + n/2) + n$
= $8T(n/8) + 3n$
= :
= $nT(1) + logn * n$
= $O(n log n)$

quick sort: picking the pivot

$$T(n) = T(i) + T(n-i-1) + n$$

average-case partitioning

assume that the size of a partition is equally likely (that is, probability is I/n) the average value of T(i) or T(n-i-1) is $\frac{1}{n}\sum_{j=0}^{n-1}T(j)$

$$T(n) = \frac{2}{n} \left[\sum_{j=0}^{n-1} T(j) \right] + n$$

$$nT(n) = 2\left[\sum_{j=0}^{n-1} T(j) \right] + n^{2}$$

$$(n-1)T(n-1) = 2\left[\sum_{j=0}^{n-2} T(j) \right] + (n-1)^{2}$$

$$nT(n) - (n-1)T(n-1) = 2T(n-1) + 2n - 1$$

$$nT(n) = (n+1)T(n-1) + 2n$$

$$\frac{T(n)}{n+1} = \frac{T(n-1)}{n} + \frac{2}{n+1}$$

$$\frac{T(n)}{n+1} = \frac{T(1)}{2} + 2\sum_{j=3}^{n+1} \frac{1}{j}$$

$$\frac{T(n)}{n+1} = O(\log n), \quad T(n) = O(n \log n)$$