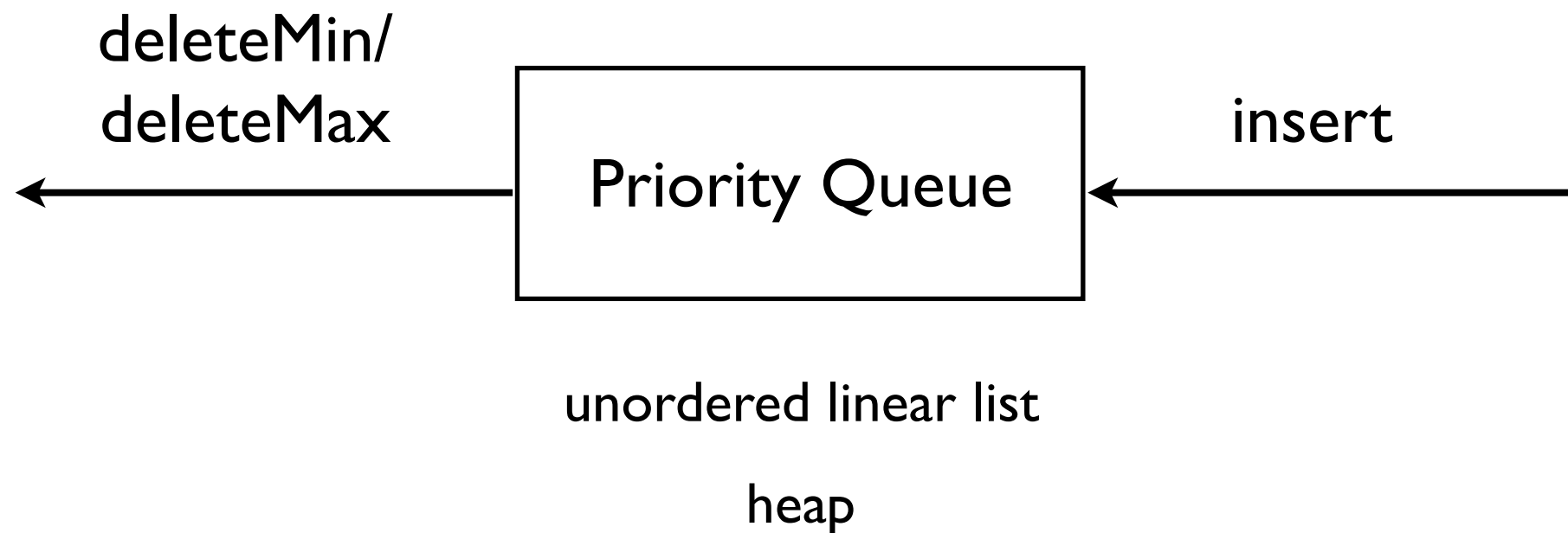


Data Structure:

Heap

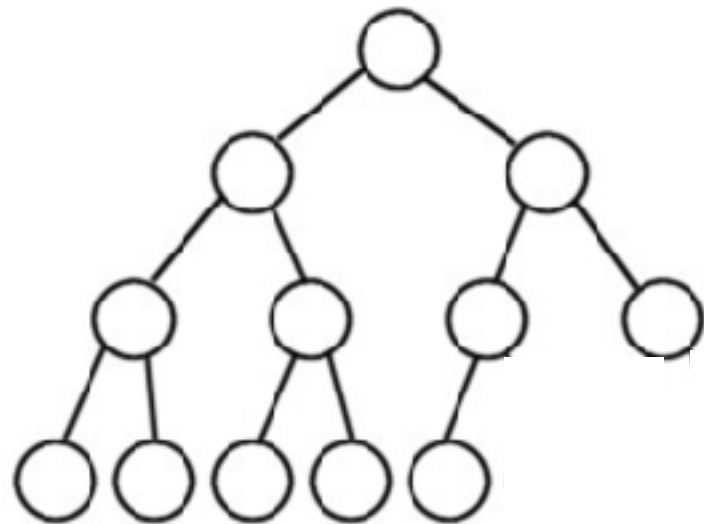
priority queue (heap)

- the element to be deleted is the one with the highest (or lowest) priority
- priority queue Q supports
 - insert (x, Q)
 - $y = \text{pop}(Q)$ (=deleteMin(Q) or deleteMax(Q))
- priority queue is used for scheduling



binary (min) heap

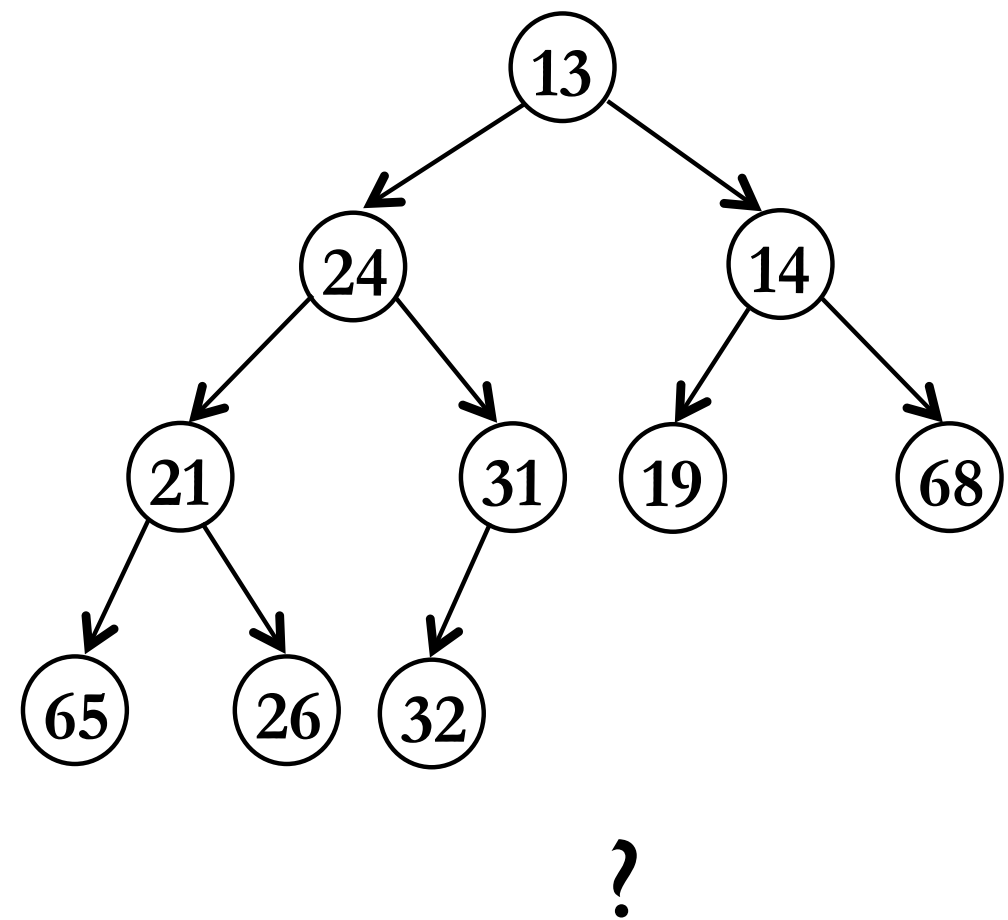
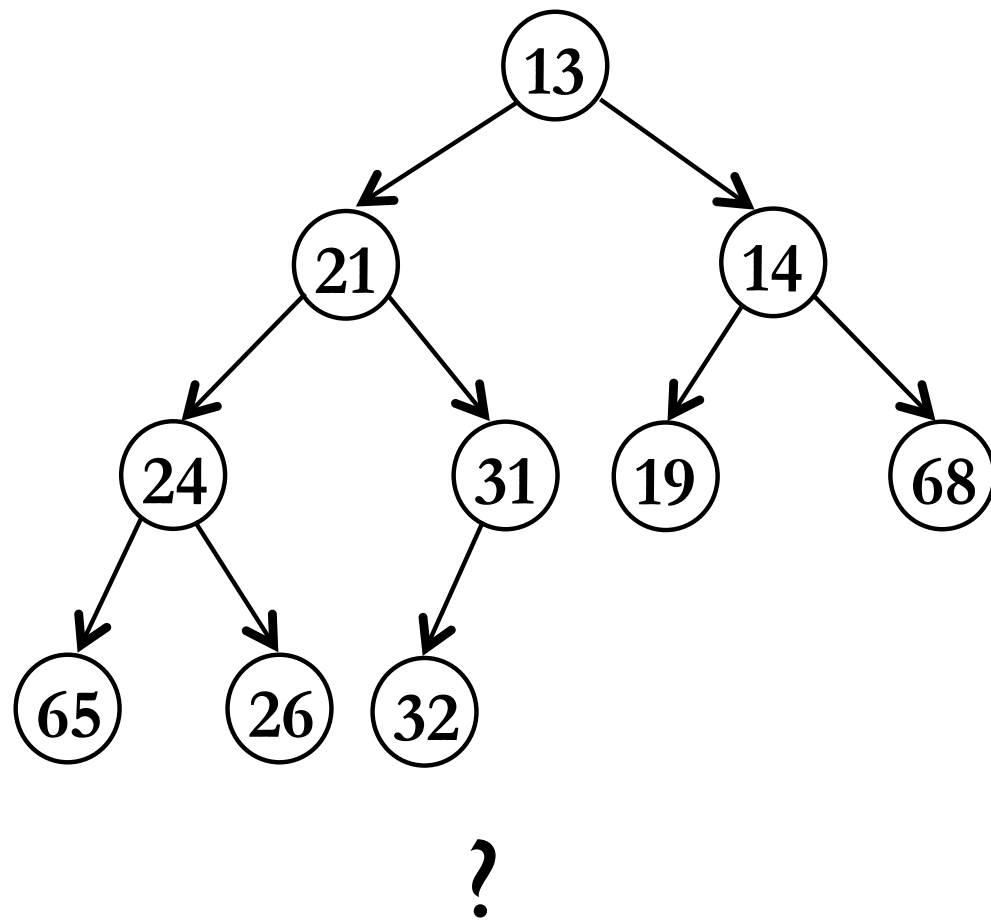
- a min heap is a **complete binary tree** and **partially ordered tree** in which the key value in each node is no larger than the key values in its children
- **complete tree**
 - every level of tree is completely filled, with the exception of the bottom level, which is filled from left to right



binary (min) heap

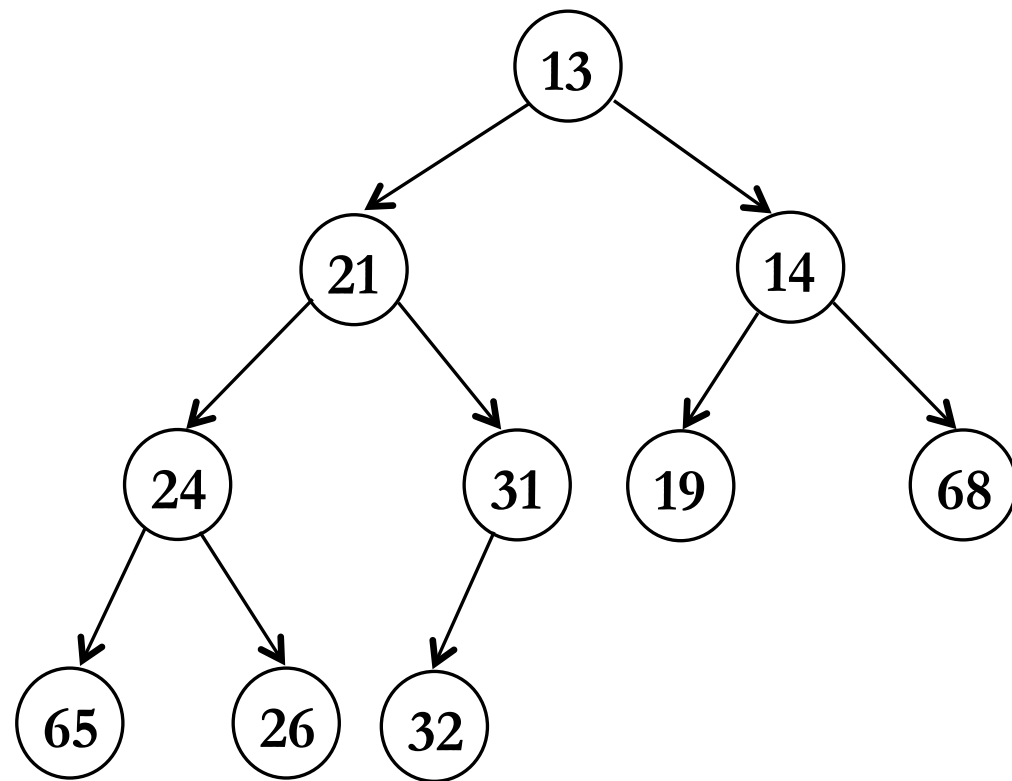
- partially ordered tree

- the key of each internal node is less than or equal to the keys of its children
- the smallest element should be at the root



binary heap

- binary heap can be stored in array since it is a complete tree

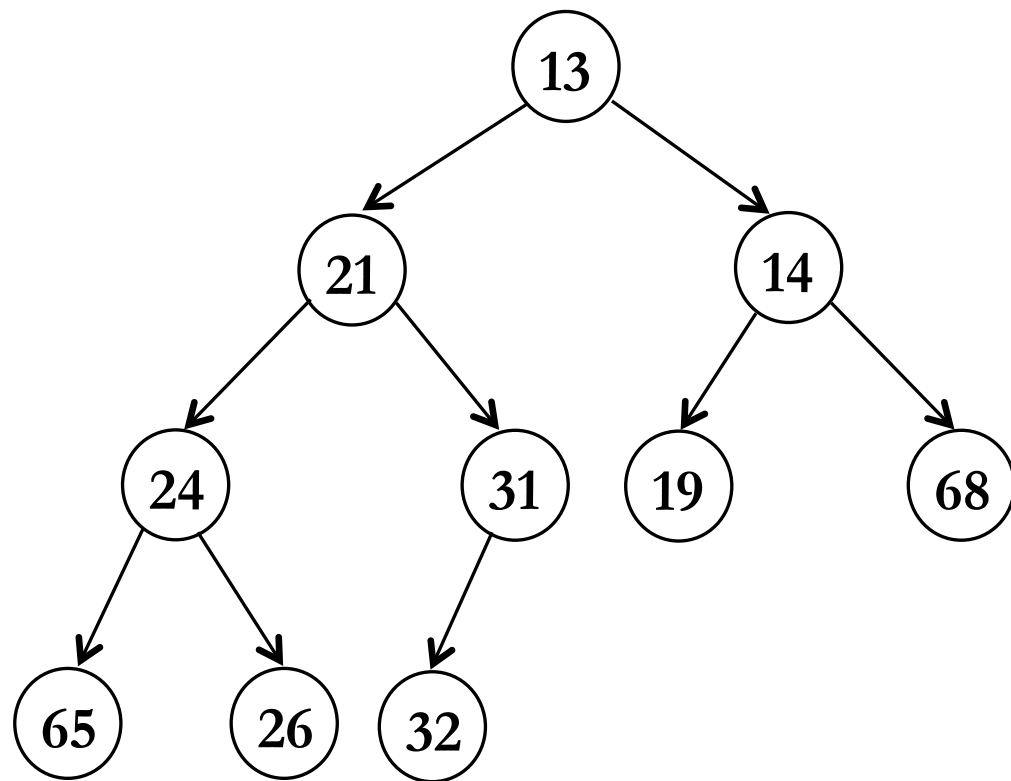


- $\text{left_child}(i) = 2i$ (when $2i \leq n$)
- $\text{right_child}(i) = 2i + 1$ (when $2i + 1 \leq n$)
- $\text{parent}(i) = \text{floor}(i/2)$ (when $i \geq 2$)

array
index

	13	21	14	24	31	19	68	65	26	32	
0	1	2	3	4	5	6	7	8	9	10	11

binary heap

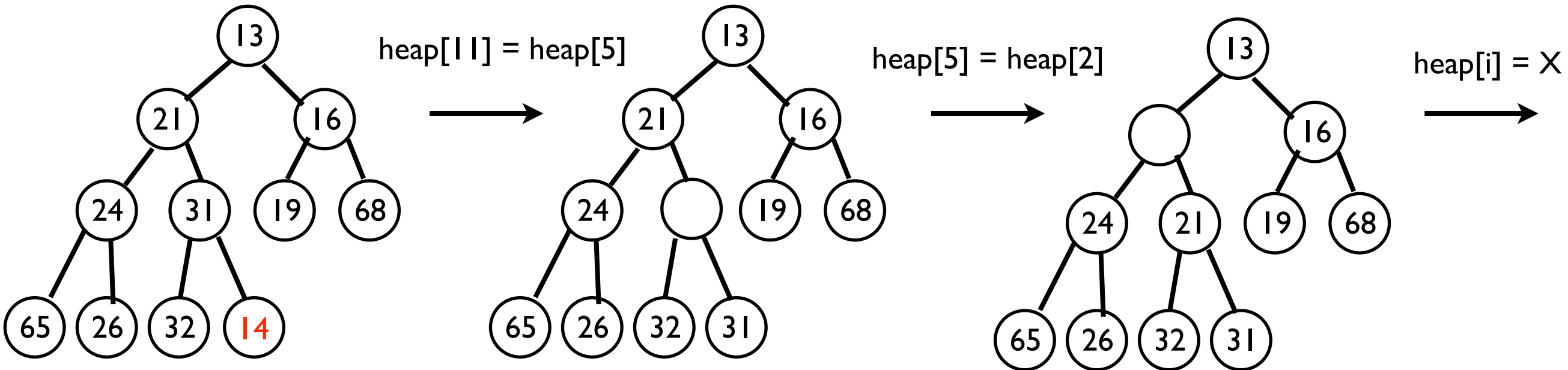


```
struct HeapStruct
{
    int Capacity; // max heap capacity
    int Size;     // current heap size
    ElementType *Elements;
};
```

insertion

insertion of 14

x=14



i=11
 $\text{heap}[\text{floor}(i/2)] \leq X \text{ ?}$

i=5
 $\text{heap}[\text{floor}(i/2)] \leq X \text{ ?}$

i=2
 $\text{heap}[\text{floor}(i/2)] \leq X \text{ ?}$

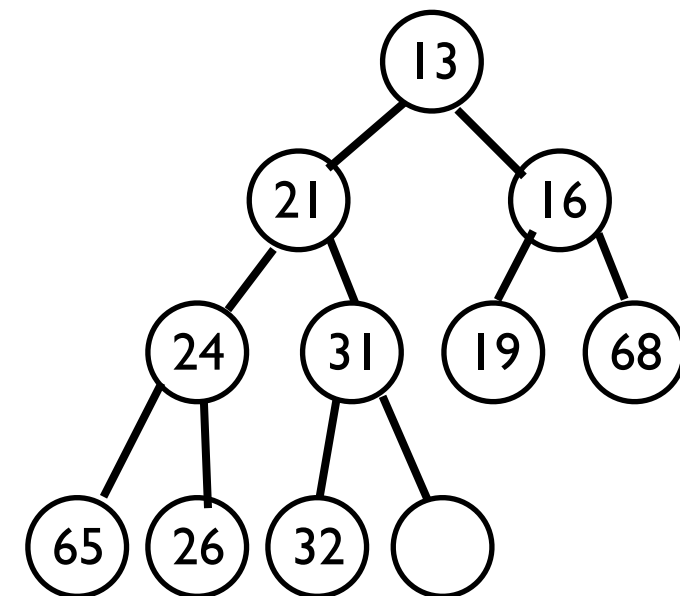
	13	21	16	24	31	19	68	65	26	32	14	
i	0	1	2	3	4	5	6	7	8	9	10	11

insertion

```
void Insert( ElementType X, PriorityQueue H )
{
    int i;
    if (IsFull( H ) )
    {
        Error( "Priority queue is full" );
        return;
    }

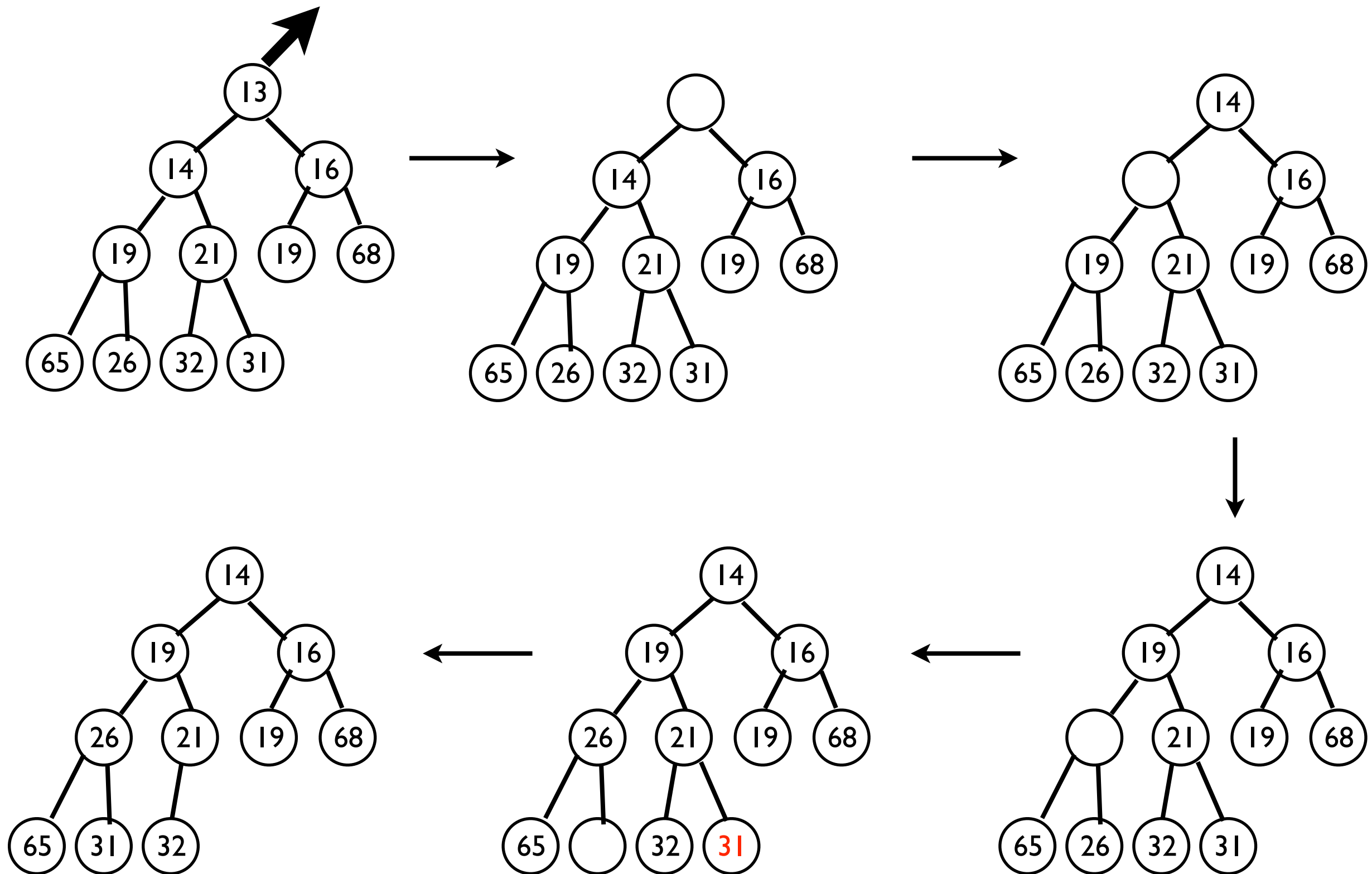
    /*percolating up*/
    for( i = ++H->size; H->Elements[ i/2 ] > X; i /= 2 )
        H->Elements[ i ] = H->Elements[ i/2 ];

    H->Elements[ i ] = X;
}
```

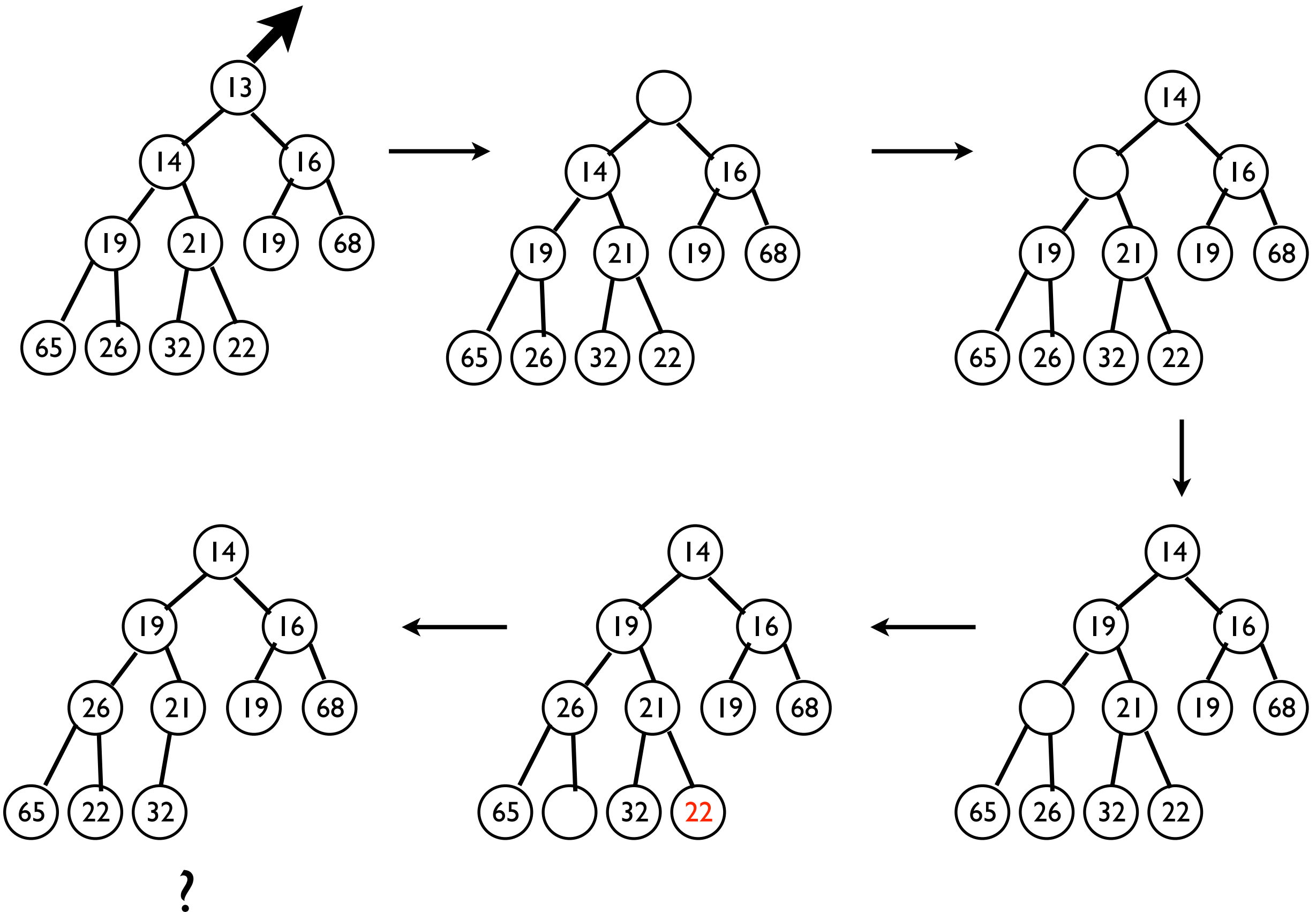


the complexity of the insertion function is $O(\log_2 n)$

DeleteMin: a possible way?

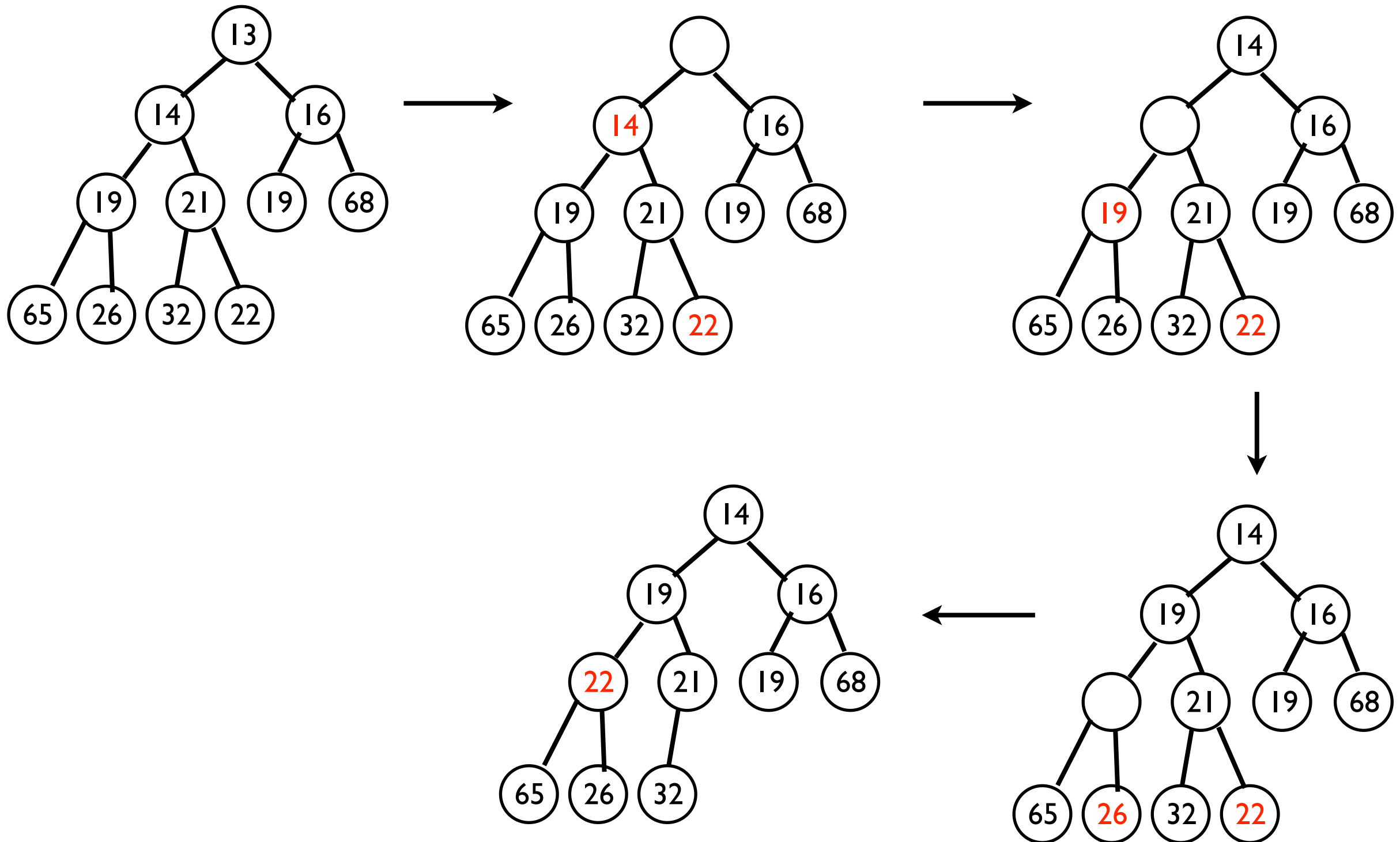


DeleteMin: what if?



DeleteMin

- choose the smaller one between $H \rightarrow \text{Elements}[LChild]$ and $H \rightarrow \text{Elements}[RChild]$
- choose the smaller one between LastElement and $H \rightarrow \text{Elements}[Child]$



DeleteMin

```
ElementType DeleteMin( PriorityQueue H )
{
    int i, Child;
    ElementType MinElement, LastElement;

    MinElement = H->Elements[ 1 ];
    LastElement = H->Elements[ H->Size-- ];

    /*percolating down*/
    for( i = 1; i*2 <= H->Size; i = Child )
    {
        Child = i * 2;
        if( Child != H->Size && H->Elements[ Child + 1 ] < H->Elements[ Child ] )
            Child++;

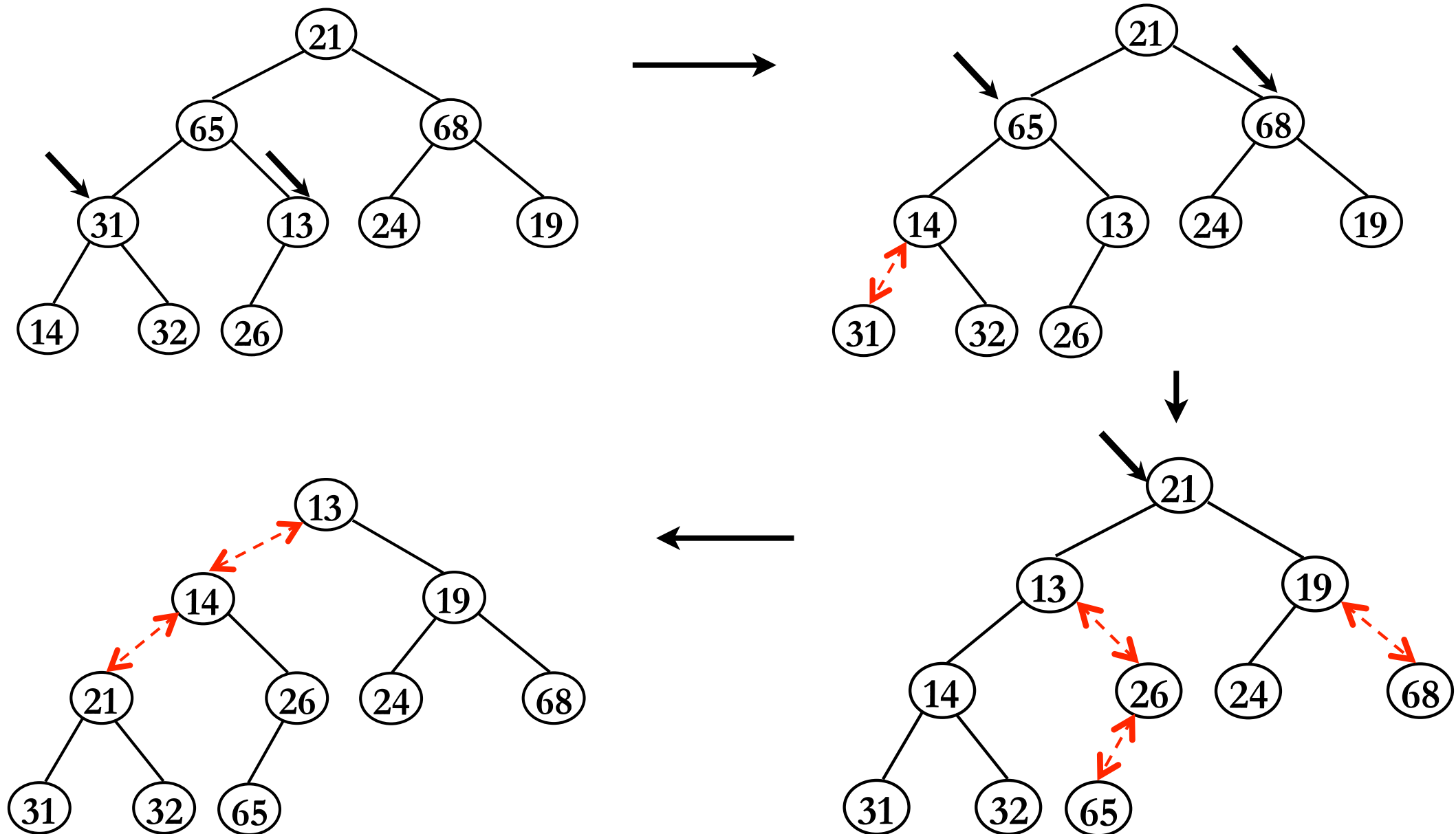
        if( LastElement > H->Elements[ Child ] )
            H->Elements[ i ] = H->Elements[ Child ];
        else
            break;
    }

    H->Elements[ i ] = LastElement;
    return MinElement;
}
```

the complexity of the deletion function is $O(\log_2 n)$

BuildHeap

- Build a Heap containing n keys takes $O(n \log n)$ with consecutive insertions
- But it can take $O(n)$ if they are already in array.
- Starting with the lowest non-leaf node, working back towards root, perform percolating-down on each node of the tree.



BuildHeap

Let's assume that the tree is complete:

There is one key at level 0, which might sift down h levels.

There are two keys at level 1, which might sift down $h - 1$ levels

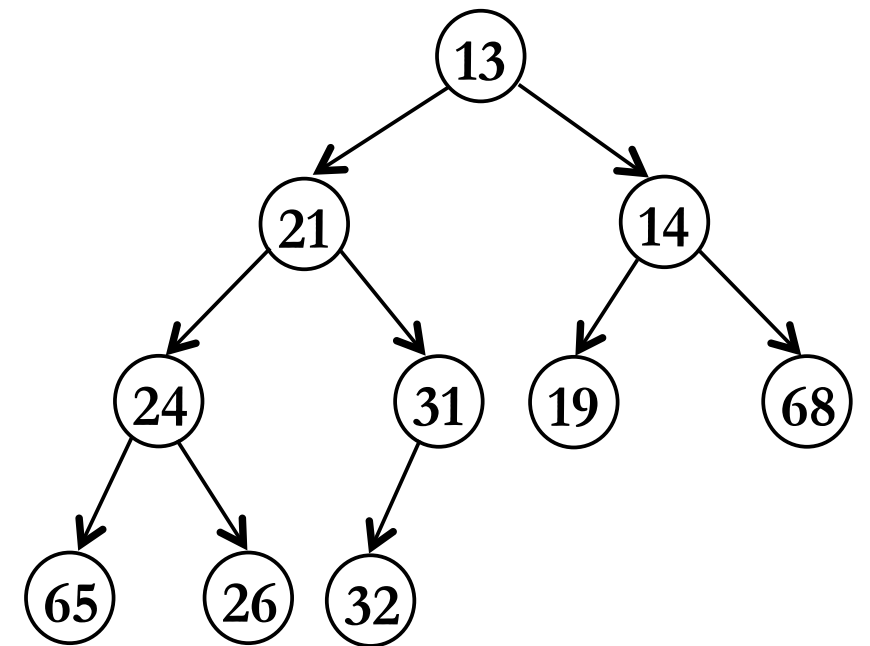
There are four keys at level 2, which might sift down $h - 2$ levels

...

$$S = h + 2(h - 1) + 4(h - 2) + \dots + 2^{h-1}(1)$$

$$2S = 2h + 4(h - 1) + 8(h - 2) + \dots + 2^{h-1}(2) + 2^h(1)$$

$$\begin{aligned} 2S - S &= -h + (2 + 4 + \dots + 2^{h-1}) + 2^h \\ &= -h - 1 + (1 + 2 + 4 + \dots + 2^{h-1}) + 2^h \\ &= 2^h + 2^h - (h + 2) = 2 \cdot 2^h - h - 2 \\ &= 2 \cdot 2^{\log n} - \log n - 2 \leq 2n \end{aligned}$$



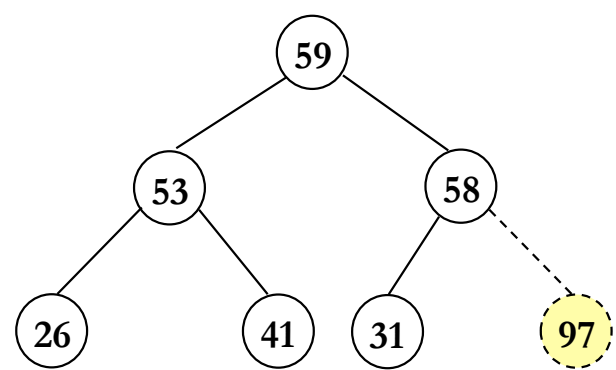
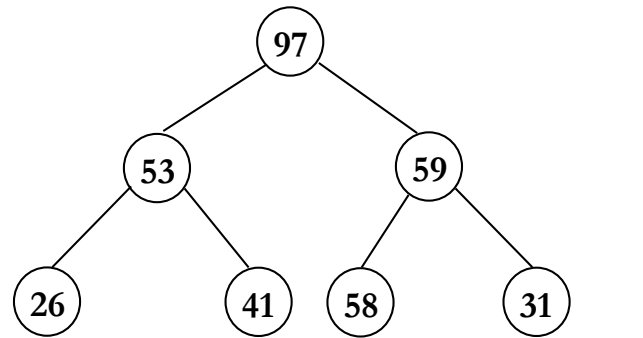
heap sort

- building binary heap of n elements: $O(n)$
- DeleteMin operation n times: $O(n \log n)$
- need extra space to save the sorted list: use the last cell in the previous heap

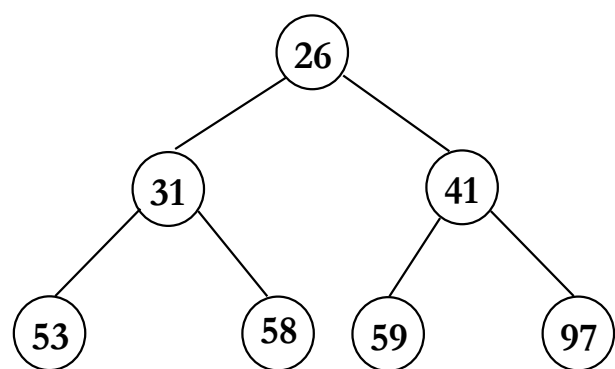
```
void HeapSort (ElementType A[], int N)
{
    int i;
    for (i = N/2; i > 0; i --)    /* Build Heap */
        PercDown (A, i, N);

    for (i = N; i > 0; i --)
    {
        Swap(&A[1], &A[i]);    /*DeleteMax */
        PercDown(A, 1, i-1);
    }
}
```

heap sort (by increasing order with max heap)



⋮



	31	41	59	26	53	58	97		
0	1	2	3	4	5	6	7	8	9

↓ BuildHeap

	97	53	59	26	41	58	31		
0	1	2	3	4	5	6	7	8	9

↓ DeleteMax

	59	53	58	26	41	31	97		
0	1	2	3	4	5	6	7	8	9

⋮

	26	31	41	53	58	59	97		
0	1	2	3	4	5	6	7	8	9