Image Processing

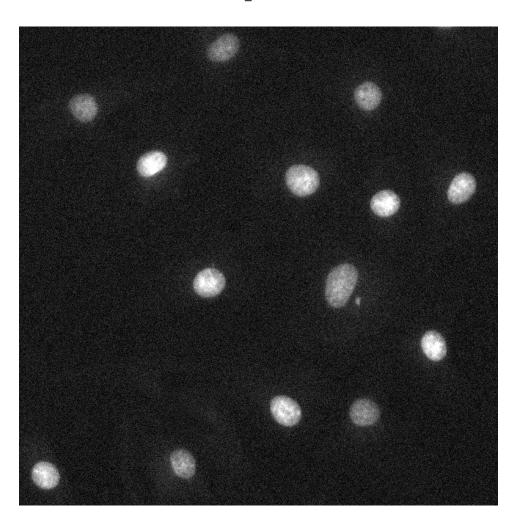
Segmentation

• Segmentation is the division of an image into discrete regions.

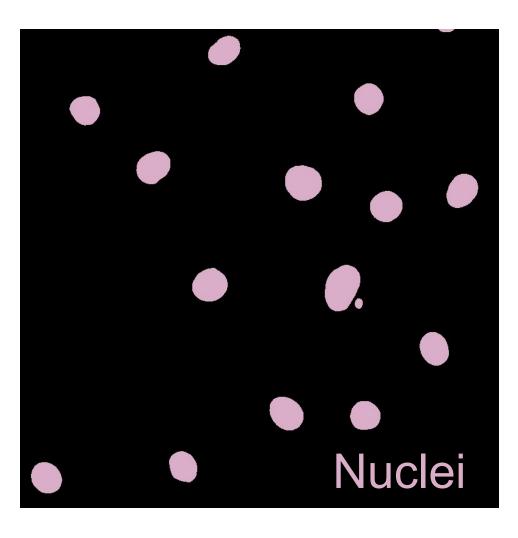




Input

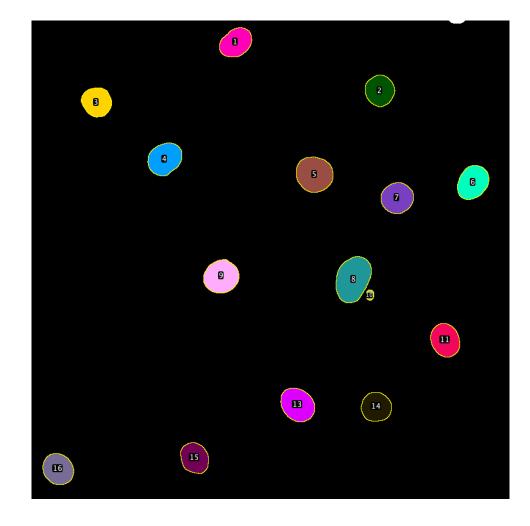


Semantic



Background

Instance



Background

Nucleus 1

Nucleus 2

Nucleus 3

...



How do we get segments?



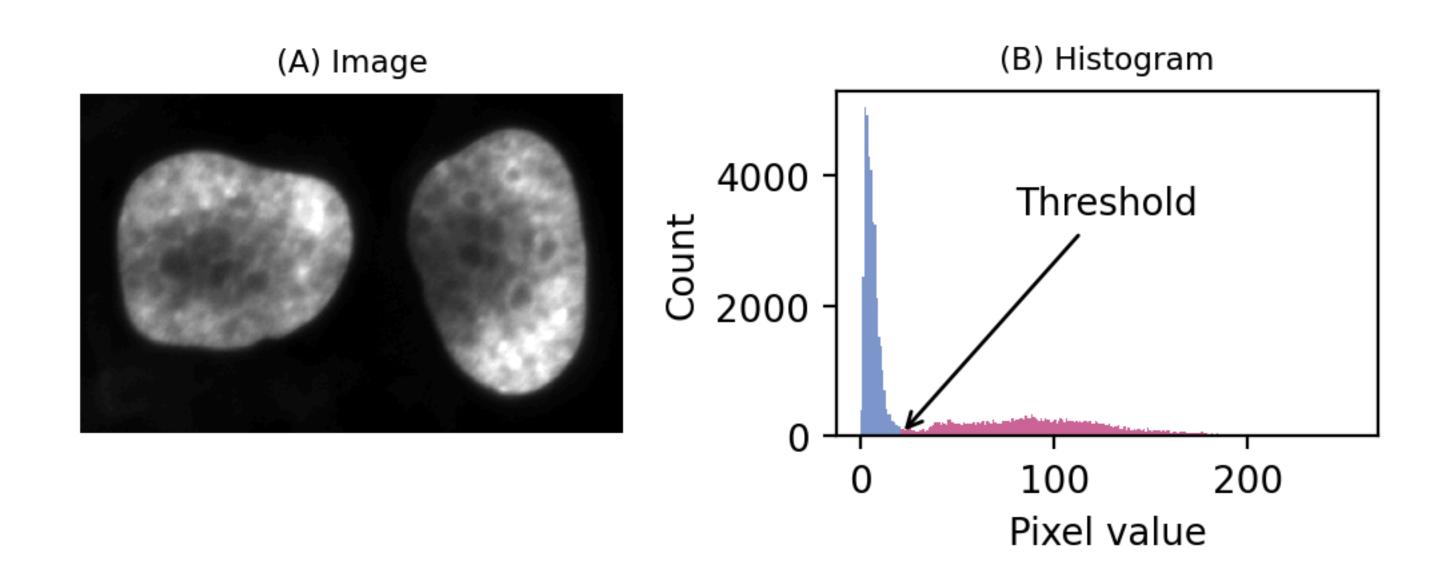
- Thresholding-based
- Interactive tools based on classic machine learning
- Deep-learning based (Stardist, Cellpose)

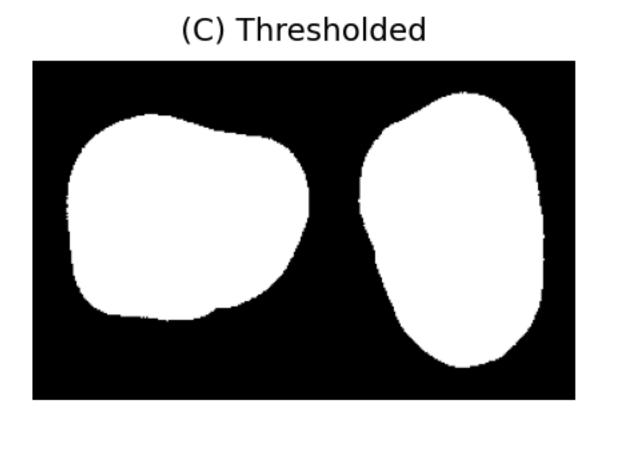




The easiest way to segment an image is often by applying a *global threshold*.

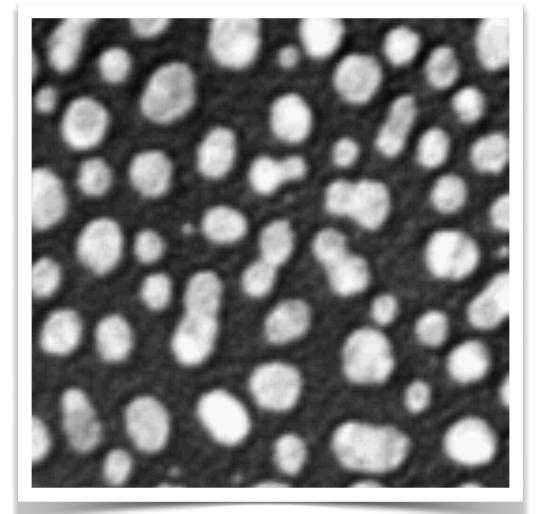
This identifies pixels that are above or below a fixed threshold value, giving a *binary image as the output*.



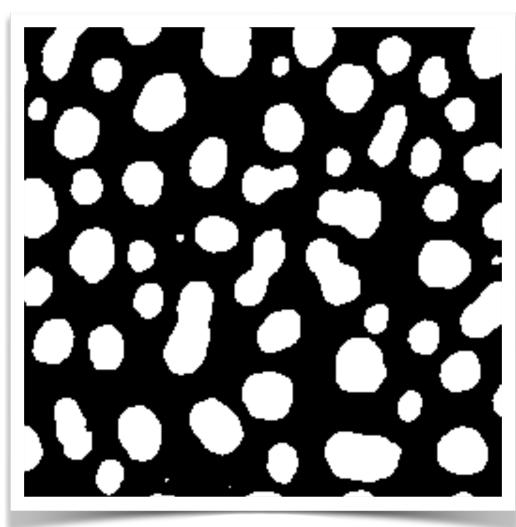




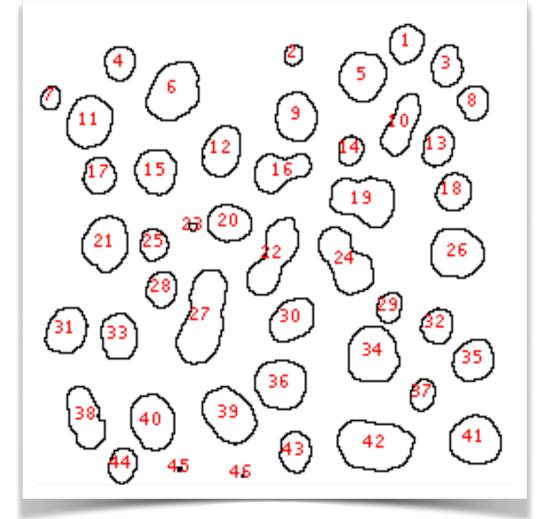




Original, 8 bit grayscale Blobs: Fiji example



Thresholded



Instance Segmented

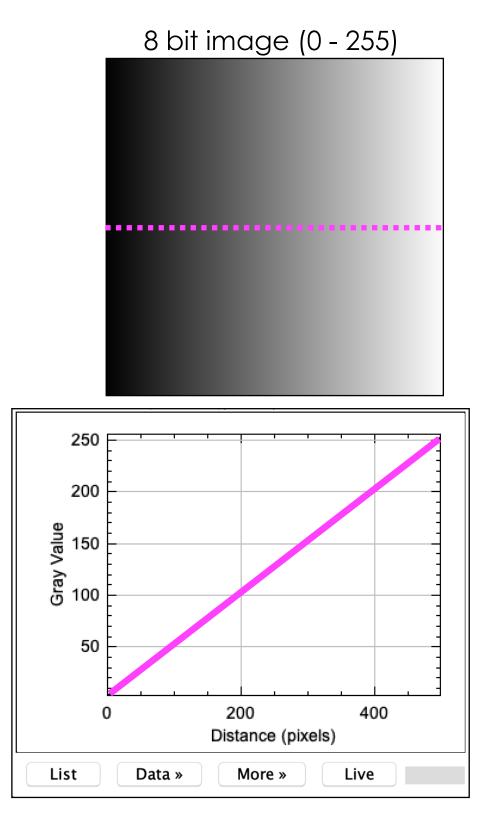
Instance Segmentation in FIJI: keeping white (connected-) objects.





Thresholding method

Select only a range of digital values in the image.





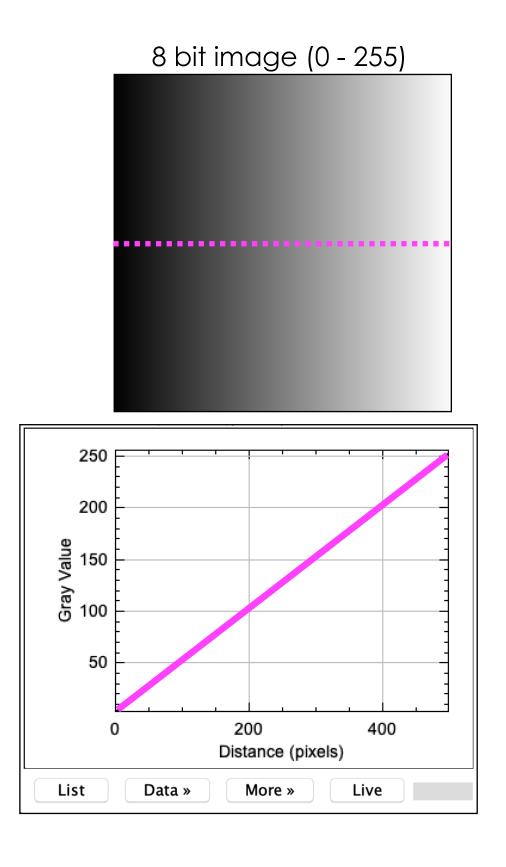


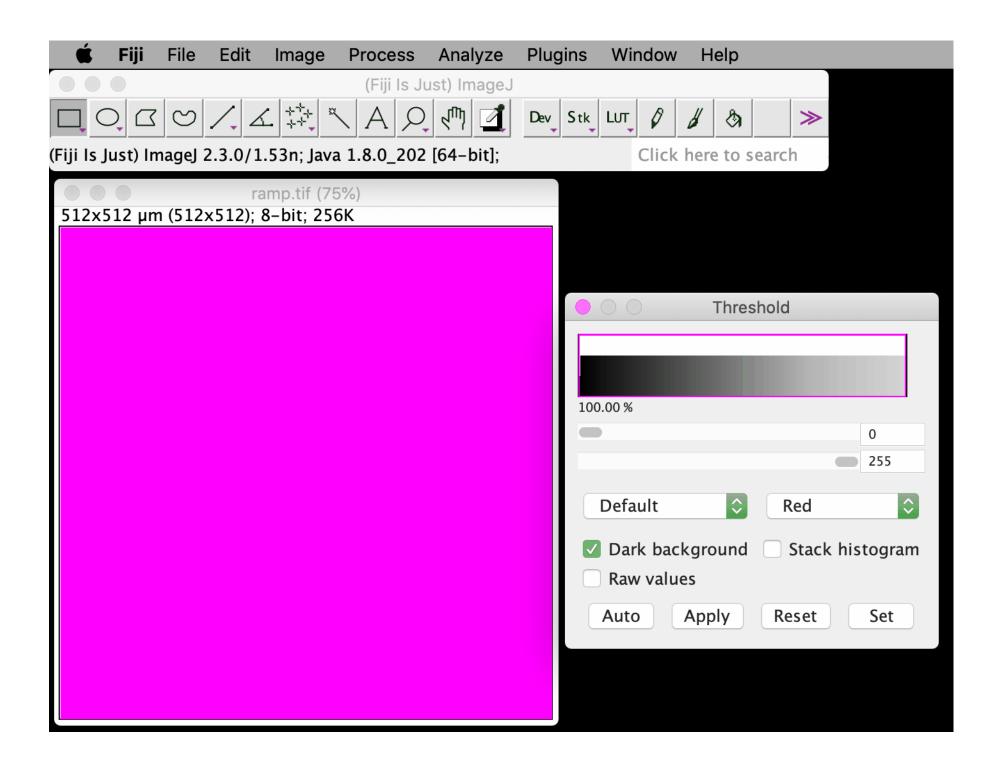


Select only a range of digital values in the image.

in Fiji: Image > Adjust > Threshold...

(cmd) + shift + t





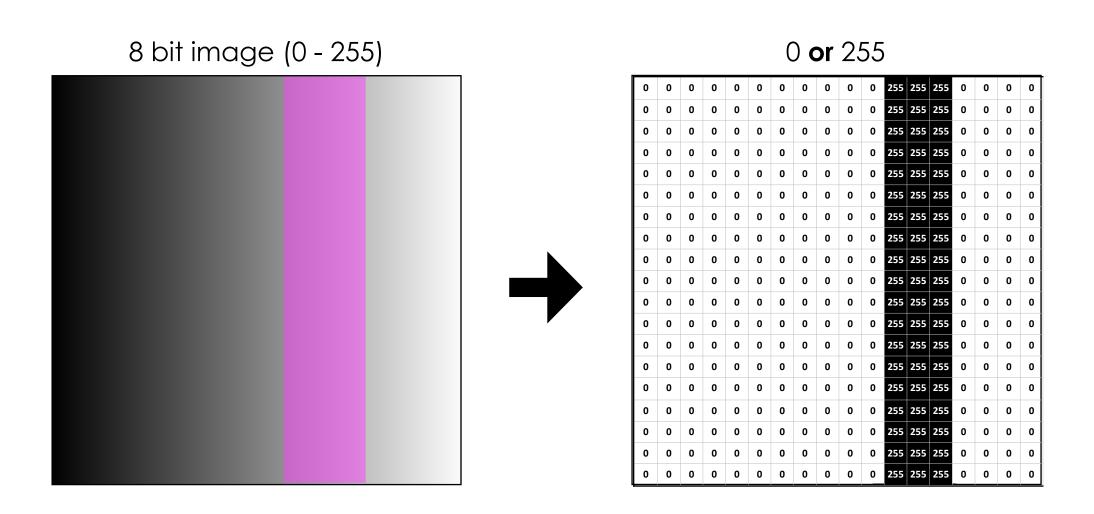
The result of the thresholding process is a **Binary Mask**.







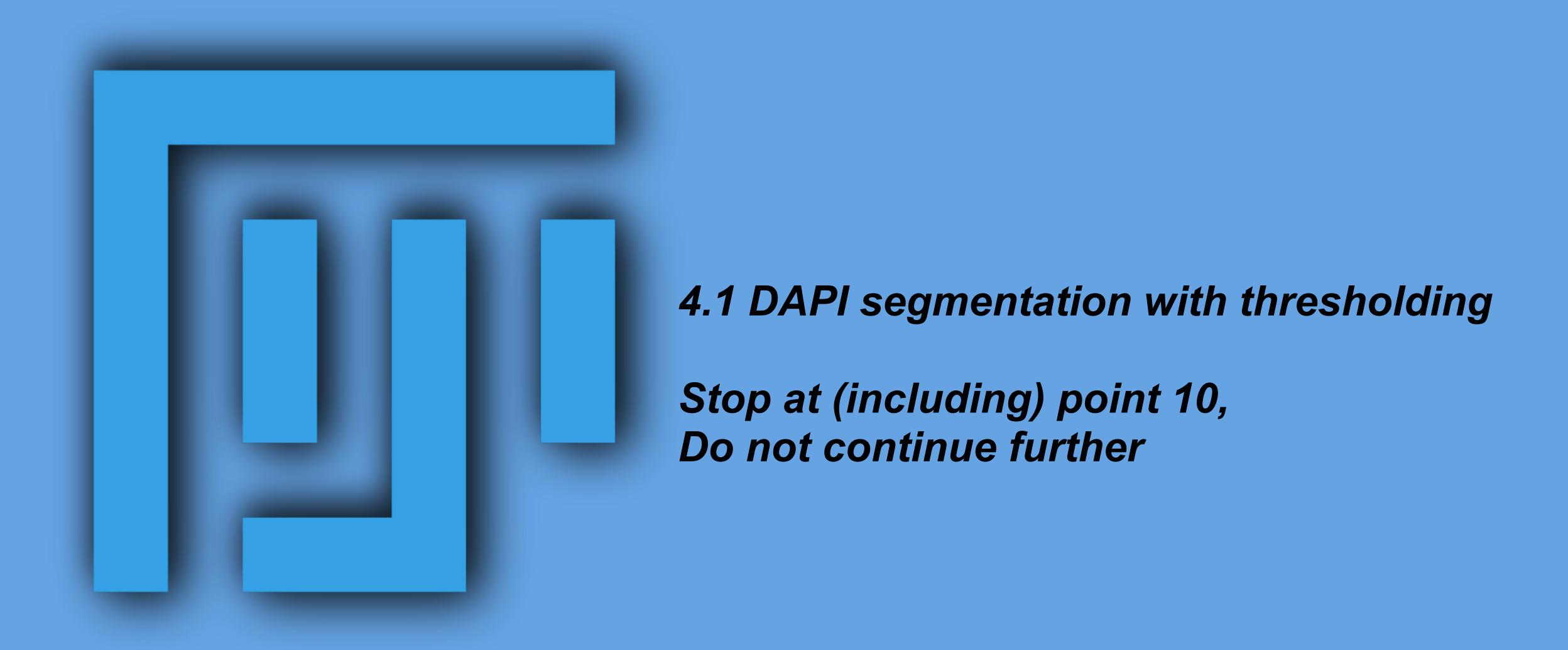
Generate a binary mask.



Binary because the image has only two pixel values, one for the selected pixels and one for the "discarded" pixels.

In Fiji the two pixel values are 0 and 255.

Segmentation with thresholding—exercises



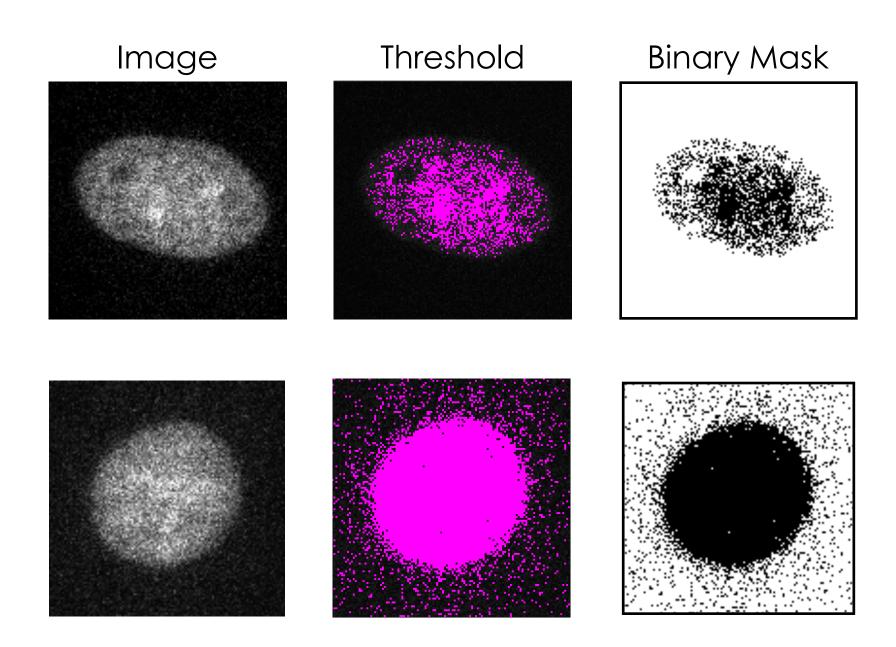






What can go wrong?

Usually, if you apply **thresholding** to the **"ORIGINAL" image** (the one you get out of the microscope), you won't be able to precisely **select all/only the pixels** you are interested in.



- Fluorescence label (e.g. DAPI)
- **Background** (uneven illumination, out-of-focus light, aberration, ...)
- **Noise** (detector read noise, Poisson noise, ...)