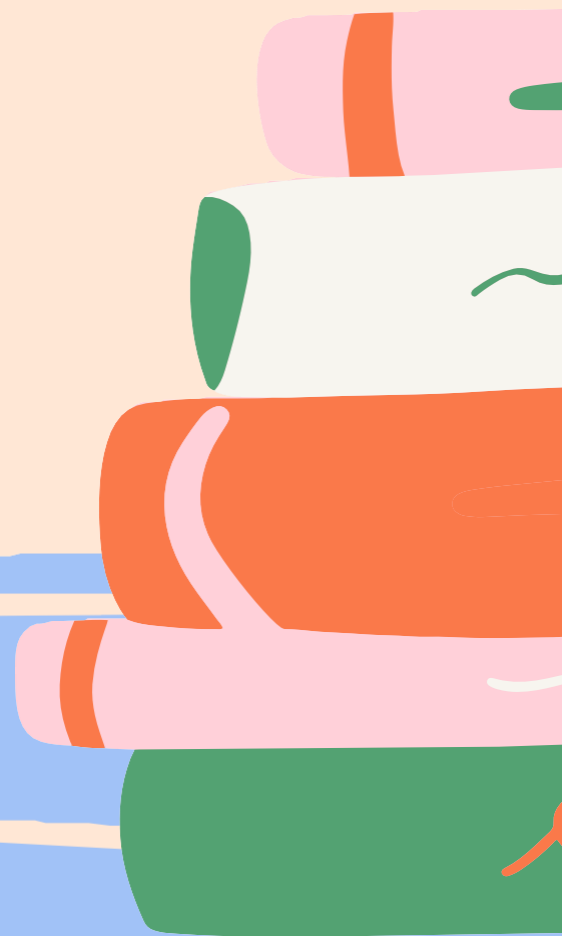


UNIVERSITY OF SCIENCE, VNU-HCM

# A\* Algorithm

Group 14 - CSC10004



# SINCERELY, THANKS!!

Teacher Đinh Bá Tiến

Teacher Hồ Tuấn Thanh

Teacher Nguyễn Lê Hoàng Dũng

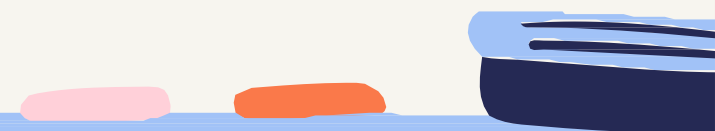
Teacher Trương Phước Lộc

## Team Member

19127216 - Đặng Hoàn Mỹ

19127544 - Nguyễn Hoàn Hoài Tâm

19127609 - Đinh Quang Tú



# “WHAT??.”

Introduction

History

Terms & Data Structure

Implement

Complexity

Graph Example

Application

## QUIZ!!!



# What is A\* Algorithm?

19127609 – Đinh Quang Tú



A\* Algorithm is one of the most successful search algorithms to find the shortest path between nodes or graphs.



## HOW CAN WE GO TO THE GOAL?

fast?  
less consuming?  
many obstacles?



## A\* ALGORITHM

find the shortest  
distance; we also want  
save as much time as  
possible



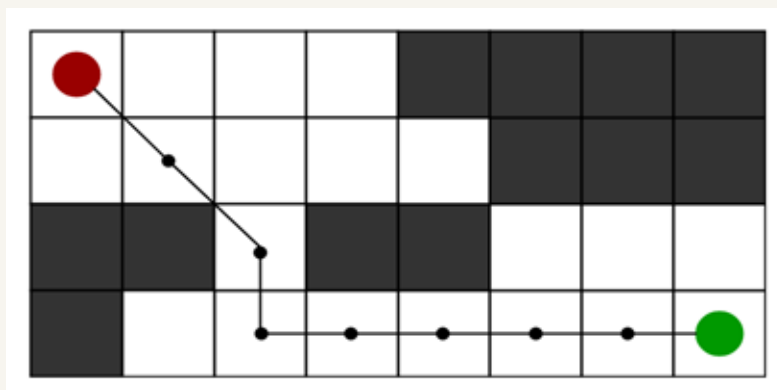
# HISTORY

- 1968
- the **Shakey project** aimed to build a mobile robot that has artificial intelligence to plan its actions
- combine heuristic approaches like Greedy Best- First-Search and formal approaches like **Dijkstra's Algorithm**.

# APPLICATION

Have everything you need within reach.

- Graph Traversal & Path-findings
- Games & Web-based maps
  - ❑ Warcraft III



2D Grid having several obstacles and we start from the source red cell to reach towards a goal green cell



# What is A\* Algorithm?

19127216 – Đặng Hoàn Mỹ

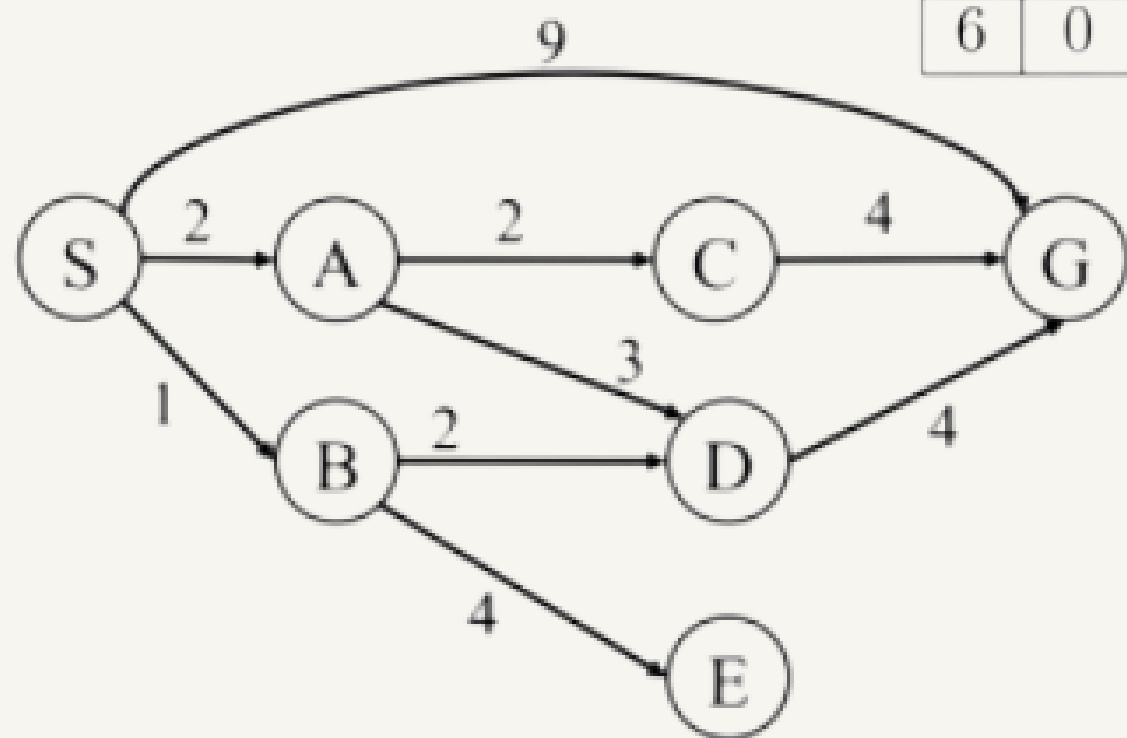




# Terms

Heuristics? Cost? Admissible? Consistent?

- **Heuristics** the estimated cost of moving from the current state to the goal state.
- **Cost** the cost that we arrange on the graph (weight).



Heuristic						
S	A	B	C	D	E	G
6	0	6	4	1	10	0

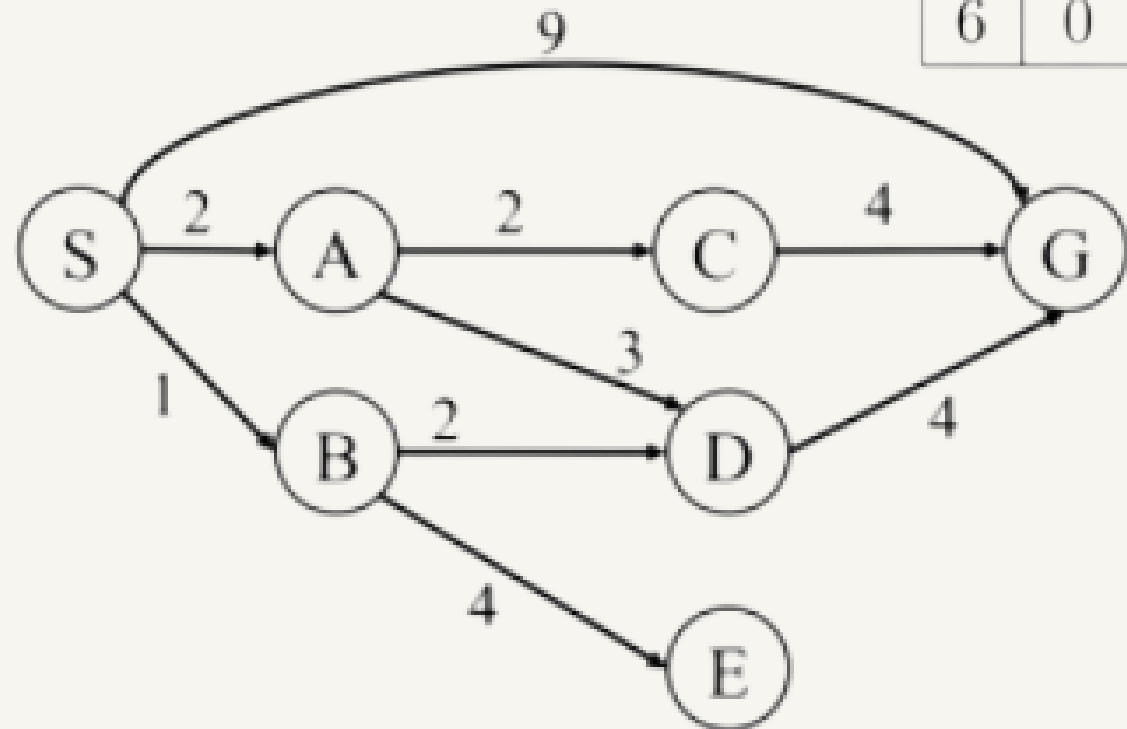


# Terms

Heuristics? Cost? Admissible? Consistent?

- **Admissible heuristic** the estimated cost must always be lower than or equal to the actual cost of reaching the goal state.

$$\forall n, 0 \leq h(n) \leq h^*(n)$$



Heuristic						
S	A	B	C	D	E	G
6	0	6	4	1	10	0



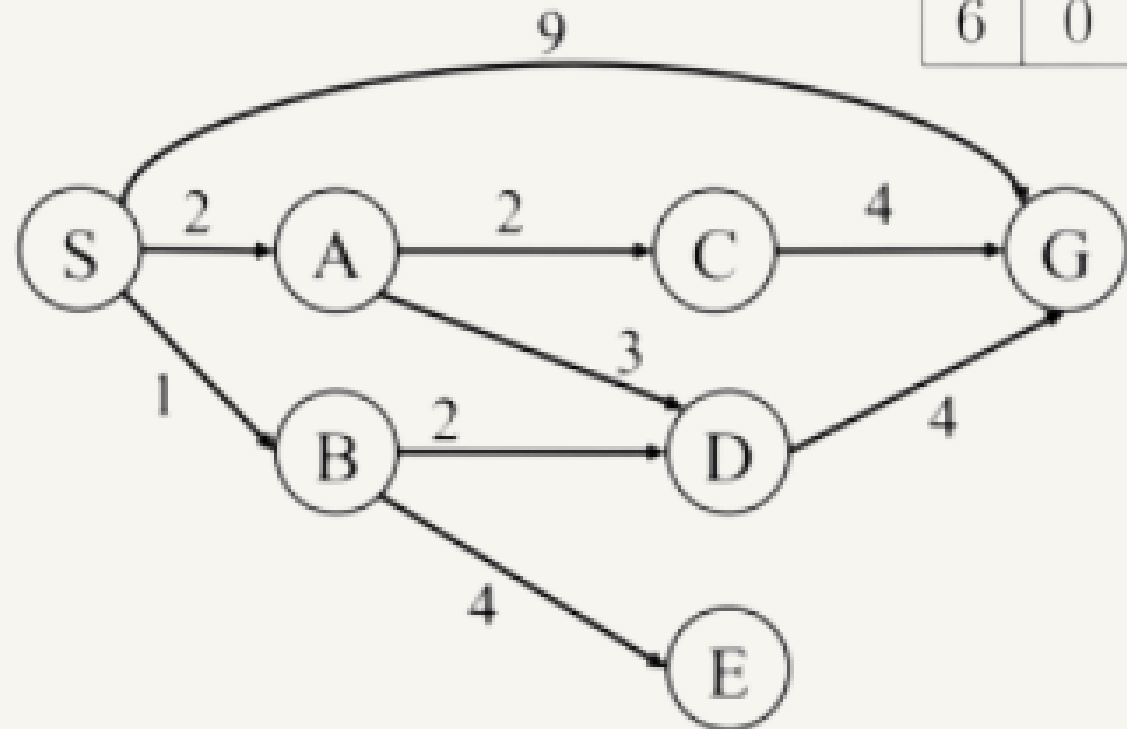
# Terms

Heuristics? Cost? Admissible? Consistent?

- **Consistent heuristic** less than or equal to the estimated distance from any neighboring vertex to the goal, plus the cost of reaching that neighbor.

$$h(A) \leq \text{cost}(A, C) + h(C)$$

$\forall A, C$  with  $C$  is a successor of  $A$



Heuristic						
S	A	B	C	D	E	G
6	0	6	4	1	10	0



# DATA STRUCTURE

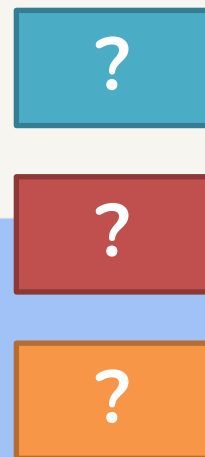
This plays important role in A\*.

frontier is a priority queue

- > keep track of the node

- > rearrange that to get the best node

frontier



# DATA STRUCTURE

This plays important role in A\*.

frontier is a priority queue

-> keep track of the node

-> rearrange that to get the best node

frontier

$$f(n) = g(n) + (n) \mid V \mid P$$

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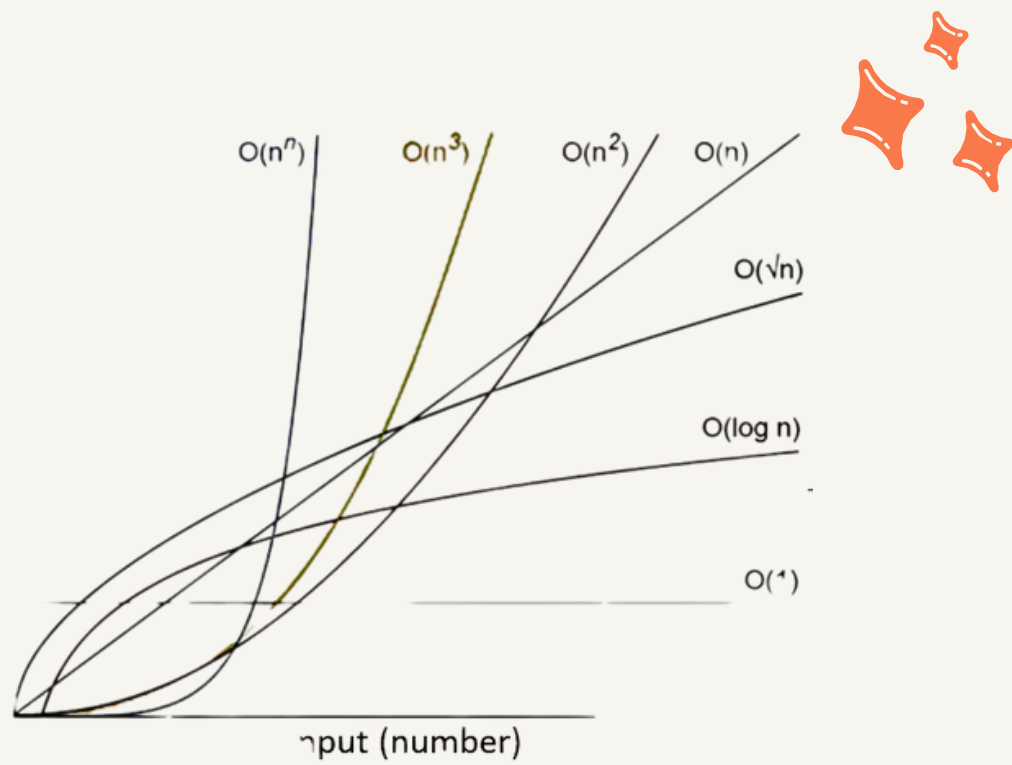
# IMPLEMENT

The main technique for this algorithm is using frontier as a priority queue to put the nodes while waiting.

- get the smallest cost of a path from that and put in the visited to mark up what has been visited
- catch the goal, we start to reverse the path (the parents of visited nodes) that we saved in the expanded
- there is no goal, we traverse all the children of that node and put it in the frontier with the formula

$$f(n) = g(n) + h(h)$$



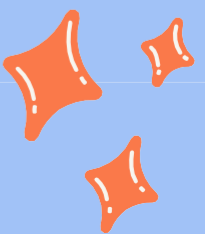
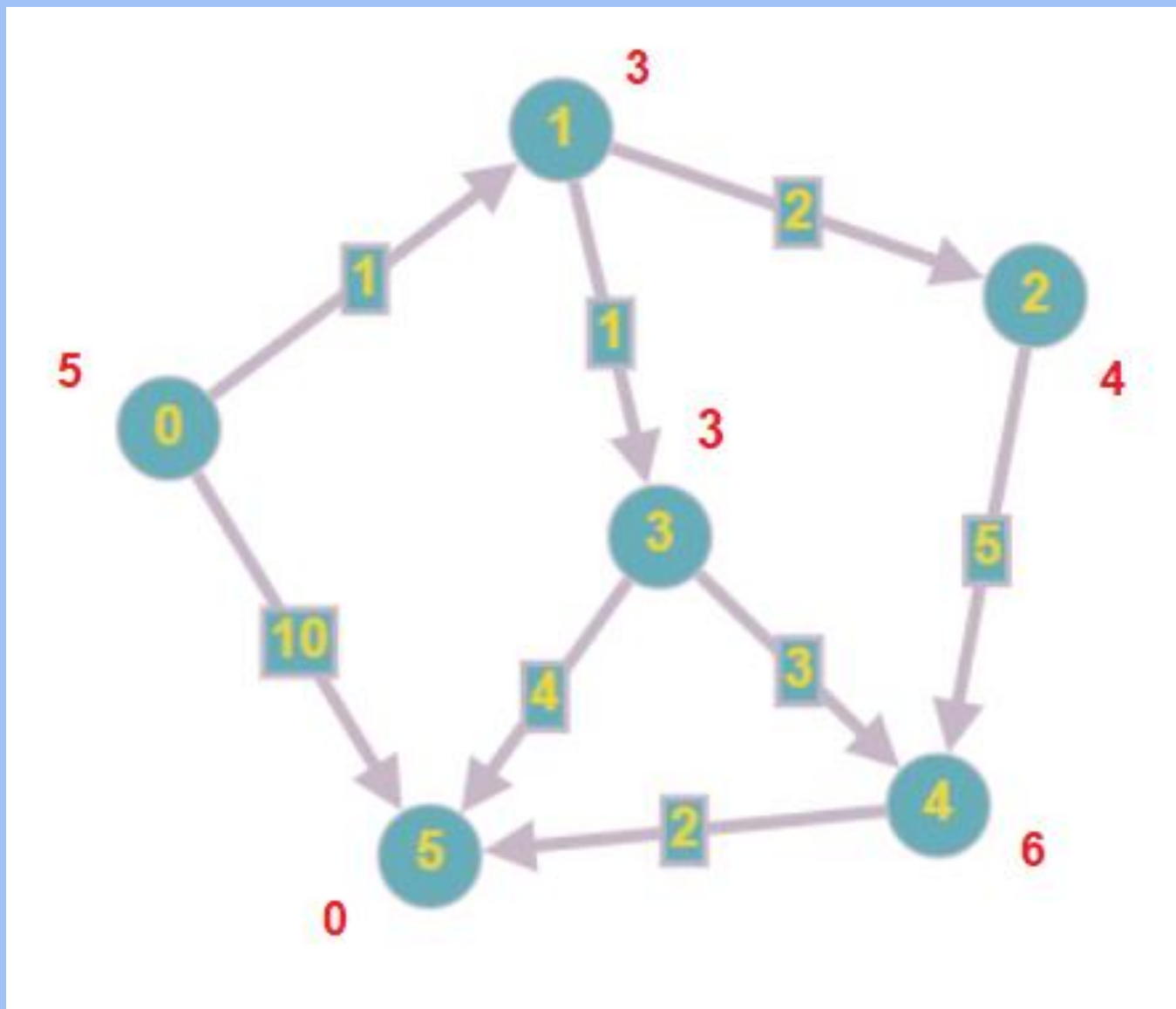


# COMPLEXITY

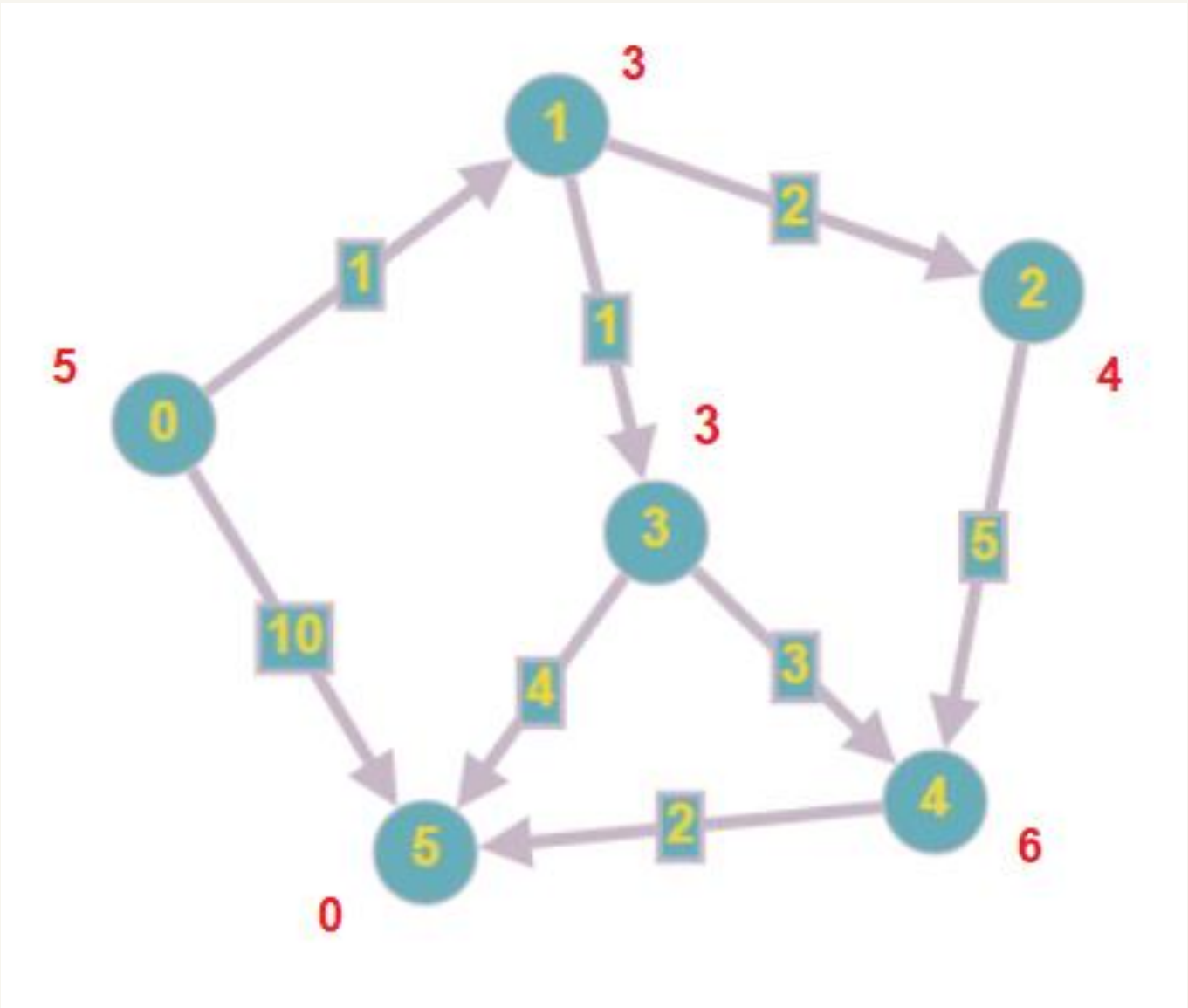
The number of nodes expanded is exponential in the depth of the solution (the shortest path)  $d$ , where  $b$  is the branching factor (the average number of successors per state)

$$O(b^d)$$

# GRAPH EXAMPLE







Frontier

$f(n) = g(n) + h(n)$	V	P
$4 = 1 + 3$	1	0
$7 = 3 + 4$	2	1
$11 = 5 + 6$	4	3
$5 = 6 + 0$	5	3

Expanded

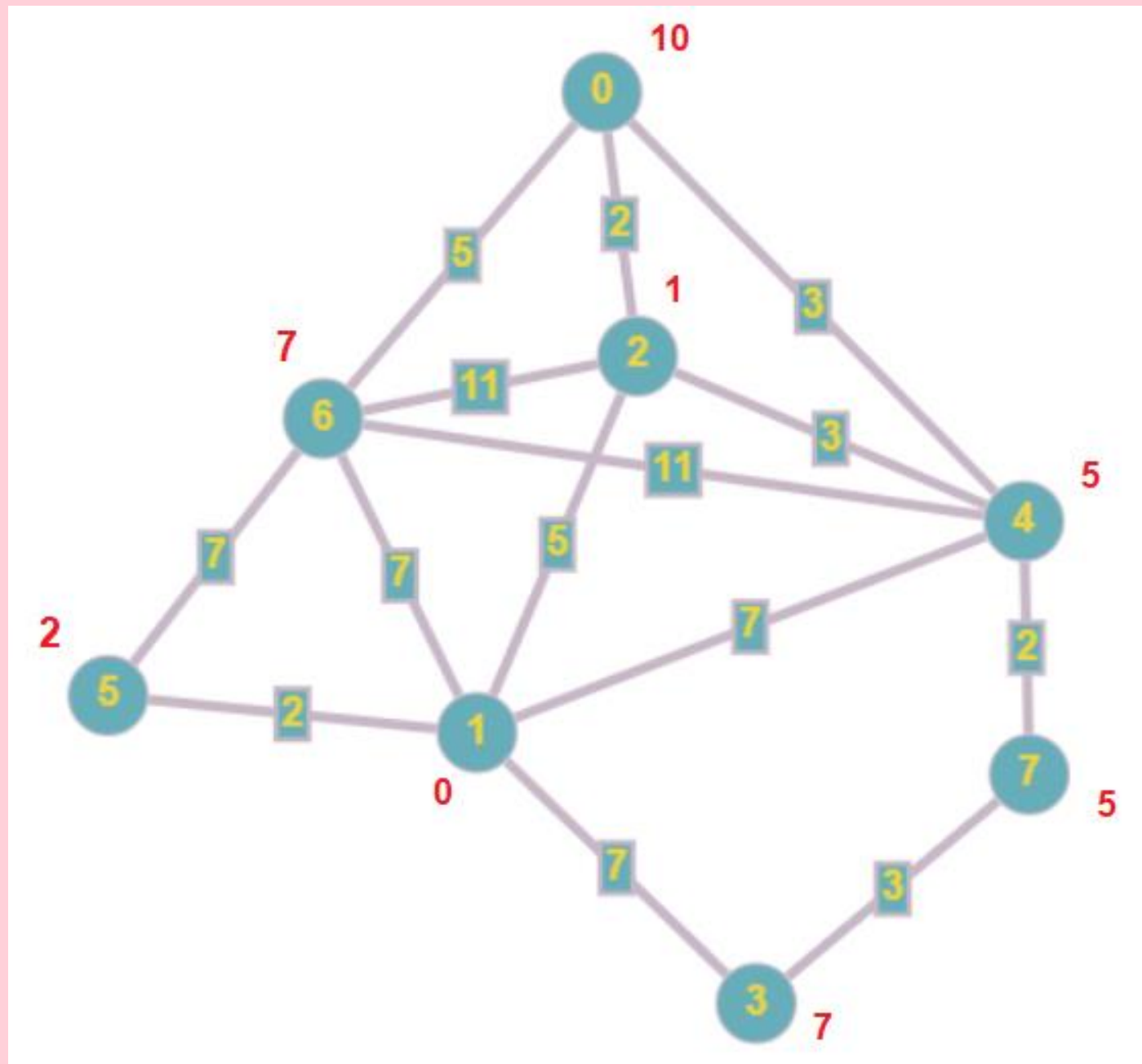
V	P

Path

0	1	3	5
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Is it better than any algorithm?

# BETTER?

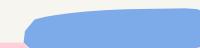


Dijkstra's Algorithm expands double number of nodes to find the same path. (0, 2, 4, 7, 6, 1)

A\* Algorithm just expands only 3 nodes which is exact the same path. (0, 2, 1)



# QUIZ!!!



# THANK YOU FOR LISTENING

