

UNIVERSITY OF SCIENCE, VNU-HCM

A* Algorithm

Group 14 - CSC10004







SINCERELY, THANKS!!

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"WHAT??."

Introduction
History
Terms & Data Structure
Implement
Complexity
Graph Example
Application

QUIZ!!!







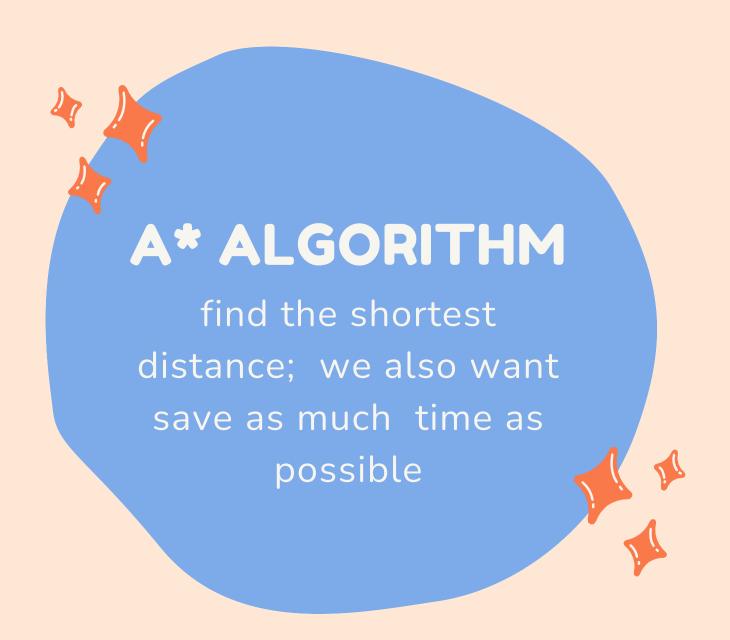
What is A*Algorithm?

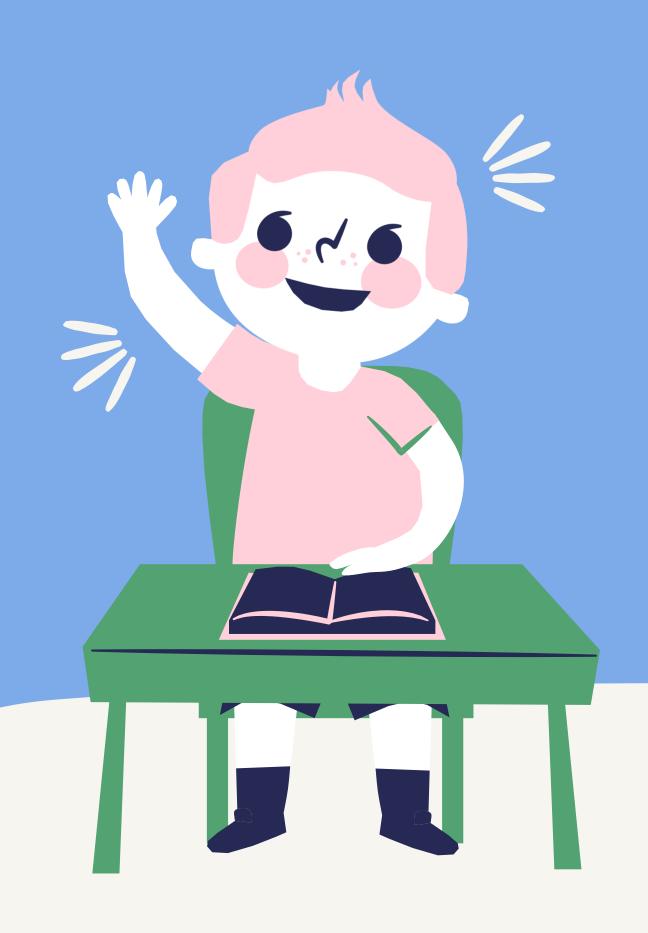
19127609 – Đinh Quang Tú



A* Algorithm is one of the most successful search algorithms to find the shortest path between nodes or graphs.







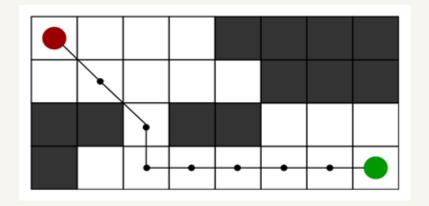
HISTORY

- 1968
- the Shakey project aimed to build a mobile robot that has artificial intelligence to plan its actions
- combine heuristic approaches like Greedy Best- First-Search and formal approaches like **Dijkstra's Algorithm**.

APPLICATION

Have everything you need within reach.

- Graph Traversal & Path-findings
- Games & Web-based maps
 - Warcarft III



2D Grid having several obstacles and we start from the source red cell to reach towards a goal green cell







What is A*Algorithm?

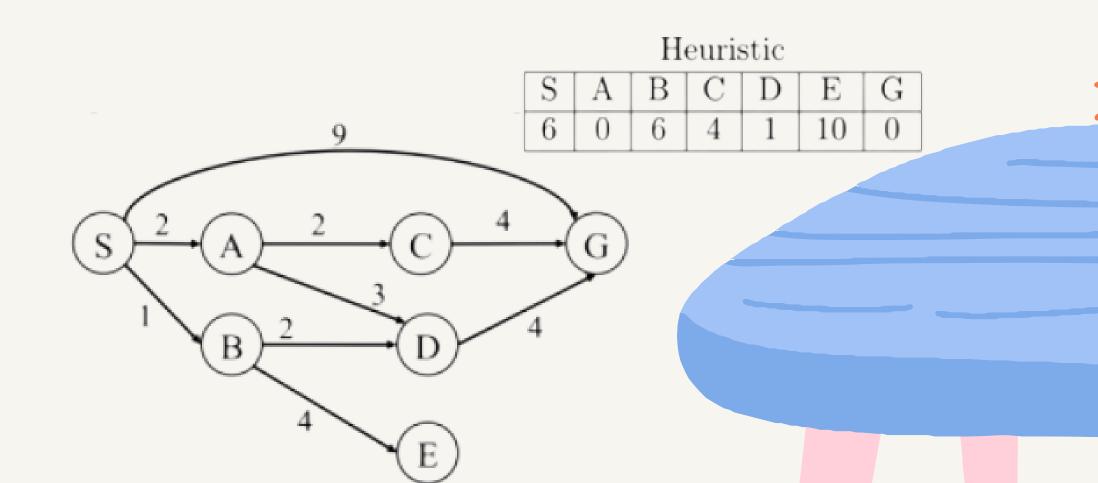
19127216 – Đặng Hoàn Mỹ



Terms

Heuristics? Cost? Admissible? Consistent?

- **Heuristics** the estimated cost of moving from the current state to the goal state.
- Cost the cost that we arrange on the graph (weight).



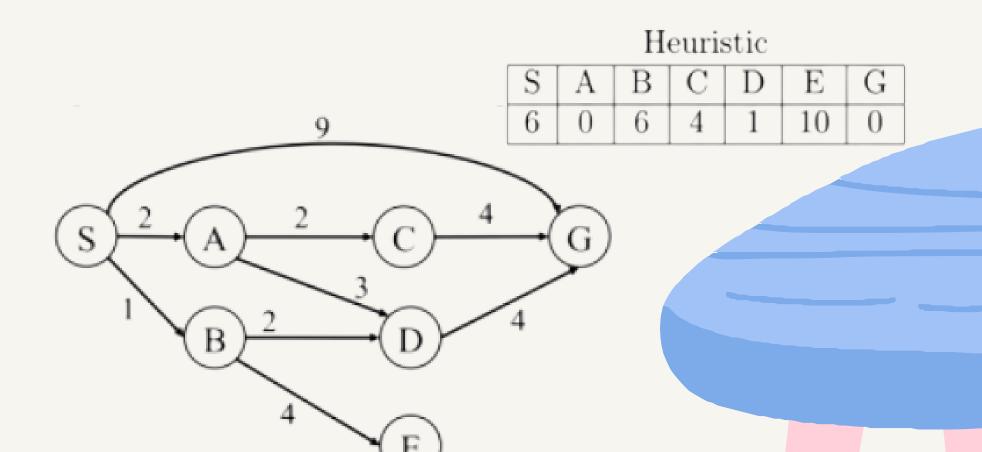


Terms

Heuristics? Cost? Admissible? Consistent?

• Admissible heuristic the estimated cost must always be lower than or equal to the actual cost of reaching the goal state.

$$\forall n, 0 \leq h(n) \leq h^*(n)$$



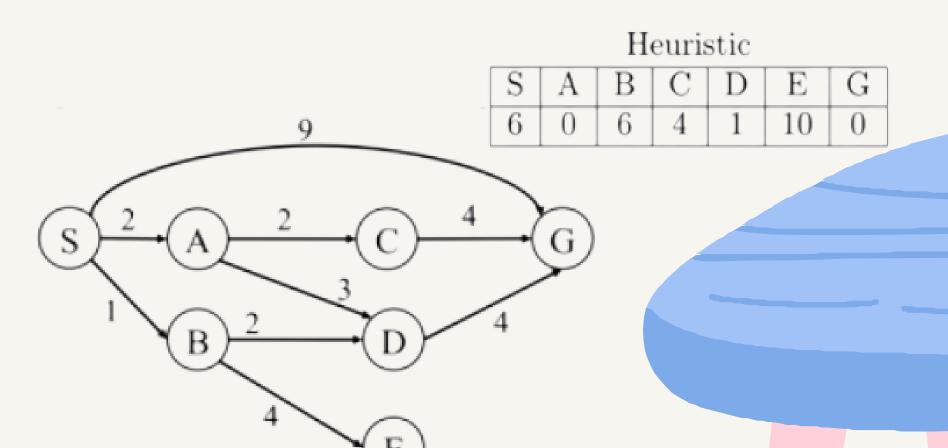


Terms

Heuristics? Cost? Admissible? Consistent?

• Consistent heuristic less than or equal to the estimated distance from any neighboring vertex to the goal, plus the cost of reaching that neighbor.

 $h(A) \le cost(A, C) + h(C)$ \(\forall A, C\) with C is a successor of A







DATA STRUCTURE

This plays important role in A*.

frontier is a priority queue

- -> keep track of the node
- -> rearrange that to get the best node

frontier

- ?
- ?
- ?



DATA STRUCTURE

This plays important role in A*.

frontier is a priority queue

- -> keep track of the node
- -> rearrange that to get the best node

frontier

$$f(n) = g(n) + (n) | V | P$$

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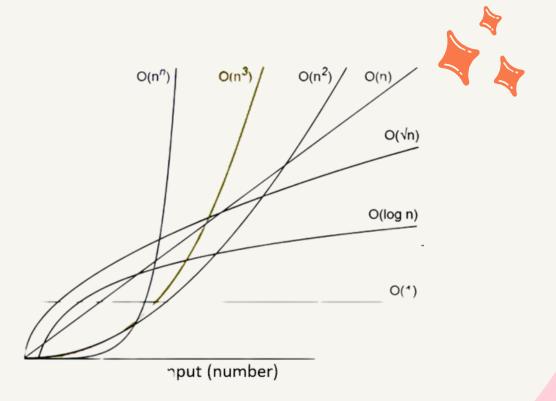
IMPLEMENT

The main technique for this algorithm is using frontier as a priority queue to put the nodes while waiting.

- get the smallest cost of a path from that and put in the visited to mark up what has been visited
- catch the goal, we start to reverse the path (the parents of visited nodes) that we saved in the expanded
- there is no goal, we traverse all the children of that node and put it in the frontier with the formula

$$f(n) = g(n) + h(h)$$



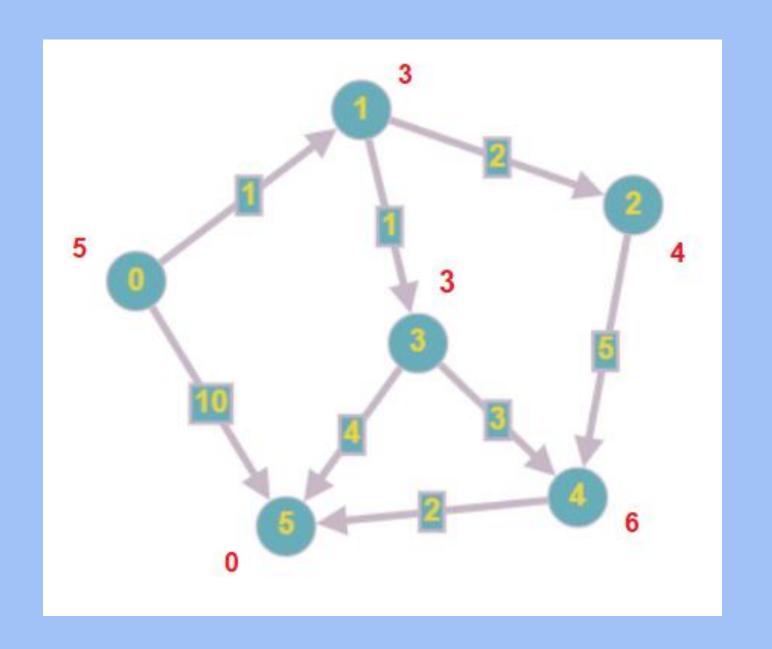


COMPLEXITY



The number of nodes expanded is exponential in the depth of the solution (the shortest path) d, where b is the branching factor (the average number of successors per state) $O(b^d)$

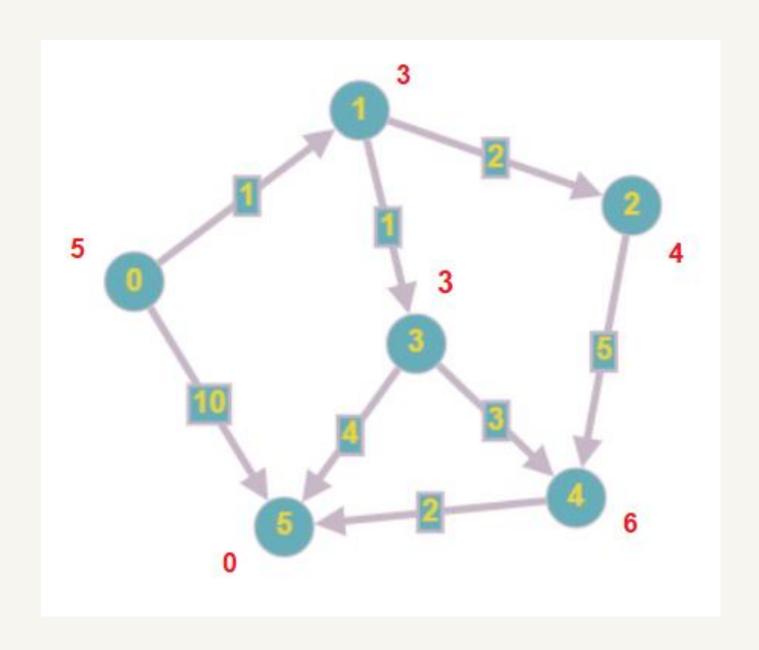
GRAPH EXAMPLE







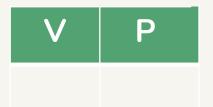




Frontier

f(n) = g(n) + h(n)	V	Р
4 = 1 + 3		0
7 = 3 + 4	2	
11 = 5 + 6	4	3
5 = 6 + 0	5	3

Expanded



Path

0

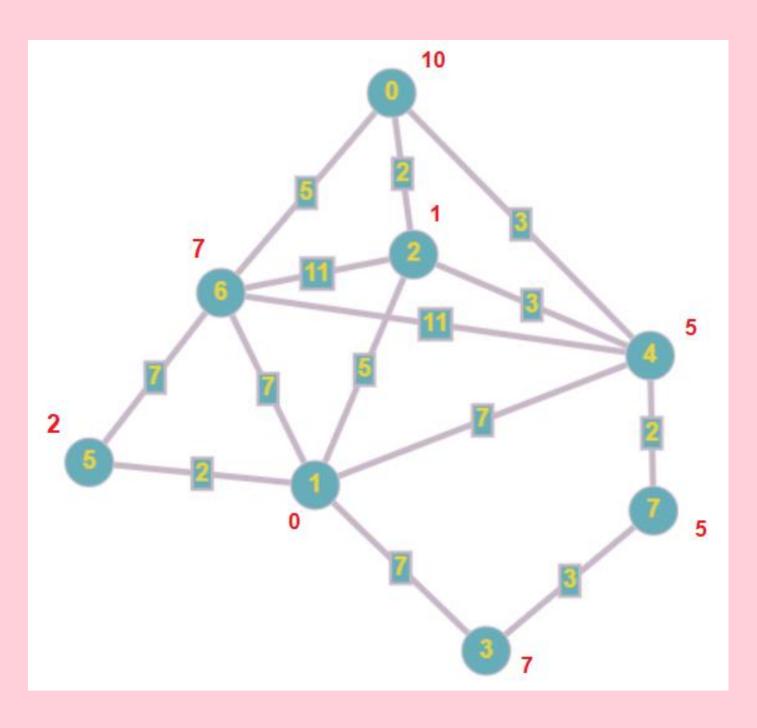
1

3

5

Is it better than any algorithm?

BETTER?



Dijkstra's Algorithm expands double number of nodes to find the same path. (0, 2, 4, 7, 6, 1)

A* Algorithm just expands only 3 nodes which is exact the same path. (0, 2, 1)



Quang Tú – 25%

- Find out the introduction and history
- Some terminologies (heuristic, f(n) = g(n) + h(n))
- Application

Hoàn Mỹ - 50%

- Notes for implementation, time/ space complexity
- Some terminologies (consistency and admissibility, completeness and optimality)
- Comparison
- Write source code (Graph)
- Graph demo (draw -> result)
- Report composer and PowerPoint arranger

Hoài Tâm – 25%

- Find the questions for Quiz and put the questions on Kahoot
- Template for PowerPoint and report

THANK YOU FOR LISTENING

