# **Digital Circuits Characteristics**

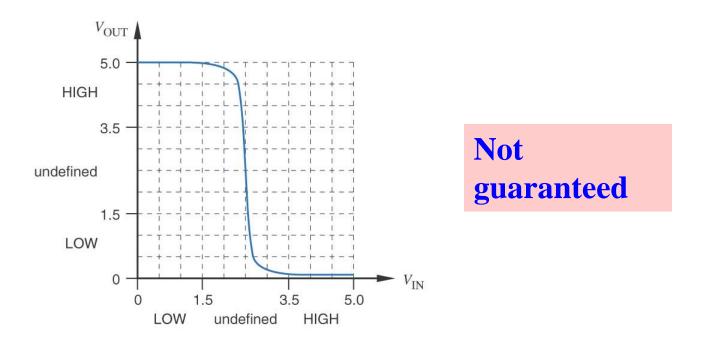


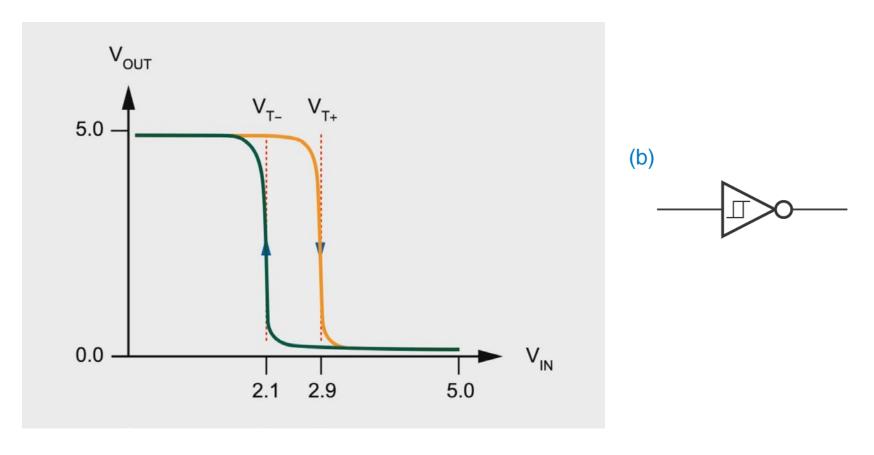
Fig. 3-25 Typical input-output transfer characteristic of a CMOS inverter

## **Schmitt-Trigger Inputs**

#### Fig. 3-47

- A Schmitt-Trigger inverter is characterised by 2 threshold voltages: VT- and VT+
- When input voltage V<sub>IN</sub> rises above VT+, output V<sub>OUT</sub> will switch to low.
- When input voltage V<sub>IN</sub> drops below VT-, output V<sub>OUT</sub> will switch to high.
- This non-symmetric behaviour is called hysteresis.

## **Schmitt-Trigger Inverter**



(a) input-output transfer characteristic

(b) logic symbol

Fig. 3-47 Schmitt-trigger inverter

## **Schmitt-Trigger Inverter**

- Fig. 3-48
- When input voltage (V<sub>IN</sub>) rises slowly, or has minor fluctuations around VT, a standard inverter will give unstable, fluctuating output.
- The output of a Schmitt-Trigger inverter in such situations has clean transitions and does not fluctuate.

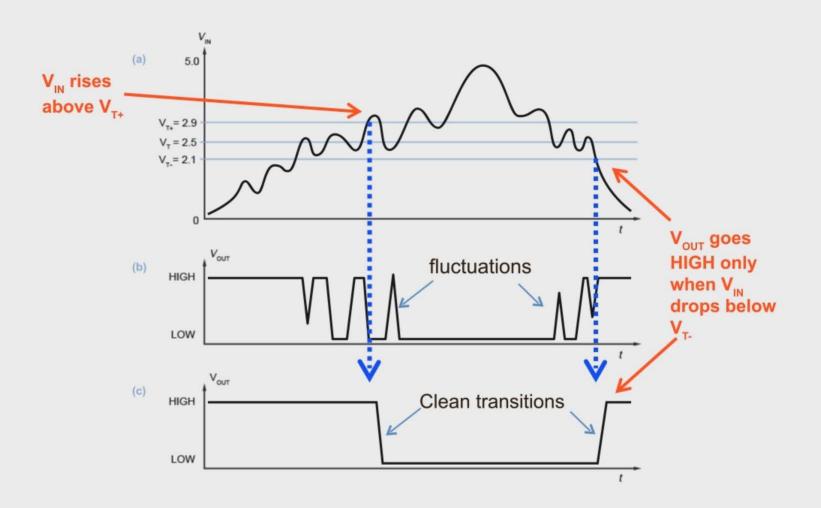


Fig. 3-48 Device operation with slowly changing inputs: (a) a noisy, slowly changing input; (b) output produced by an ordinary inverter; (c) output produced by an inverter with 0.8V of hysteresis.

# **Combinational PLA**

- PLD = Programmable Logic Devices
- Examples are PLA, PAL, CPLD, FPGA
- PLA: Programmable Logic Array
- PAL: Programmable Array Logic
- CPLD: Complex PLD
- FPGA: Field Programmable Gate Array
- SOM/SOP Boolean expressions can be easily implemented on a PLA

#### **PLA Example**

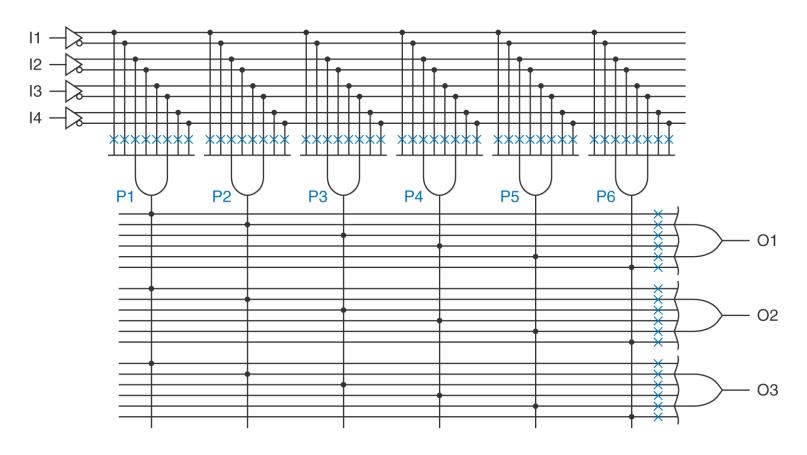


Figure 6-21 A  $4 \times 3$  PLA with six product terms.

#### X : indicate programmable connections

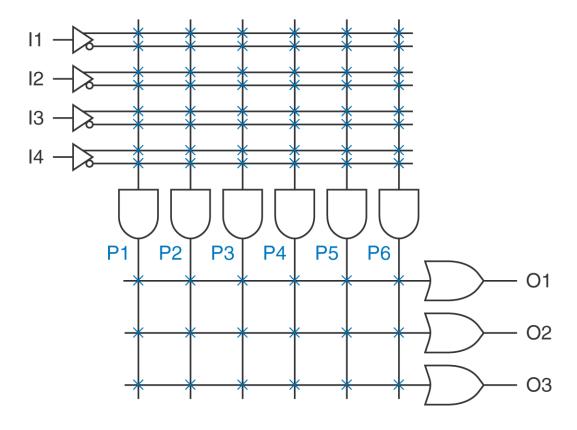


Figure 6-22

Compact representation of a  $4 \times 3$  PLA with six product terms.

#### PLA Example: SOP implementation

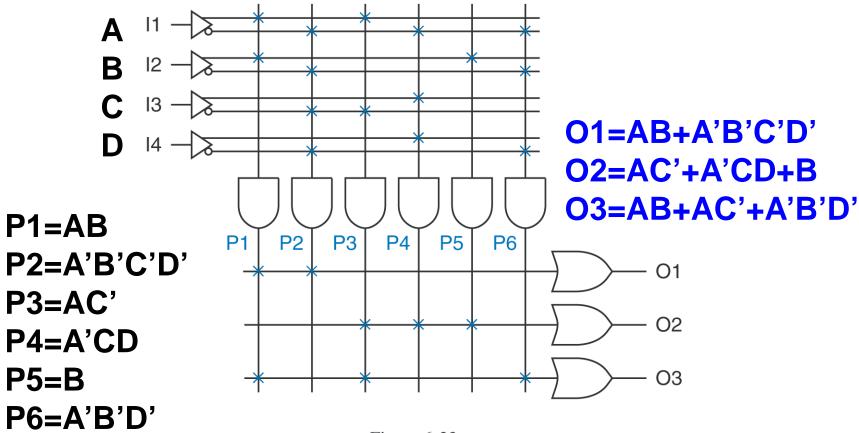


Figure 6-23

A  $4 \times 3$  PLA programmed with a set of three logic equations.

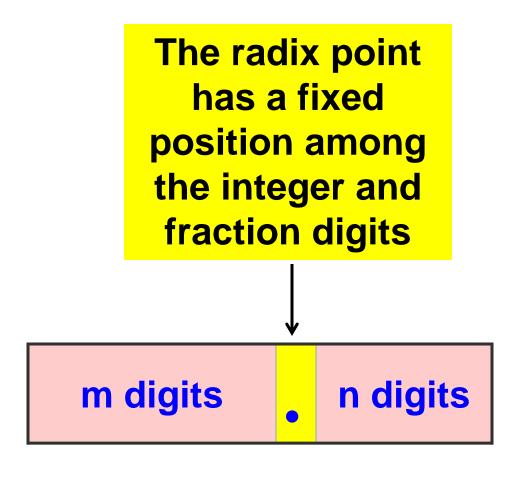
#### **PLA Example (truth table)**

Α	В	С	D	01	O2	О3
0	0	0	0	1	0	1
0	0	0	1	0	0	0
0	0	1	0	0	0	1
0	0	1	1	0	1	0
0	1	0	0	0	1	0
0	1	0	1	0	1	0
0	1	1	0	0	1	0
0	1	1	1	0	1	0
1	0	0	0	0	1	1
1	0	0	1	0	1	1
1	0	1	0	0	1	0
1	0	1	1	0	1	0
1	1	0	0	1	1	1
1	1	0	1	1	1	1
1	1	1	0	1	1	1
1	1	1	1	1	1	1

# **Fixed-point numbers**

### **Examples:**

- 102<sub>10</sub>
- 123.456<sub>10</sub>
- 2000.AD<sub>16</sub>
- 1001.0101<sub>2</sub>



- Fixed-point numbers are usually used for representing integers only
- Disadvantages of using fixed-point arithmetic for non-integers:
  - relatively small range of numbers that can be represented
  - possible loss of significant digits during computation

# Floating-point numbers

Machine equivalent of scientific notation

A floating-point number Z is represented as:

S × RE

e.g.  $2.99792458 \times 10^5$ 

#### S x RE

#### Where

- S is the *significand*, usually a signed fractional fixed-point number
- R is the *radix* (e.g. 2 for binary, 8 for octal, 10 for decimal, etc.)
- E is the *exponent*, usually a signed fixed-point integer

# Example: the IEEE Standard 754 on floating-point arithmetic

Single precision (32 bits):

			DIT
31	30	22	0
*	Exponent	Significand (mag)	

Double precision (64 bits):



- \* is the sign bit of significand
- radix is 2
- significand is in sign-magnitude notation
- exponent is in 2's complement notation