

# 1 Terminology

**Directed tree:** A directed graph that would be a tree if we ignored the directions of the edges.

**Arborescence:** A directed tree with a “root” such that every node of it has a unique path to it from the root. There’s always exactly one root.

**Spanning subgraph** of  $D(V, A)$ : A subgraph  $D(V, B)$  such that  $B \subseteq A$ .

**Branching system** of  $D(V, A)$  with  $k$  specified root nodes: A collection of edge-disjoint arborescences rooted at the  $k$  root nodes, with each arborescence being a spanning subgraph of  $D'(V \setminus R, A)$  with  $R$  containing all roots that are not part of the arborescence. By “edge-disjoint” we mean that none of these arborescences share any edges. Also, every node has at most  $k$  incoming edges (at most one from each arborescence).

**Optimal branching system** of a weighted digraph with  $k$  specified root nodes: the branching system with the lowest total weight.

# 2 Algorithm

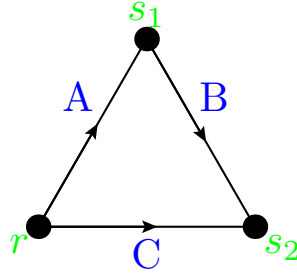
To find an OBS we need to find a min-cost set of edges which is both a basis of matroid  $M_1$  and of  $M_2$ :

- $M_1 = (E, J_1)$  in which  $j \in J_1$  has no edges entering any root nodes, and at most  $k$  edges entering each other node of the graph.
- $M_2 = (E, J_2)$  in which  $j \in J_2$  can be partitioned into at most  $k$  **arborescences**.

# 3 Examples:

## 3.1 3-nodes

### 3.1.1 1 root



The branchings systems are:

$$B_1 = \{A, C\} \tag{3.1}$$

$$B_2 = \{A, B\} \tag{3.2}$$

We also have:

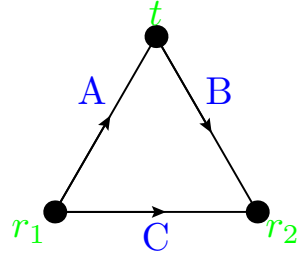
$$J_1 = \{P(B_1) \cup P(B_2)\} \tag{3.3}$$

$$= \{\emptyset, A, C, \{A, C\}, B, \{A, B\}\} \tag{3.4}$$

$$J_2 = J_1 \tag{3.5}$$

Therefore, we have  $J_1 \cap J_2 = J_1$  and if  $c(A) < 0$  and  $c(B) = c(D) > 0$ , we have that the OBS obtained from minimizing over  $J_1 \cap J_2$  is  $\{A\}$ , even though it is a non-spanning arborescence! Also if  $c(A) = c(B) = c(C) > 0$ , the OBS obtained from minimizing over  $J_1 \cap J_2$  would be  $\{\emptyset\}$  for which if we consider the root to be  $r$ , the arborescence would also not be spanning the graph.

### 3.1.2 2 roots



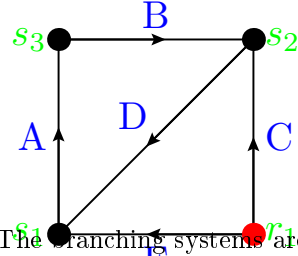
The only branching system is:

$$B = \{A\}. \quad (3.6)$$

**We also have that  $J_1 = J_2 = B$ .**

## 3.2 4-nodes:

### 3.2.1 1 root



The branching systems are:

$$B_1 = \{E, B, A\}, \quad (3.7)$$

$$B_2 = \{E, B, D\}, \quad (3.8)$$

$$B_3 = \{D, C, B\}. \quad (3.9)$$

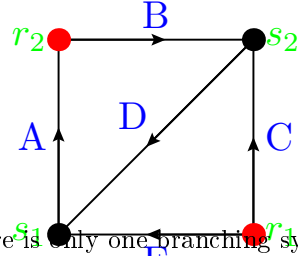
**We also have that:**

$$J_1 = \{B_1, B_2, B_3, \{A, C, B\}\} \quad (3.10)$$

$$J_2 = \{B_1, B_2, B_3\}. \quad (3.11)$$

Since  $J_2 \subset J_1$ , we know that  $J_1 \cap J_2 = J_2$ , **so the OBS will be the min-cost branching system in  $J_2$ .**

### 3.2.2 2 roots



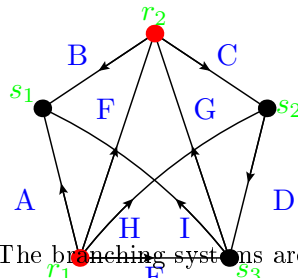
There is only one branching system:

$$B = \{E, B, D, C\}, \quad (3.12)$$

**We also have that:  $J_1 = J_2 = B$ .**

## 3.3 5-nodes:

### 3.3.1 2 roots



The branching systems are:

$$B_1 = \{B, C, A, H, D, E\}, \quad (3.13)$$

$$B_2 = \{B, C, D, E, H, I\}, \quad (3.14)$$

$$B_3 = \{C, D, I, A, H, E\}. \quad (3.15)$$

**We also have that:  $J_1 = J_2 = \{B_1, B_2, B_3\}$ .**