1 Terminology

Directed tree: A directed graph that would be a tree if we ingored the directions of the edges.

Arborescence: A directed tree with a "root" such that every node of it has a unique path to it from the root. There's always exactly one root.

Spanning subgraph of D(V, A): A subgraph D(V, B) such that $B \subseteq A$.

Branching system of D(V, A) with k specified root nodes: A collection of edge-disjoint arborescences rooted at the k root nodes, with each arborescence being a spanning subgraph of $D'(V \setminus R, A)$ with R containing all roots that are not part of the arborescence. By "edge-disjoint" we mean that none of these arborescences share any edges. Also, every node has at most k incoming edges (at most one from each arborescence).

Optimal branching system of a weighted digraph with k specified root nodes: the branching system with the lowest total weight.

2 Algorithm

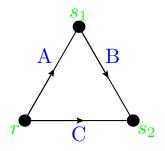
To find an OBS we need to find a min-cost set of edges which is both a basis of matroid M_1 and of M_2 :

- $M_1=(E,J_1)$ in which $j \in J_1$ has no edges entering any root nodes, and at most k edges entering each other node of the graph.
- $M_2=(E,J_2)$ in which $j\in J_2$ can be partitioned into at most k forests.

3 Examples:

3.1 3-nodes

3.1.1 1 root



The branching systems are:

$$\mathcal{B}_1 = \{A, C\} \tag{3.1}$$

$$\mathcal{B}_2 = \{A, B\} \tag{3.2}$$

We also have:

$$J_1 = \{ P(B_1) \cup P(B_2) \} \tag{3.3}$$

$$= \{\emptyset, \{A\}, \{C\}, \{A, C\}, \{B\}, \{A, B\}\}$$
(3.4)

$$J_2 = \{ P(\{A, B\}) \cup P(A, C) \cup P(B, C) \}$$
(3.5)

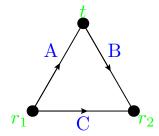
$$b(J_1) = \{\mathcal{B}_1, \mathcal{B}_2\} \tag{3.6}$$

$$b(J_2) = \{ \mathcal{B}_1, \mathcal{B}_2, \{B, C\} \}. \tag{3.7}$$

So we have that:

$$b(J_1) \cap b(J_2) = \{ \mathcal{B}_1, \mathcal{B}_2 \}. \tag{3.8}$$

3.1.2 2 roots



There's no branching systems because it's impossible for an arborescence rooted at r_2 to be spanning.

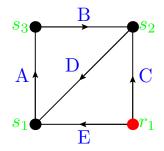
$$J_1 = \{\emptyset, \{A\}\} \tag{3.9}$$

$$J_2 = P(\{A, C, B\}) \tag{3.10}$$

Therefore $b(J_1)=\{\{A\}\}$ and $b(J_2)=\{\{A,B,C\}\}$ and $b(J_1)\cap b(J_2)=\emptyset$ meaning that there's no branching systems.

3.2 4-nodes:

3.2.1 1 root



The branching systems are:

$$\mathcal{B}_1 = \{ E, A, B \}, \tag{3.11}$$

$$\mathcal{B}_2 = \{C, E, A\},\tag{3.12}$$

$$\mathcal{B}_3 = \{C, D, A\}. \tag{3.13}$$

We also have that:

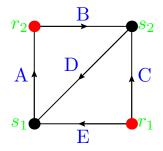
$$b(J_1) = \{ \mathcal{B}_1, \mathcal{B}_2, \mathcal{B}_3, \{A, B, D\} \}$$
(3.14)

$$b(J_2) = \{\mathcal{B}_1, \mathcal{B}_2, \mathcal{B}_3, \{A, B, C\}, \{B, C, E\}, \{B, D, C\}, \{B, D, E\}, \{A, D, E\}\}.$$
(3.15)

So we find that:

$$b(J_1) \cap b(J_2) = \{ \mathcal{B}_1, \mathcal{B}_2, \mathcal{B}_3 \}. \tag{3.16}$$

3.2.2 2 roots



There is only one branching system:

$$\mathcal{B} = \{E, B, D, C\}. \tag{3.17}$$

We also have that:

$$b(J_1) = \{\mathcal{B}\}\tag{3.18}$$

$$b(J_2) = \{A, B, C, D, E\}, \tag{3.19}$$

$$b(J_1) \cap b(J_2) = \emptyset \tag{3.20}$$

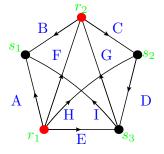
So we need to remove A (which is going into a root). By doing that we have:

$$b(J_2) = b(J_1), (3.21)$$

$$b(J_2) \cap b(J_2) = \mathcal{B}. \tag{3.22}$$

3.3 5-nodes:

3.3.1 2 roots



The branching systems are:

$$\mathcal{B}_1 = \{A, H, E; B, C, D\}, \tag{3.23}$$

$$\mathcal{B}_2 = \{ E, I, H; B, C, D \}, \tag{3.24}$$

$$\mathcal{B}_3 = \{A, H, E; C, D, I\}. \tag{3.25}$$

We also have that: $b(J_1) = b(J_2) = \{\mathcal{B}_1, \mathcal{B}_2, \mathcal{B}_3\}.$