

# 1 Terminology

**Directed tree:** A directed graph that would be a tree if we ignored the directions of the edges.

**Arborescence:** A directed tree with a “root” such that every node of it has a unique path to it from the root. There’s always exactly one root.

**Spanning subgraph** of  $D(V, A)$ : A subgraph  $D(V, B)$  such that  $B \subseteq A$ .

**Branching system** of  $D(V, A)$  with  $k$  specified root nodes: A spanning subgraph of  $D$  created by edge-disjoint arborescences rooted at the  $k$  root nodes. Edge-disjoint means none of these arborescences share any edges. Every node has at most  $k$  incoming edges (at most one from each arborescence).

**Optimal branching system** of a weighted digraph with  $k$  specified root nodes: the branching system with the lowest total weight.

# 2 Algorithm

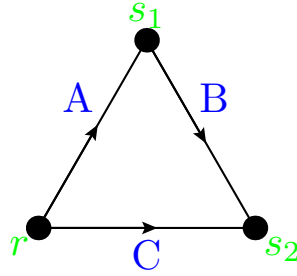
To find an OBS we need to find a min-cost set of edges which is both a basis of matroid  $M_1$  and of  $M_2$ :

- $M_1=(E, J_1)$  in which  $j \in J_1$  has no edges entering any root nodes, and at most  $k$  edges entering each other node of the graph.
- $M_2=(E, J_2)$  in which  $j \in J_2$  can be partitioned into at most  $k$  **arborescences**.

# 3 Examples:

## 3.1 3-nodes

3.1.1 1 root (it seems that  $J_1$  also should contain subsets of  $B_1$  and  $B_2$ )



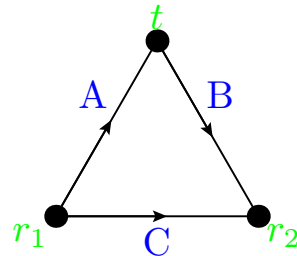
The branchings systems are:

$$B_1 = \{A, C\} \tag{3.1}$$

$$B_2 = \{A, B\} \tag{3.2}$$

**We also have that  $J_1 = J_2 = \{B_1, B_2\}$ .**

## 3.1.2 2 roots



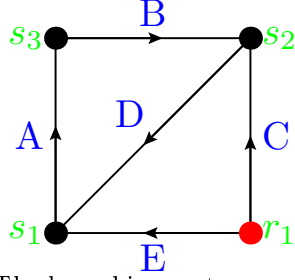
The only branching system is:

$$B = \{A\}. \tag{3.3}$$

**We also have that  $J_1 = J_2 = B$ .**

### 3.2 4-nodes:

#### 3.2.1 1 root



The branching systems are:

$$B_1 = \{E, B, A\}, \quad (3.4)$$

$$B_2 = \{E, B, D\}, \quad (3.5)$$

$$B_3 = \{D, C, B\}. \quad (3.6)$$

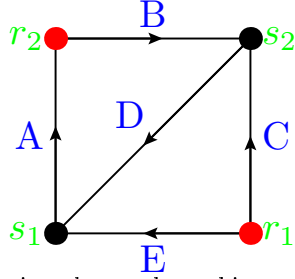
**We also have that:**

$$J_1 = \{B_1, B_2, B_3, \{A, C, B\}\} \quad (3.7)$$

$$J_2 = \{B_1, B_2, B_3\}. \quad (3.8)$$

Since  $J_2 \subset J_1$ , we know that  $J_1 \cap J_2 = J_2$ , **so the OBS will be the min-cost branching system in  $J_2$ .**

#### 3.2.2 2 roots



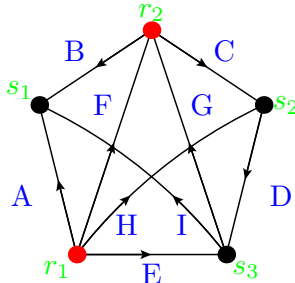
There is only one branching system:

$$B = \{E, B, D, C\}, \quad (3.9)$$

**We also have that:  $J_1 = J_2 = B$ .**

### 3.3 5-nodes:

#### 3.3.1 2 roots



The branching systems are:

$$B_1 = \{B, C, A, H, D, E\}, \quad (3.10)$$

$$B_2 = \{B, C, D, E, H, I\}, \quad (3.11)$$

$$B_3 = \{C, D, I, A, H, E\}. \quad (3.12)$$

**We also have that:  $J_1 = J_2 = \{B_1, B_2, B_3\}$ .**