

What are the possible axial point groups for a molecule of a certain size or formula?

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For each axial point group, we determine *all* possible structures in terms of the number of atoms and the chemical formula. We provide examples of molecules of each size and formula if they are known, and hence we determine the yet-to-be discovered molecules with under five atoms for each point group. We present a set of principles that can be used for proofs about the possibility or impossibility for a molecule of a certain size and/or formula to have a point group symmetry. We also resolve some inconsistencies in a table by P. Atkins, M. Child and C. Phillips, add missing entries to it, and improve it further in a number of ways.

I. INTRODUCTION

One might wonder why, despite group theory being applied to molecules for about 100 years [19], the questions that are being addressed in this paper do not appear to have been answered yet. Indeed we have asked all living authors of [1–18, 36] if they have ever come across a list of all possible point groups for a 4-atom (tetraatomic) system, and in all cases we were explicitly told that they were unaware of such a list, or we received no response at all. We have determined all possible point groups for systems with *any* number of atoms, and we have gone a step even further by determining all possible point groups for structures with a given chemical formula.

After searching through all of [1–18, 36] thoroughly, the closest work that we found to the results in this paper, is the table of “Shapes” found in the 2008 version of the famous “Tables for Group Theory” document by P. Atkins, M. Child and C. Phillips [1]. Nothing similar was found in any of [1–18, 36], and the table of “shapes” in [1] has several shortcomings which we will address and fix in Section III, before we begin presenting the main results of our work in the following sections.

For investigating the novelty of our work, we believe that our thorough examination through all of [1–18, 36] was a fair survey of the known literature on the topic. The 2007 paper [39] reported a thorough survey of known published works that provided character tables for the S_8 and D_{8h} point groups, and our list [1–18, 36] includes all of those works, in addition to [39] itself, the papers that cited [39], and also thoroughly selected work on the topic that did not provide S_8 and D_{8h} character tables.

Our paper focuses on *axial* point groups, which are those belonging to the series C_n , C_{nv} , C_{nh} , $S_{2n}D_n$, D_{nh} , D_{nd} (including C_s which

is equivalent to C_{1h} and C_{1v} , and C_i which is equivalent to S_2). For the *polyhedral* point groups T , T_d , T_h , O , O_h , I , I_h , we will present even more novel results in a forthcoming paper. For example, in all of the literature that we have seen (including [1–18, 36]), the shape with the smallest number of vertices (or the system containing the smallest number of atoms) for which the point group is O , is the snub cube which has 24 vertices (or atoms), but within the last month we have discovered that it is possible to construct an object with only 20 vertices (or for the atoms in a 20-atom system to be arranged) such that the point group is O [43]. Likewise, in all of the literature that we have seen, the shape with the smallest number of vertices for which the point group is I , is the snub dodecahedron which has 60 vertices, but within the last month we have discovered that it is possible to construct an object with only 50 vertices such that the point group is I [43].

The next section of this paper will explain the context which made *us* feel compelled to answer the questions that this paper addresses; for any readers that wish to skip the motivation section, the rest of the paper is self-contained and does not require knowledge of any of the material presented there. The second paragraph of this introduction already described the contents of Section III. The diagrams in Section III will make it easier to follow Section IV, which contains the foundation for obtaining our main results which are provided in Section V and summarized in Section VI. Overall our results are as follows (all results appear to be novel or unusually difficult to find in existing places):

- In Section III: A table that presents visual examples of structures for all aforementioned axial point groups for $2 \geq n \geq 6$ and $n = \infty$,
 - in a more clear way than in [1],
 - with inconsistencies in [1] resolved,
 - with more of the $n = \infty$ shapes presented than in [1],
 - with structures requiring fewer atoms than in [1] for the C_n and D_n series,

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- with an extra column showing additional structures (in some cases these are more realistic than in [1]) for the $n = 2$ cases, and.
- In Section IV: Properties of some point groups that are very helpful for obtaining or explaining new results, and for pedagogical purposes.
- In Section V: For each axial point group, we determine
 - the minimum number of atoms (cardinality) required;
 - all possible cardinalities allowed (the minimum cardinality is a special case of this); and
 - all possible chemical formulas allowed (the list of all possible cardinalities is a special case of this).
- In Section VI: As a consequence of the results in Section V,
 - we were able to list in table X all possible point groups allowed for systems with m atoms for $m = 1 - 8$ (and a table with *arbitrary* values of m can be generated with the results from V but would take up too much space);
 - we also explicitly listed the specific point groups (and diagrams of example structures) that are possible for systems with the specific formulas A_3 , A_2B , and ABC for triatomic systems and A_4 , A_3B , A_2B_2 , A_2BC , and $ABCD$ for tetraatomic systems (analogous lists for *arbitrary* chemical formulas can also be generated with the results from V but would take up too much space);
 - we attempted to provide examples of known molecules with each possible point group for each formula A_3 , A_2B , ABC , A_4 , A_3B , A_2B_2 , A_2BC , and $ABCD$, and this led us to the discovery of shapes for which no molecule/complex has yet been synthesized or found, despite the existence of such molecules/complexes being proven to be possible (this was not a surprise for larger structures, but we determined that the minimum number of atoms required for the point group D_2 is 4 but we could not find any example of a 4-atom molecule with the D_2 point group despite the apparent simplicity that would come with such a small molecular size).

Section VII briefly mentions how the results of this work can be used for forthcoming projects.

II. MOTIVATION FOR THIS WORK

Our need for answers to the question in the present paper's title, arose during other work. GW100 is a dataset of 100 systems (95 molecules and 5 atoms) which was introduced in a 2015 paper [37] and by the end of 2020, already more than 100 electronic structure methods/codes were used to calculate energies for all systems in the GW100 dataset. It has therefore become a monumental dataset for benchmarking, and efforts were made in 2021 [20] and 2023 [21] to improve the most accurate calculations that had been done on the system until then [22], and therefore to create one of the best known sets of benchmark data in existence for electronic structure calculations.

However, for many of the molecules in the GW100 dataset, calculations are done at geometries that were optimized using density functional theory, which means that the results are dependent on the basis set and density functional used; and it also had an effect on the comparisons that have been made between calculations that were done for the GW100 dataset and experimental data on the same dataset. For many of those molecules, very accurate bond lengths and angles that were determined from high-resolution spectroscopic experiments, are available in places such as the Landolt–Bornstein volumes and related books [23–35] and also in the original papers in which the geometric data was determined.

The books [23–35] provide only the *point group*, a 3D diagram, and usually the minimum number of bond lengths, bond angles and dihedrals necessary to generate all XYZ coordinates or a z-matrix. An example is the entry for H_2Si_2 in [26] (this molecule is not in GW100 but it is useful for illustrating this point) which provides the point group (C_{2v}), a 3D shape that is redrawn in Fig. of this paper, and *only* two bond lengths and a dihedral angle: $r_{Si-Si} = (2.2154 \pm 0.0020)\text{\AA}$, $r_{Si-H} = (1.6680 + 0.0030)\text{\AA}$, $\varphi = (104.22 + 0.30)^\circ$ (the original experimental paper from which this data came [41] and the previous paper on the same molecule [40], also provided no additional bond lengths or angles). But to do electronic structure calculations we need either the XYZ coordinates of all atoms, or a z-matrix for the molecule, and there is no software for obtaining either of these from just the limited information given (point group, 3D diagram, two bond lengths and a dihedral angle). A software for generating a z-matrix from this data would be significantly simpler to write than a software for generating XYZ coordinates of all atoms, but the z-matrix for this system would need at least one bond angle, and the reader might find it surprising that the simplest formula for the H-Si-H angle in H_2Si_2 is (in terms of the provided dihedral angle φ , the provided Si-Si bond length r_1 and the provided Si-H bond length r_2):

$$\theta = \arcsin \left(\frac{\sin \left(\frac{\varphi}{2} \right) \sqrt{4r_2^2 - r_1^2}}{r_2} \right). \quad (1)$$

Such a formula is not expected to be found in any compilation of formulas. Determining this formula can be accomplished with some high school level trigonometry (applications of the ordinary cosine law), and applications of the *dihedral cosine law* which is unlikely to be taught in high school or university-level curricula, but can be learned and applied to such small molecules within a day by most researchers; however with the pace of research today, the derivation of such a formula would ideally be done by software rather than by hand. Unfortunately, not even the most advanced symbolic computation or computer algebra software can provide a user with Eq. 1 based on the information given.

Furthermore, the interest today in machine learning and big data analysis has led to the introduction of much larger datasets than GW100, such as GW5000 and OE62 (both from Stuke *et al.* [38]) which involve more than 5000 and 61000 molecules respectively, but the geometries for the molecules in these datasets have issues similar to the ones for the GW100 dataset. This reinforces our motivation for constructing a software that could, for example, convert the thousands of geometries from the Landolt–Börnstein series and related compilations of spectroscopically determined geometry data, into z-matrices or XYZ coordinates.

We believe that as machine learning and big data analysis become more popular over the next century, there will be a rise in interest in being able to categorize molecules (e.g. for training neural networks) and the question of which point groups are possible for molecules of a certain size of formula, will be asked more and more. Anyone seeking the answers to these questions will be able to find them in this paper.

A software to generate z-matrices (or even XYZ coordinates) for molecules with the data presented in experimental papers, such as for H₂Si₂, would require specific code blocks for each molecular shape. It is possible for two molecules with the same point group and formula to have very different shapes (for example see Fig. X, in which two isomers of H₂Si₂ are shown, both with the C_{2v} point group, but one of them being pyramidal and the other one being planar), so a general-purpose “z-matrix constructor” or “XYZ-coordinates constructor” that uses only bond lengths, bond angles and dihedral angles, would need specific code blocks based on their point groups and formulas, in addition to other characteristics. However, a natural first step towards constructing such a software would be to categorize *n*-atom molecules based on their molecular formulas and point groups (the Landolt–Börnstein volumes and related books [23–35], the CCCBDB [42], and the CRC Handbook of Chemistry and Physics are some examples in which point groups are already used to help describe molecules), and then to write the relevant z-matrix-construction or

XYZ-construction code for each case, adding sub-cases when necessary (e.g. to distinguish between the two types of C_{2v} shapes for A₂B₂ molecules as depicted in Fig. X).

For *n* atoms, how many cases do we need to consider in order to cover each point group at least once in the software? That is the essence of the question in the present paper’s title, and as mentioned in the opening paragraph of this Introduction section, it appears that this question has not been answered before, or at least the answer is not easily available. We also go even one step further, by determining all possible *chemical formulas* for a particular point group of an *n*-atom system. For example, in order for a 7-atom molecule to have the point group C_i its formula needs to be A₂B₂C₂D (with any of the variables B, C, or D being allowed to be a duplicate of one of the previous letters) but a 7-atom molecule whose chemical formula does not have that structure cannot have the point group C_i (e.g. for reasons that will be explained in this work, there is no arrangement of the atoms of C₃H₃N such that the point group of the molecule can be C_i).

III. TABLE OF EXAMPLE SHAPES FOR ALL AXIAL POINT GROUP SERIES

IV. GENERAL PRINCIPLES FOR POSSIBLE MOLECULES

The following general principles will be used. They might seem obvious, but we don’t see them in textbooks (maybe the first one is in textbooks) [1–18, 36].

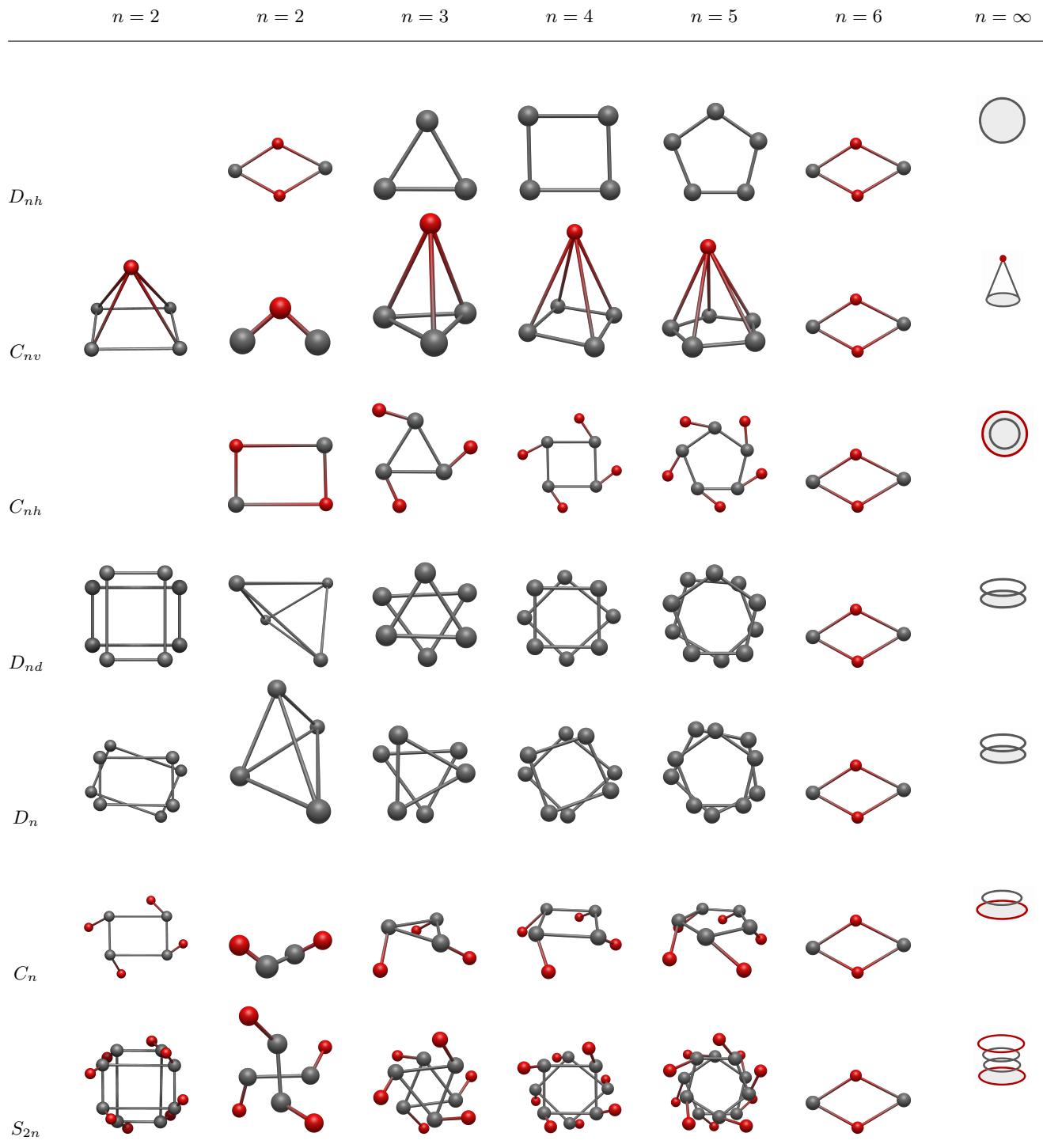
Ability to orient a molecule according to the valid point group operations on the molecule:

Any molecule with a rotation axis, called a C_{*n*}-axis, can be oriented in an xyz (Cartesian) coordinate system such that for the largest possible *n* value in C_{*n*}, the *z*-axis is aligned with a C_{*n*} axis, and a σ_{*h*} plane is a mirror plane coinciding with the *xy*-plane in the coordinate system.

Existence of a C_{*n*} axis:

The existence of a C_{*n*} axis is only possible if the molecule contains a subset of atoms that are vertices of an *n*-sided polygon with equal side-lengths (a regular *n*-gon). A C_{*n*} axis would be in the center of this polygon, and since we can call this axis the *z*-axis, all atoms that form vertices of the polygon, would have to have the same *z*-coordinates. Therefore, a minimum of *n* atoms is needed in order to have a C_{*n*} axis.

If a C_{*n*} axis is the *z*-axis, then after a C_{*n*} rotation, an atom that originally had coordinates (x, y, z), will have coordinates (x', y', z) in which the *z*-coordinate



does not change, because of the definition of a C_n rotation, and the new coordinates (x', y') can be different from the old ones (x, y) but will coincide with the original (x, y) coordinates of another identical atom in the molecule if the axis is indeed a C_n axis.

Necessary and sufficient conditions for the D_{nh} point group:

A regular n -gon with uniform vertices (in a molecule, this would mean the presence of identical

atoms at the vertices) has a point group of D_{nh} , and any object with the D_{nh} point group must contain a subset of identical vertices that form a regular n -gon if with $n \geq 3$.

Action of the S_n operation:

An S_n operation is by definition a C_n operation followed by a σ_h reflection operation. If we define the associated C_n -axis to be the z -axis, and the σ_h plane to be the xy -plane, then if an atom originally had coor-

dinates (x, y, z) , it will have coordinates (x', y', z) after the C_n rotation, and coordinates $(x', y', -z)$ after the σ_h reflection. So S_n operation moves atoms from (x, y, z) to $(x', y', -z)$. As described in the section about the existence of a C_n axis, the new coordinates (x', y') can be different from the old ones (x, y) but will coincide with the original xy -coordinates of another identical atom in the molecule if the molecule indeed has a C_n axis.

Action of the inversion operation, i :

We can always choose center of inversion to be at the origin $(0, 0, 0)$, so if an atom is located at (x, y, z) , the inversion operator will move it to $(-x, -y, -z)$.

V. POSSIBLE NUMBER OF ATOMS AND MOLECULAR FORMULAS FOR EACH POINT GROUP

As usual, we only consider the maximum point group. All in order of number of atoms (except C_i is before others).

C_s

Any two atoms form a line, and if all atoms of a molecule are on the same line, then the point group will be promoted to either $C_{\infty v}$ or $D_{\infty h}$. Likewise, a single atom has the point group K_h , so it is not possible for a molecule with fewer than three atoms to have the point group C_s . Three atoms is enough for the point group of a molecule to be C_s though, as in the example ABC. **The minimum number of atoms required is three, and any formula is allowed.**

C_1

Any three atoms form a plane or a line, and if all atoms of a molecule are on the same plane, then that plane is a reflection/mirror plane. Therefore if a molecule has three or fewer atoms, it will at least have one reflection plane, and would be promoted from C_1 to at least C_s . Four atoms is enough for the point group of a molecule to be C_1 though, as in the example ABCD. **The minimum number of atoms required is four, and any formula is allowed.**

C_i

Any five atoms with an inversion center will lie on the same plane (or same line) and will therefore have a reflection/mirror plane. Since the C_i point group does not have any reflection elements, for any five atom molecule with an inversion center the maximal point group must be larger than C_i .

If we have three or fewer atoms, then there does not even need to be an inversion center for the atoms to be confined to a plane (or line).

If we have four atoms, and we make the inversion center the origin, the atoms must come in pairs according to the inversion operation i that was described

earlier: $A = (x_1, y_1, z_1)$ will be paired with $-A = (-x_1, -y_1, -z_1)$ and $B = (x_2, y_2, z_2)$ will be paired with $-B = (-x_2, -y_2, -z_2)$. Assuming that no two atoms will have the same xyz -coordinates, none of these four atoms can be on the origin. A and $-A$ form a line, and B and $-B$ form another line, and that these two lines both intersect at the origin, and two lines that cross are always co-planar.

If we have five atoms, the fifth one must be at the origin, because atoms need to either be paired or at the origin in order for the inversion operation to be valid on the system of atoms. However, the other four atoms form a plane that contains the origin (because the plane is formed by two lines that intersect at the origin). Therefore the fifth atom will also be on the same plane as the other four atoms, and the point group will be promoted beyond C_i .

Six atoms is enough for a molecule's maximal point group to be C_i , for example $C_2H_2Br_2Cl_2$ with the two carbons removed. **The minimum number of atoms required is six, and the formula must be of the form $A_2B_2C_2D_2 \dots$ or $AB_2C_2D_2 \dots$ depending on if the number of atoms is even or odd.**

C_{nv}

$$\underline{n = 2}$$

If we have any fewer than three atoms, the point group of the system will be promoted to K_h , $D_{\infty h}$ or $C_{\infty v}$, however three atoms is indeed enough for the point group of a molecule to be C_{2v} , as in the case of H_2O . **The minimum number of atoms required is three, and the most general formula is $A_2BCD \dots$ since the extra atoms C, D, \dots can be placed on the C_2 axis without any loss of valid symmetry operations, and without allowing any new valid symmetry operations.**

$$\underline{n \geq 3}$$

Since the point group of a regular n -gon with identical atoms at each vertex is required in order to have the C_n axis that forms part of the point group C_{nv} and we have already mentioned in the previous section that the point group of such a structure would be D_{nh} , we would need at least one additional atom to break any symmetries in D_{nh} that are not present in C_{nv} . It turns out that one additional atom is not only necessary, but also sufficient, since if this atom is placed on a C_n axis that goes through the center of the n -gon, but the atom is not placed on the plane of the n -gon, it will break the horizontal mirror plane and any S_n axes, while maintaining the n vertical mirror planes that are in C_{nv} . The only point group with a C_n axis and n vertical mirror planes, without having any horizontal mirror planes or S_n axes, is C_{nv} , so the pyramid that we have formed must have the point group C_{nv} . **The minimum number of atoms required is $n+1$, and the most general formula is $A_nBCD \dots$**

D_{nh}

$n = 2$

If we have any fewer than three atoms, the point group of the system will be promoted to K_h , $D_{\infty h}$ or $C_{\infty v}$; however all D_{nh} point groups with even values of n (including D_{2h}) have an inversion element i , and the only way for a three atom system to have an inversion element is for it to be linear, which would promote it either to $D_{\infty h}$ or $C_{\infty v}$. If we choose the origin $(0, 0, 0)$ to be the center of inversion, and one atom is at the position (x, y, z) , then an identical atom would need to be at the position $(-x, -y, -z)$ and the third atom would need to be at the origin. We therefore would have two identical atoms on a *line* going through the origin, and a third atom in the center of that line. We therefore would need a minimum of four atoms for the D_{2h} point group, and indeed four atoms is enough as in the case of Br_2Na_2 . **The minimum number of atoms required is four, and the most general formula for the minimal structure is A_2B_2 .**

$n \geq 3$

Since a regular n -gon with identical atoms at each vertex is both necessary and sufficient for the point group of a system of atoms to be D_{nh} for $n \geq 3$, we can conclude the **the minimum number of atoms required is n , and the formula for this minimal structure would be A_n** . An even number of additional atoms can be added along the C_n axis in such a way that no new valid symmetry operations are made possible, and such that none of the existing valid symmetry operations are invalidated, provided that these atoms are added in pairs on each side of the plane formed by the n -gon. One additional atom can also be added at the center of the n -gon. Therefore **the most general formula for a structure with n atoms plus an even number of additional atoms would be $A_nB_2C_2D_2\cdots$, and for an odd number of additional atoms the most general formula would be $A_nBC_2D_2\cdots$** .

C_n

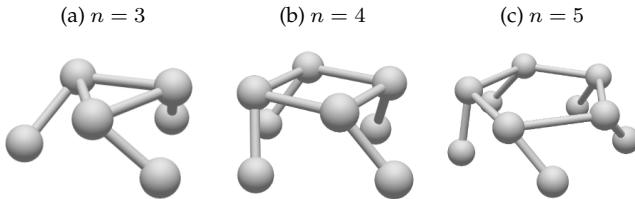
$n = 2$

If we have any fewer than three atoms, the point group of the system will be promoted to K_h , $D_{\infty h}$ or $C_{\infty v}$; and if we have only three atoms, they form a plane which will be a mirror plane, meaning that the point group of the system which contains a C_2 axis will be promoted to C_{2v} or D_{3h} . Four atoms would be enough for the point group of the system to be C_2 though, as in the case of H_2O_2 . **The minimum number of atoms required is four.** In terms of the possible formulas, if we have two atoms at positions A and B , then after rotation around the C_2 axis (which we will make the z -axis, as we described in the previous section), these atoms will be at positions $A' = (-x_1 - y_1, z_1)$ and $B' = (-x_2 - y_2, z_2)$ respectively, and for the C_2 operation to be valid, the atoms that were originally at positions A and A' need to be identical, and likewise for the atoms that were originally at B and B' . **The most general formula is therefore $A_2B_2CD\cdots$ since the extra atoms C,D,\dots can be placed on the C_2 axis without any loss of valid symmetry operations, and if their positions are chosen carefully, no new valid symmetry operations would be introduced.**

$n \geq 3$

Since the point group of a regular n -gon with identical atoms at each vertex is required in order to have a C_n axis, and we have already mentioned in the previous section that the point group of such a structure would be D_{nh} , we would need at least one additional atom to break any symmetries in D_{nh} that are not present in C_n . In order for the C_n operation to remain valid, we can either add any number of atoms (including just one) on the C_n axis, or a full set of n more atoms that form a regular n -gon with the C_n axis going through its center and perpendicular to the plane formed by the n -gon. However, adding any number of atoms to the C_n axis will not break the σ_v planes, so by adding one or more atoms to the C_n axis that goes through the center of a regular n -gon, would form a structure with a C_{nv} point group, so instead of adding any number of atoms to the C_n axis, we must add at least one set of n more atoms forming a regular n -gon (and we know that this one set is enough for us to form a structure in which C_n is the point group, as in Fig. 1). The two parallel n -gons, A_n and B_n , must lie on different planes so that the molecular is not planar, and therefore would not get promoted to C_{nh} . **The minimum number of atoms required is $2n$, and the most general formula would be $A_nB_nCD\cdots$ since in addition to the A_nB_n structure, extra atoms C,D,\dots can be placed on the C_n axis without any loss of valid symmetry operations, and if their positions are chosen carefully, no new valid symmetry operations would be introduced.**

Figure 1: Structures with the point group C_n and with the minimum number of atoms, $2n$.



Not explained well.

$n \geq 3$

We can repeat everything that was written in the section about C_n , except with the second regular n -gon (the one that is added) being rotated by π/n radians (and the two regular n -gons still being on two different planes). Such a structure with $2n$ atoms is possible, as in the case of...

C_{nh}

$n = 2$

d

$n \geq 3$

We can repeat everything that was written in the section about C_n , except that the structure is now allowed for the two regular n -gons to be on the same plane (and therefore concentric since they share the same C_n axis) since having all atoms on the same plane means that the structure lies on a σ_h plane, which is allowed (and needed) for the point group to be C_{nh} . All other elements of the C_{nh} point group can be generated from the C_n and σ_h operations, so the point group of the described structure is indeed C_{nh} . Such a structure with $2n$ atoms is possible, as in the case of...

S_{2n}

$n = 2$

If we have any fewer than three atoms,

$n \geq 3$

Since S_{2n} is a generator of the S_{2n} point group, C_n is in the point group because $S_{2n}^2 = C_n$. This means we need a regular n -gon with the C_n axis cutting perpendicularly through its center, but a regular n -gon will not satisfy the S_{2n} operation unless all atoms are at the origin. You need $2n$ to have an S_{2n} axis, but then you'd get D_{nh} , so you need another $2n$ to break the D_{nh} . **The minimum number of atoms required is $4n$.**

D_n

$n = 2$

Not explained well.

$n \geq 3$

Not explained well.

Point groups Number of atoms

Minimum 1 2 3 4 5 6 7 8

		1	2	3	4	5	6	7	8
K_h	1	✓	✗	✗	✗	✗	✗	✗	✗
$D_{\infty h}$	2	✗	✓	✓	✓	✓	✓	✓	✓
$C_{\infty v}$	2	✗	✓	✓	✓	✓	✓	✓	✓
D_{nh}	$n \geq 3$	n	✗	✗	✓	✓	✓	✓	✓
D_{nh}	$n = 2$	4	✗	✗	✗	✓	✓	✓	✓
D_{nd}	$n \geq 2$	$2n$	✗	✗	✗	✓	✓	✓	✓
D_n	$n \geq 2$	$2n$	✗	✗	✗	✓	✓	✓	✓
S_{2n}	$n \geq 2$	$4n$	✗	✗	✗	✗	✗	✗	✓
C_{nv}	$n \geq 2$	$n + 1$	✗	✗	✓	✓	✓	✓	✓
C_{nh}	$n \geq 2$	$2n$	✗	✗	✗	✓	✓	✓	✓
C_n	$n \geq 2$	$2n$	✗	✗	✗	✓	✓	✓	✓
C_s	3	✗	✗	✓	✓	✓	✓	✓	✓
C_i	6	✗	✗	✗	✗	✗	✓	✓	✓
C_1	4	✗	✗	✗	✓	✓	✓	✓	✓

D_{nd}

$n = 2$

VI. SUMMARY OF OUR RESULTS

N Possible groups (not including subgroups)

1								K_h
2								
3	C_s		C_{2v}			D_{3h}		$D_{\infty h} C_{\infty v}$
4	C_s	$C_1 C_2$	C_{2h}	$C_{2v} C_{3v}$	D_2	D_{2d}	$D_{2h} D_{3h} D_{4h}$	T_d
5	C_s	$C_1 C_2$	C_{2h}	$C_{2v} C_{3v} C_{4v}$	D_2	D_{2d}	$D_{2h} D_{3h} D_{4h} D_{5h}$	$D_{\infty h} C_{\infty v}$
6	C_s	$C_1 C_2 C_3$	$C_{2h} C_{3h}$	$C_{2v} C_{3v} C_{4v} C_{5v}$	D_2	D_3	$D_{2d} D_{3d} D_{2h} D_{3h} D_{4h} D_{5h} D_{6h}$	$O_h D_{\infty h} C_{\infty v}$
7	C_s	$C_1 C_2 C_3$	$C_{2h} C_{3h}$	$C_{2v} C_{3v} C_{4v} C_{5v} C_{6v}$	D_2	D_3	$D_{2d} D_{3d} D_{2h} D_{3h} D_{4h} D_{5h} D_{6h} D_{7h}$	$O_h D_{\infty h} C_{\infty v}$
8	C_s	$C_1 C_2 C_3 C_4$	$C_{2h} C_{3h} C_{4h} C_{2v} C_{3v} C_{4v} C_{5v} C_{6v} C_{7v} S_4$		D_2	D_3	$D_{2d} D_{3d} D_{2h} D_{3h} D_{4h} D_{5h} D_{6h} D_{7h} T_d$	$O_h D_{\infty h} C_{\infty v}$

A. Possible point groups for 3-atom (triatomic) molecules

Point group	Chemical formula type		
	A_3	A_2B	ABC
$D_{\infty h}$	C_3	CO_2	\times
$C_{\infty v}$		N_2O	HOS
D_{3h}	H_3^+	\times	\times
C_{2v}	O_3	H_2O	\times
C_s	$H \cdots H_2$	HO_2	HNO

B. Possible point groups for 4-atom (tetraatomic) molecules

VII. OUTLOOK

Apart from finding molecules to fill in the tables, z-matrix generator in OpenMolcas.

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Group	A ₄	A ₃ B	A ₂ B ₂	A ₂ BC	ABCD
T_d					
$D_{\infty h}$					
$C_{\infty v}$	Unlikely				
D_{4h}					
D_{3h}					
D_{2h}					
D_{2d}					
D_2					
C_{3v}					
C_{2v}					
C_{2h}					
C_2					
C_s					
C_1					

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