Construction and Verification of Software

2019 - 2020

MIEI - Integrated Master in Computer Science and Informatics

Consolidation block

Lecture 7 - Arrays in Separation Logic
João Costa Seco (joao.seco@fct.unl.pt)
based on previous editions by Luís Caires (lcaires@fct.unl.pt)



Outline

- Recap on Separation Logic
- Arrays in Separation Logic
- Basic Algorithms
- The Bag ADT
- Properties of elements in arrays (Bank)

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Lecture 7 - Part I - Recap of Separation Logic

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Separation Logic (recap)

Separation logic assertions used in our CVS course are described by the following grammar:

$$A ::=$$
 Separation Logic Assertions
$$L \mapsto V \qquad \text{Memory Access}$$

$$\mid A * A \qquad \text{Separating Conjunction}$$

$$\mid \text{emp} \qquad \text{Empty heap}$$

$$\mid B \qquad \text{Boolean condition (pure, not spatial)}$$

$$\mid B?A : A \qquad \text{Conditional}$$

$$B ::= B \wedge B \mid B \vee B \mid V = V \mid V \neq V \mid ...$$
 $V ::= ...$ Pure Expressions
 $L ::= x.\ell$ Object field

Separation Logic (recap)

The assignment rule in separation logic is

$$\{x \mapsto V\} \ x := E \ \{x \mapsto E\}$$

 it follows the small footprint principle, the precondition refers exactly to the part of the memory used by the fragment!

Separation Logic (recap)

The assignment rule in separation logic is

$$\{x.\ell \mapsto V\} \ x.\ell := E \ \{x.\ell \mapsto E\}$$

- it follows the small footprint principle, the precondition refers exactly to the part of the memory used by the fragment!
- The memory locations here are fields of objects. We also have to model dynamically allocated arrays.

Example of Separation Logic in Verifast

```
/*@
  predicate Node(Node t; Node n, int v) = t.nxt |-> n &*& t.val |-> v;
  predicate List(Node n;) = n == null ? emp : Node(n, ?nn, _) &*& List(nn);
                                                                    public static void main(String args[])
  predicate StackInv(Stack t;) = t.head |-> ?h &*& List(h);
                                                                    //@ requires true;
@*/
                                                                    //@ ensures true;
class Stack {
                                                                      Stack s = new Stack();
  private Node head;
                                                                      s.push(0);
                                                                      s.pop();
  public Stack()
                                                                      if(! s.isEmpty()) {
  //@ requires true;
                                                                        //@ open NonEmptyStackInv(_);
  //@ ensures StackInv(this);
                                                                        s.push(1);
  { head = null; }
                                                                        s.pop();
  public int pop()
  //@ requires NonEmptyStackInv(this);
  //@ ensures StackInv(this);
      int val = head.getValue(); head = head.getNext(); return val; }
  public boolean isEmpty()
  //@ requires StackInv(this);
  //@ ensures result?StackInv(this):NonEmptyStackInv(this);
  { return head == null; }
```

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Lecture 7 - Part II - Arrays in Separation Logic

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 Arrays are dynamically allocated regions that need to be explicitly described by specially designed predicates.

```
public static int sum(int[] a)
//@ requires ???
//@ ensures ???
  int total = 0; int i = 0;
  while(i < a.length)</pre>
    //@ invariant ???
    int tmp = a[i]; total = total + tmp;
    i++;
  return total;
```

 The access to an array in verifast is disciplined by predicates that describe segments of, one position:

```
array_element(a, index, v);
```

to denote that the value (v) is stored in position (index) of the array value (a).

or more than one position:

```
array_slice(a, 0, n, vs);
```

to denote the access to the positions of array (a) from (0) to (n) with values given by the list (vs).

Properties about the elements of the array:

```
array_slice_deep(a, i, j, P, unit, vs, unit);
to denote that predicate (P) is valid for all values (vs)
stored in the array (a) in the positions from (i) to (j).
```

Where the predicate has the signature:

```
predicate P<A,T,S>(A a, T v; S n);
```

Properties about the elements of the array:

```
array_slice_deep(a, i, j, P, unit, vs, unit);
to denote that predicate (P) is valid for all values (vs)
stored in the array (a) in the positions from (i) to (j).
```

Where the predicate has the signature:

```
predicate P<A,T,S>(A a, T v; S n);
```

```
predicate Positive(unit a, int v; unit n) = v >= 0 &*& n == unit;
array_slice_deep(s,0,n,Positive,unit,elems,_)
```

fixpoint int sum(list<int> vs) {

```
switch(vs) {
    case nil: return 0;
    case cons(h, t): return h + sum(t);
}
public static int sum(int[] a)
//@ requires array_slice(a, 0, a.length, ?vs);
//@ ensures array_slice(a, 0, a.length, vs) &*& result == sum(vs);
  int total = 0; int i = 0;
  while(i < a.length)</pre>
    //@ invariant 0 <= i &*& i <= a.length &*& array_slice(a, 0, a.length, vs)</pre>
        &*& total == sum(take(i, vs));
    int tmp = a[i]; total = total + tmp;
    //@ length_drop(i, vs);
    //@ take_one_more(vs, i);
    i++;
  return total;
```

 With auxiliary functions and definitions that define properties over the values of arrays.

```
Notice that (a) is a parameter
of the function and not an L-
value. It does not need a
spatial assertion.
```

```
lemma void take_one_more<t>(list<t> vs, int i)
 requires 0 <= i && i < length(vs);
 ensures append(take(i, vs), cons(head(drop(i, vs)), nil)) == take(i + 1, vs);
 switch(vs) {
   case nil:
                                          And auxiliary lemmas that
   case cons(h, t):
     if(i == 0)
                                          can be applied in the
     } else {
                                          course of the proof.
       take_one_more(t, i - 1);
 }
lemma_auto(sum(append(xs, ys))) void sum_append(list<int> xs, list<int> ys)
 requires true;
 ensures sum(append(xs, ys)) == sum(xs) + sum(ys);
 switch(xs) {
   case nil:
   case cons(h, t): sum_append(t, ys);
```

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Lecture 7 - Part III - Managing Arrays in objects

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Verifast Example

 Consider a Bag of integers ADT based on an array with limited capacity.

```
public class Bag {
    int store[];
    int nelems;
    int get(int i) {...}
    int size() {...}
    boolean add(int v) {...}
}
```

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- Fields must be considered in separate heap chunks, pure conditions can be added to assertions and predicates.
- Array access is disciplined by the predicate array_slice

```
int get(int i)
  //@ requires this.store |-> ?s &*& array_slice(s,0,?n,_) &*& 0 <= i &*& i < n;
  //@ ensures ...;
{
  return store[i];
}</pre>
```

 The representation invariant captures the legal states of the ADT, including the access to the array.

```
public class Bag {
    int store[];
    int nelems;
    /*@
      predicate BagInv(int n) =
          store |-> ?s
      &*& nelems |-> n
      &*& s != null
      &*& 0<=n &*& n <= s.length
      &*& array_slice(s,0,n,?elems)
      &*& array_slice(s,n,s.length,?others)
    @*/
```

• So...

```
int get(int i)
  //@ requires BagInv(?n) &*& 0 <= i &*& i < n;
  //@ ensures BagInv(n);
{
  return store[i];
}</pre>
```

For all methods and fields...

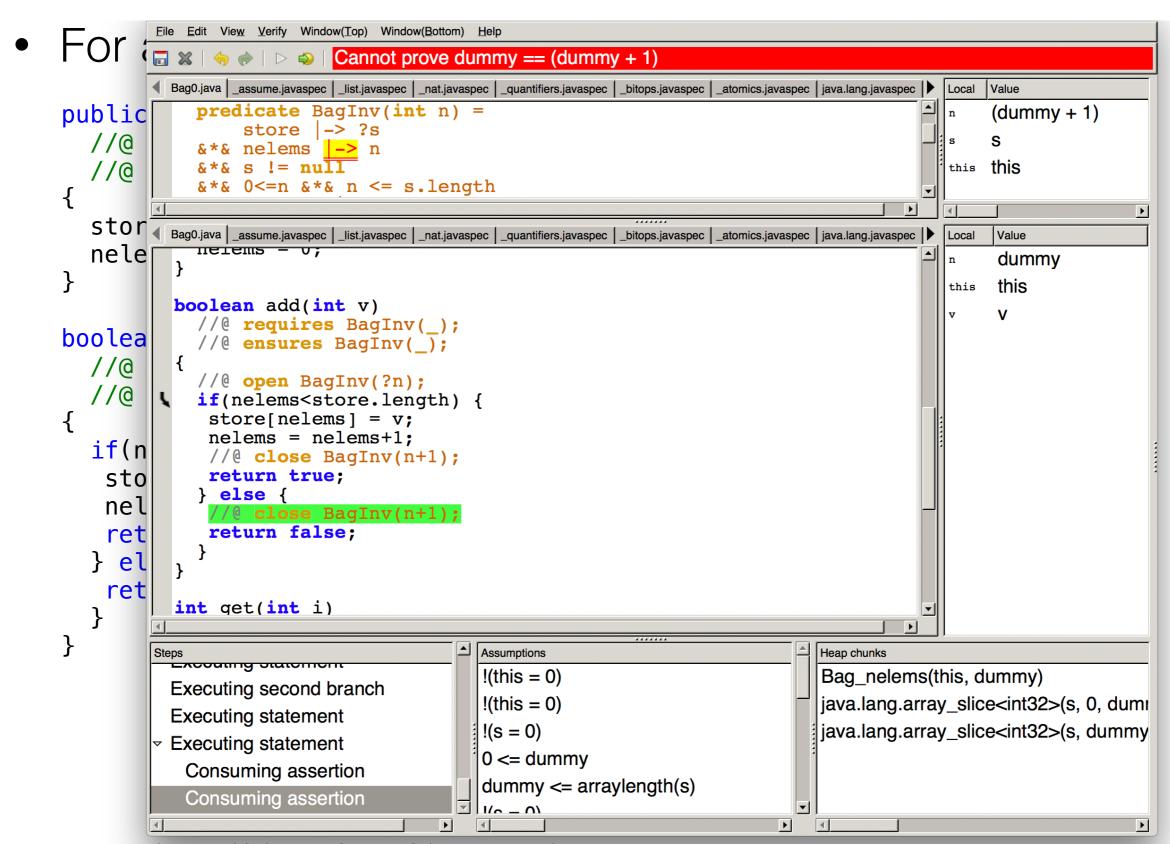
```
int get(int i)
  //@ requires BagInv(?n) &*& 0 <= i &*& i < n;
  //@ ensures BagInv(n);
{
  return store[i];
}
int size()
  //@ requires this.nelems |-> ?n &*& n >= 0;
  //@ ensures result>=0;
{
  return nelems;
}
```

For all methods and fields...

```
public Bag(int size)
 //@ requires size >= 0;
  //@ ensures BagInv(0);
  store = new int[size];
  nelems = 0;
boolean add(int v)
  //@ requires BagInv(_);
  //@ ensures BagInv(_);
  if(nelems<store.length) {</pre>
   store[nelems] = v;
   nelems = nelems+1;
   return true;
  } else {
   return false;
```

For all methods and fields...

```
public Bag(int size)
 //@ requires size >= 0;
  //@ ensures BagInv(0);
  store = new int[size];
  nelems = 0;
boolean add(int v)
  //@ requires BagInv(?n);
 //@ ensures BagInv(n+1); // Does not hold, why?
  if(nelems<store.length) {</pre>
   store[nelems] = v;
   nelems = nelems+1;
   return true;
  } else {
   return false;
```



 The parameters for the representation invariant predicate are specification level and define an abstract state.

```
boolean add(int v)
  //@ requires BagInv(?m);
  //@ ensures result ? BagInv(m+1) : BagInv(m);
{
    //@ open BagInv(?n);
    if(nelems<store.length) {
        store[nelems] = v;
        nelems = nelems+1;
        //@ close BagInv(n+1);
        return true;
    } else {
        //@ close BagInv(n);
        return false;
    }
}</pre>
```

 The access to an array in verifast is disciplined by predicates that describe segments of the array:

```
array_element(a, index, v);
array_slice(a, 0, n, vs);
array_slice_deep(a, i, j, P, unit, vs, unit);
```

 The values of the array are accessed through specification level list values and related operations

```
drop( n, vs )
take( n, vs )
append( vs, vs')
```

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Lecture 7 - Part IV - An example of an ADT (Bank)

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- Properties of values stored in arrays can also be captured by the array predicates.
- Examples:
 - Bag of positive integers
 - Array of ADT objects (with representation invariants)

```
/*@
predicate AccountInv(Account a;int b) = a.balance |-> b &*& b >= 0;
@*/
public class Account {
    int balance;
    public Account()
    //@ requires true;
    //@ ensures AccountInv(this,0);
      balance = 0;
```

The bank holds an array of accounts...

```
public class Bank {
    Account store[];
    int nelems;
    int capacity;
    Bank(int max)
        nelems = 0;
        capacity = max;
        store = new Account[max];
```

And implements a couple of operations...

```
public class Bank {
    Account store[];
    int nelems;
    int capacity;
    Account retrieveAccount()
        Account c = store[nelems-1];
        store[nelems-1] = null;
        nelems = nelems-1;
        return c;
```

And implements a couple of operations...

```
public class Bank {
    Account store[];
    int nelems;
    int capacity;
    void addnewAccount()
        Account c = new Account();
        store[nelems] = c;
        nelems = nelems + 1;
```

```
/*@
predicate AccountP(unit a, Account c; unit b) = AccountInv(c,?n) &*& b == unit;
@*/
public class Bank {
/*@
predicate BankInv(int n, int m) =
     this nelems |-> n
     &*& this capacity |-> m
     \& *\& m > 0
     &*& this.store |-> ?accounts
     &*& accounts.length == m
     &*& 0 <= n &*& n<=m
     &*& array_slice_deep(accounts, 0, n, AccountP, unit, _, _)
     &*& array_slice(accounts, n, m,?rest) &*& all_eq(rest, null) == true;
@*/
```

array slice assertions

The predicate declared in file java.lang.javaspec by

```
predicate array_slice<T>(T[] array, int start, int end; list<T> elements);
represents the footprint of the array fragment
    array[start .. end-1]
```

- elements is the list of array "values" v_i such that a[i] | -> v_i
- elements is an immutable pure value (like a OCaml list)
- array_slice(array, start, end, elements)
 is equivalent to the assertion
 - V = [Vstart, Vend-1]
 - a[start] |-> v_{start}
 &*& a[start+1] |-> v_{start+1} &*& ... &*& a[end-1] |-> v_{end-1}

array slice assertions

The predicate declared in file java.lang.javaspec by

```
predicate array_slice_deep<T, A, V>(
    T[] array,
    int start,
    int end,
    predicate(A, T; V) p,
    A info;
    list<T> elements,
    list<V> values);
```

is as in the (simple) $array_slice$ where elements is the list of array values v_i such that $a[i] \mid l-> v_i$, and the predicate $p(a,v_i;o_i)$ holds for each v_i and values is the list of all values o_i

```
public class Bank {
    Account store[];
    int nelems;
    int capacity;
    Bank(int max)
    //@ requires max>0;
    //@ ensures BankInv(0,max);
      nelems = 0;
      capacity = max;
      store = new Account[max];
```

```
public class Bank {
    Account store[];
    int nelems;
    int capacity;
    Account retrieveLastAccount()
    //@ requires BankInv(?n,?m) &*& n>0;
    //@ ensures BankInv(n-1,m) &*& AccountInv(result,_);
        Account c = store[nelems-1];
        nelems = nelems-1;
        return c;
        // The post-condition does not hold, Why?
    }
```

```
public class Bank {
    Account store[];
    int nelems;
    int capacity;
    Account retrieveLastAccount()
    //@ requires BankInv(?n,?m) &*& n>0;
    //@ ensures BankInv(n-1,m) &*& AccountInv(result,_);
        Account c = store[nelems-1];
        store[nelems-1] = null;
        nelems = nelems-1;
        return c;
```

```
public class Bank {
    Account store[];
    int nelems;
    int capacity;
    void addnewAccount()
    //@ requires BankInv(?n,?m) &*& n < m;</pre>
    //@ ensures BankInv(n+1,m);
        Account c = new Account();
        store[nelems] = c;
        //@ array_slice_deep_close(store, n, AccountP, unit);
        nelems = nelems + 1;
```

array slice "lemmas"

```
lemma void array_slice_deep_close<T, A, V>(
    T[] array, int start, predicate(A, T; V) p, A a);
requires array_slice<T>(array,start,start+1,?elems) &*& p(a, head(elems), ?v);
ensures array_slice_deep<T,A,V>(array, start, start+1, p, a, elems, cons(v,nil));
```

- transforms the spec of an array element in a (singleton)
 array_slice spec into a (singleton) array_slice_deep
- there are other lemmas, that join together slices
- verifast is usually able to apply lemmas automatically, but not always, in that case the programmer needs to "help", by calling the needed lemmas.

array slice "lemmas"

```
lemma void array_slice_split<T>(T[] array, int start, int start1);
requires
    array_slice<T>(array, start, ?end, ?elems) &*&
    start <= start1 &*& start1 <= end;
ensures
    array_slice<T>(array, start, start1, take(start1 - start, elems)) &*&
    array_slice<T>(array, start1, end, drop(start1 - start, elems)) &*&
    elems == append(take(start1 - start, elems), drop(start1 - start, elems))
```

 this "lemma" splits one array slice assertion into two (sub) array slice assertions.

array slice "lemmas"

```
lemma void array_slice_join<T>(T[] array, int start);
requires
    array_slice<T>(array, start, ?start1, ?elems1) &*&
    array_slice<T>(array, start1, ?end, ?elems2);
ensures
    array_slice<T>(array, start1, end, append(elems1, elems2));
```

 this "lemma" joins two array slice assertions into a single array slice assertion.

arrav slice "lemmas"

```
package java.lang;
import java.util.*;
/*@
inductive unit = unit;
inductive pair<a, b> = pair(a, b);
fixpoint a fst<a, b>(pair<a, b> p) {
    switch (p) {
       case pair(x, y): return x;
}
fixpoint b snd<a, b>(pair<a, b> p) {
   switch (p) {
       case pair(x, y): return y;
}
fixpoint t default value<t>();
inductive boxed int = boxed int(int);
fixpoint int unboxed int(boxed int i) { switch (i) { case boxed int(value): return value; } }
inductive boxed bool = boxed bool(boolean);
fixpoint boolean unboxed bool(boxed bool b) { switch (b) { case boxed bool(value): return value; } }
predicate array element<T>(T[] array, int index; T value);
predicate array slice<T>(T[] array, int start, int end; list<T> elements);
predicate array_slice_deep<T, A, V>(T[] array, int start, int end, predicate(A, T; V) p, A info; list<T> elements
lemma auto void array element inv<T>();
   requires [?f]array element<T>(?array, ?index, ?value);
   ensures [f]array element<T>(array, index, value) &*& array != null &*& 0 <= index &*& index < array.length;
```