Gaussian Process Regression

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Let
$$y(x) = f(x) + \epsilon$$
 with $\epsilon \sim \mathcal{N}(0, \sigma_n^2)$.

Then $\mathbf{cov}(y(x_p), y(x_q)) = K(x_p, x_q) + \sigma_n^2 \delta_{pq}$ or in a matrix form

$$\mathbf{cov}(\mathbf{y}) = K(X, X) + \sigma_n^2 \mathbb{I}$$

The joint distribution between y and f_* is

$$\begin{bmatrix} \mathbf{y} \\ f_* \end{bmatrix} \sim \mathcal{N} \left(0, \begin{pmatrix} K(X,X) + \sigma_n^2 \mathbb{I} & K(X,X_*) \\ K(X_*,X) & K(X_*,X_*) \end{pmatrix} \right)$$

By conditioning, we get

$$f_*|X, \mathbf{y}, X_* \sim \mathcal{N}(\bar{f}_*, \operatorname{cov}(f_*)),$$

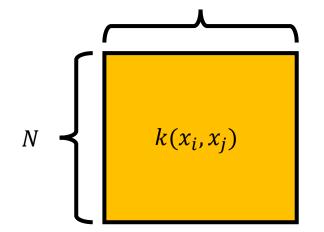
$$\bar{f}_* = K(X_*, X) \left(K(X, X) + \sigma_n^2 \mathbb{I} \right)^{-1} \mathbf{y}$$

$$\mathbf{cov}(f_*) = K(X_*, X_*) - K(X_*, X) \left(K(X, X) + \sigma_n^2 \mathbb{I} \right)^{-1} K(X, X_*)$$

- Prediction
 - $f_* = K(x_*, X)(K(X, X) + \sigma_n I)^{-1}Y$
 - $cov(f_*) = K(x_*, x_*) K(x_*, X)K(X, X)^{-1}K(X, x_*)$
 - X: Input Data Y: Output Data
- Kernel Matrix

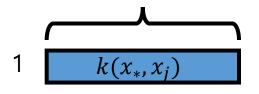
$$K(X,X) = [k(x_i,x_j)] K(x_*,X) = [k(x_*,x_j)]$$

The number of data: N



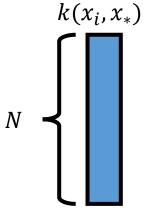
$$K(x_*, X) = [k(x_*, x_j)]$$

$$N$$



$$k(x_i, x_j) = \beta \exp(-0.5\lambda^{-1}(x_i - x_j)^2)$$

$$K(X, x_*) = [k(x_i, x_*)]$$



$$K(x_*, X) = K(X, x_*)^t$$

- Prediction
 - $f_* = K(x_*, X)(K(X, X) + \sigma_n I)^{-1}Y$
 - $cov(f_*) = K(x_*, x_*) K(x_*, X)(K(X, X) + \sigma_n I)^{-1}K(X, x_*)$

$$K(x_p, x_q) = \sigma_f^2 \exp\left(-\frac{1}{2\sigma_I^2} ||x_p - x_q||^2\right)$$

$$f_{*}$$

$$k(x_{*},X)$$

$$K(X,X)$$

$$K(X,X)$$

$$K(X,X)$$

$$K(X,X)$$

$$K(X,X)$$

- Recall: How to compute Kernel matrix!?
 - First, compute distance matrix
 - Second, compute kernel matrix using distance matrix

•
$$K(X,X) = \sigma_f^2 \exp\left(-\frac{D(X,X)}{2\sigma_I^2}\right)$$

 $X \qquad X^{2} \qquad -2XX^{t} \qquad (X^{2})^{t} \qquad D(X,X)$ $x_{i}^{2} \qquad -2x_{j}x_{i} \qquad (x_{j}-x_{i})^{2}$

 $K(x_p, x_q) = \sigma_f^2 \exp\left(-\frac{1}{2\sigma_f^2} ||x_p - x_q||^2\right)$

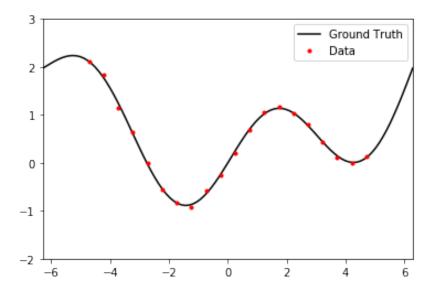
Data Generation

```
def f3(x):
    return np.sin(x) + 0.05*x**2

x = np.linspace(-2*np.pi,2*np.pi,100)
y = f3(x)

n = 20
x_data = np.linspace(-1.5*np.pi,1.5*np.pi,n)
y_data = f3(x_data) + 0.05*np.random.randn(n)

plt.plot(x,y,"k-",label="Ground Truth")
plt.plot(x_data,y_data,"r.",label="Data")
plt.legend()
plt.xlim([-2*np.pi,2*np.pi])
plt.ylim([-2,3])
plt.show()
```



- 1-D Non-linear regression problem
- Goal
 - Construct kernel matrix in tensorflow graph
 - Run Gaussian process regression

- Step 1
 - Define placeholder
 - x_star_ph : test point (unseen point)
- Step 2
 - Compute K(X,X) and $K(x_*,X)$
 - Hint : see last exercise

Define GPR

$$X^2 - 2XX^t + X^2$$

```
x_norm =
x_norm =
x_norm =
x_norm =
squared_dist_XX =
K_XX =

x_star_norm =
x_star_norm =
x_star_norm =
squared_dist_XstarX =
K_XstarX =

mean_y =

y_pred = tf.matmul(K_XstarX,tf.matmul(tf.linalg.inv(K_XX + sigma_ph*tf.identity(K_XX)),y_ph))
std_pred = tf.sqrt(beta-tf.diag_part(tf.matmul(K_XstarX,tf.matmul(tf.linalg.inv(K_XX + sigma_ph*tf.identity(K_XX)),tf.transpose(K_XstarX)))))
```

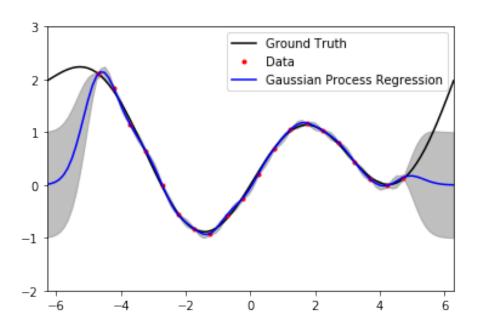
Define kernel parameter and placeholder

```
tf.reset_default_graph()
inv_lambda = 4e0
beta = 1e0
sigma = 1e-4

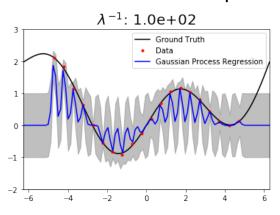
x_ph = tf.placeholder(tf.float32, shape=(None,1))
y_ph = tf.placeholder(tf.float32, shape=(None,1))
x_star_ph = tf.placeholder(tf.float32, shape=(None,1))
inv_lambda_ph = tf.placeholder(tf.float32, shape=())
beta_ph = tf.placeholder(tf.float32, shape=())
sigma_ph = tf.placeholder(tf.float32, shape=())
```

No need to optimize, run GPR!!

GPR

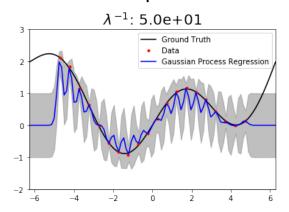


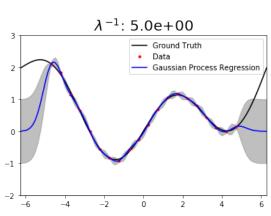
- Set various λ^{-1}
 - What is the best parameter? How to optimize it?



 λ^{-1} : 1.0e+01

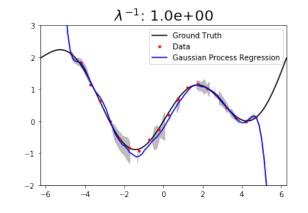
Gaussian Process Regression





Effect of Scale Parameter λ^{-1}

```
inv_lambda1 =
inv_lambda2 =
inv_lambda3 =
inv_lambda4 = 5e0
inv_lambda5 = |
```



Maximum marginal likelihood

Since $\mathbf{y} \sim \mathcal{N}(0, K + \sigma_n^2 \mathbb{I})$, the log marginal likelihood is

$$\log P(\mathbf{y}|X) = -\frac{1}{2}\mathbf{y}^T(K + \sigma_n^2 \mathbb{I})^{-1}\mathbf{y} - \frac{1}{2}\log|K + \sigma_n^2 \mathbb{I}| - \frac{n}{2}\log 2\pi,$$

which can be used to estimate σ_n^2 and parameters for the kernel function (using a gradient based method).

For example, if the following squared exponential kernel is used, the kernel parameters are (σ_f^2, σ_l^2) .

$$K(x_p, x_q) = \sigma_f^2 \exp\left(-\frac{1}{2\sigma_l^2} ||x_p - x_q||^2\right)$$

In practice, selecting the right kernel for a given problem is also an important task.

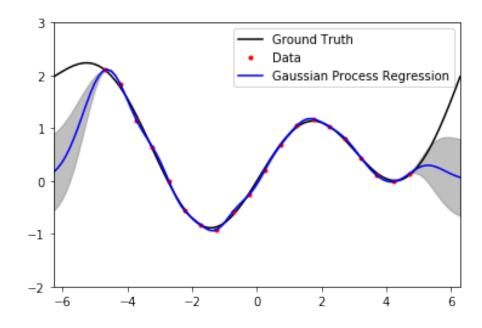
We can optimize the hyperparameter using sklearn package

```
from sklearn.gaussian_process import GaussianProcessRegressor
from sklearn.gaussian_process.kernels import RBF, ConstantKernel as C

kernel = C(1.0, (1e-3, 1e3)) * RBF(10, (1e-2, 1e2))
gp = GaussianProcessRegressor(kernel=kernel, n_restarts_optimizer=9)
gp.fit(x_data[:,np.newaxis], y_data[:,np.newaxis])

y_pred_sk, std_pred_sk = gp.predict(x[:,np.newaxis]), return_std=True)

plt.plot(x,y,"k-",label="Ground Truth")
plt.plot(x_data,y_data,"r.",label="Data")
plt.plot(x,y_pred_sk,"b-",label="Gaussian Process Regression")
plt.fill_between(x, y_pred_sk.flatten()-std_pred_sk, y_pred_sk.flatten()+std_pred_sk, color='grey', alpha='0.5')
plt.legend()
plt.xlim([-2*np.pi,2*np.pi])
plt.ylim([-2,3])
plt.show()
```



- To do
 - Define an arbitrary function
 - Generate noisy data
 - Defin GPR using sklearn packages
 - Fit hyperparameter
 - Plot the perdiction

Program your own example!

```
# Generate data

# Define gpr kernel

# Fit kernel hyperparameter

# Prediction and draw!
```