Some Useful Concepts from Information Theory COMP9418 — Advanced Topics in Statistical Machine Learning

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Acknowledgments

- [Cover & Thomas, EoIT, 2012] Elements of Information Theory. Thomas M. Cover and Joy A. Thomas. John Wiley & Sons, 2012.
- [Mackay, ITILA, 2003] Information Theory, Inference, and Learning Algorithms. David J. C. Mackay. Cambridge University Press. 2003.
- [Bishop, PRML, 2006] Pattern Recognition and Machine Learning, Christopher Bishop, 2006
- [Murphy, MLaPP, 2012] Machine Learning: A Probabilistic Perspective, Kevin P. Murphy, 2012

- Information Content & Entropy
 - Entropy of a Random Variable
 - Some Useful Properties
 - Examples
 - Maximum Entropy
- 2 Joint Entropy and Conditional Entropy
- 3 Relative Entropy (KL Divergence) and Mutual Information
- 4 Jensen's Inequality

Information Content

Information as:

- Amount of unexpected data
- message that its uncertain to receivers
 - ▶ If we are told that a very likely event has happened vs an unlikely event

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Entropy (or information content) of an outcome x:

$$h(x) = \log_2 \frac{1}{p(x)}$$

- Choice of logarithm basis is arbitrary
- If we use log₂ we measure information in bits

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• The expectation of the entropy of each outcome wrt p(x)

We call this the entropy of the r.v. X (Note dependency on distribution)

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Note that we can write:

$$H(X) = -\sum_{x} p(x) \log_2 p(x)$$

and define: $0 \log 0 \equiv 0$, as $\lim_{p\to 0} p \log p = 0$.

Some Useful Properties

Non-negativity:

$$0 \le p(x) \le 1 \to \log \frac{1}{p(x)} \ge 0$$
$$\sum_{x} p(x) \log \frac{1}{p(x)} \ge 0$$
$$H(X) \ge 0$$

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• Change of base:

$$H_b(X) = -\sum_{x} p(x) \log_b p(x)$$
$$= \sum_{x} p(x) \log_a p(x) \log_b a$$
$$H_b(X) = \log_b a H_a(X)$$

If we use natural logarithm the units are call nats

Let
$$X \in \{0,1\}$$
 with $X \sim \text{Bern}(X|\theta)$ and $\theta = p(X=1)$:

$$H(X) = -\theta \log \theta - (1 - \theta) \log (1 - \theta)$$

$$0.6$$

$$x^{\text{S}}$$

$$0.4$$

$$0.2$$

$$0.5$$

$$\theta = p(X=1)$$

Example 1 — Bernoulli Distribution

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• Concave function of the distribution

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- Concave function of the distribution
- Minimum when there is no uncertainty $\theta=1$ or $\theta=0$
- ullet Maximum when there is maximum uncertainty heta=0.5
- For $\theta = 0.5$ (e.g. a fair coin) $H_2(X) = 1$ bit.

Example 2

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The entropy of this rv is given by:

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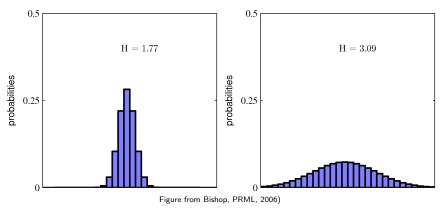
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- This agrees with the number of bits needed to describe X
- In this case all the outcomes have representations of the same length

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Categorical distributions with 30 different states:



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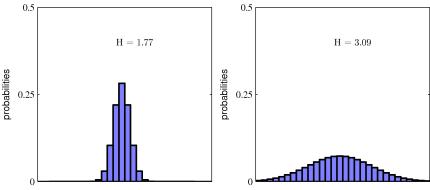


Figure from Bishop, PRML, 2006)

• The more sharply peaked the lower the entropy

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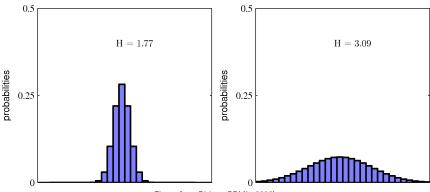


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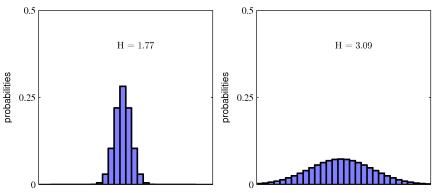


Figure from Bishop, PRML, 2006)

- The more sharply peaked the lower the entropy
- The more evenly spread the higher the entropy
- Maximum for *uniform* distribution: $H(X) = -\log \frac{1}{30} \approx 3.40$ nats

When will the entropy be minimum?

Maximum Entropy

Consider a discrete variable X taking on values from the set $\mathcal X$

• Let p_i be the probability of each state, with $i=1,\ldots,|\mathcal{X}|$

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The entropy is maximized if \mathbf{p} is uniform:

$$H(X) \leq \log |\mathcal{X}|$$

With equality iff $p_i = \frac{1}{|\mathcal{X}|}$ for all i

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Joint Entropy

The joint entropy H(X, Y) of a pair of discrete random variables with joint distribution p(X, Y) is given by:

$$H(X, Y) = \sum_{x \in \mathcal{X}} \sum_{y \in \mathcal{Y}} p(x, y) \log \frac{1}{p(x, y)}$$
$$= \mathbb{E}_{X, Y} \left[\log \frac{1}{p(X, Y)} \right]$$

Conditional Entropy

The conditional entropy of Y given X = x is the entropy of the probability distribution p(Y|X = x):

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The conditional entropy of Y given X, is the average over X of the conditional entropy of Y given X = x:

$$H(Y|X) = \sum_{x \in \mathcal{X}} p(x)H(Y|X = x)$$
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This measures the average uncertainty that remains about Y when X is known.

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Relative Entropy

Introduction

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 - ▶ q(X): Would need H(p) + D(p||q) bits on average to describe the r.v.

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- D(p||q): Distance/divergence between two distributions
- Machine Learning: Approximating a posterior p(X) with q(X)
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 - ▶ p(X): Can construct a code with average description length H(p)
 - q(X): Would need H(p) + D(p||q) bits on average to describe the r.v.

A measure of divergence between two distributions is the *relative entropy* or *Kullback-Leibler divergence*

Definition

The relative entropy or Kullback-Leibler (KL) divergence between two probability distributions p(X) and q(X) is defined as:

$$\mathsf{KL}(p\|q) = \sum_{x \in \mathcal{X}} p(x) \log \frac{p(x)}{q(x)} = \mathbb{E}_{p(X)} \left[\log \frac{p(X)}{q(X)} \right].$$

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- Note:
 - ▶ Both p(X) and q(X) are defined over the same alphabet X
 - KL in statistics
- Conventions:

$$0\log\frac{0}{0}\stackrel{\text{def}}{=}0$$
 $0\log\frac{0}{q}\stackrel{\text{def}}{=}0$ $p\log\frac{p}{0}\stackrel{\text{def}}{=}\infty$

Relative Entropy Properties

•
$$KL(p||q) \geq 0$$

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Properties

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- $\mathsf{KL}(p||q) = 0 \Leftrightarrow p = q$
- $KL(p||q) \neq KL(q||p)$
- Not a true distance since is not symmetric and does not satisfy the triangle inequality
- Very important in machine learning and information theory

Example (from Cover & Thomas, 2006)

Let $X \in \{0,1\}$ and consider the distributions p(X) and q(X) such that:

$$p(X = 1) = \theta_p$$
 $p(X = 0) = 1 - \theta_p$
 $q(X = 1) = \theta_q$ $q(X = 0) = 1 - \theta_q$

What distributions are these?

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What distributions are these?

Compute $\mathsf{KL}(p\|q)$ and $\mathsf{KL}(q\|p)$ with $\theta_p = \frac{1}{2}$ and $\theta_q = \frac{1}{4}$

$$\mathsf{KL}(p\|q) = heta_p \log rac{ heta_p}{ heta_q} + (1- heta_p) \log rac{1- heta_p}{1- heta_q}$$

$$\begin{aligned} \mathsf{KL}(p\|q) &= \theta_p \log \frac{\theta_p}{\theta_q} + (1 - \theta_p) \log \frac{1 - \theta_p}{1 - \theta_q} \\ &= \frac{1}{2} \log \frac{\frac{1}{2}}{\frac{1}{4}} + \frac{1}{2} \log \frac{\frac{1}{2}}{\frac{3}{4}} = 1 - \frac{1}{2} \log 3 \approx 0.2075 \text{ bits} \end{aligned}$$

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Example (from Cover & Thomas, 2006) — Cont'd

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When will KL(p||q) = KL(q||p)?

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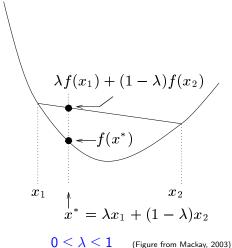
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Intuitively, how much information, on average, X conveys about Y (or vice versa).

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Convex Functions:

Introduction



A function is convex \smile if every cord of the function lies above the function

Convex and Concave Functions Definitions

Definition

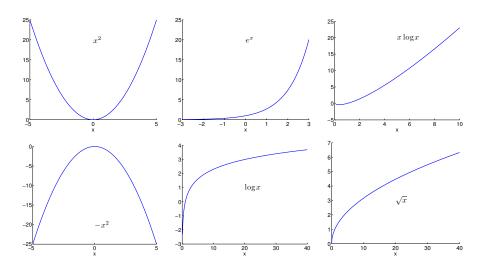
A function f(x) is convex \smile over (a, b) if for all $x_1, x_2 \in (a, b)$ and $0 < \lambda < 1$:

$$f(\lambda x_1 + (1-\lambda)x_2) \le \lambda f(x_1) + (1-\lambda)f(x_2)$$

We say f is strictly convex \smile if for all $x_1, x_2 \in (a, b)$ the equality holds only for $\lambda = 0$ and $\lambda = 1$.

Similarly, a function f is concave \frown if -f is convex \smile , i.e. if every cord of the function lies below the function.

Examples of Convex and Concave Functions



Verifying Convexity

Theorem (Cover & Thomas, Th 2.6.1)

If a function f has a second derivative that is non-negative (positive) over an interval, the function is convex \smile (strictly convex \smile) over that interval.

This allows us to verify convexity or concavity.

Examples:

•
$$x^2$$
: $\frac{d}{dx}\left(\frac{d}{dx}(x^2)\right) = \frac{d}{dx}(2x) = 2$

•
$$e^x$$
: $\frac{d}{dx}\left(\frac{d}{dx}(e^x)\right) = \frac{d}{dx}(e^x) = e^x$

•
$$\sqrt{x}$$
, $x > 0$: $\frac{d}{dx} \left(\frac{d}{dx} \left(\sqrt{x} \right) \right) = \frac{1}{2} \frac{d}{dx} \left(\frac{1}{\sqrt{x}} \right) = -\frac{1}{4} \frac{1}{\sqrt{x^3}}$

Convexity, Concavity and Optimization

if f(x) is concave \frown and there exists a point at which

$$\frac{df}{dx}=0$$
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Note: the converse does not hold: if a concave f(x) is maximized at some x, it is not necessarily true that the derivative is zero there.

- f(x) = -|x|: is maximized at x = 0 where its derivative is undefined
- ullet $f(p)=\log p$ with $0\leq p\leq 1$, is maximized at p=1 where $rac{df}{dp}=1$

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- ullet $f(p)=\log p$ with $0\leq p\leq 1$, is maximized at p=1 where $rac{df}{dp}=1$
- Generalization to multivariate functions.
- Similarly for convex functions (and minimization)
- Can use second derivative and first derivative together

Jensen's Inequality for Convex Functions

Theorem: Jensen's Inequality

If f is a convex \smile function and X is a random variable then:

$$\mathbb{E}[f(X)] \geq f(\mathbb{E}[X]).$$

Moreover, if f is strictly convex \smile , the equality implies that $X = \mathbb{E}[X]$ with probability 1, i.e X is a constant.

Similarly for a concave \frown function: $\mathbb{E}[f(X)] \leq f(\mathbb{E}[X])$.

Example (from Mackay, 2003)

There squares have average area $\overline{A}=100$ m². The average of the lengths of their sides is $\overline{\ell}=10$ m. What can be said about the largest of the three squares?

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We are given:

$$\mathbb{E}[X] = 10$$
 $\mathbb{E}[f(X)] = 100$,

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Let $X \in \{\ell_1, \ell_2, \ell_3\}$ denote the length of the side of a square with $\mathbf{p} = (1/3, 1/3, 1/3)$.

We are given:

$$\mathbb{E}[X] = 10 \qquad \mathbb{E}[f(X)] = 100,$$

where $f(x) = x^2$, which is a strictly convex \smile function.

Example (from Mackay, 2003)

There squares have average area $\overline{A}=100$ m². The average of the lengths of their sides is $\overline{\ell}=10$ m. What can be said about the largest of the three squares?

Solution:

Let $X \in \{\ell_1, \ell_2, \ell_3\}$ denote the length of the side of a square with $\mathbf{p} = (1/3, 1/3, 1/3)$.

We are given:

$$\mathbb{E}[X] = 10 \qquad \mathbb{E}[f(X)] = 100,$$

where $f(x) = x^2$, which is a strictly convex \smile function.

Therefore $f(\mathbb{E}[X]) = \mathbb{E}[f(X)]$, implying that X is a constant and the three lengths $\ell_1 = \ell_2 = \ell_3 = 10$.

Gibbs' Inequality

Theorem

The relative entropy (or KL divergence) between two distributions p(X) and q(X) with $X \in \mathcal{X}$ is non-negative:

$$\mathsf{KL}(p||q) \geq 0$$

with equality if and only if p(x) = q(x) for all x.

Proof Using Jensen's inequality.

Continuous Random Variables

• Differential Entropy: It is possible to define:

$$H(x) = \mathbb{E}_{p(x)}[-\log p(x)] = -\int p(x)\log p(x)dx$$

However, it does not satisfy all properties, e.g. it can be negative.

• KL Divergence: Similarly, we have seen:

$$\mathsf{KL}(p\|q) \stackrel{\scriptscriptstyle\mathsf{def}}{=} \mathbb{E}_{p(x)} \left[\log \frac{p(x)}{q(x)} \right] = \int p(x) \log \frac{p(x)}{q(x)} dx,$$

which always satisfies Gibbs' inequality.

Summary & Conclusions

- Entropy as a measure of information content
- Computation of entropy of discrete random variables
- Joint and conditional entropies
- Relative entropy
- Convex Functions, Jensen's inequality, Gibbs' inequality
- Reading:
 - * Mackay (ITILA, 2003): Sec. 1.2 1.5, 2.5, 2.6 2.10, 8.1
 - * Bishop (PRML, 2006): Sec. 1.6
 - * Murphy (MLaPP, 2012): Sec. 2.8