# Machine Learning and Data Mining

Optimization in ML

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# Machine Learning in a nutshell

Every (supervised) ML algorithm ever:

ightharpoonup a model  $\mathcal A$  - set of all possible solutions:

$$\mathcal{A} \subseteq \{f : \mathcal{X} \to \mathcal{Y}\}$$

- $\mathcal{X}$ ,  $\mathcal{Y}$  sample and target spaces.
- a search procedure:

$$S: (\mathcal{X} \times \mathcal{Y})^n \to \mathcal{A}$$

#### **Decision Trees:**

- model: piece-wise constant functions;
- search procedure: very sinful one.

#### SVM:

- linear functions (in some space);
- search procedure: margin maximization.

#### Logistic regression:

- linear functions;
- search procedure:  $cross-entropy \rightarrow min$ , any optimization method.

In Deep Learning models are often decoupled from search procedures.

Machine Learning in a nutshell

Often, model-search can be factorized further:

parametrized model:

$$\mathcal{A} = \{ f_{\theta} : \mathcal{X} \to \mathcal{Y} \mid \theta \in \Theta \subseteq \mathbb{R}^n \}$$

optimization problem:

$$L(f_{\theta}, D) = \mathcal{L}(\theta) \to_{\theta} \min$$

- ▶  $D \in (\mathcal{X} \times \mathcal{Y})^N$  training set;
- **p** optimization method *O*:

$$\theta^{t+1} = O\left[\theta^t, \mathcal{L}\right].$$

- parametrized model:
  - heavily domain/data dependent;
- optimization problem:
  - more or less universal:

$$\mathcal{L} = \{\log, \text{hinge}, \dots\} - \text{loss} + \{l_1, l_2\} - \text{regularization};$$

- **▶** optimization method *O*:
  - ightharpoonup heavily-dependent on nature of  $\mathcal{L}$ .

## Optimization in ML

#### Optimization methods:

- heavily restrict:
  - > speed of the algorithm:
  - quality of solutions;
- some optimization methods allows for new models:
  - discreet or mixed parameters;
  - variable size models.

# **Gradient methods**

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#### The zoo

- SGD, SGD with momentum:
  - you have no memory;
  - you have to write optimizer in 1 minute;
- Nesterov momentum:
  - you want to fine-tune your solution.
- RMSprop:
  - you have little memory and you gradients explode/vanish;
  - you have 2 minutes before submitting your code for training;
- adagrad, adadelta, adam, adamax:
  - methods to go.

Details are likely to be considered in Deep Learning course.

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## Second-order methods

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#### Flow chart

Do you have a nearly-quadratic target function?

- **▶** <u>yes</u>: is the problem low-dimensional?
  - yes: go Newton!
  - <u>no</u>: use gradient or quasi-Newton methods;
- <u>no</u>: use gradient or quasi-Newton methods.

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# Hyper-parameter optimization

## Hyper-parameter optimization

Hyper-parameter optimization is a meta-algorithm that operates on union of models parametrized by  $\psi$ :

$$\mathcal{A} = \bigcup_{\psi} \mathcal{A}_{\psi} = \{ f_{\theta_{\psi}}^{\psi} \mid \theta_{\psi} \in \Theta_{\psi} \}$$

outer loss might differ from inner loss:

$$\psi^* = \operatorname*{arg\,max}_{\psi} Q \left( \operatorname*{arg\,min}_{\theta_{\psi}} L(\theta_{\psi}) \right)$$

- no sacred meaning, just for convinience:
- ightharpoonup example: L cross-entropy, Q ROC AUC.

## Hyper-parameter optimization

Outer optimization is usually evaluated on a separate set:

- via train-validation-test split;
- via cross-validation;
- the main reason for split into outer and inner problems.

Alternatevely, BIC or similar can be used.

Outer optimization problem is usually non-differentiable:

number of units, maximal depth of trees.

#### **Grid-search**

Usually, ML algorithms are designed to have **a few**, **non-sensitive** hyper-parameters:

- outer problem is mostly convex and changes slowly;
- grid-search often works perfectly fine.

Modifications, alternatives:

- randomized grid-search;
- random walk.

## **Gradient-free methods**

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#### **Gradient-free methods**

- local optimization:
  - 'traditional' methods;
- **▶** global optimization:
  - gradient and Hessian are fundamentally local properties;
  - evolutionary methods;
- black-box optimization:
  - variational optimization;
  - Bayesian optimization.

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## Traditional gradient-free methods

- evaluation of objective function is cheap;
- in practice, **often** can be replaced by gradient-methods:

$$\mathsf{cheap} \Rightarrow \begin{bmatrix} \mathsf{closed\text{-}form\ expression} \\ & \mathsf{or} \\ & \mathsf{allow\ approximation} \end{bmatrix} \Rightarrow \mathsf{differentiable}.$$

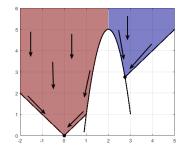
example: Powell, Nelder-Mead.

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#### Multi-start

Just launch local procedure multiple times with different initial guesses.

- each local optima acts like an attractor for local methods;
- effective if depth of local optima positively depend on area of attraction.



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#### **Evolution methods**

There are just so many...

#### Basic operations:

- ightharpoonup mutation: x' = x + noise;
- rightharpoonup crossover:  $x' = \operatorname{crossover}(x_1, x_2);$

#### Application:

- you have no idea how to optimize objective function;
- evolution algorithms basically can handle any parametrization:
  - e.g. DNA molecules.

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## Memetic algorithms

```
def memetic(global_step=evolutionary,
            locally optimize=annealing):
  population = []
  mature population = [ <random> ]
  while ...:
    population = global step(mature population)
    mature population = [
      locally optimize(x) for x in population
  return mature population
multistart = lambda locally optimize:
                                       memetic(
  random sampling, locally optimize
```

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#### Black-box optimization

- heavy objective;
- non-differentiable:
  - complex computer simulations (e.g. aero-dynamics);
- so multi-modal, gradient does not have sense:
  - extremely deep networks (e.g. recurrent networks);

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## Surrogate optimization

A type of black-box optimization.

Given known samples  $\mathcal{O}^t = \{(\theta_i, L_i)\}_{i=1}^t$ :

- **▶** fit regression (surrogate) model to  $\{(\theta_i, L_i)\}_{i=1}^t$ ;
- **ightharpoonup** find the most promising  $heta_{t+1}$  with conventional optimization methods;
- evaluate objective in  $\theta_{t+1}$ ;
- $\mathcal{D}^{t+1} = \mathcal{O}^t \cup \{(\theta_{t+1}, L_{t+1})\};$
- repeat.

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## **Bayesian optimization**

The most well-known black-box optimization method.

#### Surrogate model:

- ightharpoonup must estimate:  $P(y \mid D, x)$ ;
- usually Gaussian processes:
  - easy to handle (normal distribution everywhere);
  - computationally expensive  $O(n^3)$ , n number of points.
- possible to use Random Forest or Boosting;
- the most promising point is defined by aquisition function:

 $a(x) \to \max$ 

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## **Aquisition functions**

ightharpoonup f' - current minimum; D - observed values.

Probability of improvement:

$$a_{pi}(x) = \mathbb{E}\left[\mathbb{I}[f(x) > f'] \mid D\right] \underbrace{= \Phi(f', \mu(x), K(x, x))}_{GP}$$

Expected improvement:

$$\underbrace{a_{ei}(x) = \mathbb{E}\left[\max(0, f' - f(x)) \mid D\right] = \underbrace{(f' - \mu(x))\Phi(f', \mu(x), K(x, x)) + K(x, x)\phi(f', \mu(x), K(x, x))}_{GP}$$

Lower confidence bound:

$$a_{lcb}(x) = \mu(x) + \beta \sigma(x)$$

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## Variational optimization

$$\min_{x} f(x) \le \mathop{\mathbb{E}}_{x \sim \pi_{\psi}} f(x) = J(\psi)$$

 $\bullet$   $\pi_{\psi}$  - search distribution;

$$\nabla J(\psi) = \nabla \underset{x \sim \pi_{\psi}}{\mathbb{E}} f(x) =$$

$$\int_{x} f(x) (\nabla \pi(x \mid \psi)) \frac{\pi(x \mid \psi)}{\pi(x \mid \psi)} dx =$$

$$\int_{x} f(x) \nabla \log \pi(x \mid \psi) \pi(x \mid \psi) dx =$$

$$\underset{x \sim \pi_{\psi}}{\mathbb{E}} f(x) \nabla \log \pi(x \mid \psi) \approx$$

$$\frac{1}{n} \sum_{i=1}^{n} f(x_{i}) \nabla \log \pi(x_{i} \mid \psi)$$

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#### **Evolution Strategies**

Evolution Strategies - is a subset of variational optimization (?).

- Repeat:
  - ▶ sample  $\{x_i\}_{i=1}^n$  from  $\pi(\cdot \mid \psi)$ ;
  - evaluate  $f_i = f(x_i)$ ;
  - **compute:**

$$\nabla J(\psi) \approx \frac{1}{n} \sum_{i=1}^{n} f_i \nabla \log \pi(x_i \mid \psi)$$

• update  $\psi$ , e.g.

$$\psi \leftarrow \operatorname{adamax}(\nabla J(\psi))$$

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## **Evolution Strategies**

- ightharpoonup d dimensionality of the problem;
- $\bullet$   $\pi_{\psi}$  Gaussian:
  - ▶  $\dim(\psi) = O(d^2)$ : covariance matrix and mean vector;
  - $O(d^3)$  operations per step;
- $\bullet$   $\pi_{\psi}$  Gaussian with independent components:
  - $|\psi| = O(d)$ : diagonal covariance matrix and mean vector;
  - O(d) operations per step;
- $\bullet$   $\pi_{\psi}$  scaled normal:
  - ▶  $|\psi| = O(d)$ : variance  $\sigma$  and mean vector;
  - $\bullet$  O(d) operations per step;
  - ▶ less samples for estimating gradient.

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# Summary

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#### **Summary**

Known your optimization algorithms:

- **▶** differentiable ⇒ gradient methods;
- super heavy objective ⇒ Bayesian;
- non-differentiable ⇒ Variational Optimization;
- ightharpoonup wierd model  $\Rightarrow$  evolutionary optimization.

Don't blindly follow this.

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## References, gradient-methods

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