

Machine Learning and Data Mining

Recapitulation

Maxim Borisyak

National Research University Higher School of Economics (HSE)

September 11, 2018

Statistical estimations

—

Setup

Given:

- data: $X = \{x_i\}_{i=1}^N$;
- parameterized family of distributions $P(x \mid \theta)$.

Problem:

- estimate θ .

Maximum likelihood estimation

$$\begin{aligned}L(\theta) &= P(X \mid \theta); \\ \hat{\theta} &= \arg \max_{\theta} L(\theta).\end{aligned}$$

$$\mathcal{L}(\theta) = -\log \prod_i P(x_i \mid \theta) = -\sum_i \log P(x_i \mid \theta)$$

- consistent estimation: $\hat{\theta} \rightarrow \theta$ as $N \rightarrow \infty$;
- *might be biased*;
- equal to MAP estimation with uniform prior.

MLE: example

Given samples $\{x_i\}_{i=1}^N$ from a normal distribution estimate its mean.

$$\mu = \arg \min_{\mu} \mathcal{L}(X) =$$

$$\arg \min_{\mu} u - \sum_i \log \left(\frac{1}{Z} \exp \left[-\frac{(x_i - \mu)^2}{2\sigma^2} \right] \right) =$$

$$\arg \min_{\mu} \sum_i (x_i - \mu)^2 = \frac{1}{N} \sum_i x_i$$

Bayesian inference

$$P(\theta \mid X) = \frac{1}{Z} P(X \mid \theta) P(\theta);$$

- often, posterior distribution of predictions is of the main interest:

$$P(f(x) = y \mid X) = \int \mathbb{I}[f(x, \theta) = y] P(\theta \mid X) d\theta$$

- with a few exceptions posterior is intractable;
- often, approximate inference is utilized instead.

BI: example

Given samples $\{x_i\}_{i=1}^N$ from a normal distribution estimate mean under a normal prior.

$$P(\mu | X) = \frac{1}{Z} P(X | \mu) P(\mu) =$$
$$\frac{1}{Z} \exp \left[-\frac{\mu^2}{2c^2} \right] \cdot \prod \exp \left[-\frac{(x_i - \mu)^2}{2\sigma^2} \right]$$

$$\log P(\mu | X) = -Z - \frac{\mu^2}{2c^2} - \sum_i \frac{(x_i - \mu)^2}{2\sigma^2}$$

Maximum a posteriori estimation

$$\begin{aligned}\hat{\theta} &= \arg \max_{\theta} P(\theta \mid X) = \arg \max_{\theta} P(X \mid \theta) P(\theta) = \\ &\arg \min_{\theta} [-\log P(X \mid \theta) - \log P(\theta)] = \\ &\arg \min_{\theta} [\text{neg log likelihood} + \text{penalty}] \\ \hat{\theta} &= \arg \min_{\theta} \left[-\log P(\theta) - \sum_i \log P(x_i \mid \theta) \right]\end{aligned}$$

- sometimes called **structural loss**:
 - i.e. includes 'structure' of the predictor into the loss.

MAP: example

Given samples $\{x_i\}_{i=1}^N$ from a normal distribution estimate mean under a normal prior.

$$\begin{aligned}\hat{\mu} &= \arg \max_{\mu} \log P(\mu \mid X) = \\ &\arg \max_{\mu} \left[-Z - \frac{\mu^2}{2c^2} - \sum_i \frac{(x_i - \mu)^2}{2\sigma^2} \right] = \\ &\arg \min_{\mu} \left[\lambda \mu^2 + \sum_i (x_i - \mu)^2 \right] = \frac{1}{N + \lambda} \sum_i x_i\end{aligned}$$

Machine Learning

Structure of a Machine Learning problem

Given:

- description of the problem:
 - prior knowledge;
- data:
 - input space: \mathcal{X} ;
 - output space: \mathcal{Y} ;
- metric M .

Problem:

- find a learning algorithm: $A : \mathcal{D} \rightarrow (\mathcal{X} \rightarrow \mathcal{Y})$ such that:

$$M(A(\text{data})) \rightarrow \max$$

Differences from statistics

Machine Learning:

- usually, probability densities are intractable;
- high-dimensionality/small sample sizes;
- hence, no p-values etc;
- less formal assumptions.

Supervised learning

Regression

Output: $y \in \mathbb{R}$.

Assumptions:

- $y = f(x) + \varepsilon(x)$;
- $\varepsilon(x)$ - noise:
 - $\forall x_1, x_2 : x_1 \neq x_2 \Rightarrow \varepsilon(x_1)$ independent from $\varepsilon(x_2)$;
 - $\forall x : \mathbb{E} \varepsilon(x) = 0$.
- often, $\varepsilon(x)$ is assumed not to be dependent on x .

Regression loss

$$\begin{aligned}\mathcal{L}(f) &= - \sum_i \log P((x_i, y_i) \mid f) = \\ &\quad - \sum_i \log P_\varepsilon(y_i - f(x_i) \mid f, x_i) = \\ &\quad \quad \quad - \sum_i \log P_\varepsilon(y_i - f(x_i) \mid x_i)\end{aligned}$$

Regression: MSE

- $\varepsilon \sim \mathcal{N}(0, \sigma_\varepsilon^2)$;
- $\sigma_\varepsilon^2 = \text{const}$ (unknown);

$$\begin{aligned}\mathcal{L}(f) &= - \sum_i \log P_\varepsilon(y_i - f(x_i) \mid x_i) = \\ &\sum_i \left[Z(\sigma_\varepsilon^2) - \frac{(y_i - f(x_i))^2}{2\sigma_\varepsilon^2} \right] \sim \\ &\sum_i (y_i - f(x_i))^2 \rightarrow \min\end{aligned}$$

$$f^*(x) = \mathbb{E}[y \mid x]$$

Regression: MAE

- $\varepsilon \sim \text{Laplace}(0, b_\varepsilon)$;
- $b_\varepsilon = \text{const}$ (unknown);

$$\begin{aligned}\mathcal{L}(f) &= - \sum_i \log P_\varepsilon(y_i - f(x_i) \mid x_i) = \\ &\sum_i \left[Z(b_\varepsilon) - \frac{|y_i - f(x_i)|}{2b_\varepsilon} \right] \sim \\ &\sum_i |y_i - f(x_i)| \rightarrow \min\end{aligned}$$

$$f^*(x) = \text{median}[y \mid x]$$

Linear regression

$$f(x) = w \cdot x$$

Linear regression + MSE + MLE

$$\mathcal{L}(w) = \sum_i (w \cdot x_i - y_i)^2 = \|Xw - y\|^2 \rightarrow \min;$$

$$\frac{\partial}{\partial w} \mathcal{L}(w) = 2X^T(Xw - y) = 0;$$

$$w = (X^T X)^{-1} X^T y.$$

$$\begin{aligned}\mathcal{L}(w) &= \sum_i (w \cdot x_i - y_i)^2 + \lambda \|w\|^2 = \\ &\quad \|Xw - y\|^2 + \lambda \|w\|^2 \rightarrow \min; \\ \frac{\partial}{\partial w} \mathcal{L}(w) &= 2X^T(Xw - y) + 2\lambda w = 0; \\ w &= (X^T X + \lambda I)^{-1} X^T y.\end{aligned}$$

Linear regression + MSE + Bayesian Inference

- prior:

$$w \sim \mathcal{N}(0, \Sigma_w);$$

- data model:

$$\varepsilon \sim \mathcal{N}(0, \sigma_\varepsilon^2).$$

Linear regression + MSE + Bayesian Inference

$$P(w \mid y, X) \propto P(y \mid w, X)P(w) \propto$$

$$\exp \left[-\frac{1}{2\sigma_\epsilon^2} (y - Xw)^T (y - Xw) \right] \cdot \exp \left[-\frac{1}{2} w^T \Sigma_w^{-1} w \right] =$$

$$\exp \left[-\frac{1}{2} (w - w^*)^T A_w (w - w^*) \right]$$

where:

- $A_w = \frac{1}{\sigma_\epsilon^2} X X^T + \Sigma_w^{-1};$
- $w^* = \frac{1}{\sigma_\epsilon^2} A_w^{-1} X y.$

To make prediction y' in point x' :

$$\begin{aligned} P(y' \mid y, X, x') &= \\ &\int P(y' \mid w, x') P(w \mid X, y) = \\ &\mathcal{N} \left(\frac{1}{\sigma_{\varepsilon}^2} x'^T A^{-1} X y, x'^T A^{-1} x' \right) \end{aligned}$$

Basis expansion

To capture more complex dependencies basis functions can be introduced:

$$f(x) = \sum_i w \cdot \phi(x)$$

where:

- $\phi(x) \in \mathbb{R}^K$ - expanded basis.
- ϕ is fixed.

Basis expansion: example

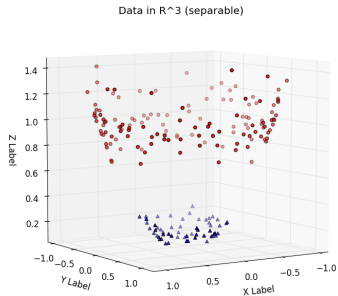
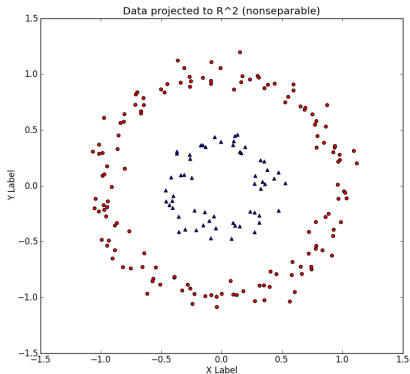
Regression with polynomials:

$$\phi(x) = \{1, x_1, \dots, x_n, x_1^2, x_1x_2, \dots, x_n^2, \dots\}$$

Periodic functions:

$$\phi(x) = \{1, \sin(x), \cos(x), \sin(2x), \cos(2x), \dots\}$$

Basis expansion: example



Source: eric-kim.net

Classification

- classes: $y \in \{1, 2, \dots, m\}$;
- classifier:

$$f : \mathcal{X} \rightarrow \mathbb{R}^m;$$
$$\sum_{k=1}^m f^k(x) = 1.$$

$$\mathcal{L}(f) = - \sum_i \sum_{k=1}^m \mathbb{I}[y_i = k] \log f^k(x_i);$$
$$\text{cross-entropy}(f) = \sum_i y'_i \cdot f(x_i).$$

- often employed trick to make $f(x)$ a proper distribution:

$$f(x) = \text{softmax}(g(x));$$

$$f^i(x) = \frac{\exp(g^i(x))}{\sum_k \exp(g^k(x))}.$$

Logistic regression

$$\begin{aligned}g(x) &= Wx + b; \\f(x) &= \text{softmax}(g(x)).\end{aligned}$$

Another form:

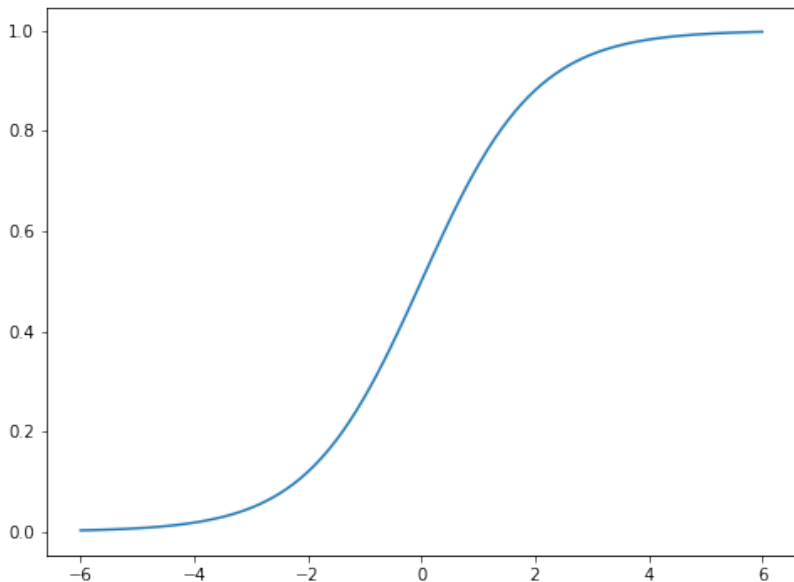
$$\frac{\log P(y = i \mid x)}{\log P(y = j \mid x)} = \frac{w_i \cdot x + b_i}{w_j \cdot x + b_j}$$

Logistic regression: 2 classes

$$\begin{aligned} f_1(x) &= \frac{\exp(w_1 \cdot x + b_1)}{\exp(w_1 \cdot x + b_1) + \exp(w_2 \cdot x + b_2)} = \\ &\frac{1}{1 + \exp((w_2 - w_1) \cdot x + b_2 - b_1)} = \\ &\frac{1}{1 + \exp(w' \cdot x + b')} = \end{aligned}$$

sigmoid($w' \cdot x + b'$).

Logistic regression: 2 classes



Training logistic regression

$$\mathcal{L}(w) = \sum_i \mathbb{I}[y_i = 1] \log(1 + \exp(wx_i + b)) + \mathbb{I}[y_i = 0] \log(1 + \exp(-wx_i - b))$$

- has no analytical solution;
- smooth and convex.

$$f(\theta) \rightarrow \min;$$
$$\theta^* = \arg \min_{\theta} f(\theta).$$

$$\theta^{t+1} = \theta^t - \alpha \nabla f(\theta^t);$$
$$\theta^t \rightarrow \theta^*, t \rightarrow \infty;$$

Gradient Descent

```
1:  $\theta :=$  initialization  
2: for  $t := 1, \dots$  do  
3:    $\theta := \theta - \alpha \nabla f(\theta^t)$   
4: end for
```

Stochastic Gradient Descent

$$f(\theta) = \sum_{i=1}^N f_i(\theta)$$

```
1:  $\theta :=$  initialization  
2: for  $t := 1, \dots$  do  
3:    $i := \text{random}(1, \dots, N)$   
4:    $\theta := \theta - \alpha \nabla f_i(\theta^t)$   
5: end for
```

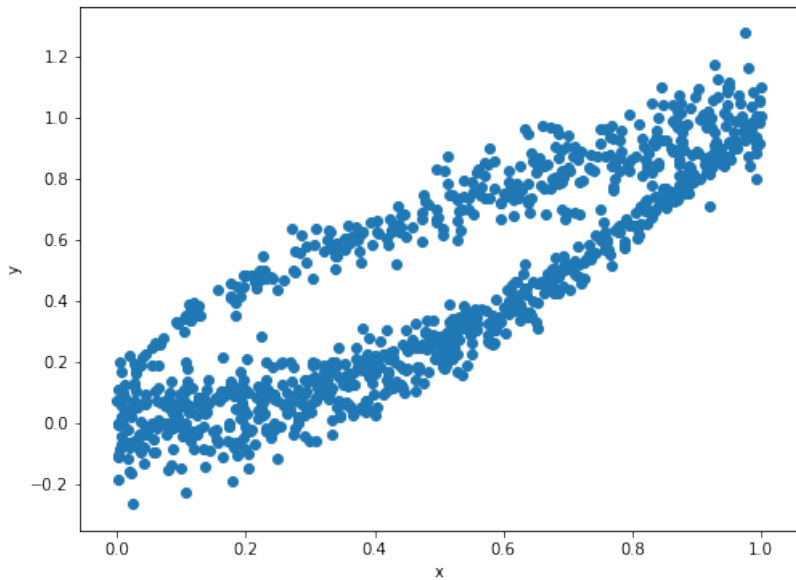
Illustration



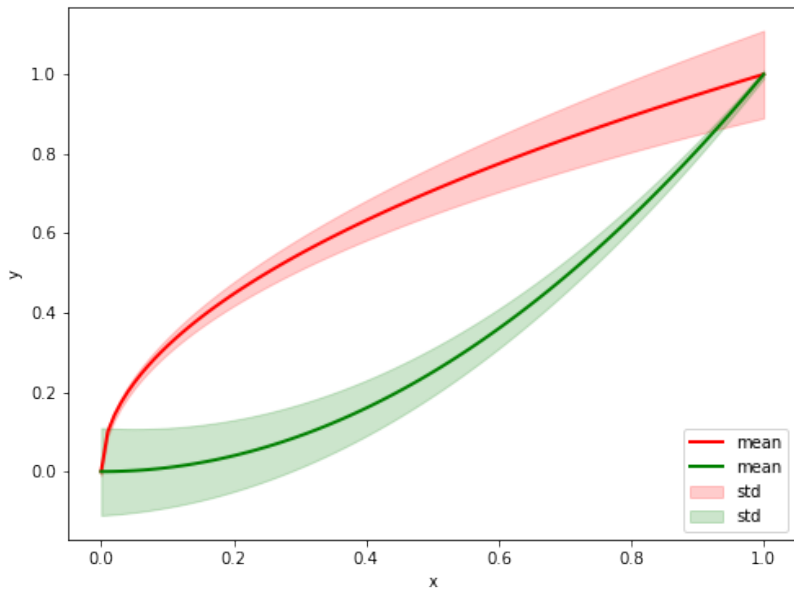
- Batch gradient descent
- Mini-batch gradient Descent
- Stochastic gradient descent

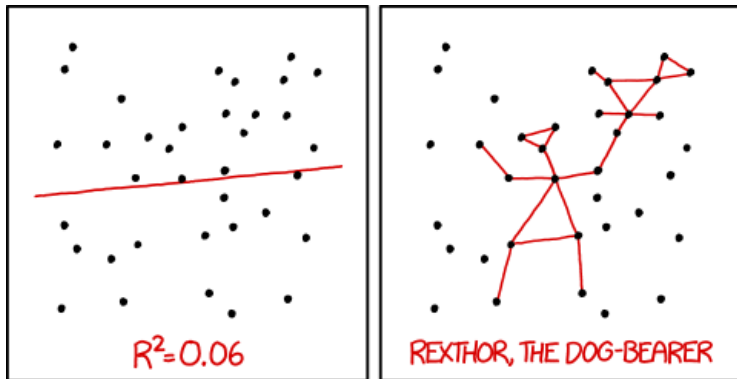
Source: towardsdatascience.com

Tricky example



Tricky example





I DON'T TRUST LINEAR REGRESSIONS WHEN IT'S HARDER
TO GUESS THE DIRECTION OF THE CORRELATION FROM THE
SCATTER PLOT THAN TO FIND NEW CONSTELLATIONS ON IT.

My first neural network

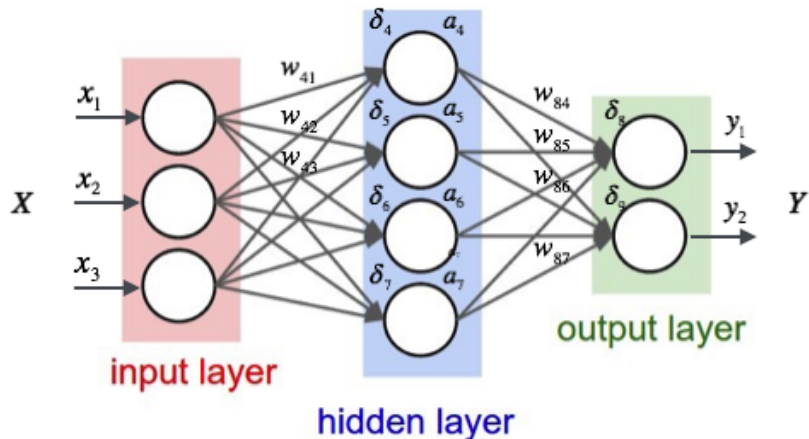
Universal Approximation Theorem

If ϕ is a non-constant, continuous, bounded, monotonic function, then every continuous function f on a compact set from \mathbb{R}^n can be approximated with any precision $\varepsilon > 0$ by:

$$g(x) = c + \sum_{i=1}^N \alpha_i \phi(w_i \cdot x + b_i)$$

given large enough N .

Universal Approximators



Stochastic Gradient Descent and Co.

How to train a neural network

Stochastic Gradient Descent and Co.

- how to initialize?
- how to choose an appropriate learning rate?
- how many units?
- which activation function to choose?