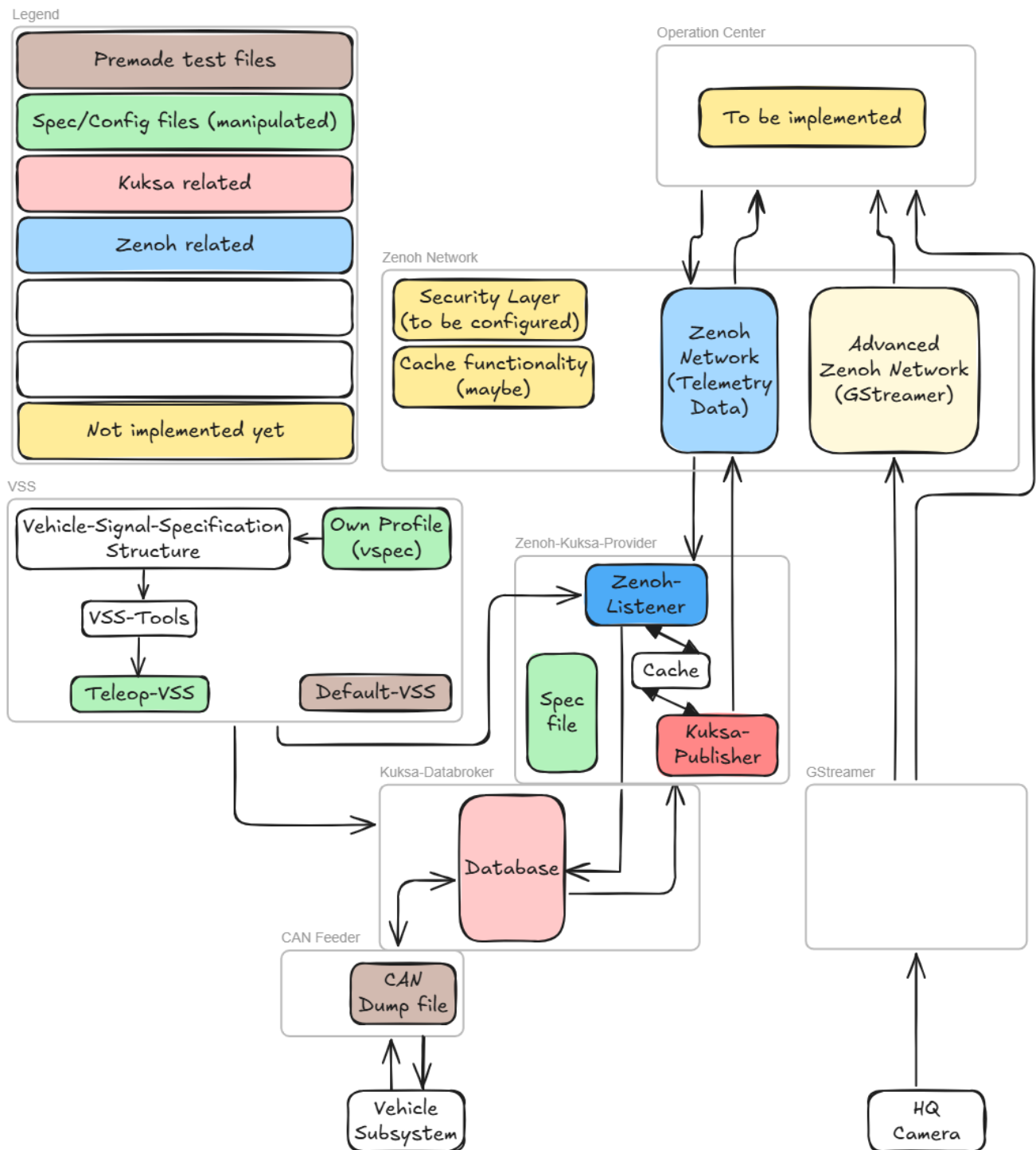


# Teleop-Main

A summary/overview of this project



## Description

This project has the purpose to conceive and realize the stack and implementation for teleoperated driving.

It uses [zenoh](#) to maintain connection while driving and allows management from a distance.

To store the used data, especially for the subsystem, the [kuksa databroker](#) is used.

This allows the corresponding CAN Feeder ([CAN Provider](#)) to write CAN messages to the vehicle.

For the communication between kuksa and zenoh a [VSS](#) (more specific: a vspec file) is needed.

Through a custom vspec file a VSS for the Zenoh-Kuksa-Provider and the kuksa databroker is generated.