

# RNN

## HSK

June 2024

## 1 Introduce

Formula 1 has to go to Appendix for RNN BPPT.

$$x_t = x_t^o E \quad (1)$$

$$h_t = \Theta_h(W h_{t-1} + U x_t + b) \quad (2)$$

$$\Omega_t = V h_t + c \quad (3)$$

$$\hat{y}_t = \Theta_y(\Omega_t) \quad (4)$$

$$L_t = -y_t \ln(\hat{y}_t) \quad (5)$$

in (1), we use embedding layer.  $\Theta$ 's represent all activation functions. In our example for analytics,  $\Theta_h$  is tanh in (2), while  $\Theta_y$  is softmax in (4), which is usually used.

## 2 Through Time for Recurrent Neural Network

### 2.1 Softmax

Softmax  $(x_t) = S_t = \frac{e^{x_t}}{\sum_k e^{x_k}}$  for  $t = 1, \dots, k$

Since softmax is a  $\mathbb{R}^k \rightarrow \mathbb{R}^k$  mapping function, most general Jacobian matrix for it:

$$\frac{\partial S}{\partial x} = \begin{bmatrix} \frac{\partial S_1}{\partial x_1} & \dots & \frac{\partial S_1}{\partial x_k} \\ \vdots & & \\ \frac{\partial S_k}{\partial x_1} & \dots & \frac{\partial S_k}{\partial x_k} \end{bmatrix}$$

Let's compute  $\frac{\partial S_i}{\partial x_j}$  for some arbitrary  $i$  and  $j$  :

$$\frac{\partial S_i}{\partial x_j} = \frac{\partial}{\partial x_j} \frac{e^{x_i}}{\sum_k e^{x_k}}$$

Let's examine the formula for division

$$f(x) = \frac{g(x)}{h(x)},$$

$$f'(x) = \frac{g'(x)h(x) - g(x)h'(x)}{h(x)^2}$$

In our case  $g_i = e^{x_i}$  and  $h_i = \sum e^{x_k}$ . No matter which  $x_j$ , when we compute the derivative of  $h_i$  with respect to  $x_j$ , the answer will always be  $e^{x_j}$ .

$$\frac{\partial}{\partial x_j} h_i = \frac{\partial}{\partial x_j} \sum e^{x_k} = \sum \frac{\partial e^{x_k}}{\partial x_j} = e^{x_j}$$

because  $\frac{\partial e^{x_k}}{\partial x_j} = 0$  for  $k \neq j$ . There are on the mean-fully derivatives for  $i = j$  in  $\frac{\partial S}{\partial x}$  matrices for our problem.

$$\begin{aligned} \frac{\partial \frac{e^{x_i}}{\sum e^{x_k}}}{\partial x_j} &= \frac{e^{x_i} \sum e^{x_k} - e^{x_j} e^{x_i}}{(\sum e^{x_k})^2} \\ &= \frac{e^{x_i} (\sum e^{x_k} - e^{x_j})}{(\sum e^{x_k})^2} \\ &= \frac{e^{x_i}}{\sum e^{x_k}} \cdot \left( \frac{\sum e^{x_k}}{\sum e^{x_k}} - \frac{e^{x_j}}{\sum e^{x_k}} \right) \end{aligned}$$

$$S_i (1 - S_j) \tag{6}$$

Now we found what derivative of softmax. Let's go back to the loss function.

## 2.2 Derivative of Loss Function and $\Omega_t$

Let's examine the derivative formula for logarithm

$$f(x) = \log_y x$$

$$f'(x) = \frac{x'}{x} \cdot \log_e y$$

$$\begin{aligned}
L(\hat{y}, y) &= - \sum y_t \log (\text{softmax}(\Omega_t)) \\
\frac{\partial L}{\partial \Omega_t} &= - \frac{\partial}{\partial \Omega_t} \sum y_t \log (\text{softmax}(\Omega_t)) \\
&= - \sum y_t \frac{\partial \log (\text{softmax}(\Omega_t))}{\partial \Omega_t} \\
&= - \sum \frac{\partial \hat{y}_t}{\partial \Omega_t} \cdot \frac{y_t}{\hat{y}_t} \\
&= - \sum S_{t,i} (1 - S_{t,j}) \cdot \frac{y_t}{\hat{y}_t} \\
&= - \sum (1 - S_{t,j}) y_t \\
&= - \sum (y_t - S_{t,j} \hat{y}_t) \\
&= \sum S_{t,i} \hat{y}_t - \sum y_t \\
&= S_{t,j} \sum \hat{y}_t - \sum y_t \\
&= \sum (\hat{y}_t - y_t)
\end{aligned}$$

$$\frac{\partial L_t}{\partial \hat{\Omega}_t} = (\hat{y}_t - y_t) \quad (7)$$

### 2.3 Derivative of V

The weight V is consistent across the entire time sequence, allowing us to perform differentiation at each time step and then aggregate the results.

$$\begin{aligned}
\frac{\partial L}{\partial V} &= \sum_{t=1}^S \frac{\partial L_t}{\partial V} \\
&= \sum_{t=1}^S \frac{\partial L_t}{\partial \hat{y}_t} \frac{\partial \hat{y}_t}{\partial \Omega_t} \frac{\partial \Omega_t}{\partial V} \\
&= \sum_{t=1}^S \frac{\partial L}{\partial \Omega_t} \frac{\partial \Omega_t}{\partial V}
\end{aligned}$$

We know that this formula  $\frac{\partial \hat{y}_t}{\partial \Omega_t}$  from (7) and no other function exists between Omega and V, so simply taking the derivative coefficient of V yields h, thus the answer is h.

$$= \sum_{t=1}^S (\hat{y}_t - y_t) \cdot h_t^\top \quad (8)$$

## 2.4 Derivative of $c$

Similar to  $V$ , but its derivative is easier to calculate since it stands alone in the function.

$$\begin{aligned}\frac{\partial L}{\partial c} &= \sum_{t=1}^T \frac{\partial L_t}{\partial c} \\ &= \sum_{t=1}^T \frac{\partial L_t}{\partial \hat{y}_t} \frac{\partial \hat{y}_t}{\partial \Omega_t} \frac{\partial \Omega_t}{\partial c} \\ &= \sum_{t=1}^T \frac{\partial L}{\partial \Omega_t} \frac{\partial \Omega_t}{\partial c}\end{aligned}$$

In this case, The Analytical Derivatives of  $c$  becomes:

$$= \sum_{t=1}^T (\hat{y}_t - y_t) \quad (9)$$

## 2.5 Derivative of $W$

This function employs recursion, therefore, computing its derivative may take some time.

$$\begin{aligned}h_t &= \tanh(W h_{t-1} + U x_t + b) \\ h_1 &= \tanh(W h_0 + U x_1 + b) \quad h_2 = \tanh(W h_1 + U x_2 + b) \\ h_3 &= \tanh(W h_2 + U x_3 + b) \quad h_4 = \tanh(W h_3 + U x_4 + b)\end{aligned}$$

By placing  $h_t$  into the last term, we get:

$$\begin{aligned}h_4 &= \\ &\tanh(W \tanh(W \tanh(W \tanh(W h_0 + U x_1 + b) + U x_2 + b) + U x_3 + b) + U x_4 + b)\end{aligned}$$

We start from the first step go to the last step:

$$\begin{aligned}\frac{\partial L_1}{\partial W} &= \frac{\partial L_1}{\partial \hat{y}_1} \frac{\partial \hat{y}_1}{\partial h_1} \frac{\partial h_1}{\partial W} \\ \frac{\partial L_2}{\partial W} &= \frac{\partial L_2}{\partial \hat{y}_2} \frac{\partial \hat{y}_2}{\partial h_2} \frac{\partial h_2}{\partial h_1} \frac{\partial h_1}{\partial W} + \frac{\partial L_2}{\partial \hat{y}_2} \frac{\partial \hat{y}_2}{\partial h_2} \frac{\partial h_2}{\partial h_2} \frac{\partial h_2}{\partial W} \\ \frac{\partial L_3}{\partial W} &= \frac{\partial L_3}{\partial \hat{y}_3} \frac{\partial \hat{y}_3}{\partial h_3} \frac{\partial h_3}{\partial h_1} \frac{\partial h_1}{\partial W} + \frac{\partial L_3}{\partial \hat{y}_3} \frac{\partial \hat{y}_3}{\partial h_3} \frac{\partial h_3}{\partial h_2} \frac{\partial h_2}{\partial W} + \frac{\partial L_3}{\partial \hat{y}_3} \frac{\partial \hat{y}_3}{\partial h_3} \frac{\partial h_3}{\partial h_3} \frac{\partial h_3}{\partial W} \\ \frac{\partial L_4}{\partial W} &= \frac{\partial L_4}{\partial \hat{y}_4} \frac{\partial \hat{y}_4}{\partial h_4} \frac{\partial h_4}{\partial h_1} \frac{\partial h_1}{\partial W} + \frac{\partial L_4}{\partial \hat{y}_4} \frac{\partial \hat{y}_4}{\partial h_4} \frac{\partial h_4}{\partial h_2} \frac{\partial h_2}{\partial W} + \frac{\partial L_4}{\partial \hat{y}_4} \frac{\partial \hat{y}_4}{\partial h_4} \frac{\partial h_4}{\partial h_3} \frac{\partial h_3}{\partial W} + \frac{\partial L_4}{\partial \hat{y}_4} \frac{\partial \hat{y}_4}{\partial h_4} \frac{\partial h_4}{\partial h_4} \frac{\partial h_4}{\partial W}\end{aligned}$$

Simplifying:

$$\begin{aligned}
\frac{\partial L_1}{\partial W} &= \frac{\partial L_1}{\partial \hat{y}_1} \frac{\partial \hat{y}_1}{\partial h_1} \frac{\partial h_1}{\partial W} \\
\frac{\partial L_2}{\partial W} &= \frac{\partial L_2}{\partial \hat{y}_2} \frac{\partial \hat{y}_2}{\partial h_2} \frac{\partial h_2}{\partial h_1} \frac{\partial h_1}{\partial W} + \frac{\partial L_2}{\partial \hat{y}_2} \frac{\partial \hat{y}_2}{\partial h_2} \frac{\partial h_2}{\partial W} \\
\frac{\partial L_3}{\partial W} &= \frac{\partial L_3}{\partial \hat{y}_3} \frac{\partial \hat{y}_3}{\partial h_3} \frac{\partial h_3}{\partial h_1} \frac{\partial h_1}{\partial W} + \frac{\partial L_3}{\partial \hat{y}_3} \frac{\partial \hat{y}_3}{\partial h_3} \frac{\partial h_3}{\partial h_2} \frac{\partial h_2}{\partial W} + \frac{\partial L_3}{\partial \hat{y}_3} \frac{\partial \hat{y}_3}{\partial h_3} \frac{\partial h_3}{\partial W} \\
\frac{\partial L_4}{\partial W} &= \frac{\partial L_4}{\partial \hat{y}_4} \frac{\partial \hat{y}_4}{\partial h_4} \frac{\partial h_4}{\partial h_1} \frac{\partial h_1}{\partial W} + \frac{\partial L_4}{\partial \hat{y}_4} \frac{\partial \hat{y}_4}{\partial h_4} \frac{\partial h_4}{\partial h_2} \frac{\partial h_2}{\partial W} + \frac{\partial L_4}{\partial \hat{y}_4} \frac{\partial \hat{y}_4}{\partial h_4} \frac{\partial h_4}{\partial h_3} \frac{\partial h_3}{\partial W} + \frac{\partial L_4}{\partial \hat{y}_4} \frac{\partial \hat{y}_4}{\partial h_4} \frac{\partial h_4}{\partial W}
\end{aligned}$$

Since the calculation process needs to be simplified, let's expand  $\frac{h_t}{h_k}$

$$\begin{aligned}
\frac{\partial L_1}{\partial W} &= \frac{\partial L_1}{\partial \hat{y}_1} \frac{\partial \hat{y}_1}{\partial h_1} \frac{\partial h_1}{\partial W} \\
\frac{\partial L_2}{\partial W} &= \frac{\partial L_2}{\partial \hat{y}_2} \frac{\partial \hat{y}_2}{\partial h_2} \frac{\partial h_2}{\partial h_1} \frac{\partial h_1}{\partial W} + \frac{\partial L_2}{\partial \hat{y}_2} \frac{\partial \hat{y}_2}{\partial h_2} \frac{\partial h_2}{\partial W} \\
\frac{\partial L_3}{\partial W} &= \frac{\partial L_3}{\partial \hat{y}_3} \frac{\partial \hat{y}_3}{\partial h_3} \frac{\partial h_3}{\partial h_2} \frac{\partial h_2}{\partial h_1} \frac{\partial h_1}{\partial W} + \frac{\partial L_3}{\partial \hat{y}_3} \frac{\partial \hat{y}_3}{\partial h_3} \frac{\partial h_3}{\partial h_2} \frac{\partial h_2}{\partial W} + \frac{\partial L_3}{\partial \hat{y}_3} \frac{\partial \hat{y}_3}{\partial h_3} \frac{\partial h_3}{\partial W} \\
\frac{\partial L_4}{\partial W} &= \frac{\partial L_4}{\partial \hat{y}_4} \frac{\partial \hat{y}_4}{\partial h_4} \frac{\partial h_4}{\partial h_3} \frac{\partial h_3}{\partial h_2} \frac{\partial h_2}{\partial h_1} \frac{\partial h_1}{\partial W} + \frac{\partial L_4}{\partial \hat{y}_4} \frac{\partial \hat{y}_4}{\partial h_4} \frac{\partial h_4}{\partial h_3} \frac{\partial h_3}{\partial h_2} \frac{\partial h_2}{\partial W} + \frac{\partial L_4}{\partial \hat{y}_4} \frac{\partial \hat{y}_4}{\partial h_4} \frac{\partial h_4}{\partial h_3} \frac{\partial h_3}{\partial W} + \frac{\partial L_4}{\partial \hat{y}_4} \frac{\partial \hat{y}_4}{\partial h_4} \frac{\partial h_4}{\partial W}
\end{aligned}$$

Let us group them under a  $\sum \prod$  for step  $t$ :

$$\frac{\partial L_t}{\partial W} = \sum_{k=1}^t \frac{\partial L_t}{\partial \hat{y}_t} \frac{\partial \hat{y}_t}{\partial h_t} \prod_{j=k}^{t-1} \left( \frac{\partial h_{j+1}}{\partial h_j} \right) \frac{\partial h_k}{\partial W}$$

Let us now present the formula for  $\mathcal{S}$  steps:

$$\frac{\partial L}{\partial W} = \sum_{t=1}^{\mathcal{S}} \left( \sum_{k=1}^t \frac{\partial L_t}{\partial \hat{y}_t} \frac{\partial \hat{y}_t}{\partial h_t} \prod_{j=k}^{t-1} \left( \frac{\partial h_{j+1}}{\partial h_j} \right) \frac{\partial h_k}{\partial W} \right) \quad (10)$$

Finally, we insert the individual partial derivatives to calculate our final gradients of  $L$  with respect to  $W$ , where:

$$\begin{aligned}
\frac{\partial L_t}{\partial \hat{y}_t} &= (y_t - \hat{y}_t) \\
\frac{\partial \hat{y}_t}{\partial h_t} &= V^\top \\
\frac{\partial h_{j+1}}{\partial h_j} &= W^\top (1 - h_{j+1}^2) \\
\frac{\partial h_k}{\partial W} &= (1 - h_k^2) h_{k-1}
\end{aligned}$$

In this case, The Analytical Derivatives of Eq. (10) becomes:

$$\frac{\partial L}{\partial W} = \sum_{t=1}^{\mathcal{S}} \left( \sum_{k=1}^t (y_t - \hat{y}_t) V^\top \prod_{j=k}^{t-1} \left( W^\top (1 - h_{j+1}^2) \right) (1 - h_k^2) h_{k-1} \right) \quad (11)$$

## 2.6 Derivative of $U$

Now, let's derive the gradient with respect to  $U$ . Similarly, we calculate the gradient with respect to  $U$  like Eq. (10) as follows:

$$\frac{\partial L}{\partial U} = \sum_{t=1}^S \left( \sum_{k=1}^t \frac{\partial L_t}{\partial \hat{y}_t} \frac{\partial \hat{y}_t}{\partial h_t} \prod_{j=k}^{t-1} \left( \frac{\partial h_{j+1}}{\partial h_j} \right) \frac{\partial h_k}{\partial U} \right) \quad (12)$$

we insert the individual partial derivatives to calculate our final gradients of  $L$  with respect to  $W$ , where:

$$\begin{aligned} \frac{\partial L_t}{\partial \hat{y}_t} &= (y_t - \hat{y}_t) \\ \frac{\partial \hat{y}_t}{\partial h_t} &= V^\top \\ \frac{\partial h_{j+1}}{\partial h_j} &= W^\top (1 - h_{j+1}^2) \\ \frac{\partial h_k}{\partial U} &= (1 - h_k^2) x_k \end{aligned}$$

In this case, The Analytical Derivatives of Eq. (12) becomes:

$$\frac{\partial L}{\partial W} = \sum_{t=1}^S \left( \sum_{k=1}^t (y_t - \hat{y}_t) V^\top \prod_{j=k}^{t-1} \left( W^\top (1 - h_{j+1}^2) \right) (1 - h_k^2) h_{k-1} \right) \quad (13)$$

## 2.7 Derivative of $b$

Now, let's derive the gradient with respect to  $b$ . Similarly, we calculate the gradient with respect to  $b$  like Eq. (12) as follows:

$$\frac{\partial L}{\partial b} = \sum_{t=1}^S \left( \sum_{k=1}^t \frac{\partial L_t}{\partial \hat{y}_t} \frac{\partial \hat{y}_t}{\partial h_t} \prod_{j=k}^{t-1} \left( \frac{\partial h_{j+1}}{\partial h_j} \right) \frac{\partial h_k}{\partial b} \right) \quad (14)$$

we insert the individual partial derivatives to calculate our final gradients of  $L$  with respect to  $W$ , where:

$$\begin{aligned} \frac{\partial L_t}{\partial \hat{y}_t} &= (y_t - \hat{y}_t) \\ \frac{\partial \hat{y}_t}{\partial h_t} &= V^\top \\ \frac{\partial h_{j+1}}{\partial h_j} &= W^\top (1 - h_{j+1}^2) \\ \frac{\partial h_k}{\partial b} &= (1 - h_k^2) \end{aligned}$$

In this case, The Analytical Derivatives of Eq. (14) becomes:

$$\frac{\partial L}{\partial W} = \sum_{t=1}^S \left( \sum_{k=1}^t (y_t - \hat{y}_t) V^\top \prod_{j=k}^{t-1} \left( W^\top (1 - h_{j+1}^2) \right) (1 - h_k^2) \right) \quad (15)$$

## 2.8 Derivative of $E$

ADD THIS ONE TO THE APPENDIX AS TH DIFFERENCE WHEN EMBEDDING LAYERS ARE USED

This function employs recursion, therefore, computing its derivative may take some time.

$$\begin{aligned} x_t &= x_t^o E \\ h_t &= \tanh(W h_{t-1} + U x_t + b) \\ h_1 &= \tanh(W h_0 + U x_1 + b) \quad h_2 = \tanh(W h_1 + U x_2 + b) \\ h_3 &= \tanh(W h_2 + U x_3 + b) \quad h_4 = \tanh(W h_3 + U x_4 + b) \end{aligned}$$

By placing  $h_t$  into the last term, we get:

$$\begin{aligned} h_4 &= \\ &\tanh(W \tanh(W \tanh(W \tanh(W h_0 + U x_1 + b) + U x_2 + b) + U x_3 + b) + U x_4 + b) \end{aligned}$$

We start from the first step go to the last step:

$$\begin{aligned} \frac{\partial L_1}{\partial E} &= \frac{\partial L_1}{\partial \hat{y}_1} \frac{\partial \hat{y}_1}{\partial h_1} \frac{\partial h_1}{\partial x_1} \frac{\partial x_1}{\partial E} \\ \frac{\partial L_2}{\partial E} &= \frac{\partial L_2}{\partial \hat{y}_2} \frac{\partial \hat{y}_2}{\partial h_2} \frac{\partial h_2}{\partial h_1} \frac{\partial h_1}{\partial x_1} \frac{\partial x_1}{\partial E} + \frac{\partial L_2}{\partial \hat{y}_2} \frac{\partial \hat{y}_2}{\partial h_2} \frac{\partial h_2}{\partial x_2} \frac{\partial x_2}{\partial E} \\ \frac{\partial L_3}{\partial E} &= \frac{\partial L_3}{\partial \hat{y}_3} \frac{\partial \hat{y}_3}{\partial h_3} \frac{\partial h_3}{\partial h_1} \frac{\partial h_1}{\partial x_1} \frac{\partial x_1}{\partial E} + \frac{\partial L_3}{\partial \hat{y}_3} \frac{\partial \hat{y}_3}{\partial h_3} \frac{\partial h_3}{\partial h_2} \frac{\partial h_2}{\partial x_2} \frac{\partial x_2}{\partial E} + \frac{\partial L_3}{\partial \hat{y}_3} \frac{\partial \hat{y}_3}{\partial h_3} \frac{\partial h_3}{\partial x_3} \frac{\partial x_3}{\partial E} \\ \frac{\partial L_4}{\partial W} &= \frac{\partial L_4}{\partial \hat{y}_4} \frac{\partial \hat{y}_4}{\partial h_4} \frac{\partial h_4}{\partial h_1} \frac{\partial h_1}{\partial x_1} \frac{\partial x_1}{\partial E} + \frac{\partial L_4}{\partial \hat{y}_4} \frac{\partial \hat{y}_4}{\partial h_4} \frac{\partial h_4}{\partial h_2} \frac{\partial h_2}{\partial x_2} \frac{\partial x_2}{\partial E} + \frac{\partial L_4}{\partial \hat{y}_4} \frac{\partial \hat{y}_4}{\partial h_4} \frac{\partial h_4}{\partial h_3} \frac{\partial h_3}{\partial x_3} \frac{\partial x_3}{\partial E} \\ &\quad + \frac{\partial L_4}{\partial \hat{y}_4} \frac{\partial \hat{y}_4}{\partial h_4} \frac{\partial h_4}{\partial x_4} \frac{\partial x_4}{\partial E} \end{aligned}$$

Simplifying:

$$\begin{aligned}
\frac{\partial L_1}{\partial E} &= \frac{\partial L_1}{\partial \hat{y}_1} \frac{\partial \hat{y}_1}{\partial h_1} \frac{\partial h_1}{\partial x_1} \frac{\partial x_1}{\partial E} \\
\frac{\partial L_2}{\partial E} &= \frac{\partial L_2}{\partial \hat{y}_2} \frac{\partial \hat{y}_2}{\partial h_2} \frac{\partial h_2}{\partial h_1} \frac{\partial h_1}{\partial x_1} \frac{\partial x_1}{\partial E} + \frac{\partial L_2}{\partial \hat{y}_2} \frac{\partial \hat{y}_2}{\partial h_2} \frac{\partial h_2}{\partial x_2} \frac{\partial x_2}{\partial E} \\
\frac{\partial L_3}{\partial E} &= \frac{\partial L_3}{\partial \hat{y}_3} \frac{\partial \hat{y}_3}{\partial h_3} \frac{\partial h_3}{\partial h_1} \frac{\partial h_1}{\partial x_1} \frac{\partial x_1}{\partial E} + \frac{\partial L_3}{\partial \hat{y}_3} \frac{\partial \hat{y}_3}{\partial h_3} \frac{\partial h_3}{\partial h_2} \frac{\partial h_2}{\partial x_2} \frac{\partial x_2}{\partial E} + \frac{\partial L_3}{\partial \hat{y}_3} \frac{\partial \hat{y}_3}{\partial h_3} \frac{\partial h_3}{\partial x_3} \frac{\partial x_3}{\partial E} \\
\frac{\partial L_4}{\partial E} &= \frac{\partial L_4}{\partial \hat{y}_4} \frac{\partial \hat{y}_4}{\partial h_4} \frac{\partial h_4}{\partial h_1} \frac{\partial h_1}{\partial x_1} \frac{\partial x_1}{\partial E} + \frac{\partial L_4}{\partial \hat{y}_4} \frac{\partial \hat{y}_4}{\partial h_4} \frac{\partial h_4}{\partial h_2} \frac{\partial h_2}{\partial x_2} \frac{\partial x_2}{\partial E} + \frac{\partial L_4}{\partial \hat{y}_4} \frac{\partial \hat{y}_4}{\partial h_4} \frac{\partial h_4}{\partial h_3} \frac{\partial h_3}{\partial x_3} \frac{\partial x_3}{\partial E} \\
&\quad + \frac{\partial L_4}{\partial \hat{y}_4} \frac{\partial \hat{y}_4}{\partial h_4} \frac{\partial h_4}{\partial x_4} \frac{\partial x_4}{\partial E}
\end{aligned}$$

Since the calculation process needs to be simplified, let's expand  $\frac{h_t}{h_k}$

$$\begin{aligned}
\frac{\partial L_1}{\partial E} &= \frac{\partial L_1}{\partial \hat{y}_1} \frac{\partial \hat{y}_1}{\partial h_1} \frac{\partial h_1}{\partial x_1} \frac{\partial x_1}{\partial E} \\
\frac{\partial L_2}{\partial E} &= \frac{\partial L_2}{\partial \hat{y}_2} \frac{\partial \hat{y}_2}{\partial h_2} \frac{\partial h_2}{\partial h_1} \frac{\partial h_1}{\partial x_1} \frac{\partial x_1}{\partial E} + \frac{\partial L_2}{\partial \hat{y}_2} \frac{\partial \hat{y}_2}{\partial h_2} \frac{\partial h_2}{\partial x_2} \frac{\partial x_2}{\partial E} \\
\frac{\partial L_3}{\partial E} &= \frac{\partial L_3}{\partial \hat{y}_3} \frac{\partial \hat{y}_3}{\partial h_3} \frac{\partial h_3}{\partial h_2} \frac{\partial h_2}{\partial h_1} \frac{\partial h_1}{\partial x_1} \frac{\partial x_1}{\partial E} + \frac{\partial L_3}{\partial \hat{y}_3} \frac{\partial \hat{y}_3}{\partial h_3} \frac{\partial h_3}{\partial h_2} \frac{\partial h_2}{\partial x_2} \frac{\partial x_2}{\partial E} + \frac{\partial L_3}{\partial \hat{y}_3} \frac{\partial \hat{y}_3}{\partial h_3} \frac{\partial h_3}{\partial x_3} \frac{\partial x_3}{\partial E} \\
\frac{\partial L_4}{\partial E} &= \frac{\partial L_4}{\partial \hat{y}_4} \frac{\partial \hat{y}_4}{\partial h_4} \frac{\partial h_4}{\partial h_3} \frac{\partial h_3}{\partial h_2} \frac{\partial h_2}{\partial h_1} \frac{\partial h_1}{\partial x_1} \frac{\partial x_1}{\partial E} + \frac{\partial L_4}{\partial \hat{y}_4} \frac{\partial \hat{y}_4}{\partial h_4} \frac{\partial h_4}{\partial h_3} \frac{\partial h_3}{\partial h_2} \frac{\partial h_2}{\partial x_2} \frac{\partial x_2}{\partial E} + \frac{\partial L_4}{\partial \hat{y}_4} \frac{\partial \hat{y}_4}{\partial h_4} \frac{\partial h_4}{\partial h_3} \frac{\partial h_3}{\partial x_3} \frac{\partial x_3}{\partial E} \\
&\quad + \frac{\partial L_4}{\partial \hat{y}_4} \frac{\partial \hat{y}_4}{\partial h_4} \frac{\partial h_4}{\partial x_4} \frac{\partial x_4}{\partial E}
\end{aligned}$$

Let us group them under a  $\sum \prod$  for step  $t$ :

$$\frac{\partial L_t}{\partial E} = \sum_{k=1}^t \frac{\partial L_t}{\partial \hat{y}_t} \frac{\partial \hat{y}_t}{\partial h_t} \prod_{j=k}^{t-1} \left( \frac{\partial h_{j+1}}{\partial h_j} \right) \frac{\partial h_k}{\partial x_k} \frac{\partial x_k}{\partial E}$$

Let us now present the formula for  $\mathcal{S}$  steps:

$$\frac{\partial L}{\partial E} = \sum_{t=1}^{\mathcal{S}} \left( \sum_{k=1}^t \frac{\partial L_t}{\partial \hat{y}_t} \frac{\partial \hat{y}_t}{\partial h_t} \prod_{j=k}^{t-1} \left( \frac{\partial h_{j+1}}{\partial h_j} \right) \frac{\partial h_k}{\partial x_k} \frac{\partial x_k}{\partial E} \right) \quad (16)$$

Finally, we insert the individual partial derivatives to calculate our final gradients of  $L$  with respect to  $W$ , where:



$$\begin{aligned}
\frac{\partial L_t}{\partial \hat{y}_t} &= (y_t - \hat{y}_t) \\
\frac{\partial \hat{y}_t}{\partial h_t} &= V^\top \\
\frac{\partial h_{j+1}}{\partial h_j} &= W^\top (1 - h_{j+1}^2) \\
\frac{\partial h_k}{\partial x_k} &= (1 - h_k^2) U \\
\frac{\partial x_k}{\partial E} &= x_k^o
\end{aligned}$$

In this case, The Analytical Derivatives of Eq. (16) becomes:

$$\frac{\partial L}{\partial E} = \sum_{t=1}^S \left( \sum_{k=1}^t (y_t - \hat{y}_t) V^\top \prod_{j=k}^{t-1} \left( W^\top (1 - h_{j+1}^2) \right) (1 - h_k^2) U x_k^o \right) \quad (17)$$