

THE UNIVERSITY OF TEXAS AT AUSTIN

EE381V LARGE SCALE OPTIMIZATION

Problem Set 1

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Chapter 1

Matlab and Computational Assignment

Appendix A

Codes Printout

A.1 Orthogonal Matching Pursuit

A.1.1 OMP Routine

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%% Orthogonal matching Pursuit
function Iset = omp (X, y, SPARSITY)
%% INITIALIZATION
[target_feat_dot_prod, target_feat_idx] = max(X' * y);
Iset = [target_feat_idx];
%% AUGMENTATION
residual = y;
for iter = 1:(SPARSITY-1),
           \mbox{\ensuremath{\$}} perpendicular complement of y to X_i
           phi = X(:, Iset);
           P = phi * inv(phi'*phi) * phi';
           I = eye(size(P));
           residual = (I - P) * residual;
           % elect new atom and add to selected atom set
           [target_feat_dot_prod, target_feat_idx] = max(X' * residual);
           % NOTE that new feature(atom) will not pre-exist in Iset
           % This is theoreotically guaranteed by orthogonal projection
           Iset = [Iset, target_feat_idx];
end
```

A.1.2 Regression Script

```
%%% Invoke CVX least square regression after OMP
%%% feature selection
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SPARSITY = 5; % SPARSITY parameter for OMP
%%% Small-scale dataset
tic
Iset1 = omp(X1, y1, SPARSITY);
subX1 = X1(:, Iset1);
cvx_begin
               variable sub_b1(SPARSITY);
               minimize(norm(subX1 * sub_b1 - y1))
toc
Tset.1
RegressionError1 = norm(subX1*sub_b1 - y1)
TestingError1 = norm(X1test(:,Iset1)*sub_b1 - y1test)
\(\frac{1}{2}\) \(\frac{1}2\) \(\frac{1}2\) \(\frac{1}2\) \(\frac{1}2\) \(\frac{1}2\) \(\frac{1}2\) \(\frac{1}
%%% Medium-scale dataset
Iset2 = omp(X2, y2, SPARSITY);
subX2 = X2(:, Iset2);
cvx_begin
              variable sub_b2(SPARSITY);
               minimize(norm(subX2 * sub_b2 - y2))
cvx end
toc
Tset.2
RegressionError2 = norm(subX2*sub_b2 - y2)
TestingError2 = norm(X2test(:,Iset2)*sub_b2 - y2test)
%%% Large-scale dataset
Iset3 = omp(X3, y3, SPARSITY);
subX3 = X3(:, Iset3);
cvx_begin
               variable sub_b3(SPARSITY);
              minimize(norm(subX3 * sub_b3 - y3))
cvx_end
toc
Tset.3
RegressionError3 = norm(subX3*sub_b3 - y3)
TestingError3 = norm(X3test(:,Iset3)*sub_b3 - y3test)
```