

# Evolutionary Computation

- Computational procedures patterned after biological evolution.
- Search procedure that probabilistically applies search operators to set of points in the search space.
- Lamarck and others:  
Species transmute over time
- Darwin and Wallace:  
Consistent, heritable variation among individuals in population  
Natural selection of the fittest
- Mendel and genetics:  
A mechanism for inheriting traits  
genotype -> phenotype mapping
- Types of evolutionary computation (EC):
  - . Genetic Algorithm (GA)
  - . Genetic Programming (GP)
  - . Evolutionary Strategy (ES)
  - . Evolutionary Programming (EP)

- **Foundations of genetic algorithms (GAs):  
some major questions**

- (1) What are the law describing the behavior of schemas in GAs?
- (2) How can we characterize the types of fitness landscapes on which the GA is likely to perform well?
- (3) What does it mean for a GA to perform well? That is, what is the GA good at doing?
- (4) How can we characterize the types of fitness landscapes on which the GA outperforms other search methods, eg. hill-climbing?

- **Some implementation issues for genetic algorithms**

- . **Representation:**

How to best encode the problem to be solved.

- . **Fitness scaling:**

How to scale fitness to maintain constant population and to achieve the best rate of evolution.

- . **Genetic operators:**

Which operators to use; how often to apply various operators.

- . **Population size**

- . **Maintaining diversity in the population  
(to prevent the premature convergence)**

## - Basic genetic algorithm

```
begin
  initialize the generation number:  $t \leftarrow 0$ 
  initialize the population at  $t$ :  $P(t)$ 
  while (not termination-condition) do
    begin
       $t \leftarrow t + 1$ 
      select  $P(t)$  from  $P(t-1)$ 
      recombine  $P(t)$ 
      evaluate  $P(t)$ 
    end
  end
end
```

## - Example of genetic algorithm

. maximize a function of  $k$  variables:

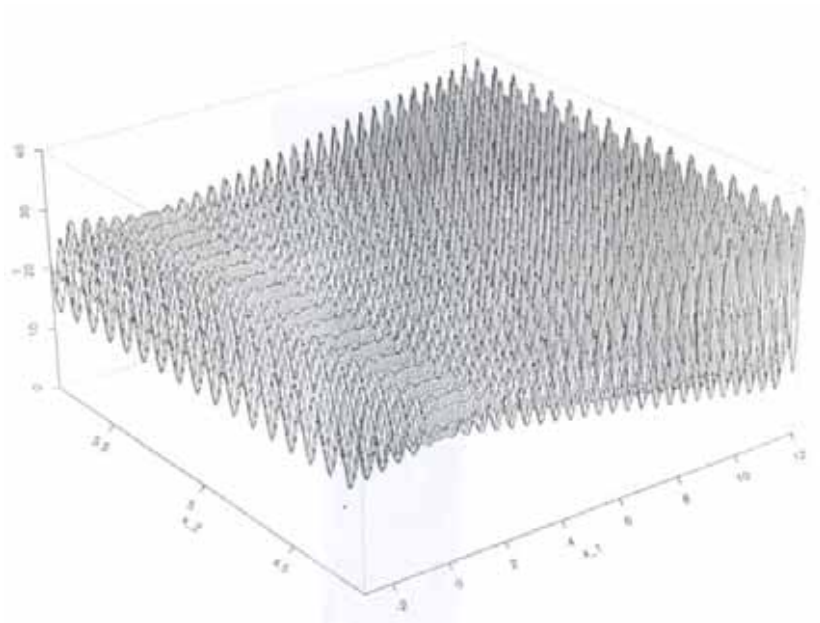
$$f(x_1, \dots, x_k): R^k \rightarrow R$$

where  $x_i \in [a_i, b_i]$ .

eg.  $f(x_1, x_2) = 21.5 + x_1 \sin(4\pi x_1) + x_2 \sin(20\pi x_2)$

where  $-3.0 \leq x_1 \leq 12.1$  and  $4.1 \leq x_2 \leq 5.8$ .

. The plot of  $f(x_1, x_2) = 21.5 + x_1 \sin(4\pi x_1) + x_2 \sin(20\pi x_2)$ :



. Encoding of  $x_i$

We will consider the bit string for each  $x_i$ .

Let the required precision be 6 decimal places.

Then,

$$(b_i - a_i) \cdot 10^6 \leq 2^{m_i} - 1$$

where  $m_i$  represents the smallest integer for binary representation.

Each bit string is interpreted by

$$x_i = a_i + \text{deciaml}(m_i \text{ bits}) \cdot \frac{b_i - a_i}{2^{m_i} - 1}.$$

For the given function  $f(x_1, x_2)$ , the input range is given by

$$-3.0 \leq x_1 \leq 12.1 \quad \text{and} \quad 4.1 \leq x_2 \leq 5.8.$$

Let us consider 4 decimal digit precision for  $x_1$  and  $x_2$ , that is,

$$2^{17} < 15.1 \cdot 10^4 \leq 2^{18} \quad \text{and} \quad 2^{14} < 1.7 \cdot 10^4 \leq 2^{15}.$$

In this case, we need  $m = 18 + 15 = 33$  bits to encode a  $(x_1, x_2)$  pair, that is, each chromosome has 33 bits.

An example of chromosome:

(010001001011010000111110010100010)

The first 18 bits 010001001011010000 represents

$$x_1 = -3.0 + \text{decimal}(010001001011010000_2) \cdot \frac{12.1 - (-3.0)}{2^{18} - 1} = 1.052426.$$

The next 15 bits 111110010100010 represents

$$x_2 = 4.1 + \text{decimal}(111110010100010_2) \cdot \frac{5.8 - 4.1}{2^{15} - 1} = 5.755330.$$

So the chromosome

(010001001011010000111110010100010)

corresponds to  $(x_1, x_2) = (1.052426, 5.755330)$ .

The fitness value for this chromosome is

$$f(1.052426, 5.755330) = 20.252640.$$

## . Evaluation

The fitness of the population is measured by

$$F = \sum_{i=1}^N eval(v_i)$$

where  $N$  represents the population size and  $eval(v_i)$  represents the fitness value for each chromosome  $v_i$ .

**eg.**  $v_i = (m_1 \text{ bit string for } x_1, m_2 \text{ bit string for } x_2)$

$$v_i \rightarrow (x_1, x_2) \quad (\text{decoding})$$

$$eval(v_i) = f(x_1, x_2)$$

## . initial population:

```
v1 = (100110100000001111111010011011111)
v2 = (111000100100110111001010100011010)
v3 = (000010000011001000001010111011101)
v4 = (100011000101101001111000001110010)
v5 = (000111011001010011010111111000101)
v6 = (000101000010010101001010111111011)
v7 = (001000100000110101111011011111011)
v8 = (100001100001110100010110101100111)
v9 = (010000000101100010110000001111100)
v10 = (000001111000110000011010000111011)
v11 = (011001111110110101100001101111000)
v12 = (110100010111101101000101010000000)
v13 = (111011111010001000110000001000110)
v14 = (010010011000001010100111100101001)
v15 = (1110111011011110000100011111011110)
v16 = (110011110000011111100001101001011)
v17 = (011010111111001111010001101111101)
v18 = (011101000000001110100111110101101)
v19 = (000101010011111111110000110001100)
v20 = (101110010110011110011000101111110)
```

. evaluation of the fitness function values:

```
eval(v1) = f(6.084492, 5.652242) = 26.019600  
eval(v2) = f(10.348434, 4.380264) = 7.580015  
eval(v3) = f(-2.516603, 4.390381) = 19.526329  
eval(v4) = f(5.278638, 5.593460) = 17.406725  
eval(v5) = f(-1.255173, 4.734458) = 25.341160  
eval(v6) = f(-1.811725, 4.391937) = 18.100417  
eval(v7) = f(-0.991471, 5.680258) = 16.020812  
eval(v8) = f(4.910618, 4.703018) = 17.959701  
eval(v9) = f(0.795406, 5.381472) = 16.127799  
eval(v10) = f(-2.554851, 4.793707) = 21.278435  
eval(v11) = f(3.130078, 4.996097) = 23.410669  
eval(v12) = f(9.356179, 4.239457) = 15.011619  
eval(v13) = f(11.134646, 5.378671) = 27.316702  
eval(v14) = f(1.335944, 5.151378) = 19.876294  
eval(v15) = f(11.089025, 5.054515) = 30.060205  
eval(v16) = f(9.211598, 4.993762) = 23.867227  
eval(v17) = f(3.367514, 4.571343) = 13.696165  
eval(v18) = f(3.843020, 5.158226) = 15.414128  
eval(v19) = f(-1.746635, 5.395584) = 20.095903  
eval(v20) = f(7.935998, 4.757338) = 13.666916
```

. selection (roulette wheel selection)

The probability of selection  $p_i$  for each  $v_i$  is given by

$$p_i = \text{eval}(v_i) / F.$$

Then, the cumulative probability  $q_i$  for each  $v_i$  is given by

$$q_i = \sum_{j=1}^i p_j.$$

selection process:

(1) Generate a random number  $r \in [0,1]$ .

(2) If  $r < q_1$ , select  $v_1$ .

Otherwise, select  $v_i$  such that  $q_{i-1} < r \leq q_i$ .

As a result, we construct a new population.

. the probability of a selection  $p_i$  for each chromosome  $v_i$ :

$$\begin{array}{ll} p_1 = eval(v_1)/F = 0.067099 & p_2 = eval(v_2)/F = 0.019547 \\ p_3 = eval(v_3)/F = 0.050355 & p_4 = eval(v_4)/F = 0.044889 \\ p_5 = eval(v_5)/F = 0.065350 & p_6 = eval(v_6)/F = 0.046677 \\ p_7 = eval(v_7)/F = 0.041315 & p_8 = eval(v_8)/F = 0.046315 \\ p_9 = eval(v_9)/F = 0.041590 & p_{10} = eval(v_{10})/F = 0.054873 \\ p_{11} = eval(v_{11})/F = 0.060372 & p_{12} = eval(v_{12})/F = 0.038712 \\ p_{13} = eval(v_{13})/F = 0.070444 & p_{14} = eval(v_{14})/F = 0.051257 \\ p_{15} = eval(v_{15})/F = 0.077519 & p_{16} = eval(v_{16})/F = 0.061549 \\ p_{17} = eval(v_{17})/F = 0.035320 & p_{18} = eval(v_{18})/F = 0.039750 \\ p_{19} = eval(v_{19})/F = 0.051823 & p_{20} = eval(v_{20})/F = 0.035244 \end{array}$$

. recombination process:

(1) cross-over

the probability of cross-over:  $p_c$

for each chromosome in the (new) population,

(a) generate a random number  $r \in [0,1]$ .

(b) if  $r < p_c$ , select the given chromosome for cross-over.

mate the selected chromosomes randomly.

for each pair of coupled chromosomes, generate

a random integer  $\in [1, \dots, m-1]$ . (one-point cross-over)



eg.  $(b_1, b_2, \dots, b_{pos}, b_{pos+1}, \dots, b_m) \dashrightarrow (b_1, b_2, \dots, b_{pos}, c_{pos+1}, \dots, c_m)$   
 $(c_1, c_2, \dots, c_{pos}, c_{pos+1}, \dots, c_m) \dashrightarrow (c_1, c_2, \dots, c_{pos}, b_{pos+1}, \dots, b_m)$

## (2) mutation

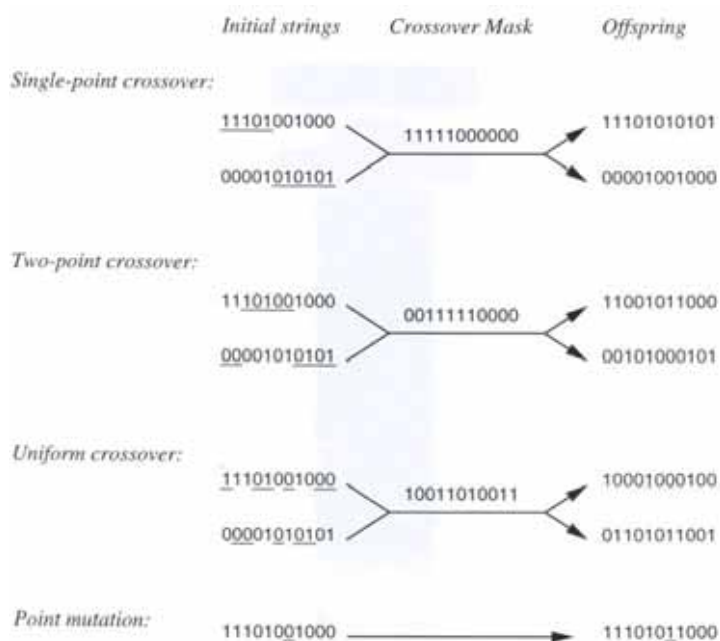
the probability of mutation:  $p_m$

for each bit within the chromosome,

(a) generate a random number  $r \in [0,1]$ .

(b) if  $r < p_m$ , mutate the bit ( $0 \rightarrow 1, 1 \rightarrow 0$ ).

## . cross-over and mutation operators



- **Schema theorem (Holland, 1975)**

- . Schema: any string composed of 0s, 1s, and \*s.
- . Schema theorem characterizes the evolution of population by the number of instances representing each possible schema.

Let  $m(s,t)$  be the number of instances of schema  $s$  in population at time  $t$ .

Then, what is  $E[m(s,t+1)]$  in terms of  $m(s,t)$ ?

Here, we consider

$f(h)$  = the fitness of the individual bit string  $h$ ,

$\bar{f}(t)$  = the average fitness of the population at time  $t$ ,

$n$  = the total number of individuals in the population,

$h \in s \cap P_t$ , that is, the individual  $h$  is both a representative of schema  $s$  and a member of the population at time  $t$ , and  
 $\hat{u}(s,t)$  = the average fitness of instances of schema  $s$  in the population at time  $t$ .

- . The probability of selecting  $h$  in one selection step:

$$\Pr\{h\} = \frac{f(h)}{\sum_{i=1}^n f(h_i)} = \frac{f(h)}{n\bar{f}(t)}$$

- . The probability of selecting an instance of  $s$ :

$$\Pr\{h \in s\} = \sum_{h \in s \cap P_t} \frac{f(h)}{n\bar{f}(t)} = \frac{\hat{u}(s,t)m(s,t)}{n\bar{f}(t)}$$

- . The expected number of instances of  $s$  resulting from the  $n$  independent selection steps that create the entire new generation is given by

$$E[m(s, t+1)] = n \cdot \Pr\{h \in s\} = \frac{\hat{u}(s, t)m(s, t)}{\bar{f}(t)}. \quad \dots \quad (1)$$

- . recombination process: cross-over

Let  $d(s)$  be the distance between the leftmost and rightmost defined bits in  $s$  and  $l$  be the length of the individual bit strings. Then, the probability of destruction of a schema  $s$  is given by

$$p_d(s) = \frac{d(s)}{l-1} \quad \text{and}$$

the probability of schema survival is given by

$$p_s(s) = 1 - p_d(s) = 1 - \frac{d(s)}{l-1}.$$

Let  $p_c$  be the probability of cross-over. Then,

$$p_s(s) \geq 1 - p_c \frac{d(s)}{l-1}. \quad \dots \quad (2)$$

- . recombination process: mutation

Let  $p_m$  be the probability of mutation. Then, the probability of single bit survival is  $1 - p_m$  and the probability of schema survival is given by

$$p_s(s) = (1 - p_m)^{o(s)}$$

where  $o(s)$  represents the number of bits (non \*s) in  $s$ .

Since  $p_m \ll 1$  (usually set as  $1/l$ ),

$$p_m \approx 1 - o(s) \cdot p_m \quad \dots \quad (3)$$

Therefore, from (1), (2), and (3),

$$\begin{aligned} E[m(s, t+1)] &\geq \frac{\hat{u}(s, t)m(s, t)}{\bar{f}(t)} \left(1 - p_c \frac{d(s)}{l-1}\right) (1 - p_m)^{o(s)} \\ &\geq \frac{\hat{u}(s, t)m(s, t)}{\bar{f}(t)} \left(1 - p_c \frac{d(s)}{l-1} - o(s)p_m\right) \end{aligned}$$

This implies that the above-average schema with short defining length  $d(s)$  and low-order (small  $o(s)$ ) would still be sampled at exponentially increased rate.

#### . premature convergence (or crowding)

As the number of generations is increased, the chromosomes with high fitness score tend to dominated in the population.

This premature convergence is not desirable from the view point of the diversity of the population.

#### . sharing

To prevent the premature convergence the fitness function is modified by

$$f_s(x_i) = \frac{f(x_i)}{\sum_{j=1}^n s(d(x_i, x_j))}$$

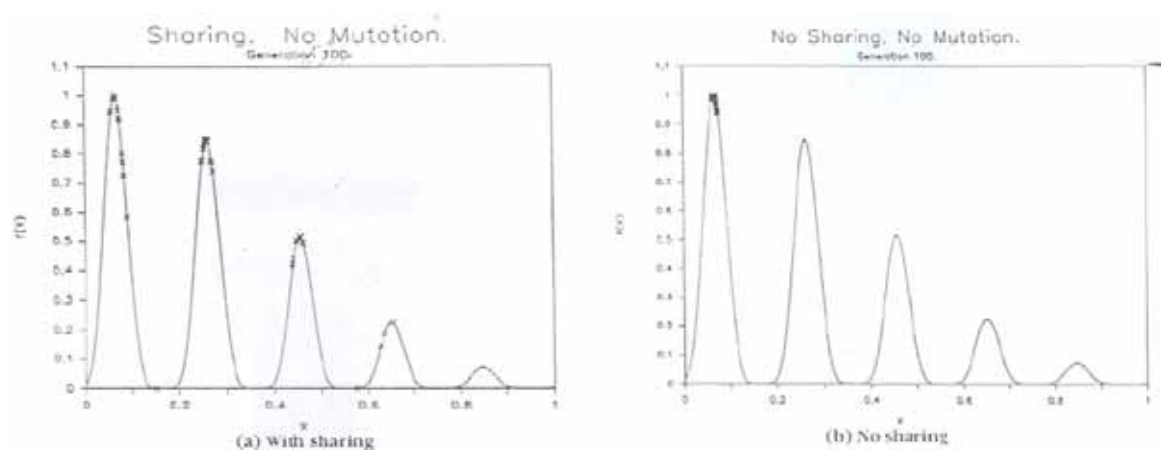
where  $x_i$  represents the  $i$ th chromosome,

$d(x_i, x_j)$  represents the distance between  $x_i$  and  $x_j$ , and  $s(d)$  represents the sharing function.

eg.  $s(d) = \frac{-x}{d_{\max}} + 1$

This sharing function gives more spreading distribution of chromosomes in the solution space.

## . Example of sharing



- **Convergence of genetic algorithm (Rudolph, 1994)**

- . GA can be analysed by a finite Markov chain describing a probability trajectory over a finite state space  $S$  of cardinality  $|S|=N$ .

eg. Let  $l$  be the number of genes and  $n$  be the population size.

Then,  $N=2^{ln}$ .

- . Let us consider the transition matrix  $P=[p_{ij}]$  in which

$$p_{ij} \in [0,1] \quad \text{and} \quad \sum_{j=1}^{|S|} p_{ij} = 1 \quad \forall i \in S.$$

Then, the distribution of the chain after the  $t$ th step is

$$p^t = p^0 P^t$$

where  $p_0$  represents the initial distribution as a row vector.

Here, the homogeneous finite Markov chain

( $P$  is not changing over time) is completely described by a pair  $(p^0, P)$ .

- . **Definitions:**

(1)  $A$  is positive if  $a_{ij} > 0 \quad \forall i, j \in \{1, \dots, n\}$ .

(2)  $A$  is primitive if  $\exists k \in \mathbb{N}$  (integer) such that  $A^k$  is positive.

(3)  $A$  is reducible if  $A$  can be brought into the form

$$\begin{pmatrix} C & O \\ R & T \end{pmatrix}$$

(with square matrices  $C$  and  $T$ ) by applying the same permutations to rows and columns.

(4)  $A$  is stochastic if  $\sum_{j=1}^n a_{ij} = 1 \quad \forall i \in \{1, \dots, n\}$ .

(5)  $A$  is stable if it has identical rows.

. Theorem: Let  $P$  be a *primitive stochastic matrix*. Then,  $p^k$  converges as  $k \rightarrow \infty$  to a positive stable stochastic matrix  $p^\infty$  where  $p^\infty = \lim_{k \rightarrow \infty} P^k = p^0 P^\infty$  has non-zero entries and

is unique regardless of the initial distribution.

. The GA procedure can be described by

$$P = CMS$$

where  $C$ ,  $M$ , and  $S$  describe the intermediate transition caused by cross-over, mutation, and selection.

. Lemma:  $P$  is primitive

(proof)

Since  $C$  is stochastic, there exists at least one positive entry in each row of  $C$ . The matrix  $M$  is positive and  $S$  has at least one positive entry in each column. Thus,  $A = CM$  is positive. Then,  $P = AS$  is positive. Therefore,  $P$  is primitive.

- . Theorem: The GA maintaining the best solution found over time before selection converges globally optimal.

(proof)

Since  $P$  is primitive, there exists  $p^\infty$  which has unique non-zero entries. This implies that  $p_i > 0 \quad \forall i \in S$ .

Since GA keeps the best solution, the globally optimal solution can be found with the probability of 1.

## - Issues on Genetic Algorithms

- . How do they work?

efficient genetic operators

implicit parallelism

- . What are they good for?

How to characterize class of problems on which they will work well?



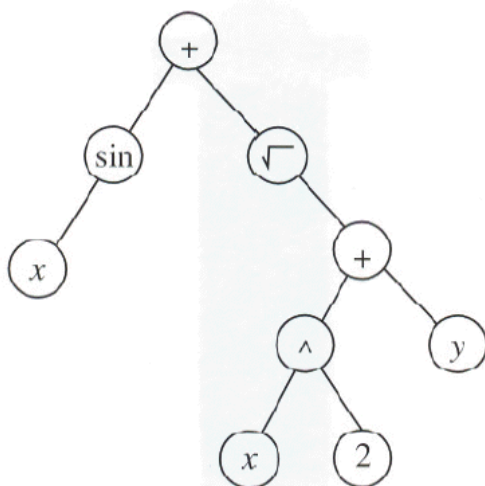
## - Some applications of genetic algorithms

- . optimization  
eg. numerical optimization, circuit design, factory scheduling
- . automatic programming  
eg. evolving optimal sorting algorithms, evolving Lisp programs
- . machine and robot learning  
eg. robot navigation, evolving artificial neural networks
- . complex data analysis and time-series prediction  
eg. weather prediction, financial market prediction,  
protein structure prediction
- . scientific models of adaptive complex systems  
eg. economics, immunology, ecology, population genetics

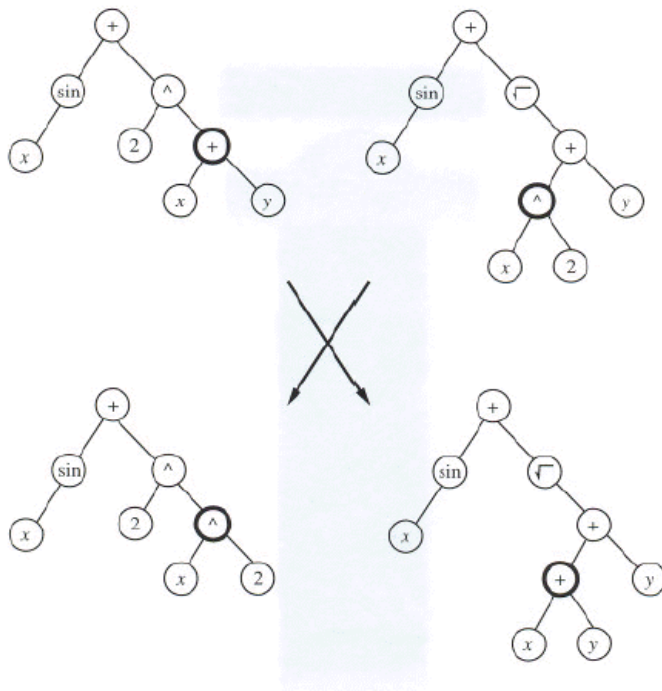
## - Genetic Programming (GP)

- . Programs in population are represented by trees

eg.  $\sin(x) + \sqrt{x^2 + y}$



## . cross-over in GP



## - Evolutionary Computation Conclusions

- . EC defines a class of search methods modeled after natural evolution.
- . Performs a randomized beam search over a hypothesis space.
- . EC methods can search any hypothesis space.
- . Global, multi-point search rather than local, single point search.
- . Do not follow gradients: if gradient information can be efficiently calculated and effective to search the solution, EC method may not be the best search method.
- . Very easy to apply to a wide range of problems.

## - References

- [illegible]