

Concepts of C++ Programming (Exercises)

winter semester 2023

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Computational Imaging and Inverse Problems (CIIP)
Technical University of Munich



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Homework 1

Who?

- Lecture:
 - PD Dr. Tobias Lasser
 - Computational Imaging and Inverse Problems (CIIP)
- Exercises:
 - First half: Jonas Jelten
 - Second half: David Frank

What?

Aim of the exercises:

- study the **concepts** of **modern C++** programming
- learn to apply those concepts in **elegant** and **efficient** solutions

Target audience:

- Bachelor students of Informatics (3rd term onwards)
- Master students of Informatics, BMC, CSE, Robotics
- anyone who is interested!

When and where?

Dates, places, and links

- Tuesday, 14:15 - 15:45, Interims II Hörsaal 2 (003)
 - Live Stream, recording: <https://live.rbg.tum.de/>
- Thursday, 17:00 - 18:30, Galileo Hörsaal (8120.EG.001) (you are here)
 - Video conference: <https://bbb.rbg.tum.de/tob-w3o-4un-gp6> (no recording!)
 - Tweedback: <https://tweedback.de/>

Generally:

- Tuesday: lecture
- Thursday: exercises

Tweedback Session-ID today: zy98

- URL: <https://tweedback.de/zy98>

Online resources

Chat platform

<https://zulip.cit.tum.de>, Streams [#CPP](#) and [#CPP Homeworks](#)

- discussions, answering questions
- automatic announcements of GitLab changes in the *Tasks* repository

Moodle course

<https://www.moodle.tum.de/course/view.php?id=90655>

- news and announcements
- materials (slides, exercise sheets etc.)

Website

https://ciip.cit.tum.de/teaching/cpp_ws23.html

Homework assignments: brief details

- One [homework assignment](#) every Thursday via Moodle
- [Deadline](#) for automated tests to pass: [+1 week](#) (Thursday 17:00)
- Your solutions have to be uploaded to a [GitLab repository](#)
- If there are any issues: use our chat at <https://zulip.cit.tum.de>, stream [#CPP Homeworks](#)
- **How to get access to your GitLab repository:**
 - log in to <https://gitlab.lrz.de>
 - edit your name (Profile, Account, Username) if you wish
 - in Moodle: go to "Add your GitLab username" activity
 - add your GitLab profile username (without @ or <https://gitlab.lrz.de/>)
(check <https://gitlab.lrz.de/-/profile/account> if unsure)
 - request access for the [Waiting Room](#) at <https://gitlab.lrz.de/cppcourse/ws2023/waiting-room>
 - your personal repository will be setup automatically

Exercise format

- Homework:
 - weekly programming assignments
 - exercises are checked automatically
 - submission possible until 1 week after the session (until Thursday 17:00)
 - Exercise Session:
 - discuss the previous week's assignments
 - reinforce topics from the lecture
 - small in-class programming exercises
 - give some pointers to the current exercise sheet
 - allow you to work on & ask about the current exercise sheet
-
- all materials will be available in Moodle
 - the level of interaction is up to you!

Homework Points

Homework \neq Bonus

Homework points are **part** of the exam **not a bonus**.

- Doing the homework makes it easier to pass the exam
- You can pass the exam without doing the homework

Please note

The exercises are quite new.

→ any feedback from you is welcome!

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Required tools

"Programming is learned by writing programs."

–Brian Kernighan

- Start by getting familiar with important tools, such as
 - your [operating system](#) (Linux, ...) + text editor
 - a [C++ compiler](#) (typically [gcc](#) and [clang](#))
 - a [text editor](#) (IDE)
 - [git](#) for source code management
 - [CMake](#) for build automation and dependency management (next week)
 - a [debugger](#) (such as [lldb](#) or [gdb](#)) for debugging (next week)

- Why an IDE?
 - syntax coloring
 - auto completion
 - static code analysis
 - facilitates debugging
 - interfaces with other tools

The screenshot shows an IDE window with a project explorer on the left and a code editor on the right. The project explorer lists various files and folders, including 'ELSA', 'glib', 'vscode', 'cmake', 'docs', 'core', 'Descriptions', 'Handlers', 'Tests', 'Utilities', 'Backtrace.cpp', 'Backtrace.h', 'CMakeLists.txt', 'Complex.h', 'DataContainer.cpp', 'DataContainer.h', 'DataContainerIterator.h', 'DiskWarnings.h', 'ElsaDefines.cpp', 'ElsaDefines.h', 'Error.cpp', 'Error.h', 'Expression.h', 'ExpressionPredictor.h', 'Geometry.cpp', 'Geometry.h', 'LinearOperator.cpp', 'LinearOperator.h', 'StringTypes.cpp', 'StringTypes.h', 'Functionals', 'Generators', 'W', 'Logging', 'Operators', 'Problems', 'Projectors', 'Projectors.cu', 'ProximityOperators', 'Quickvec', 'Solvers', 'Test_Utilities', 'CMakeLists.txt', 'Elsa.h', 'Examples', 'pybind', 'Tools', 'Elang-format', 'Elang-fidy', and 'Elang-format.py'. The code editor displays the contents of 'Geometry.cpp', which includes headers for 'Geometry.h', 'cmath', 'stdexcept', and 'Eigen/Dense'. The code defines a namespace 'elsa' and a sub-namespace 'geometry'. It then defines a struct 'Geometry' with various attributes and methods, including 'SetupRotation' and 'SetupScalingMatrix'. The code is syntax-highlighted, with comments in green, keywords in blue, and identifiers in black. A tooltip is visible over the 'auto' keyword in the 'SetupRotation' method, showing its definition: 'auto [volSpacing, s] long double cos(long double ...)'.

```

1 #include "Geometry.h"
2
3 #include <cmath>
4 #include <stdexcept>
5
6 #include <Eigen/Dense>
7
8 namespace elsa
9 {
10     using namespace geometry;
11
12     Geometry::Geometry(SourceToCenterOfRotation sourceToCenterOfRotation,
13                       CenterOfRotationIsDetector centerOfRotationIsDetector, Radian angle,
14                       VolumeData2D&& volData, SinogramData2D&& sinoData,
15                       PrincipalPointOffset offset, RotationOffset2D centerOfRotOffset)
16     : _objectDimension(2),
17       _P(RealMatrix::Identity(2, 2 + 1)),
18       _Pin(RealMatrix::Identity(2 + 1, 2)),
19       _K(RealMatrix::Identity(4, 2)),
20       _B(RealMatrix::Identity(2, 2)),
21       _t(RealVector::Zero(2)),
22       _S(RealMatrix::Identity(2 + 1, 2 + 1)),
23       _C(RealVector::Zero(2))
24     {
25         auto [volSpacing, vo] long double cos(long double ...)
26         auto [sinoSpacing, s] Transcendentals:
27         // setup rotation as 1/5 Return complex cosine of @a z.
28         real_t c = std::cos();
29         real_t s = std::sin(angle);
30         _R << -s, s, c;
31
32         // setup scaling matrix _S
33         _S << volSpacing[0], 0, 0, 0, volSpacing[1], 0, 0, 0, 1;
34
35         // set the translation _t
36         // auto centerOfRotationOffset = static_cast<RealVector_t>(centerOfRotOffset);
37         // auto centerOfRotationOffset = centerOfRotationOffset, centerOfRotationOffset;
38
39         _t = _R * (-centerOfRotOffset.get() - volOrigin);
40         _t[_objectDimension - 1] += sourceToCenterOfRotation;
41
42         // set the intrinsic parameters _K
43         real_t alpha = sinoSpacing[0];
44     }
45 }

```

IDE choices

- All have pros/cons, just choose by preference
- Free open-source software:
 - Emacs (← editor for a lifetime)
 - Doom + lsp + clangd + projectile + magit + ...
 - Vim
 - neovim + YouCompleteMe + clangd
 - Eclipse
 - QtCreator
 - Code::Blocks
 - Visual Studio Code (currently most popular)
- Proprietary:
 - Sublime
 - Visual Studio
 - CLion

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Survey

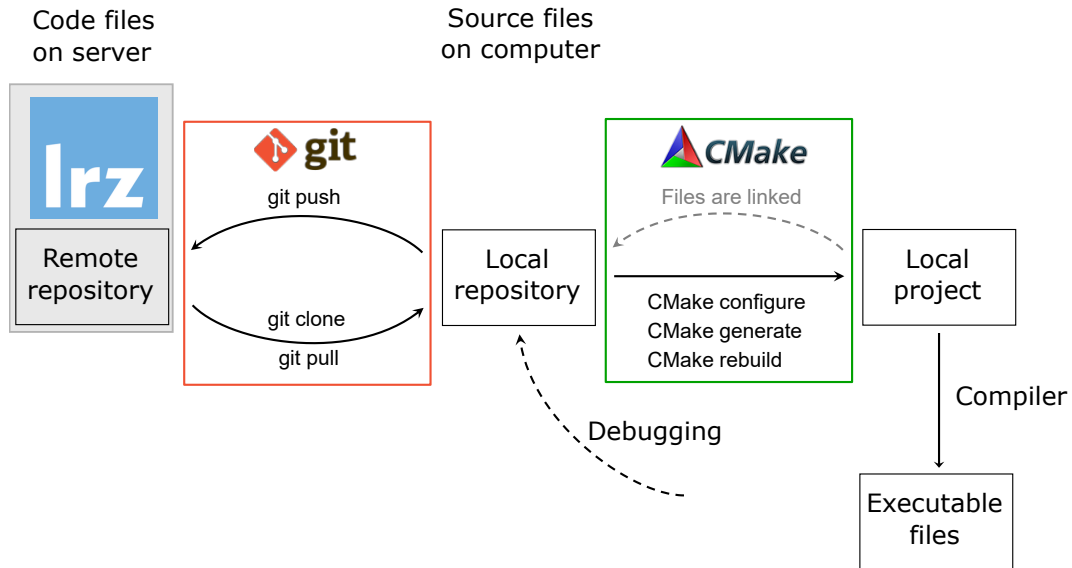
- How familiar are you with [git](#)? → Tweedback
- How familiar are you with [GitLab](#)? → Tweedback

- Version control system to
 - track file history
 - facilitate collaboration across contributors
 - provide a central remote repository
- Can be used from either the command line, a GUI, or through the IDE
- Other alternatives include SVN, CVS, Mercurial, ...

What does `git` do?

Store a named snapshot history of files and distribute them across various locations (local folders, computers, GitLab, ...)

Homework repositories



Git terminology

- **repository**: a place to store your code
- **clone**: creates a local copy of a (remote) repository
- **fork**: creates an *independent* server-side copy of a repository
- **pull**: updates the local repository with new remote changes
- **checkout**: change to/creates a branch (version) of the project
- **commit**: track the specified changes of the local repository
 - the modified files to update need to be **staged**
 - provides a snapshot of the project as possible reference/fallback point
- **push**: updates the repository with the local changes
 - ensures that the local version is compatible with the remote one
 - might involve **merging** local and remote changes
- learn more about git: <https://try.github.io/>

Git workflows

- first time setup

```
git clone <repository>
```

- getting new changes
(origin or upstream)

```
git pull <source>
```

- doing work

```
# make some changes  
git add <changed files>  
git commit  
git push  
# continue working ...
```

- try it at <https://git-school.github.io/visualizing-git/#upstream-changes>
- check for changes

```
git pull
```

- create an empty commit

```
git commit --allow-empty -m "Hello!"
```

- push the changes to the server

```
git push
```

- open source web-based git repository manager
 - server is mainly written in Ruby, PostgreSQL, Redis
 - Vue.js webui
- provides additional features to work with
 - graphical visualization of development history
 - issue tracking
 - project wikis
- basically the free-software GitHub alternative
- the LRZ hosts gitlab at `gitlab.lrz.de`

In-class Exercise

Let's simulate the homework `git` workflow with local git repositories.

- Create a `tasks` repository and a fork `username_tasks`.
- Submit changes to our repository, i.e., `push` to origin
- Get the new homework, i.e., `pull` from upstream
- Overwrite our local changes, i.e., `restore`

Creating a new GitLab Repository

- A **repository** is just a directory + git metadata
- These directories have a `.git` suffix by convention
- We use the `--bare` flag to not check out a branch

```
# Creating a git repository
mkdir /tmp/git-example/gitlab/tasks.git
cd /tmp/git-example/gitlab/tasks.git
git init --bare
```

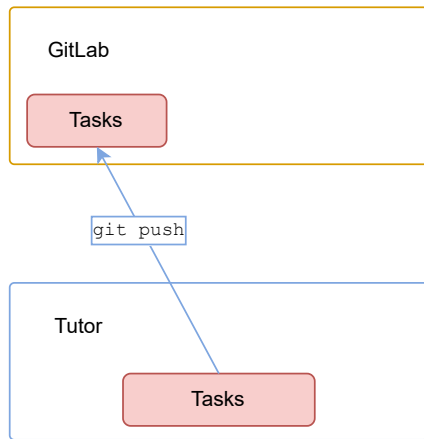
GitLab

Tasks

Adding a README

```
# Adding a README to the Tasks repository
mkdir /tmp/git-example/tutor
cd /tmp/git-example/tutor
git clone /tmp/git-example/gitlab/tasks.git
cd tasks
echo 'CIIP C++ Course' > README.md
git add README.md
git commit -m 'init'
git push
```

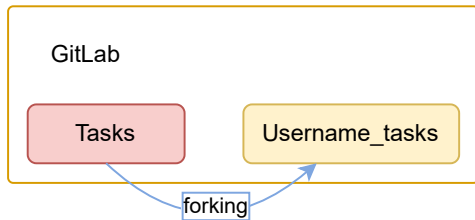
- We clone the **Tasks** repository to the **Tutor** directory
- Add a new README.md file
- Push the changes (init) to remote



Forking (Requesting Access to the Waiting Room)

- A **fork** is just a `--bare` clone.
- GitLab does the same thing when you request access to the **Waiting Room**

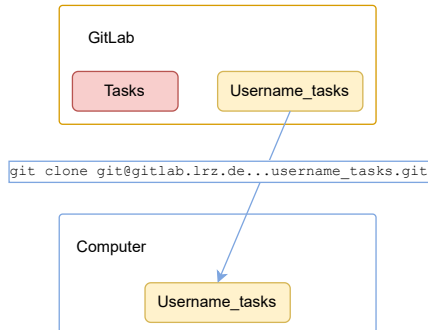
```
# Forking
cd /tmp/git-example/gitlab
git clone --bare tasks.git username_tasks.git
```



Cloning (Downloading your repository)

A **clone** is just a copy.

```
# Cloning
mkdir /tmp/git-example/computer
cd /tmp/git-example/computer
git clone /tmp/git-example/gitlab/username_tasks.git
cd username_tasks
```



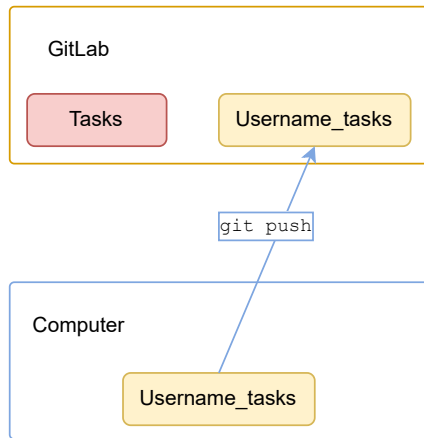
Pushing (Uploading to GitLab)

- We write "Hello!" into submission.txt
- We push our changes to `Username_tasks` (origin).

```
# Working
echo 'Hello!' > submission.txt
cat submission.txt

# Tracking changes
git add submission.txt
git commit -m 'Hello World!'

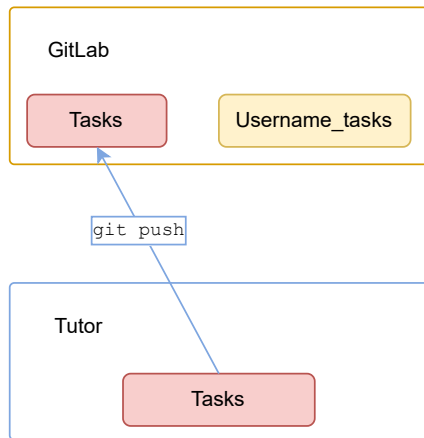
# Pushing
git push
```



Publishing a new homework sheet

- We add a new `submission.txt` file to **Tasks**
- Push the changes (Homework 0) to remote

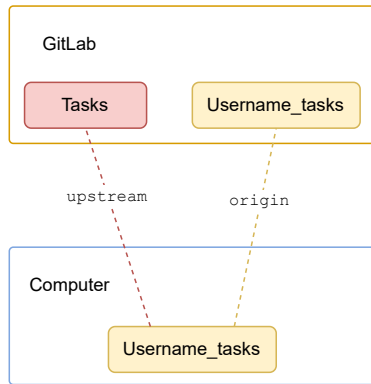
```
# Publishing the first exercise
cd /tmp/git-example/tutor/tasks
echo 'Greetings!' > submission.txt
git add submission.txt
git commit -m 'Homework 0'
git push
```



Getting the homework (Setting upstream)

We define how to access the remote **Tasks** repository (upstream)

```
# Adding upstream  
cd /tmp/git-example/computer/username_tasks  
git remote add upstream /tmp/git-example/gitlab/tasks.git
```

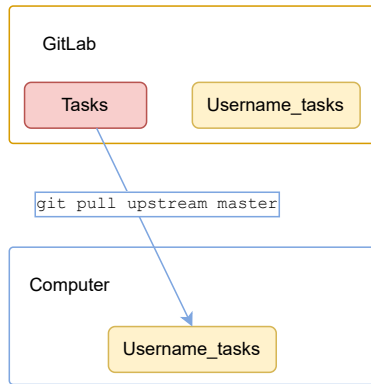


Getting the homework (Pulling from upstream)

We **pull** Homework 0 from **Tasks** (upstream)

```
# Getting Homework 0
git config pull.rebase false
git pull upstream master
```

```
From /tmp/git-example/gitlab/tasks
* branch          master      -> FETCH_HEAD
Auto-merging submission.txt
CONFLICT (add/add): Merge conflict in submission.txt
Automatic merge failed;
fix conflicts and then commit the result.
```



Upstream and merge conflicts

- Inspecting the **merge conflict**

```
cat submission.txt
<<<<<< HEAD
Hello!
=====
Greetings!
>>>>>> bc8fe100...
```

- Overwriting our changes

```
git restore -s upstream/master submission.txt
```

- Committing the changes

```
git add submission.txt
git commit -m 'restoring tasks submission.txt'
```

```
diff --git a/submission.txt b/submission.txt
index 10ddd6d..ae4bcb0 100644
--- a/submission.txt
+++ b/submission.txt
@@ -1,5 @@
+<<<<<< HEAD
+Hello!
+=====
+Greetings!
+>>>>>> bc8fe100b94adbb2f4ad1dc23ac0ab385a069800
```


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Declaration, definition, and initialization

- A declaration specifies all that is needed to use a function or type.

```
int f(int); // declares, but doesn't define function f
```

- A definition is a declaration that fully defines the entity.

```
int i; // declares and defines variable i
```

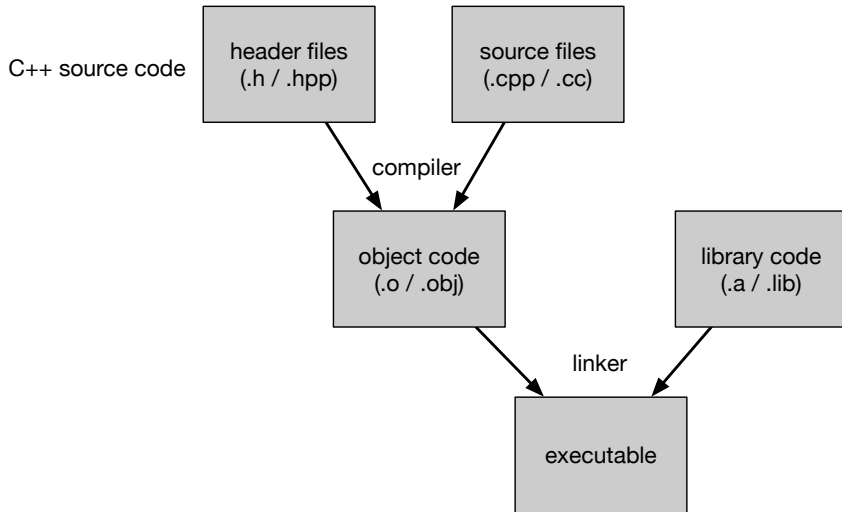
- The initialization gives an object a value.

```
int i{1}; // declares, defines, and initializes variable i
```

Headers and Sources

- `.cpp` files denote source files, which contain **definitions**.
- `.h` files denote header files, which contain **declarations** and define **interfaces**
- Therefore, header files are not explicitly passed as filename, but are included from source files.
- Each compiler invocation is a translation unit!

Compilation and linking



A first C++ program

File first.cpp (old style):

```
1  #include <iostream>
2
3  int main() {
4      std::cout << "Hello world!\n";
5  }
```

File first.cpp (C++ 23):

```
1  #include <print>
2
3  int main() {
4      std::println("Hello world!");
5  }
```

Preprocessor

- preprocess `first.cpp`

```
g++ -E -P first.cpp -o first_preprocessed.cpp
```

- resulting `first_preprocessed.cpp` includes the code from `iostream`
- file has now ~30k lines instead of 5

Compile

- compile translation unit: `first_preprocessed.cpp`

```
g++ -c first_preprocessed.cpp
```

- resulting `first_preprocessed.o` is the compiled source code without the `definition` of `std::cout`
- The member function `std::cout` is undefined (U) ¹

```
nm -C first_preprocessed.o
...
0000000000000000 T main
                 U std::ios_base_library_init()
                 U std::cout
                 U std::ostream& std::operator<< (std::ostream &, const char *)
...
```

¹For more information watch Ben Eater's videos, e.g <https://youtu.be/y0yaJXpAYZQ> or compile the code on <https://godbolt.org/>

Link and Execute

- link `first_preprocessed.o`

```
g++ first_preprocessed.o -o first
```

- and execute `first`

```
./first  
Hello world!
```


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Exercise 0:

Gain access to the course group on GitLab and install the required tools

- request access for the [Waiting Room](https://gitlab.lrz.de/cppcourse/ws2023/waiting-room) at `https://gitlab.lrz.de/cppcourse/ws2023/waiting-room`
- make sure you have all the necessary tools (git, compiler)
- set up your preferred development environment

Exercise 1:

Set up the assignments repository

- enter (and generate, if necessary) your SSH key in GitLab
- clone the repository to your machine

```
git clone git@gitlab.lrz.de:cppcourse/ws2023/your-username_tasks.git
```

- configure pulling from upstream (for future assignments)
- verify your setup: display remote git servers

```
git remote -v
```

Exercise 2:

Build the provided project manually - and fix the missing parts. Invoke the compiler directly in a shell, like you saw in this exercise session.

- build a shared library from `library.cpp`
- create a header file for the library and include it in `hw01.cpp`
- build, link, and run `hw01.cpp`

Exercise 3:

Test your library using doctest. (We use doctest to validate the solutions of upcoming homeworks.)

- Build `test.cpp` while including doctest and link it to `library`
- run `./hw01test` to test your library