

HIN2Vec: Explore Meta-paths in Heterogeneous Information Networks for Representation Learning

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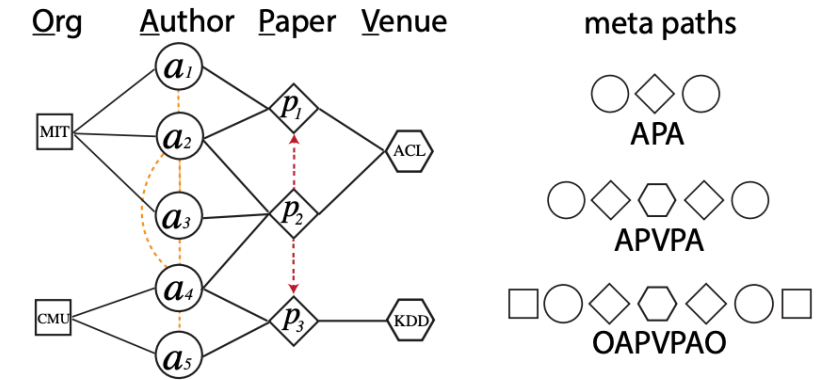
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Definition

DEFINITION 1. Information Network. An information network is a directed graph $G = (V, E, \Phi, \Psi)$, where V is the set of nodes; $E \subseteq V \times V$ is the set of edges in V . $\Phi : V \rightarrow A$ and $\Psi : E \rightarrow R$ are type mapping functions for nodes and edges, respectively. Here each node $v \in V$ is mapped to one particular node type in A , i.e., $\Phi(v) \in A$, and each link $e \in E$ belongs to a particular edge type in R , i.e., $\Psi(e) \in R$. When $|A| > 1$ or $|R| > 1$, the network is called a heterogeneous information network (HIN); otherwise, it is a homogeneous information network.

DEFINITION 2. Meta-path. Given a heterogeneous information network $G = (V, E, \Phi, \Psi)$, a meta-path π is a sequence of node types a_1, a_2, \dots, a_n and/or edge types r_1, r_2, \dots, r_{n-1} :

$$\pi = a_1 \xrightarrow{r_1} \dots a_i \xrightarrow{r_i} \dots \xrightarrow{r_{n-1}} a_n$$



(a) An academic network

Framework

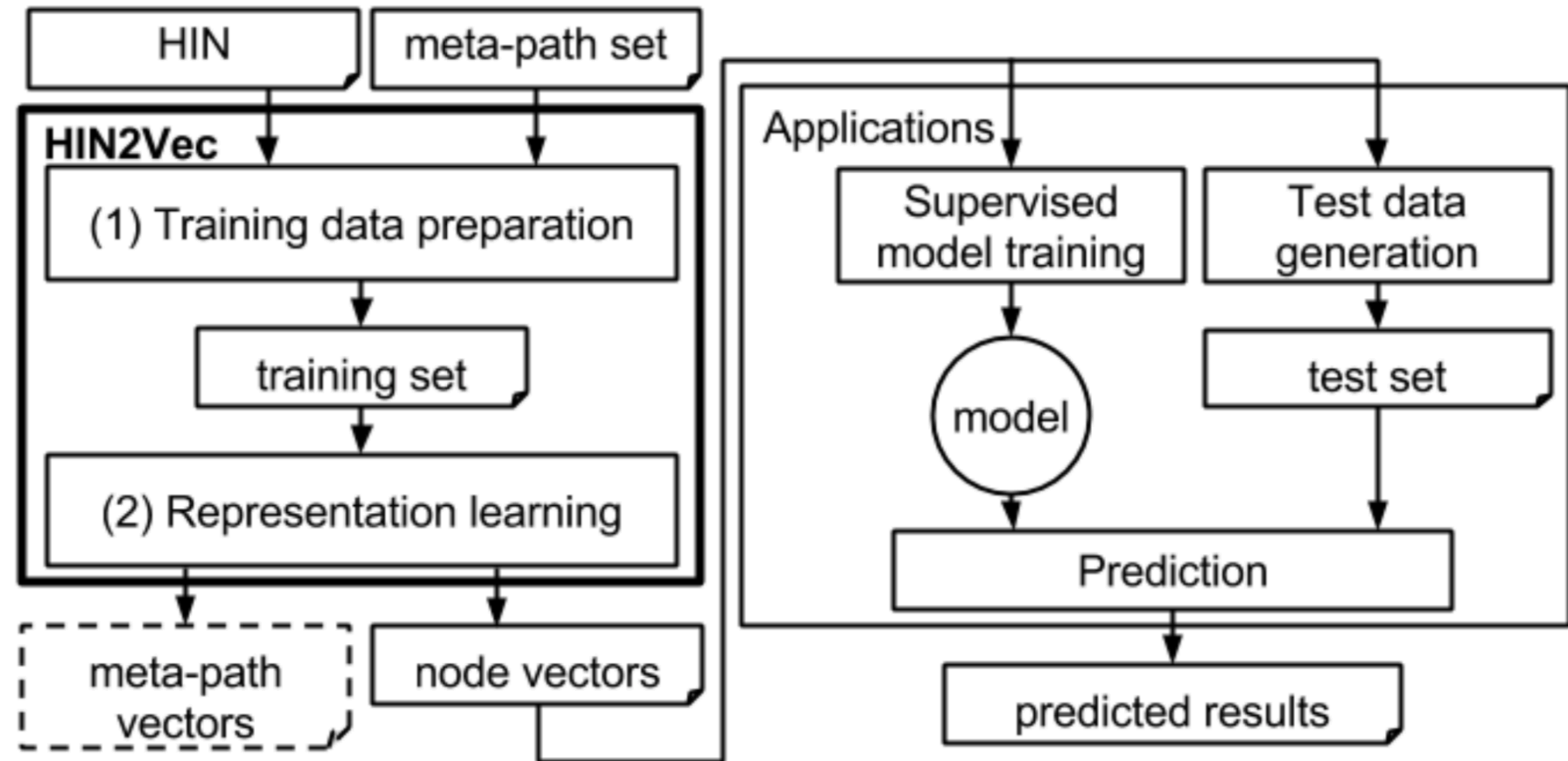


Figure 1: Overview of the HIN2Vec framework

Representation Learning

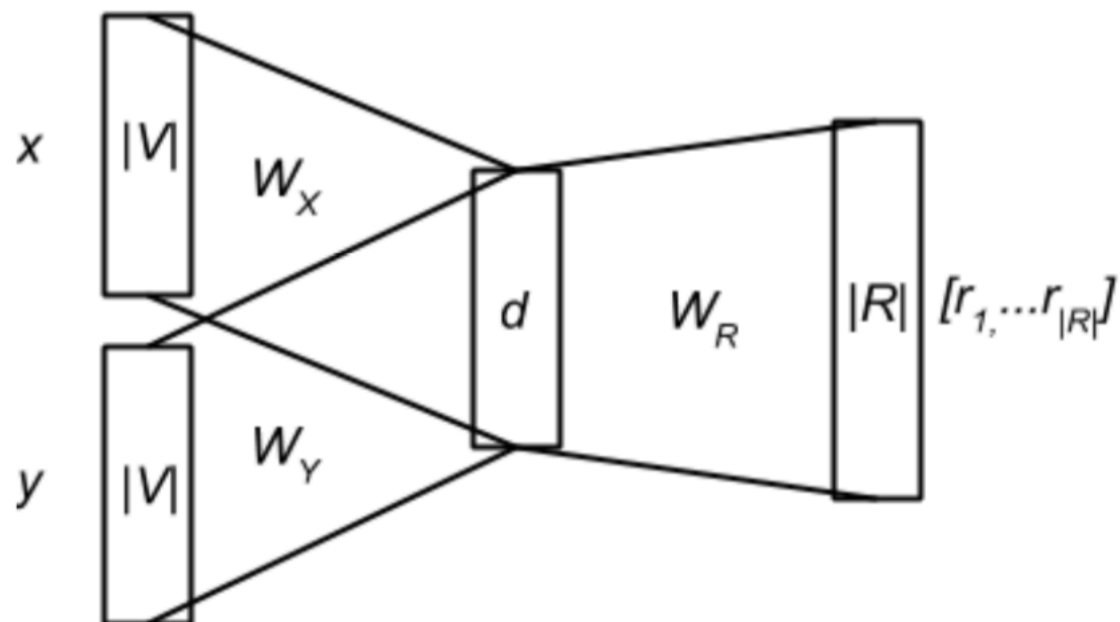


Figure 2: A conceptual model for HIN2Vec

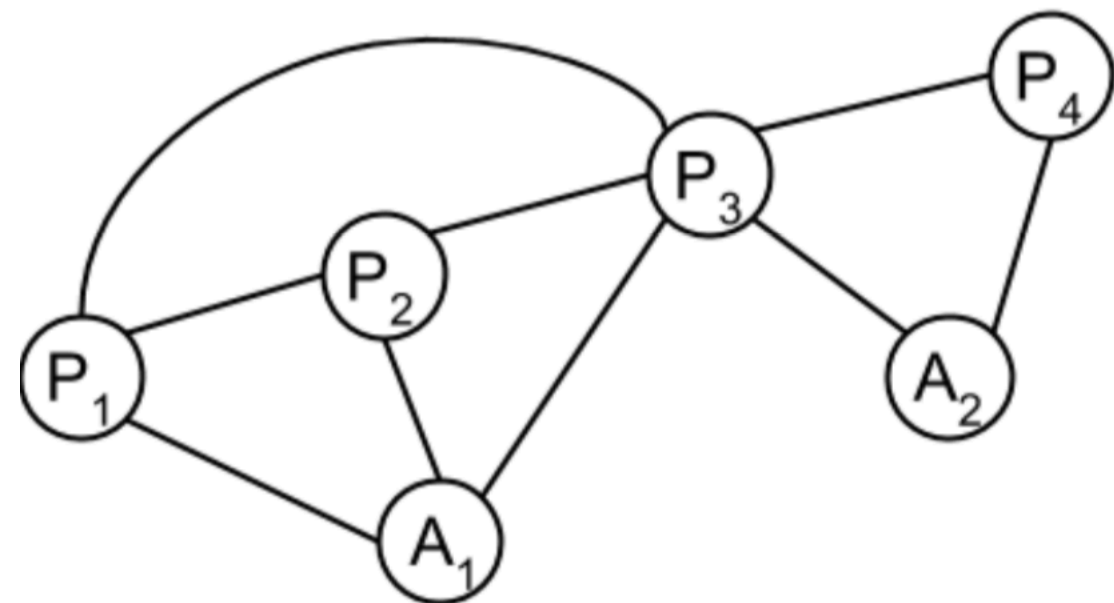


Figure 3: A paper-author HIN

$$R = \{P - P, P - A, A - P, P - P - A, P - P - P, P - A - P, A - P - P, A - P - A\}$$

Multi-label classification problem:

predict the probabilities $P(r_i | x, y)$ ($i = 1..|R|$)

For instance, P_1 and A_1 have two relationships, P-A and P-P-A. A training data entry is $\langle x : P_1, y : A_1, output : [0, 1, 0, 0, 1, 0, 0, 0] \rangle$.

Disadvantages

- **For each pair of nodes, traverse the entire network as they prepare training data to find all possible relationship types R .**
- **W_X, W_Y and W_R , need to be updated in accordance with all the relationships**

HIN2vec

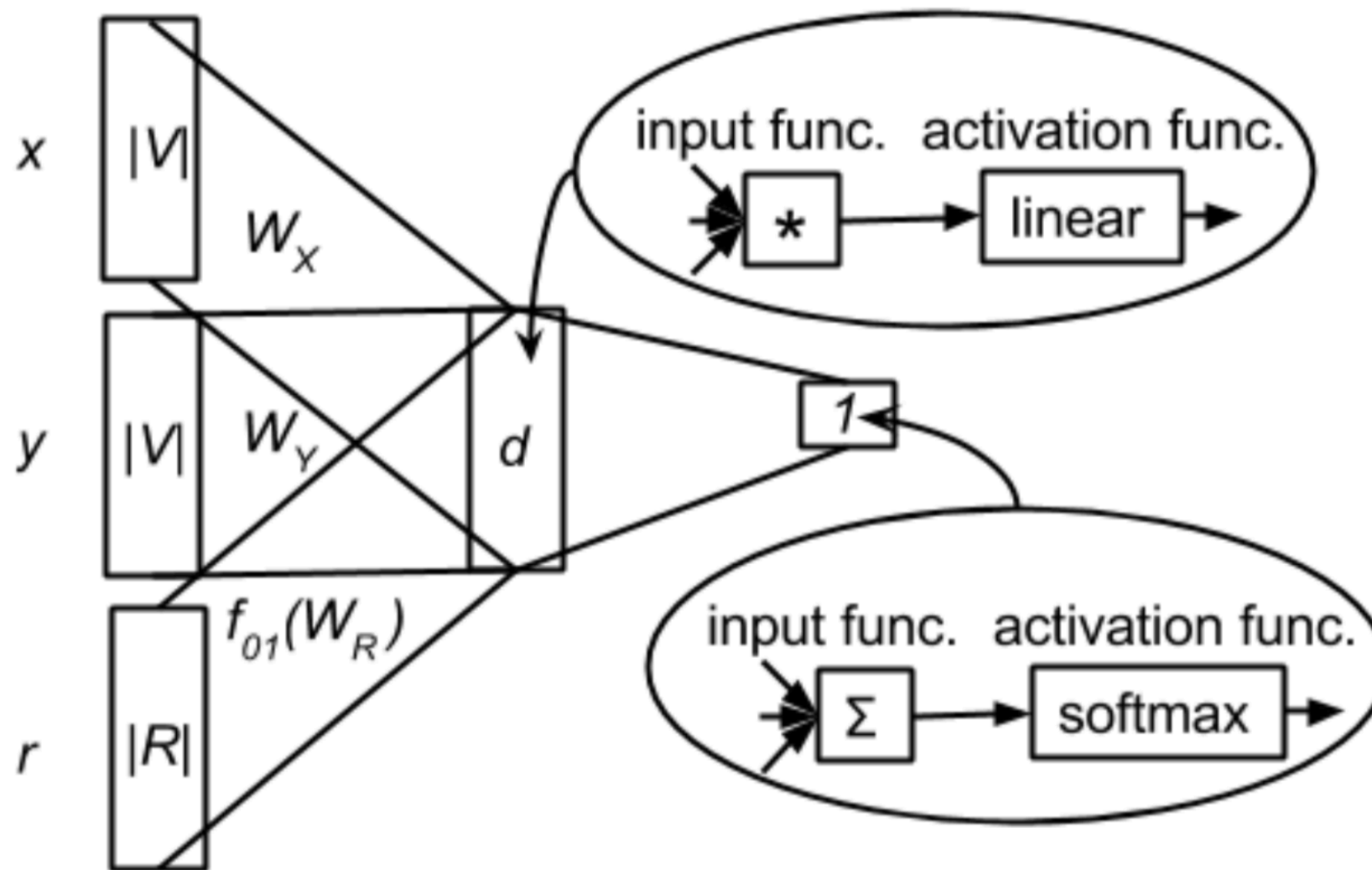


Figure 4: The HIN2Vec NN model

whether two nodes, x and y , have a specific relationship r .

Input layer:

1. The relationship type is no longer a prediction object, but appears as an input in the input layer.
2. The transformation matrix W_R of the relationship has a regularization function

Hidden layer:

1. Input is $W_x^T \vec{x}, W_y^T \vec{y}, f_{01}(W_R^T \vec{r})$
2. Output is $W_x^T \vec{x} \odot W_y^T \vec{y} \odot f_{01}(W_R^T \vec{r})$
3. Hadamard, mean, difference, and absolute value of the difference are used respectively. Finally, the Hadamard function works best.

Output layer:

1. Input is $\sum W_x^T \vec{x} \odot W_y^T \vec{y} \odot f_{01}(W_R^T \vec{r})$
2. The activation function is sigmoid function.

Regularization of W_R

Binary Step function outperforms Sigmoid.

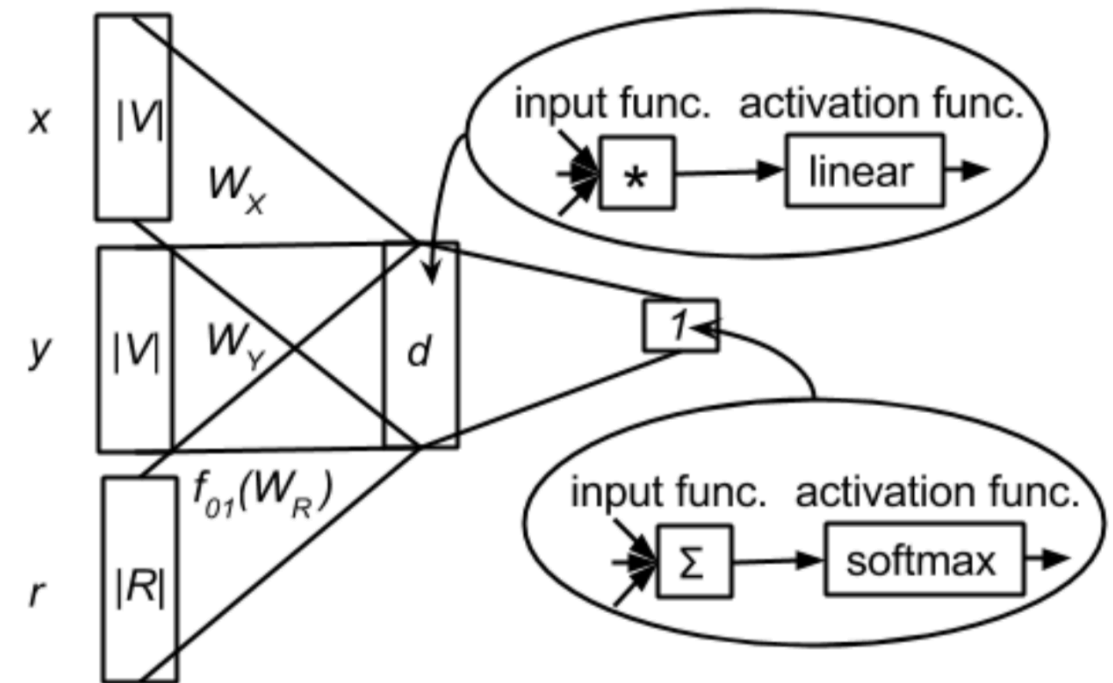


Figure 4: The HIN2Vec NN model

Optimizations

Training data form

$$\langle x, y, r, L(x, y, r) \rangle$$

The objective function \mathcal{O}

$$\mathcal{O} \propto \log \mathcal{O} = \sum_{x, y, r \in D} \log \mathcal{O}_{x, y, r}(x, y, r)$$

$$\mathcal{O}_{x, y, r}(x, y, r) = \begin{cases} P(r|x, y), & \text{if } L(x, y, r) = 1 \\ 1 - P(r|x, y), & \text{if } L(x, y, r) = 0 \end{cases}$$

$$\log \mathcal{O}_{x, y, r}(x, y, r) = L(x, y, r) \log P(r|x, y) + [1 - L(x, y, r)] \log [1 - P(r|x, y)]$$

Whether there is a relationship r between nodes x and y

$$P(r|x, y) = \text{sigmoid}(\sum W_x^T \vec{x} \odot W_y^T \vec{y} \odot f_{01}(W_R^T \vec{R}))$$

Training Data Preparation

Remove cycles during random walk

$$(A_1, A_1, A - P - A)$$

Sample negative data

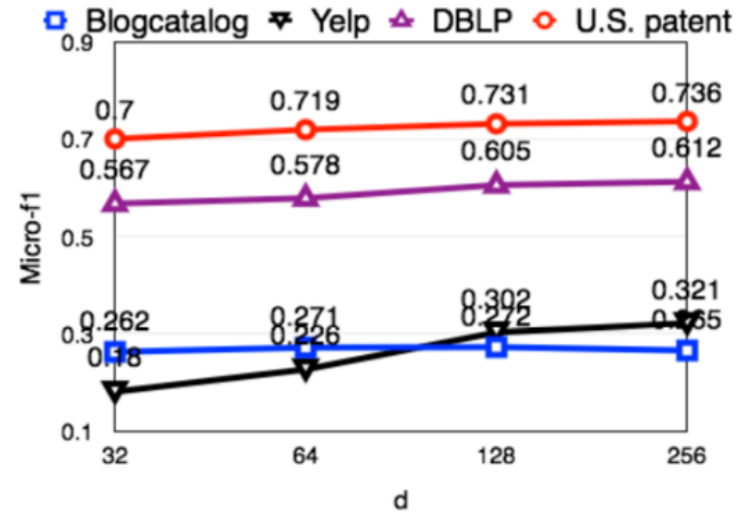
For each sampled positive entry, $\langle x, y, r \rangle$,

replacing one of the three values

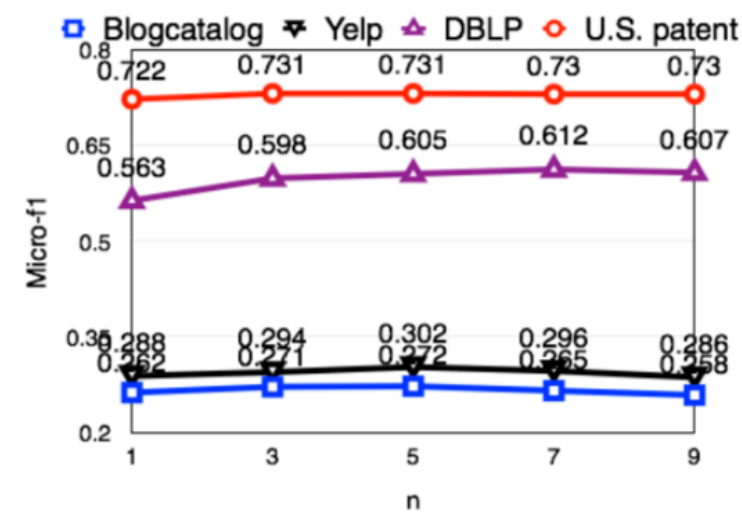
negative data entry, $\langle x'', y'', r'' \rangle$

x'' and y'' are not expected to have a certain relationship r'' .

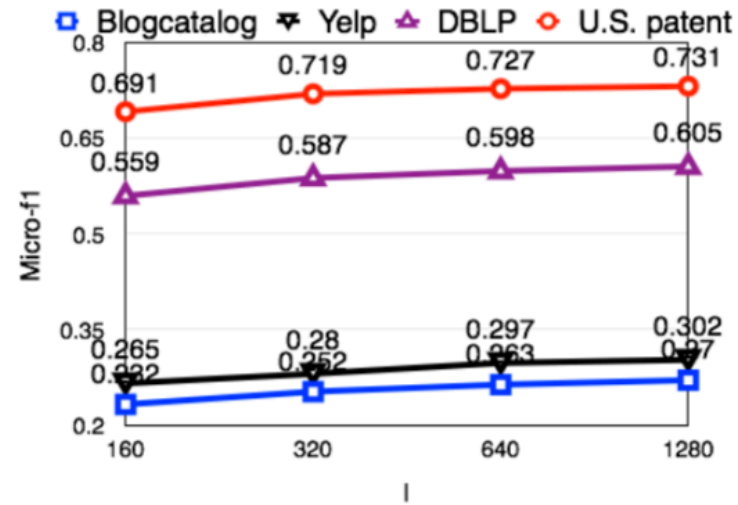
EXPERIMENTS



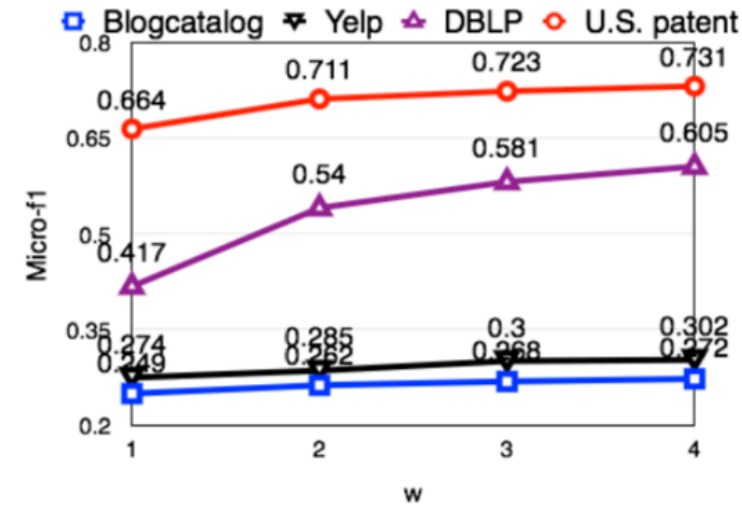
(a) Dimensionality d



(b) Number of Negative Samples n



(c) Length of Random Walks l



(d) Length of Meta-paths w

Figure 5: Parameter Tuning

how the micro-f1 changes in node classification in the networks.

Table 2: Performance Evaluation of Node Classification

| | Blogcatalog | | Yelp | | DBLP | | U.S. Patents | |
|----------|--------------------|---------------------|--------------------|---------------------|---------------------|---------------------|--------------------|--------------------|
| | micro-f1 | macro-f1 | micro-f1 | macro-f1 | micro-f1 | macro-f1 | micro-f1 | macro-f1 |
| DeepWalk | 0.244 | 0.140 | 0.276 | 0.165 | 0.481 | 0.463 | 0.675 | 0.676 |
| LINE | 0.239 | 0.128 | 0.270 | 0.163 | 0.449 | 0.429 | 0.66 | 0.663 |
| node2vec | 0.246 | 0.141 | 0.276 | 0.166 | 0.491 | 0.470 | 0.676 | 0.677 |
| PTE | 0.179 | 0.096 | 0.222 | 0.130 | 0.417 | 0.394 | 0.547 | 0.555 |
| HINE | *0.250 | *0.144 | *0.278 | *0.169 | 0.475 | 0.461 | *0.681 | *0.685 |
| ESim | 0.207 | 0.102 | 0.229 | 0.132 | *0.514 | *0.496 | 0.610 | 0.562 |
| HIN2Vec | 0.272(9.9%) | 0.158(11.3%) | 0.302(7.9%) | 0.192(12.0%) | 0.605(23.8%) | 0.594(20.1%) | 0.729(6.6%) | 0.732(6.4%) |

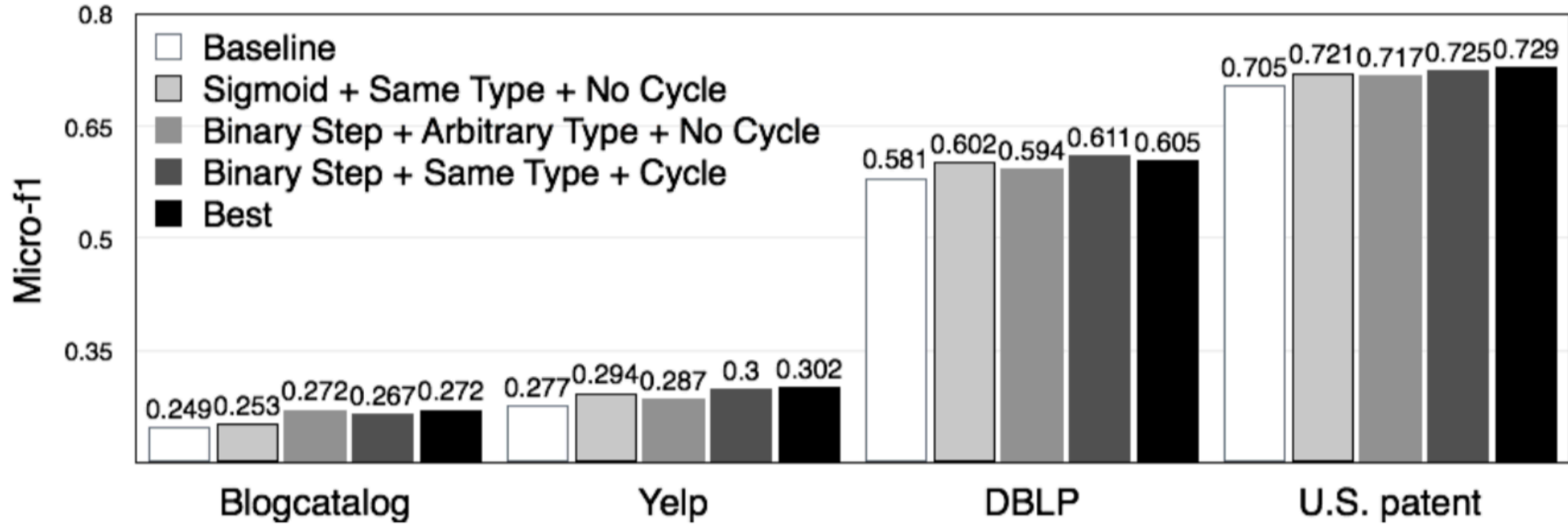


Figure 6: Comparison of approaches to issues in HIN2Vec

Table 4: Vector Functions of Node Pairs

| Functions | Hadamard | Average | Minus | Abs. Minus |
|-------------|-------------------------------|---|-------------------------------|---------------------------------|
| Description | $\vec{v}_{1i} * \vec{v}_{2i}$ | $\frac{\vec{v}_{1i} + \vec{v}_{2i}}{2}$ | $\vec{v}_{1i} - \vec{v}_{2i}$ | $ \vec{v}_{1i} - \vec{v}_{2i} $ |

Table 5: Performance Evaluation of Vector Functions

| | Blogcatalog | | Yelp | | DBLP | | U.S. Patents | |
|------------|--------------|--------------|--------------|--------------|--------------|--------------|--------------|--------------|
| | MAP | recall@100 | MAP | recall@100 | MAP | recall@100 | MAP | recall@100 |
| Hadamard | 0.141 | 0.279 | 0.028 | 0.138 | 0.265 | 0.751 | 0.176 | 0.602 |
| Average | 0.074 | 0.245 | 0.004 | 0.033 | 0.005 | 0.124 | 0.008 | 0.063 |
| Minus | 0.050 | 0.171 | 0.004 | 0.030 | 0.004 | 0.114 | 0.009 | 0.059 |
| Abs. minus | 0.130 | 0.238 | 0.023 | 0.119 | 0.249 | 0.750 | 0.130 | 0.540 |

Table 6: Performance Evaluation of Link Prediction

| | Blogcatalog | | Yelp | | DBLP | | U.S. Patents | |
|----------|--------------------|---------------------|---------------------|---------------------|---------------------|--------------------|---------------------|---------------------|
| | MAP | recall@100 | MAP | recall@100 | MAP | recall@100 | MAP | recall@100 |
| DeepWalk | 0.124 | 0.227 | *0.021 | 0.110 | 0.230 | *0.710 | 0.093 | 0.500 |
| LINE | *0.134 | *0.249 | 0.017 | 0.104 | 0.086 | 0.580 | 0.091 | 0.400 |
| node2vec | 0.125 | 0.229 | *0.021 | *0.111 | *0.231 | *0.710 | 0.095 | *0.503 |
| PTE | 0.067 | 0.139 | 0.004 | 0.034 | 0.071 | 0.324 | 0.030 | 0.243 |
| HINE | 0.085 | 0.179 | 0.016 | 0.097 | 0.205 | 0.697 | *0.103 | 0.495 |
| ESim | 0.132 | 0.185 | x | x | 0.179 | 0.633 | x | x |
| MPE | 0.141(5.0%) | 0.279(10.8%) | 0.028(31.8%) | 0.138(24.3%) | 0.265(12.8%) | 0.751(5.8%) | 0.176(70.8%) | 0.602(19.9%) |