CNN Backpropagation

Shorthand: "pd_" as a variable prefix means "partial derivative" "d_" as a variable prefix means "derivative" "_wrt_" is shorthand for "with respect to" "w_ho" and "w_ih" are the index of weights from hidden to output layer neurons and input to hidden layer neurons respectively

Comment references:

[1] Wikipedia article on Backpropagation http://en.wikipedia.org/wiki/Backpropagation#Finding_the_derivative_of_the_error (http://en.wikipedia.org/wiki/Backpropagation#Finding_the_derivative_of_the_error) [2] Neural Networks for Machine Learning course on Coursera by Geoffrey Hinton https://class.coursera.org/neuralnets-2012-001/lecture/39 (https://class.coursera.org/neuralnets-2012-001/lecture/39) [3] The Back Propagation Algorithm https://www4.rgu.ac.uk/files/chapter3%20-%20bp.pdf (https://www4.rgu.ac.uk/files/chapter3%20-%20bp.pdf)

Autor: Hermann Völlinger, DHBW Stuttgart; Date: 7.09.2024

In [8]:

```
# Importing everything we need
import random
import math

# Import libary time to check execution date+time
import time
# print the date & time of the notebook
print('*******************************************************************
print("Actual date & time of the notebook:",time.strftime("%d.%m.%Y %H:%M
print('*******************************************************************

#check versions of libraries
#print('random version is: {}'.format(random.__version__))
#print('math version is: {}'.format(math.__version__))

```

```
************************************************************************
Actual date & time of the notebook: 08.09.2024 17:22:26
************************************************************************
```

In [9]:

```python
# Definition von einme Neuronalen Netz (NN)
class NeuralNetwork:
    LEARNING_RATE = 0.5

    def __init__(self, num_inputs, num_hidden, num_outputs, hidden_layer_
        self.num_inputs = num_inputs

        self.hidden_layer = NeuronLayer(num_hidden, hidden_layer_bias)
        self.output_layer = NeuronLayer(num_outputs, output_layer_bias)

        self.init_weights_from_inputs_to_hidden_layer_neurons(hidden_laye
        self.init_weights_from_hidden_layer_neurons_to_output_layer_neuro

    def init_weights_from_inputs_to_hidden_layer_neurons(self, hidden_lay
        weight_num = 0
        for h in range(len(self.hidden_layer.neurons)):
            for i in range(self.num_inputs):
                if not hidden_layer_weights:
                    self.hidden_layer.neurons[h].weights.append(random.ra
                else:
                    self.hidden_layer.neurons[h].weights.append(hidden_la
                weight_num += 1

    def init_weights_from_hidden_layer_neurons_to_output_layer_neurons(se
        weight_num = 0
        for o in range(len(self.output_layer.neurons)):
            for h in range(len(self.hidden_layer.neurons)):
                if not output_layer_weights:
                    self.output_layer.neurons[o].weights.append(random.ra
                else:
                    self.output_layer.neurons[o].weights.append(output_la
                weight_num += 1

    def inspect(self):
        print('------')
        print('* Inputs: {}'.format(self.num_inputs))
        print('------')
        print('Hidden Layer')
        self.hidden_layer.inspect()
        print('------')
        print('* Output Layer')
        self.output_layer.inspect()
        print('------')

    def feed_forward(self, inputs):
        hidden_layer_outputs = self.hidden_layer.feed_forward(inputs)
        return self.output_layer.feed_forward(hidden_layer_outputs)

    # Uses online learning, ie updating the weights after each training c
    def train(self, training_inputs, training_outputs):
        self.feed_forward(training_inputs)

        # 1. Output neuron deltas
        pd_errors_wrt_output_neuron_total_net_input = [0] * len(self.outp
        for o in range(len(self.output_layer.neurons)):

            # ∂E/∂zⱼ
            pd_errors_wrt_output_neuron_total_net_input[o] = self.output_

        # 2. Hidden neuron deltas
        pd_errors_wrt_hidden_neuron_total_net_input = [0] * len(self.hidc
        for h in range(len(self.hidden_layer.neurons)):
```

```python

            # We need to calculate the derivative of the error with respe
            # dE/dyⱼ = Σ ∂E/∂zⱼ * ∂z/∂yⱼ = Σ ∂E/∂zⱼ * wᵢⱼ
            d_error_wrt_hidden_neuron_output = 0
            for o in range(len(self.output_layer.neurons)):
                d_error_wrt_hidden_neuron_output += pd_errors_wrt_output_

            # ∂E/∂zⱼ = dE/dyⱼ * ∂zⱼ/∂
            pd_errors_wrt_hidden_neuron_total_net_input[h] = d_error_wrt_

        # 3. Update output neuron weights
        for o in range(len(self.output_layer.neurons)):
            for w_ho in range(len(self.output_layer.neurons[o].weights))

                # ∂Eⱼ/∂wᵢⱼ = ∂E/∂zⱼ * ∂zⱼ/∂wᵢⱼ
                pd_error_wrt_weight = pd_errors_wrt_output_neuron_total_r

                # Δw = α * ∂Eⱼ/∂wᵢ
                self.output_layer.neurons[o].weights[w_ho] -= self.LEARNI

        # 4. Update hidden neuron weights
        for h in range(len(self.hidden_layer.neurons)):
            for w_ih in range(len(self.hidden_layer.neurons[h].weights))

                # ∂Eⱼ/∂wᵢ = ∂E/∂zⱼ * ∂zⱼ/∂wᵢ
                pd_error_wrt_weight = pd_errors_wrt_hidden_neuron_total_r

                # Δw = α * ∂Eⱼ/∂wᵢ
                self.hidden_layer.neurons[h].weights[w_ih] -= self.LEARNI

    def calculate_total_error(self, training_sets):
        total_error = 0
        for t in range(len(training_sets)):
            training_inputs, training_outputs = training_sets[t]
            self.feed_forward(training_inputs)
            for o in range(len(training_outputs)):
                total_error += self.output_layer.neurons[o].calculate_err
        return total_error

```

In [10]:

```python
# Definition eines Neuronnalen Layers
class NeuronLayer:
    def __init__(self, num_neurons, bias):

        # Every neuron in a layer shares the same bias
        self.bias = bias if bias else random.random()

        self.neurons = []
        for i in range(num_neurons):
            self.neurons.append(Neuron(self.bias))

    def inspect(self):
        print('Neurons:', len(self.neurons))
        for n in range(len(self.neurons)):
            print(' Neuron', n)
            for w in range(len(self.neurons[n].weights)):
                print('  Weight:', self.neurons[n].weights[w])
            print('  Bias:', self.bias)

    def feed_forward(self, inputs):
        outputs = []
        for neuron in self.neurons:
            outputs.append(neuron.calculate_output(inputs))
        return outputs

    def get_outputs(self):
        outputs = []
        for neuron in self.neurons:
            outputs.append(neuron.output)
        return outputs
```

In [11]:

```python
class Neuron:
    def __init__(self, bias):
        self.bias = bias
        self.weights = []

    def calculate_output(self, inputs):
        self.inputs = inputs
        self.output = self.squash(self.calculate_total_net_input())
        return self.output

    def calculate_total_net_input(self):
        total = 0
        for i in range(len(self.inputs)):
            total += self.inputs[i] * self.weights[i]
        return total + self.bias

    # Apply the logistic function to squash the output of the neuron
    # The result is sometimes referred to as 'net' [2] or 'net' [1]
    def squash(self, total_net_input):
        return 1 / (1 + math.exp(-total_net_input))

    # Determine how much the neuron's total input has to change to move c
    #
    # Now that we have the partial derivative of the error with respect t
    # the derivative of the output with respect to the total net input (d
    # the partial derivative of the error with respect to the total net i
    # This value is also known as the delta (δ) [1]
    # δ = ∂E/∂zⱼ = ∂E/∂yⱼ * dyⱼ/dzⱼ
    #
    def calculate_pd_error_wrt_total_net_input(self, target_output):
        return self.calculate_pd_error_wrt_output(target_output) * self.c

    # The error for each neuron is calculated by the Mean Square Error me
    def calculate_error(self, target_output):
        return 0.5 * (target_output - self.output) ** 2

    # The partial derivate of the error with respect to actual output the
    # = 2 * 0.5 * (target output - actual output) ^ (2 - 1) * -1
    # = -(target output - actual output)
    #
    # The Wikipedia article on backpropagation [1] simplifies to the foll
    # = actual output - target output
    #
    # Alternative, you can use (target - output), but then need to add it
    #
    # Note that the actual output of the output neuron is often written a
    # = ∂E/∂yⱼ = -(tⱼ - yⱼ)
    def calculate_pd_error_wrt_output(self, target_output):
        return -(target_output - self.output)

    # The total net input into the neuron is squashed using logistic func
    # yⱼ = φ = 1 / (1 + e^(-zⱼ))
    # Note that where ⱼ represents the output of the neurons in whatever
    #
    # The derivative (not partial derivative since there is only one vari
    # dyⱼ/dzⱼ = yⱼ * (1 - yⱼ)
    def calculate_pd_total_net_input_wrt_input(self):
        return self.output * (1 - self.output)

    # The total net input is the weighted sum of all the inputs to the ne
    # = zⱼ = netⱼ = x₁w₁ + x₂w₂ ...
    #
```

```python
    # The partial derivative of the total net input with respective to a
    # = ∂zⱼ/∂wᵢ = some constant + 1 * xᵢw₁^(1-0) + some constant ... = xᵢ
    def calculate_pd_total_net_input_wrt_weight(self, index):
        return self.inputs[index]
```

In [12]:

```python
##

# Blog post example:

nn = NeuralNetwork(2, 2, 2, hidden_layer_weights=[0.15, 0.2, 0.25, 0.3],
for i in range(10000):
    nn.train([0.05, 0.1], [0.01, 0.99])
    print(i, round(nn.calculate_total_error([[[0.05, 0.1], [0.01, 0.99]]]

# XOR example:

# training_sets = [
#     [[0, 0], [0]],
#     [[0, 1], [1]],
#     [[1, 0], [1]],
#     [[1, 1], [0]]
# ]

# nn = NeuralNetwork(len(training_sets[0][0]), 5, len(training_sets[0][1]
# for i in range(10000):
#     training_inputs, training_outputs = random.choice(training_sets)
#     nn.train(training_inputs, training_outputs)
#     print(i, nn.calculate_total_error(training_sets))

```

```
26 0.111688831
27 0.107285459
28 0.103100677
29 0.099126464
30 0.095354325
31 0.091775464
32 0.088380932
33 0.085161757
34 0.082109043
35 0.079214055
36 0.076468284
37 0.073863495
38 0.071391768
39 0.069045516
40 0.066817506
41 0.064700863
42 0.062689072
43 0.060775976
44 0.058955766
45 0.057222975
```

In [13]:

```
#Abschluss
# print current date and time

print("Date & Time:",time.strftime("%d.%m.%Y  %H:%M:%S"))
# end of import test
print ("*** End of Program Backpropagation ***")



```

```
Date & Time: 08.09.2024  17:32:19
*** End of Program Backpropagation ***
```